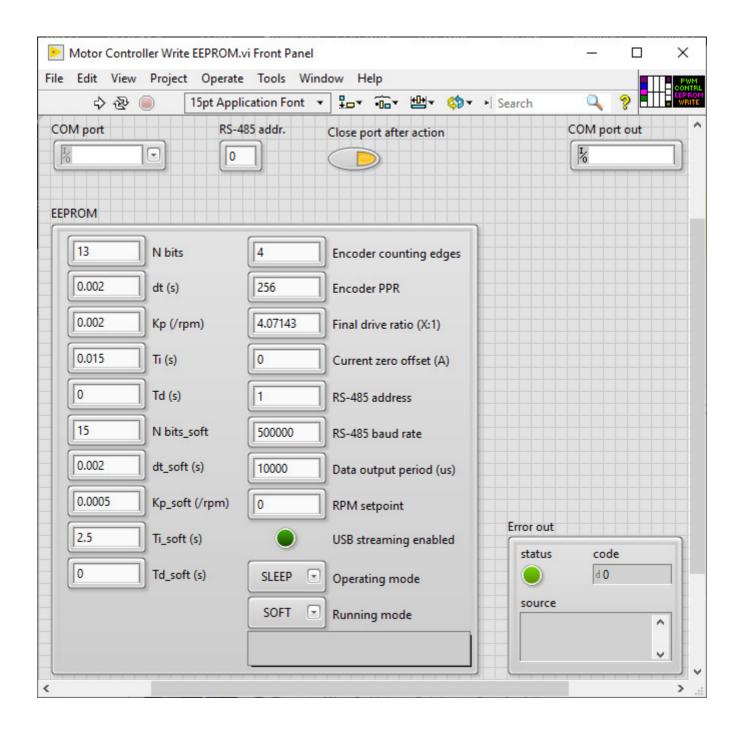
DEFAULT EEPROM VALUES.



The RS-485 address will need to be set according to the individual unit.

The current zero offset will need to be measured and set for the individual unit. This can be done simply by placing the drive into coast or sleep mode and taking a time-average of the current over sufficient time after warm-up.

The default PID coefficients are nominal and each unit + motor + load combination will have its own optimal set, again to be determined experimentally under operating conditions.