

```
#include <stdlib.h>
#include <string.h>
#include <ctype.h>
```

```
#define MAXPAROLA 30
#define MAXRIGA 80
```

```
int main(int argc, char *argv[])
```

```
{
```

```
    int freq[MAXPAROLA]; /* vettore di contatori
delle frequenze delle lunghezze delle parole */
    char riga[MAXRIGA];
    int i, inizio, lunghezza;
    FILE *f;
```

```
    for(i=0; i<MAXPAROLA; i++)
        freq[i]=0;
```

```
    if(argc != 2)
```

```
    {
        fprintf(stderr, "ERRORE: serve un parametro con il nome del file\n");
        exit(1);
    }
```

```
    f = fopen(argv[1], "r");
    if(f==NULL)
```

```
    {
        fprintf(stderr, "ERRORE: impossibile aprire il file %s\n", argv[1]);
        exit(1);
    }
```

```
    while( fgets( riga, MAXRIGA, f ) != NULL )
```

Recursion

The divide and conquer paradigm

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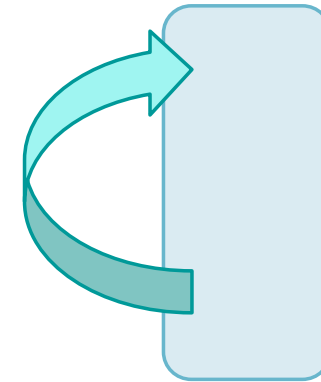
Politecnico di Torino

Definition

❖ Recursive procedure

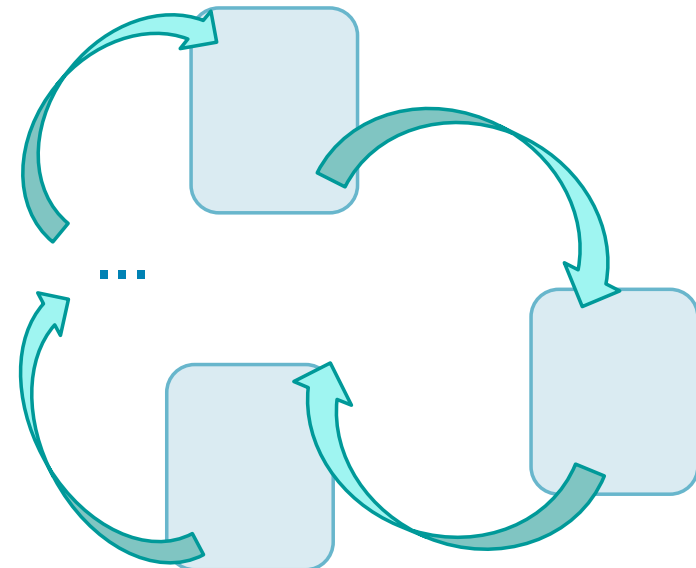
➤ **Direct** recursion

- Inside its definition there is a call to the procedure itself



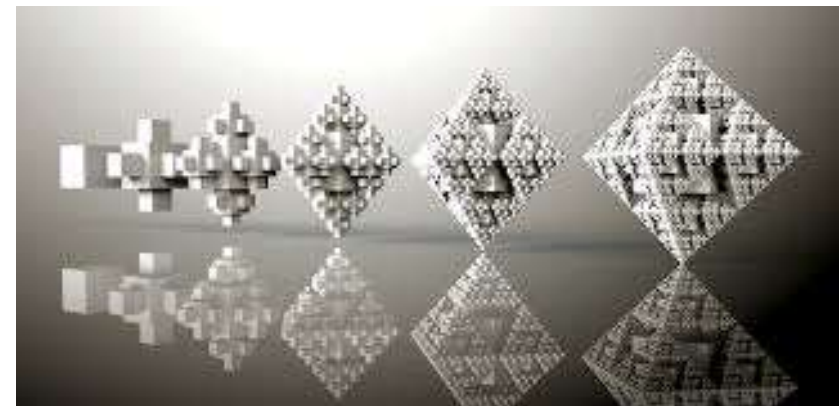
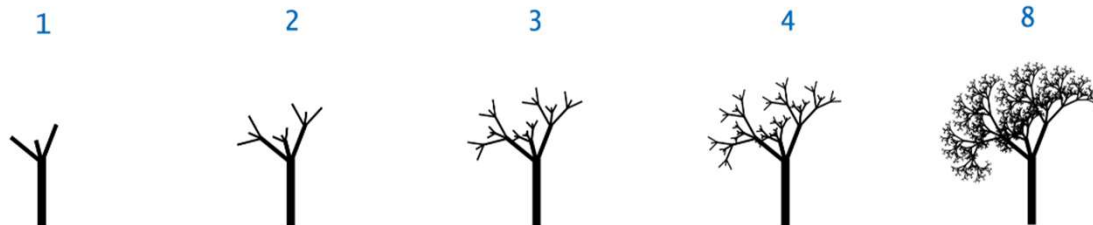
➤ **Indirect** recursion

- Inside its definition there is a call to at least one procedure that, directly or indirectly, calls the procedure itself



Definition

- ❖ Recursive algorithm
 - Based on recursive procedures



Definition

- ❖ The solution to a problem **S** applied to data **D** is recursive if we can express it as

Generic function
(f) of ...

D_{n-1} is simpler than D_n

$$S(D_n) = f(S(D_{n-1})) \quad \text{iff } D_n \neq D_0$$

$$S(D_0) = S_0 \quad \text{otherwise}$$

Termination condition

The number of times we
do apply f , i.e.,
 $i = 0 \dots n$
is the **recursion level**

Rationale

- ❖ Recursive solutions
 - Are mathematically elegant
 - Generate nice and neat procedures
- ❖ The nature of many problems is by itself recursive
 - Solution of many sub-problems may be similar to the initial one, though simpler and smaller
 - Combination of partial solutions may be used to obtain the solution of the initial problem
- ❖ Recursion is the basis for the problem-solving paradigm known as **divide and conquer**

The divide and conquer paradigm

- ❖ Recursion formulations should generate simpler and solvable sub-problems
 - We recur until
 - The sub-problems are trivial
 - All valid choices exhausted
- ❖ To reach this target, we apply the so called **divide-and-conquer** paradigm, which is based on 3 phases
 - Divide
 - Conquer
 - Combine

The divide and conquer paradigm

➤ Divide

- Starting from a problem of size n
- We partition it into $a \geq 1$ independent problems
- Each of these problems has a size \hat{n} smaller than n , i.e., $\hat{n} < n$

➤ Conquer

- Solve an elementary problem
- In this part of the algorithm we need a **termination condition**
 - All algorithms must eventually terminate
 - The recursion must be finite

➤ Combine

- Build a global solution combining partial solutions

The divide and conquer paradigm

```
solve (problem) {  
  if (problem is elementary) {  
    solution = solve_trivial (problem)  
  } else {  
    subproblem1,2,3,...,a = divide (problem)  
  
    for each  $s \in \text{subproblem}_{1,2,3,...,a}$   
      subsolutions = solve (subproblems)  
  
    solution = combine (subsolution1,2,3,...,a)  
  }  
  return solution  
}
```

Termination condition

Conquer

Divide

Recursive call

Combine

a subproblems of size n'
Each subproblem is smaller
than the original one ($n' < n$)

The divide and conquer paradigm

The else part is often avoided inserting one extra return

```
solve (problem) {  
    if (problem is elementary) {  
        solution = solve_trivial (problem)  
        return (solution)  
    }
```

Conquer

Divide

```
    subproblem1,2,3,...,a = divide (problem)
```

```
    for each  $s \in \text{subproblem}_{1,2,3,...,a}$   
        subsolutions = solve (subproblems)
```

```
    solution = combine (subsolution1,2,3,...,a)
```

```
    return solution
```

```
}
```

Combine

Complexity Analysis

❖ A **recursion equation** expresses the time asymptotic cost $T(n)$ in terms of

$D(n)$	Cost of dividing the problem
$T(\hat{n})$	Cost of the execution time for smaller inputs (recursion phase)
$C(n)$	Cost of recombining the partial solutions
Cost of the terminal cases	We often assume unit cost for solving the elementary problems $\Theta(1)$

$$T(n) = D(n) + \sum T(\hat{n}) + C(n)$$

Complexity Analysis

$$T(n) = D(n) + \sum T(\hat{n}) + C(n)$$

We suppose that the number of subproblems of size \hat{n} is a .
If $a = 1$, we have linear recursion.
If $a > 1$, we have multi-way recursion.

Complexity Analysis

Case 1

$$T(n) = D(n) + \sum T(\hat{n}) + C(n)$$

The size of the original problem n and the generated ones \hat{n} are related by a **constant factor** b in general the same for all subproblems

$$b = n/\hat{n} \text{ and } \hat{n} = n/b$$

We suppose that the number of subproblems of size \hat{n} is a .
If $a = 1$ we have linear recursion.
If $a > 1$ we have multi-way recursion.

Divide

Recur
 $T(\hat{n})$

Combine

$$T(n) = D(n) + a \cdot T\left(\frac{n}{b}\right) + C(n)$$

$$T(n) = \Theta(1)$$

$$n > \text{const}$$

$$n \leq \text{const}$$

Conquer

If $b > 1$ we have divide-and-conquer approach

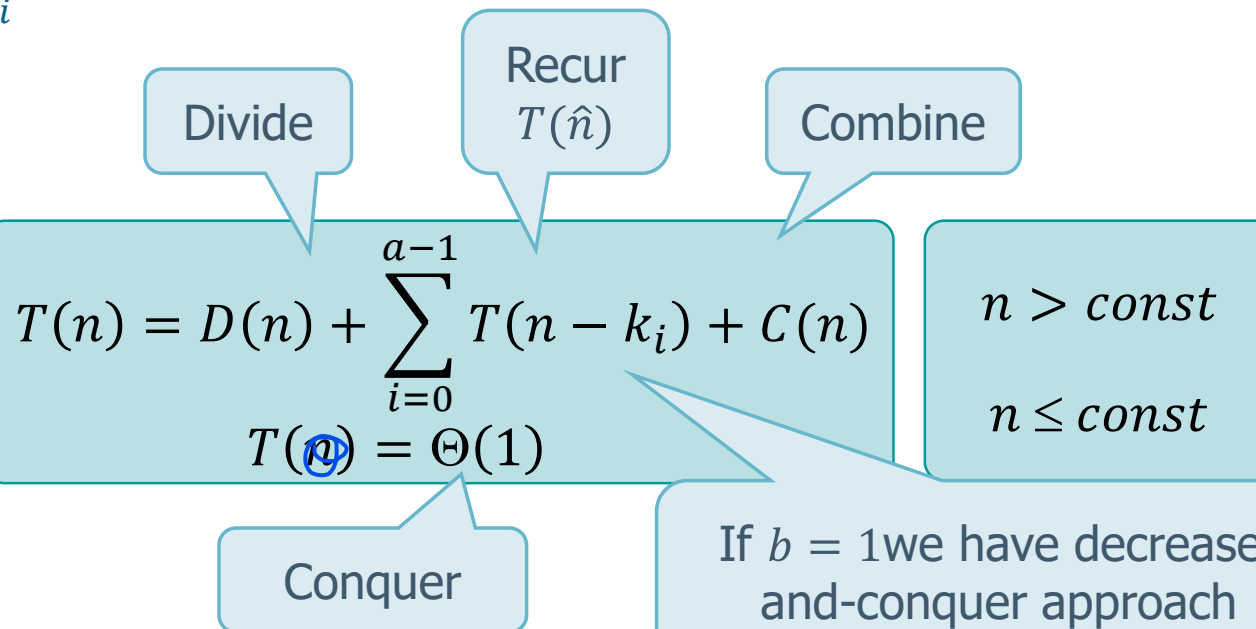
Complexity Analysis

Case 2

$$T(n) = D(n) + \sum T(\hat{n}) + C(n)$$

The size of the original problem n and the generated ones \hat{n} are related by a **constant value** k_i not always the same for all subproblems
 $\hat{n} = n - k_i$

We suppose that the number of subproblems of size \hat{n} is a .
 If $a = 1$ we have linear recursion.
 If $a > 1$ we have multi-way recursion.



A first example: Array split

❖ Given an array of $n = 2^k$ integers

Simple case
(complete tree of
height k)

❖ Recursively partition it in sub-arrays half the size,
until the termination condition is reached

➤ The termination condition is reached when sub-arrays have only 1 cell

❖ Print-out all generated partitions on standard output

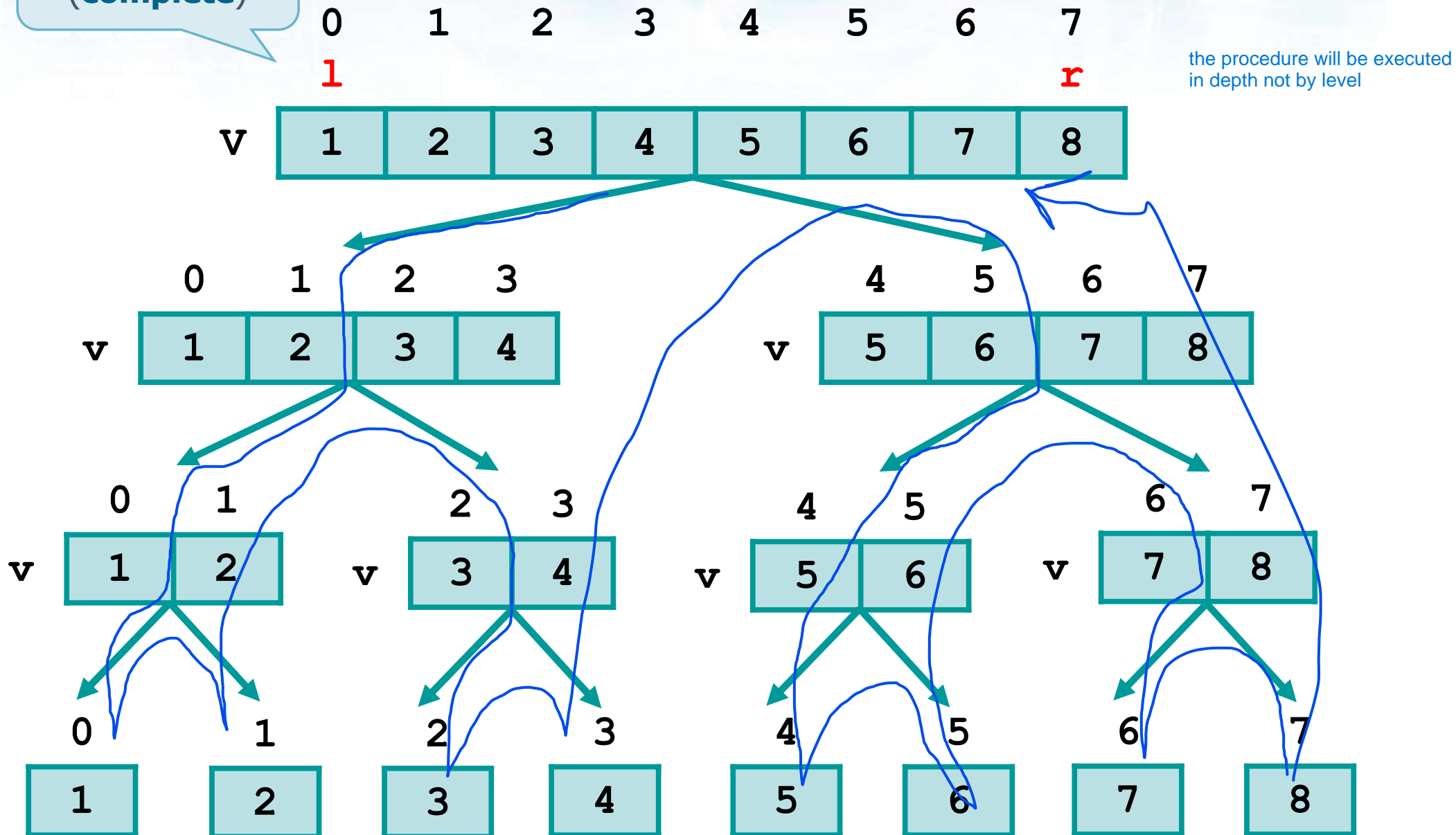
Divide and conquer

At each step we generate $a=2$ subproblems
Each subproblem has a size equal to $\hat{n} = n/2$, i.e.,

$$b = n/\hat{n} = 2$$

Solution

Recursion tree
(**complete**)



Solution 1

```
void show (
    int v[], int l, int r
) {
    int i, c;
```

Termination
condition

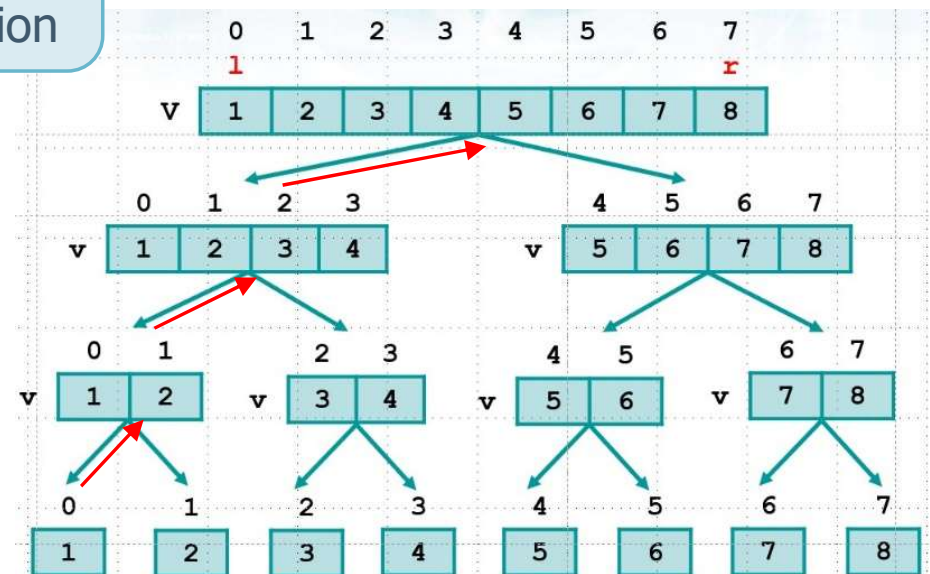
```
if (l >= r) {
    return;
}
```

Recursion:
Left recursion
Right recursion

```
c = (r+1)/2;
show (v, l, c);
show (v, c+1, r);

return;
}
```

Recursion tree
(**visited depth-first**)



Solution 1

```

void show (
    int v[], int l, int r
) {
    int i, c;

    printf ("v = ");
    for (i=l; i<=r; i++)
        printf ("%d ", v[i]);
    printf ("\n");

```

Array print
(from element l to r)

```

    if (l >= r) {
        return;
    }

```

returns to the previous level,
return will call again the function

divide

R

```

    c = (r+1)/2;
    show (v, l, c);
    show (v, c+1, r);

```

c+1 so element c is considered only once

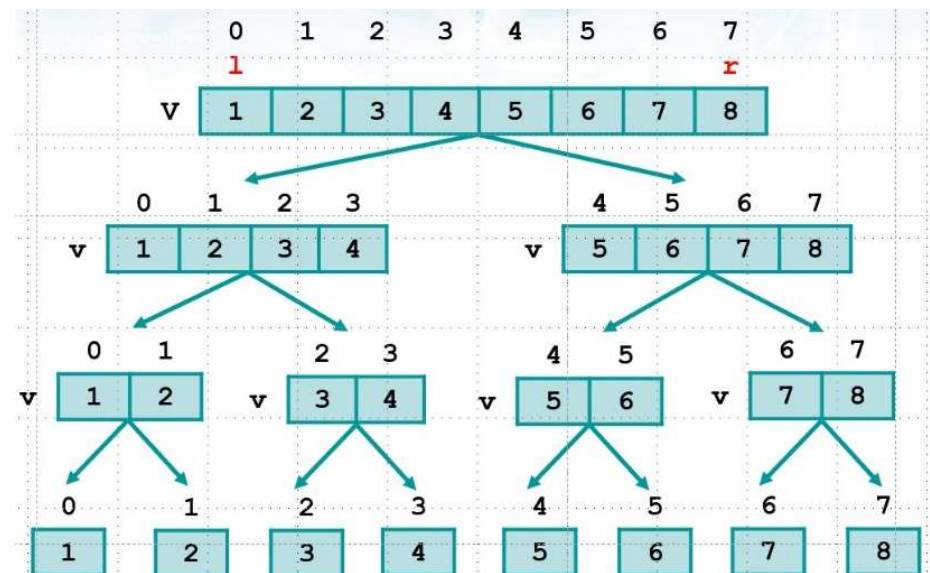
```

    return;

```

combination

Recursion tree
(**visited depth-first**)



Solution 2

```

void show (
    int v[], int l, int r
) {
    int i, c;

    if (l >= r) {
        return;
    }

    printf ("v = ");
    for (i=l; i<=r; i++)
        printf ("%d ", v[i]);
    printf ("\n");

    c = (r+1)/2;
    show (v, l, c);
    show (v, c+1, r);

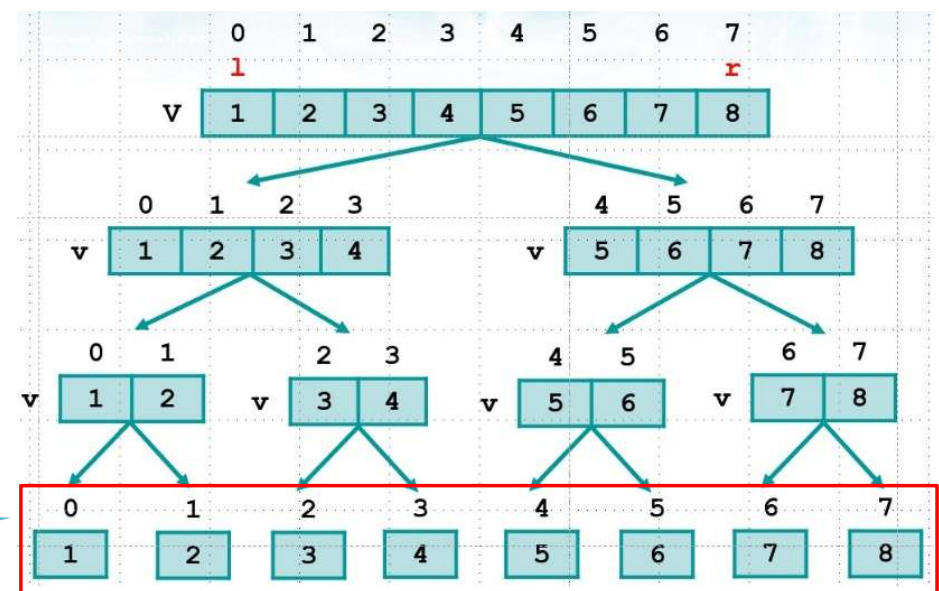
    return;
}

```

Array print
(from element l to r)

If I check before I print, the last layer is not printed

Recursion tree
(**visited depth-first**)



Not printed

Solution 2

```

void show (
    int v[], int l, int r
) {
    int i, c;

    if (l >= r) {
        return;
    }

    c = (r+1)/2;
    printf ("v = ");
    for (i=l; i<=c; i++)
        printf ...
    show (v, l, c);
    printf ("v = ");
    for (i=c+1; i<=r; i++)
        printf ...
    show (v, c+1, r);
    return;
}

```

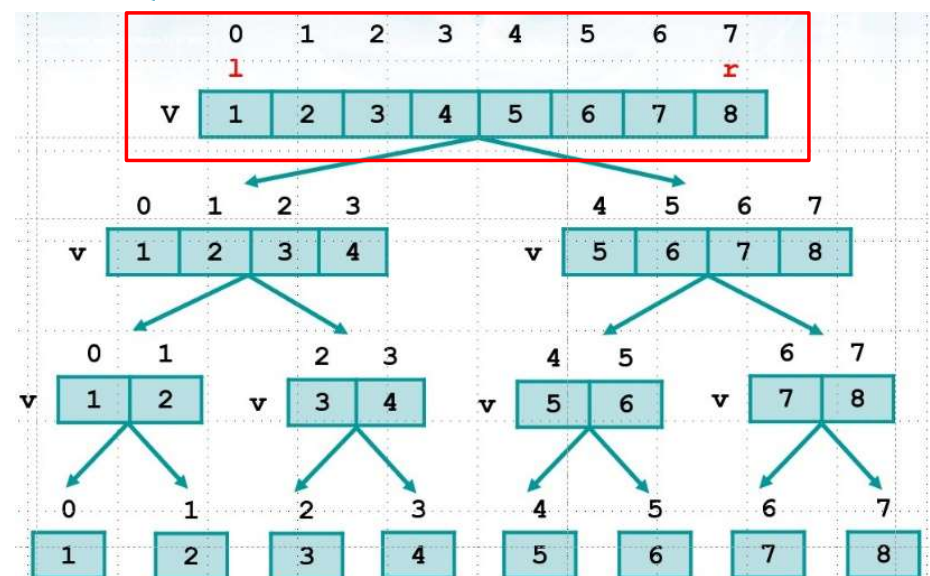
Not printed

NOTE: A LIFO stack is used for storing the state of the function calls

If termination condition is not presented, stack overflow is triggered

If I recur before printing I miss the first layer

Recursion tree
(**visited depth-first**)



Example 1: Complexity Analysis

Divide and conquer problem

Number of subproblems	$a = 2$
Reduction factor	$b = n/\hat{n} = 2$
Division cost	$D(n) = \Theta(1)$
Recombination cost	$C(n) = \Theta(1)$

$$T(n) = D(n) + a \cdot T\left(\frac{n}{b}\right) + C(n)$$

$$T(n) = \Theta(1)$$

$$n > 1$$

$$n \leq 1$$



```
void show (
    int v[], int l, int r
) {
    int i, c;
    if (l >= r) {
        return;
    }
    c = (r+1)/2;
    show (v, l, c);
    show (v, c+1, r);
    return;
}
```


Example 1: Complexity Analysis

$$\begin{array}{l} n > 1 \\ n \leq 1 \end{array} \quad \begin{array}{l} T(n) = 2 \cdot T(n/2) + 1 \\ T(1) = 1 \end{array}$$

$$\begin{array}{l} T(n) = D(n) + a \cdot T(n/b) + C(n) \\ T(n) = \Theta(1) \end{array}$$

$$n > 1$$

$$n \leq 1$$

No cost for the
combination
phase

$$T(n) = 1 + 2 \cdot T(n/2)$$

$$T(n/2) = 1 + 2 \cdot T(n/4)$$

$$T(n/4) = 1 + 2 \cdot T(n/8)$$

$$T(n/8) = 1 + 2 \cdot T(n/16)$$

$$\dots \\ T(1) = 1$$

At the i-th step

Termination condition

$$\frac{n}{2^i} = 1$$

$$n = 2^i$$

$$i = \log_2 n$$

Example 1: Complexity Analysis

$$T(n) = 1 + 2 \cdot T(n/2)$$

$$T(n/2) = 1 + 2 \cdot T(n/4)$$

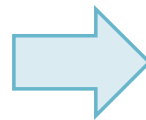
$$T(n/4) = 1 + 2 \cdot T(n/8)$$

$$T(n/8) = 1 + 2 \cdot T(n/16)$$

$$\dots$$

$$T(1) = 1$$

$i = \log_2 n$
steps



$$T(n) = 1 + 2 \cdot T(n/2)$$

$$T(n) = 1 + 2 + 4 \cdot T(n/4)$$

$$T(n) = 1 + 2 + 4 + 8 \cdot T(n/8)$$

$$T(n) = 1 + 2 + 4 + 8 + 16 \cdot T(n/16)$$

$$\dots$$

$$T(n) = \sum_{i=0}^{\log n} 2^i = \frac{(2^{\log n + 1} - 1)}{2 - 1} =$$

$$= 2 \cdot 2^{\log n} - 1 =$$

$$= 2n - 1 =$$

$$= O(n)$$

$\log_2(n)$

$$\sum_{i=0}^k x^i = \frac{(x^{k+1} - 1)}{(x - 1)}$$

sum of a geometric series

A second example: Maximum of an array

- ❖ Given an array of $n = 2^k$ integers
- ❖ Find its maximum and print it on standard output

	0	1	2	3	4	5	6	7
	l							r
v	11	1	5	6	9	36	13	4



36



Solution

- ❖ If the array size n is equal to 1 ($n = 1$)
 - Find maximum explicitly
- ❖ If the array size n is larger than 1 ($n > 1$)
 - Divide array in 2 subarrays, each being half the original array
 - Recursively search for maximum in the **left** subarray and **return** the maximum value in it
 - Recursively search for maximum in the **right** subarray and **return** the maximum value in it
 - **Compare** maximum values returned and return bigger one

Termination condition

Solution

```
result = max (v, 0, 3);
```

Implementation

```
int max(int v[],int l,int r){  
    int c, m1, m2;  
    if (l >= r)  
        return v[l];  
    c = (l + r)/2;  
    m1 = max (v, l, c);  
    m2 = max (v, c+1, r);  
    if (m1 > m2)  
        return m1;  
    else  
        return m2;  
}
```

	0	1	2	3
v	10	3	40	6

Initial call
 $l = 0, r = 3, n = 2^k$

it is enough to put $l==r$ but like this it is safer

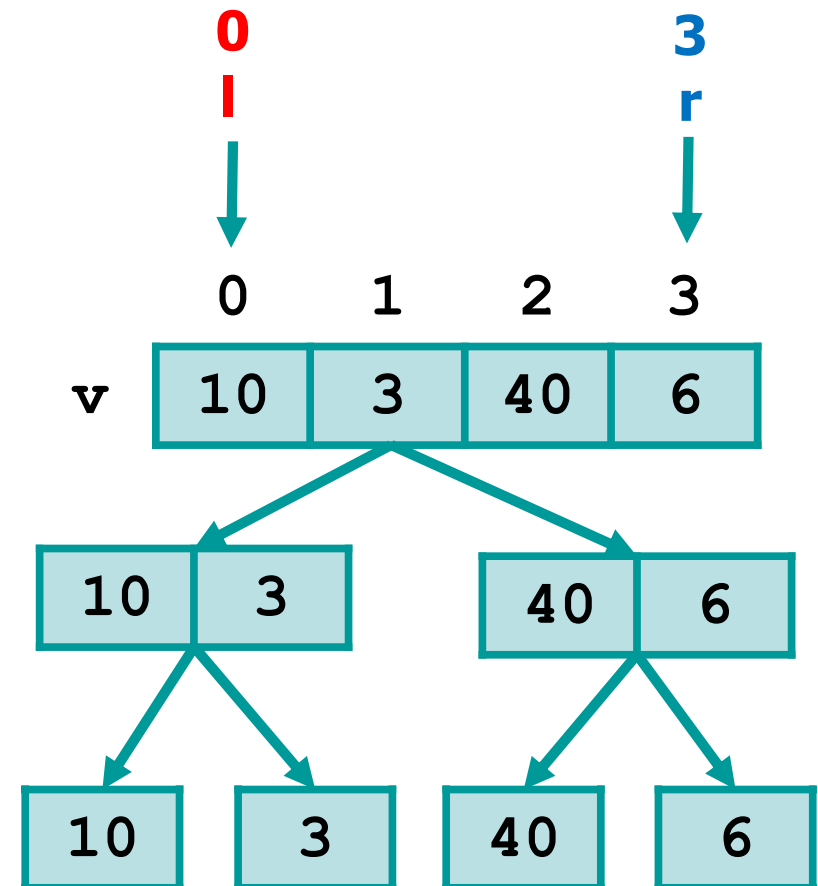
Solution

result = max (v, 0, 3);

Implementation

```
int max(int v[],int l,int r){
    int c, m1, m2;
    if (l >= r)
        return v[l];
    c = (l + r)/2;
    m1 = max (v, l, c);
    m2 = max (v, c+1, r);
    if (m1 > m2)
        return m1;
    else
        return m2;
}
```

Recursion tree
(**visited depth-first**)



Example 1: Complexity Analysis

Divide and conquer problem

Number of subproblems	$a = 2$
Reduction factor	$b = n/\hat{n} = 2$
Division cost	$D(n) = \Theta(1)$
Recombination cost	$C(n) = \Theta(1)$

$$T(n) = D(n) + a \cdot T\left(\frac{n}{b}\right) + C(n)$$

$$T(n) = \Theta(1)$$

$$n > 1$$

$$n \leq 1$$

As for
example 1 ...

$$T(n) = O(n)$$

```
int max(int v[],int l,int r){
    int c, m1, m2;
    if (l >= r)
        return v[l];
    c = (l + r)/2;
    m1 = max (v, l, c);
    m2 = max (v, c+1, r);
    if (m1 > m2)
        return m1;
    else
        return m2;
}
```

Factorial

❖ The factorial of a number can be defined using an

➤ Iterative definition

$$n! = \prod_{i=0}^{n-1} (n - i) = n \cdot (n - 1) \cdot \dots \cdot 2 \cdot 1$$

➤ Recursive definition

$$\begin{aligned} n! &= n \cdot (n - 1)! & n \geq 1 \\ 0! &= 1 \end{aligned}$$

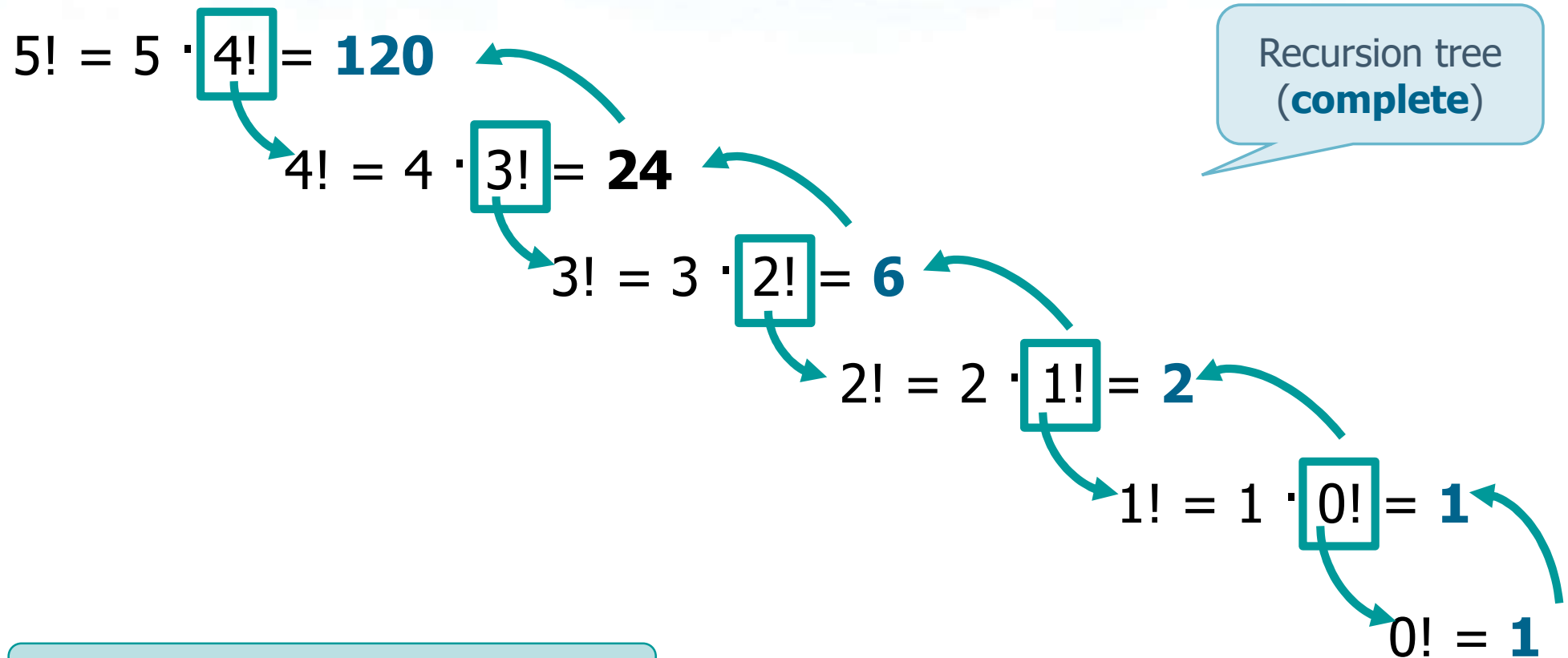
termination condition

➤ Examples

$$\begin{aligned} 3! &= 6 \\ 5! &= 120 \end{aligned}$$



An example



$$n! = n \cdot (n - 1) \quad n \geq 1$$
$$0! = 1$$

Solution

Complete program
(main and function)

```
#include <stdio.h>

long
long int fact(int n);
```

```
main() {
    long int n;
    printf("Input n: ");
    scanf("%d", &n);
    printf("%d != %d\n",
        n, fact(n));
}
```

long, to solve the problem of overflowing

```
long int fact (long int n)
{
    if (n == 0)
        return (1);
    return (n * fact(n-1));
}
```

Recursion

Alternative
implementation

```
long int fact (long int n)
{
    long int f;
    if (n == 0)
        return (1);
    f = fact (n-1);
    return (n * f);
}
```

same but not recurring
inside the return
statement

Recursion

Example 1: Complexity Analysis

Divide and conquer problem

Number of subproblems	$a = 1$
Reduction value	$k_i = 1$
Division cost	$D(n) = \Theta(1)$
Recombination cost	$C(n) = \Theta(1)$

$$T(n) = D(n) + \sum_{i=0}^{a-1} T(n - k_i) + C(n)$$

$T(n) = \Theta(1)$

$$n > 1$$

$$n \leq 1$$

```
long int fact (long int n)
{
    long int f;
    if (n == 0)
        return (1);
    f = fact (n-1);
    return (n * f);
}
```

Example 1: Complexity Analysis

$$n > 1$$

$$n \leq 1$$

$$T(n) = 1 + T(n - 1)$$

$$T(1) = 1$$

$$T(n) = D(n) + \sum_{i=0}^{a-1} T(n - k_i) + C(n)$$

$$T(n) = \Theta(1)$$

$$n > 1$$

$$n \leq 1$$

No cost for the
combination
phase

$$T(n) = 1 + T(n - 1)$$

$$T(n - 1) = 1 + T(n - 2)$$

$$T(n - 2) = 1 + T(n - 3)$$

$$T(n - 3) = 1 + T(n - 4)$$

...

$$T(1) = 1$$

Termination condition

$$n - 1 = 1$$

$$i = n - 1$$

Example 1: Complexity Analysis

$$T(n) = 1 + T(n - 1)$$

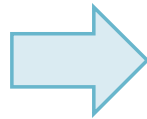
$$T(n - 1) = 1 + T(n - 2)$$

$$T(n - 2) = 1 + T(n - 3)$$

$$T(n - 3) = 1 + T(n - 4)$$

$$\dots$$
$$T(1) = 1$$

$i = n - 1$
steps



$$T(n) = 1 + T(n - 1)$$

$$T(n) = 1 + 1 + T(n - 2)$$

$$T(n) = 1 + 1 + 1 + T(n - 3)$$

$$T(n) = 1 + 1 + 1 + 1 + T(n - 4)$$

\dots

$$T(n) = 1 + 1 + 1 + 1 \dots =$$

$$= \sum_{i=0}^{n-1} 1 =$$

$$= n = O(n)$$

Fibonacci Numbers

Leonardo Pisano
known as Fibonacci
(Pisa, 1170-1242)



❖ Fibonacci numbers

➤ Iterative and recursive definition

$$F(n) = F(n-2) + F(n-1) \quad n > 1$$

$$F(0) = 0$$

$$F(1) = 1$$

➤ Example

$$F(0) = 0$$

$$F(1) = 1$$

$$F(2) = 0 + 1 = 1$$

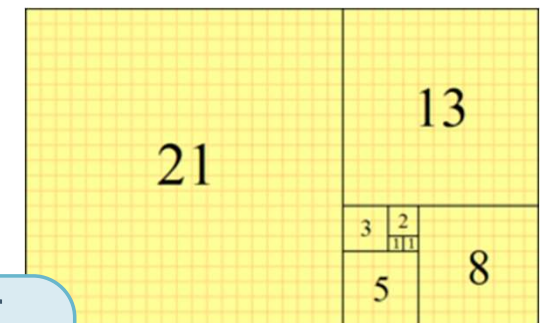
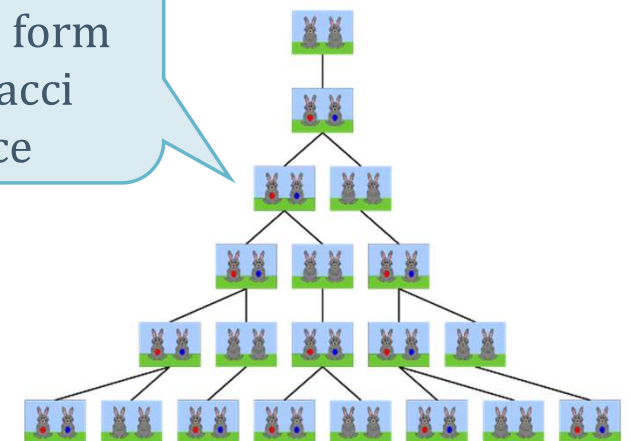
$$F(3) = 1 + 1 = 2$$

$$F(4) = 1 + 2 = 3$$

...

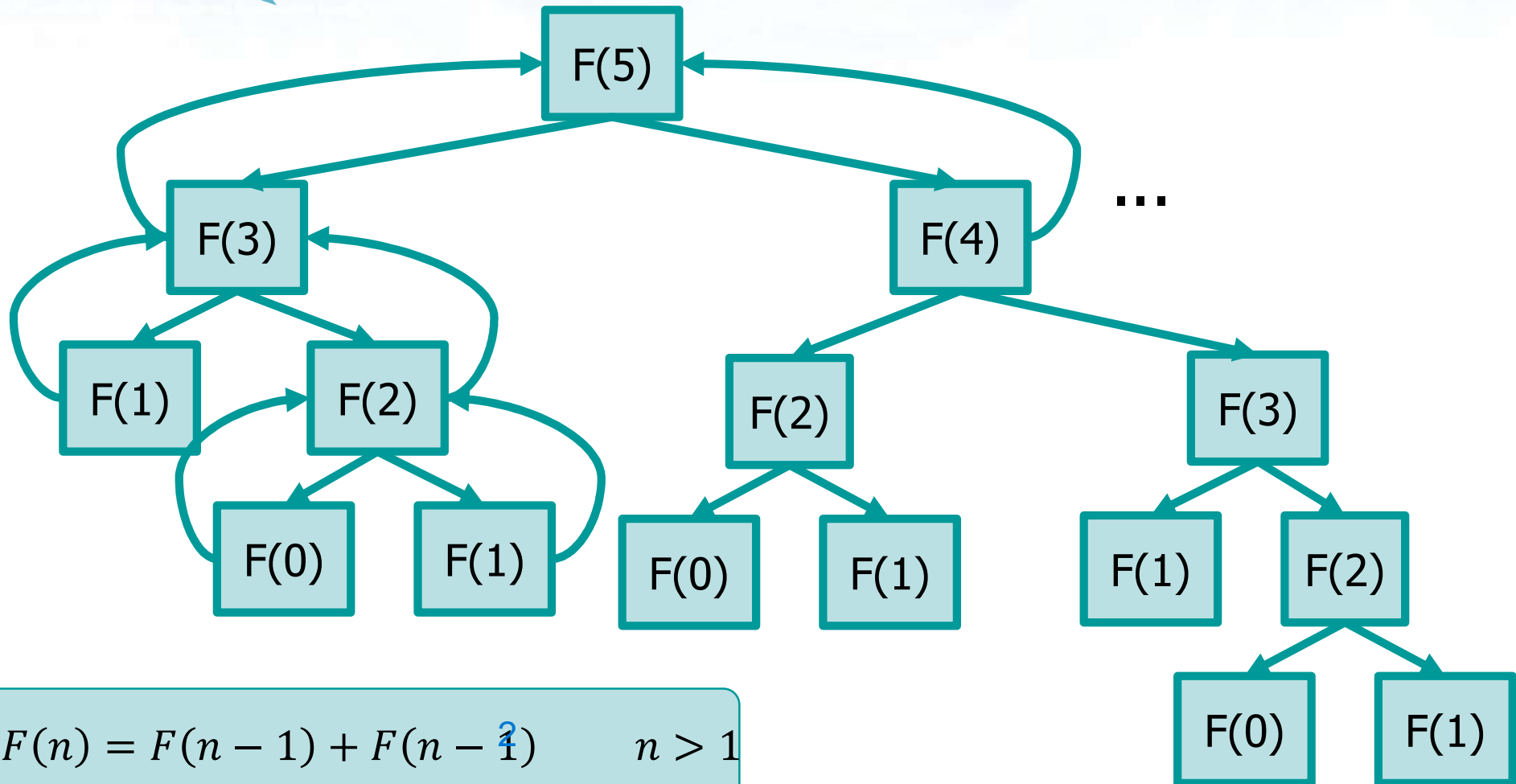
0 1 1 2 3 5 8 13 21 34 ...

The number of
rabbit pairs form
the Fibonacci
sequence



Recursion tree
(**complete**)

An Example: Computing F(5)



$$F(n) = F(n - 1) + F(n - 2) \quad n > 1$$

$$F(0) = 0$$

$$F(1) = 1$$

Solution

```
#include <stdio.h>

long int fib(long int n);

main() {
    long int n;

    printf("Input n:  ");
    scanf("%d", &n);
    printf("Fibonacci of %d is: %d \n", n, fib(n));
}

long int fib (long int n) {
    if (n == 0 || n == 1)
        return (n);
    return (fib(n-2) + fib(n-1));
}
```

Solution

```
long int fib (long int n) {  
    if (n == 0 || n == 1)  
        return (n);  
    return (fib(n-2) + fib(n-1));  
}
```

Alternative
implementation

```
long int fib (long int n) {  
    long int f1, f2;  
  
    if (n == 0 || n == 1)  
        return (n);  
    f1 = fib (n-2);  
    f2 = fib (n-1);  
    return (f1 + f2);  
}
```

Example 1: Complexity Analysis

Divide and conquer problem

Number of subproblems	$a = 2$
Reduction factor	$k_i = 1$ $k_{i-1} = 2$
Division cost	$D(n) = \Theta(1)$
Recombination cost	$C(n) = \Theta(1)$

$$T(n) = D(n) + \sum_{i=0}^{a-1} T(n - k_i) + C(n)$$

$$T(n) = \Theta(1)$$

$$n > 1$$

$$n \leq 1$$

```
long int fib (long int n) {
    long int f1, f2;

    if (n == 0 || n == 1)
        return (n);
    f1 = fib (n-2);
    f2 = fib (n-1);
    return (f1 + f2);
}
```

Example 1: Complexity Analysis

$$T(n) = 1 + T(n-1) + T(n-2)$$

$$T(0) = 1$$

$$T(1) = 1$$

$$T(n) = D(n) + \sum_{i=0}^{a-1} T(n-k_i) + C(n)$$

$$T(n) = \Theta(1)$$

$$n > 1$$

$$n \leq 1$$

No cost for the combination phase

We can make a conservative approximation

$$T(n-2) \leq T(n-1)$$

$$T(n) = 1 + 2 \cdot T(n-1)$$

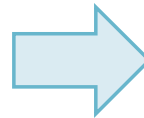
$$T(0) = 1$$

$$T(1) = 1$$

We replace
 $T(n-2)$
with $T(n-1)$

Example 1: Complexity Analysis

$$\begin{aligned} T(n) &= 1 + 2 \cdot T(n-1) \\ T(n-1) &= 1 + 2 \cdot T(n-2) \\ T(n-2) &= 1 + 2 \cdot T(n-3) \\ &\dots \\ T(0) &= 1 \\ T(1) &= 1 \end{aligned}$$



$$\begin{aligned} T(n) &= 1 + 2 \cdot T(n-1) \\ T(n) &= 1 + 2 + 4 \cdot T(n-2) \\ T(n) &= 1 + 2 + 4 + 8 \cdot T(n-3) \\ &\dots \end{aligned}$$

$$\begin{aligned} T(n) &= \sum_{i=0}^{n-1} 2^i = \\ &= 2^n - 1 = \\ &= O(2^n) \end{aligned}$$

Termination condition

$$\begin{aligned} \frac{n}{2^i} &= 1 \\ n &= 2^i \\ i &= \log_2 n \\ \text{steps} \end{aligned}$$

$$\sum_{i=0}^k x^i = \frac{(x^{k+1} - 1)}{(x - 1)}$$

Not linear.
Why?

because we are doing the same job over and over again

Binary Search

❖ Binary search

- Does key k belong to the sorted array $v[n]$?
- Yes/No

❖ Approach

- Start with (sub-)array of extremes l and r
- At each step
 - Find middle element $c = (\text{int})((l+r)/2)$
 - Compare k with middle element in the array
 - $=$: termination with success
 - $<$: search continues on left subarray
 - $>$: search continues on right subarray

Assumption
 $n = 2^k$



Example

	0	1	2	3	4	5	6	7	8	9
	l									r
v	2	4	6	8	10	12	14	16	18	20

k 8

k = key to search
l = leftmost index
r = rightmost index
c = index of the middle element

	0	1	2	3						
	l			r						
v	2	4	6	8						

			2	3						
			l	r						
v			6	8						

			3							
			l	r						
v			8							

y = middle element

Solution

```
int bin_search (int v[], int l, int r, int k){
    int c;

    if (l > r)
        return(-1);

    c = (l+r) / 2;

    if (k < v[c])
        return(bin_search (v, l, c-1, k));
    if (k > v[c])
        return(bin_search (v, c+1, r, k));

    return c;
}
```

Termination
condition

Skip the element
already checked

Example 1: Complexity Analysis

Decrease and conquer problem

Number of subproblems	$a = 1$
Reduction factor	$b = n / \hat{n} = 2$
Division cost	$D(n) = \Theta(1)$
Recombination cost	$C(n) = \Theta(1)$

$$T(n) = D(n) + a \cdot T\left(\frac{n}{b}\right) + C(n)$$

$$T(n) = \Theta(1)$$

$$n > 1$$

$$n \leq 1$$

```
int bin_search (...) {
    int c;
    if (l > r)
        return(-1);
    c = (l+r) / 2;
    if (k < v[c])
        return(bin_search (...));
    if (k > v[c])
        return(bin_search (...));
    return c;
}
```

Example 1: Complexity Analysis

$$n > 1$$

$$T(n) = 1 + T(n/2)$$

$$n \leq 1$$

$$T(1) = 1$$

$$T(n) = D(n) + a \cdot T(n/b) + C(n)$$

$$T(n) = \Theta(1)$$

$$n > 1$$

$$n \leq 1$$

No cost for the
combination
phase

$$T(n) = 1 + T(n/2)$$

$$T(n/2) = 1 + T(n/4)$$

$$T(n/4) = 1 + T(n/8)$$

$$T(n/8) = 1 + T(n/16)$$

$$\dots$$

$$T(1) = 1$$

Termination condition

$$\frac{n}{2^i} = 1$$

$$n = 2^i$$

$$i = \log_2 n$$

Example 1: Complexity Analysis

$$T(n) = 1 + T(n/2)$$

$$T(n/2) = 1 + T(n/4)$$

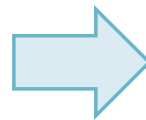
$$T(n/4) = 1 + T(n/8)$$

$$T(n/8) = 1 + T(n/16)$$

$$\dots$$

$$T(1) = 1$$

$i = \log_2 n$
steps



$$T(n) = 1 + T(n/2)$$

$$T(n) = 1 + 1 + T(n/4)$$

$$T(n) = 1 + 1 + 1 + T(n/8)$$

$$T(n) = 1 + 1 + 1 + 1 + T(n/16)$$

$$T(n) = \sum_{i=0}^{\log} 1 =$$

$$= O(\log_2(n)) = 1 + \log_2(n)$$

$$\sum_{i=0}^k x^i = \frac{(x^{k+1} - 1)}{(x - 1)}$$

Reverse printing

- ❖ Read a string from standard input
- ❖ Print it in reverse order
 - Start printing from last character and move back to first one

	0	1	2	3	4	5	6	7	8	9	10	11	12	13
s	T	h	i	s	I	s	A	S	t	r	i	n	g	\0



gnirtSAsIsihT

Solution

```
int main() {
    char str[max+1];
    printf ("Input string: ");
    scanf ("%s", str);
    printf ("Reverse string is: ");
    reverse_print (str);
}

void reverse_print (char *s) {
    if (*s == '\0') {
        return;
    }
    reverse_print (s+1);
    printf ("%c", *s);
    return;
}
```

Example 1: Complexity Analysis

Divide and conquer problem

Number of subproblems	$a = 1$
Reduction value	$k_i = 1$
Division cost	$D(n) = \Theta(1)$
Recombination cost	$C(n) = \Theta(1)$

$$T(n) = D(n) + \sum_{i=0}^{a-1} T(n - k_i) + C(n)$$

$$T(n) = \Theta(1)$$

$$n > 1$$

$$n \leq 1$$

As for the factorial ...

$$T(n) = O(n)$$

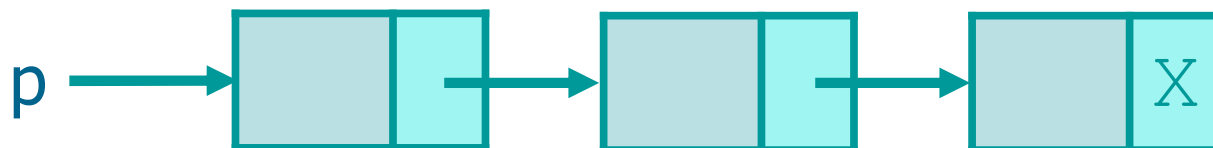
```
void reverse_print (char *s) {
    if (*s == '\0') {
        return;
    }
    reverse_print (s+1);
    printf ("%c", *s);
    return;
}
```

List processing

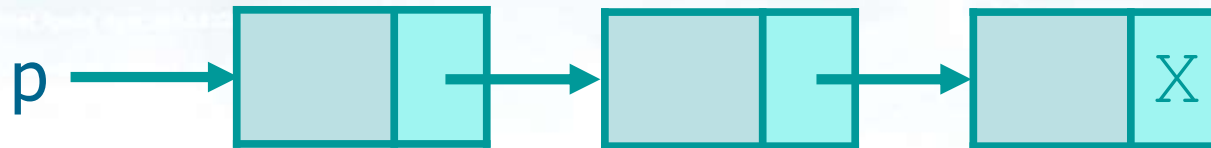
❖ Recursive list processing

- Count the number of elements in a list
- Traverse a list in order
- Traverse a list in reverse order
- Delete an element (of a given item) from the list

```
typedef struct list_s list_t;  
struct node {  
    int key;  
    ...  
    list_t *next;  
};
```



Solution



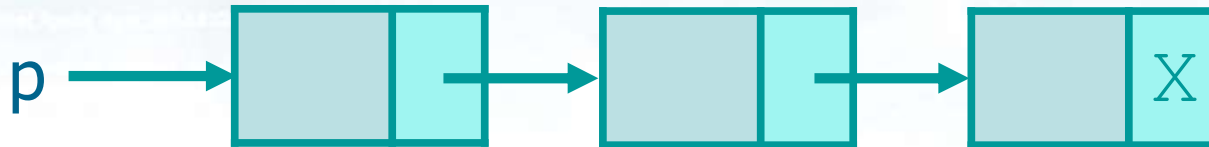
```
int count (list_t *p) {  
    if (p == NULL)  
        return 0;  
    return (1 + count(p->next));  
}
```

Count the
number of
elements

```
void traverse (list_t *p) {  
    if (p == NULL)  
        return;  
    printf ("%d", p->key);  
    traverse (p->next);  
}
```

Traverse the
list forward

Solution



```
void traverse_reverse (list_t *p) {  
    if (p == NULL)  
        return;  
    traverse_reverse (p->next);  
    printf ("%d", p->key);  
}
```

Traverse the
list backward

```
link delete(list_t *p, int val) {  
    if (p==NULL) return NULL;  
    if (p->key==val) {  
        list_t *t=p->next; free(p);  
        return t;  
    }  
    p->next = delete (p->next, val);  
    return p;  
}
```

very interesting!!!

Dispose an
element of the
list

Create (re-create) link
on the way back

Complexity Analysis

for all those functions

Divide and conquer problem

Number of subproblems	$a = 1$
Reduction value	$k_i = 1$
Division cost	$D(n) = \Theta(1)$
Recombination cost	$C(n) = \Theta(1)$

$$T(n) = D(n) + \sum_{i=0}^{a-1} T(n - k_i) + C(n)$$

$$T(n) = \Theta(1)$$

$$n > 1$$

$$n \leq 1$$

As for the
factorial ...

$$T(n) = O(n)$$

```
int count (link x) {
    if (x == NULL)
        return 0;
    return (1 + count(x->next));
}
```


Greatest Common Divisor

❖ Given 2 non-zero integers x and y , the greatest common divisor $\text{gcd}(x, y)$ is the greatest among the common divisors of x and y

➤ Inefficient algorithm are based on decomposition in prime factors of x and y

$$x = p_1^{e_1} \cdot p_2^{e_2} \cdot p_3^{e_3} \cdot \dots \cdot p_r^{e_r}$$

$$y = p_1^{f_1} \cdot p_2^{f_2} \cdot p_3^{f_3} \cdot \dots \cdot p_r^{f_r}$$

Common factors with the minimum exponent

$$\text{gcd}(x, y) = p_1^{\min(e_1, f_1)} \cdot p_2^{\min(e_2, f_2)} \cdot p_3^{\min(e_3, f_3)} \cdot \dots \cdot p_r^{\min(e_r, f_r)}$$

➤ More efficient methods are base on Euclid's algorithm



Euclid's Algorithm

❖ Version number 1

- Based on subtraction

```
if (x > y)
    gcd(x, y) = gcd(x-y, y)
else
    gcd(x, y) = gcd(x, y-x)
```



```
if (x == y)
    return x
```

Termination
condition

❖ Version number 2

- Based on the remainder of integer divisions

```
if (y > x)
    swap (x, y)

gcd (x, y) = gcd(y, x%y)
```



```
if (y == 0)
    return x
```

Examples: Version 1

$\text{gcd}(20, 8) =$

$= \text{gcd}(20-8, 8) = \text{gcd}(12, 8)$
 $= \text{gcd}(12-8, 8) = \text{gcd}(4, 8)$
 $= \text{gcd}(4, 8-4) = \text{gcd}(4, 4)$
 $= 4 \rightarrow \text{return } 4$

$\text{gcd}(600, 54) =$

$= \text{gcd}(600-54, 54) = \text{gcd}(546, 54)$
 $= \text{gcd}(546-54, 54) = \text{gcd}(492, 54) \dots$
 $= \text{gcd}(6, 54) = \text{gcd}(6, 54-6) \dots$
 $= \text{gcd}(6, 12) = \text{gcd}(6, 6)$
 $= 6 \rightarrow \text{return } 6$

very slow convergence

```
if (x > y)
    gcd(x, y) = gcd(x-y, y)
else
    gcd(x, y) = gcd(x, y-x)
```

Examples: Version 2

$\text{gcd}(20, 8) =$

$= \text{gcd}(8, 20\%8) = \text{gcd}(8, 4)$

$= \text{gcd}(4, 8\%4) = \text{gcd}(4, 0)$

$= 4 \rightarrow \text{return } 4$

much faster convergence

$\text{gcd}(600, 54) =$

$= \text{gcd}(54, 600\%54) = \text{gcd}(54, 6)$

$= \text{gcd}(6, 54\%6) = \text{gcd}(6, 0)$

$= 6 \rightarrow \text{return } 6$

```
if (y > x)
    swap (x, y)
gcd (x, y) = gcd(y, x%y)
```

Examples: Version 2

$\text{gcd}(314159, 271828) =$

$= \text{gcd}(271828, 314159 \% 271828) = \text{gcd}(271828, 42331)$

$= \text{gcd}(42331, 271828 \% 42331) = \text{gcd}(42331, 17842)$

$= \text{gcd}(17842, 42331 \% 17842) = \text{gcd}(17842, 6647)$

$= \text{gcd}(6647, 17842 \% 6647) = \text{gcd}(6647, 4548)$

$= \text{gcd}(4548, 6647 \% 4548) = \text{gcd}(4548, 2099)$

$= \text{gcd}(2099, 4548 \% 2099) = \text{gcd}(2099, 350)$

$= \text{gcd}(350, 2099 \% 350) = \text{gcd}(350, 349)$

$= \text{gcd}(349, 350 \% 349) = \text{gcd}(349, 1)$

$= \text{gcd}(1, 349 \% 1) = \text{gcd}(1, 0)$

$= 1 \rightarrow \text{return } 1$

In fact, 314159 and 271828 are mutually prime

```
if (y > x)
    swap (x, y)
gcd (x, y) = gcd(y, x%y)
```

Solution: Version 1

```
#include <stdio.h>

int gcd (int x, int y);

main() {
    int x, y;
    printf("Input x and y:  ");
    scanf("%d%d", &x, &y);
    printf("gcd of %d and %d: %d \n", x, y, gcd(x, y));
}

int gcd (int x, int y) {
    if (x == y)
        return (x);
    if (x > y)
        return gcd (x-y, y);
    else
        return gcd (x, y-x);
}
```

Solution: Version 2

```
#include <stdio.h>

int gcd (int m, int n);

main() {
    int m, n, r;
    printf("Input m and n:  ");
    scanf("%d%d", &m, &n);
    if (m>n)
        r = gcd(m, n);
    else
        r = gcd(n, m);
    printf("gcd of (%d, %d) = %d\n", m, n, r);
}

int gcd (int m, int n) {
    if(n == 0)
        return(m);
    return gcd(n, m % n);
}
```


Complexity Analysis

Divide and conquer problem

Number of subproblems	$a = 1$
Reduction value	$k_i = \text{variable}$
Division cost	$D(x, y) = \Theta(1)$
Recombination cost	$C(x, y) = \Theta(1)$

$$T(n) = D(n) + \sum_{i=0}^{a-1} T(n - k_i) + C(n)$$

$$T(n) = \Theta(1)$$

$$n > 1$$

$$n \leq 1$$

Proof beyond
the scope of
this course...

$$T(n) = O(\log(y))$$

```
int gcd (int m, int n) {
    if (n == 0)
        return m;
    return gcd(n, m % n);
}
```

Determinant

- ❖ Laplace's algorithm with unfolding on row i
 - Square matrix M ($n \times n$) with indices from 1 to n
- ❖ Computation

$$\det(M) = \sum_{j=1}^n (-1)^{(i+j)} \cdot M[i][j] \cdot \det(M_{\text{minor } i,j})$$

- Where $M_{\text{minor } i,j}$ is obtained from M ruling-out row i and column j



Example

$$M = \begin{bmatrix} -2 & 2 & -3 \\ -1 & 1 & 3 \\ 2 & 0 & -1 \end{bmatrix}$$

$$M_{minor\ 1,1} = \begin{bmatrix} -2 & 2 & -3 \\ -1 & \color{red}{1} & \color{red}{3} \\ 2 & \color{red}{0} & \color{red}{-1} \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 0 & -1 \end{bmatrix}$$

$$M_{minor\ 1,2} = \begin{bmatrix} -2 & 2 & -3 \\ \color{red}{-1} & 1 & \color{red}{3} \\ \color{red}{2} & 0 & \color{red}{-1} \end{bmatrix} = \begin{bmatrix} -1 & 3 \\ 2 & -1 \end{bmatrix}$$

$$M_{minor\ 1,3} = \begin{bmatrix} -2 & 2 & -3 \\ \color{red}{-1} & \color{red}{1} & 3 \\ \color{red}{2} & \color{red}{0} & -1 \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ 2 & 0 \end{bmatrix}$$

$$\det \begin{bmatrix} 1 & 3 \\ 0 & -1 \end{bmatrix} = -1 - 0 = -1$$

$$\det \begin{bmatrix} -1 & 3 \\ 2 & -1 \end{bmatrix} = 1 - 6 = -5$$

$$\det \begin{bmatrix} -1 & 1 \\ 2 & 0 \end{bmatrix} = 0 - 2 = -2$$

$$\begin{aligned} \det(M) &= (-1)^{(1+1)} \cdot (-2) \cdot \det(M_{minor\ 1,1}) + (-1)^{(1+2)} \cdot (2) \cdot \det(M_{minor\ 1,2}) \\ &\quad + (-1)^{(1+3)} \cdot (-3) \cdot \det(M_{minor\ 1,3}) = \\ &= (1) \cdot (-2) \cdot (-1) + (-1) \cdot (2) \cdot (-5) + (1) \cdot (-3) \cdot (-2) = 18 \end{aligned}$$

Solution

❖ Recursive algorithm

- If M has size n , indice ranges between 0 and $n-1$

❖ If $n = 2$

- Compute the trivial solution

$$\det(M) = M[0][1] \cdot M[1][0] - M[0][0] \cdot M[1][1]$$

❖ If $n > 2$

- With $row=0$ and column ranging from 0 and $n-1$
- Store in tmp the minor $M_{minor\ 0,j}$
- Recursively compute $\det(M_{minor\ 0,j})$
- Store result results in

$$sum = sum + M[0][k] \cdot pow(-1, k) \cdot \det(tmp, n - 1)$$

Solution

```
int det (int m[][MAX], int n) {
    int sum, c;
    int tmp[MAX][MAX];
    sum = 0;

    if (n == 2)
        return (det2x2(m));

    for (c=0; c<n; c++) {
        minor (m, 0, c, n, tmp);
        sum = sum + m[0][c] * pow(-1,c) * det (tmp,n-1);
    }

    return (sum);
}
```

Create minor

Recur on minor
computation

Solution

```
int det2x2(int m[][MAX]) {
    return(m[0][0]*m[1][1] - m[0][1]*m[1][0]);
}

void minor(
    int m[][MAX],int i,int j,int n,int m2[][MAX]
){
    int r, c, rr, cc;

    for (rr = 0, r = 0; r < n; r++)
        if (r != i) {
            for (cc = 0, c = 0; c < n; c++) {
                if (c != j) {
                    m2[rr][cc] = m[r][c];
                    cc++;
                }
                rr++;
            }
        }
}
```

Complexity Analysis

Divide and conquer problem

Number of subproblems	$a = n$
Reduction value	$k_i = 2n - 1$
Division cost	$D(x, y) = \Theta(1)$
Recombination cost	$C(x, y) = \Theta(1)$

$$T(n) = D(n) + \sum_{i=0}^{a-1} T(n - k_i) + C(n)$$

$$T(n) = \Theta(1)$$

$$n > 1$$

$$n \leq 1$$

Proof beyond
the scope of
this course...

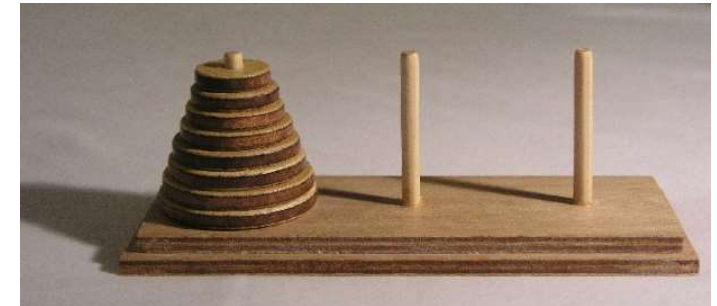
$$T(n) = O(n!)$$

```
int det (int m[][MAX], int n) {
    ...
    if (n == 2)
        return (det2x2(m));
    for (c=0; c<n; c++) {
        minor (m, 0, c, n, tmp);
        sum = sum + m[0][c] * ...;
    }
    return (sum);
}
```

Tower of Hanoi

❖ The Tower of Hanoi (also called The problem of Benares Temple or Tower of Brahma or Lucas' Tower) is a mathematical game consisting of three rods and a number of disks of various diameters

❖ It was firstly introduced the French mathematician Édouard Lucas in 1883



Édouard Lucas
(Paris, 1842-1891)



Tower of Hanoi

❖ Initial configuration

- 3 pegs
- 3 disks
- Disks of decreasing size on first peg



❖ Final configuration

- Disks of decreasing size on third peg



❖ Rules

- Access only to the top disk
- On each disk overlap only smaller disks

Tower of Hanoi

❖ Generalization

- Work with n disks (and 3 pegs)

4 disks, 3 pegs
Sequence of
correct moves



Solution

❖ Divide and Conquer strategy

➤ Initial problem

- Move n disks from 0 to 2

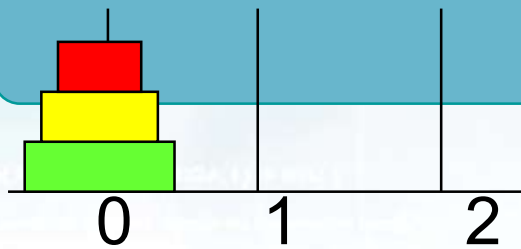
➤ Reduction to subproblems

- Move $n-1$ disks from 0 to 1, 2 temporary storage
- Move last disk from 0 to 2
- Move $n-1$ disks from 1 to 2, 0 temporary storage

➤ Termination condition

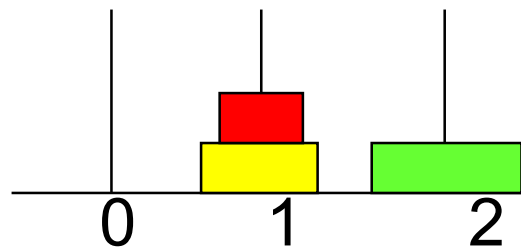
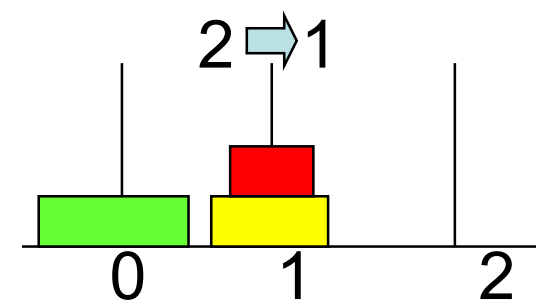
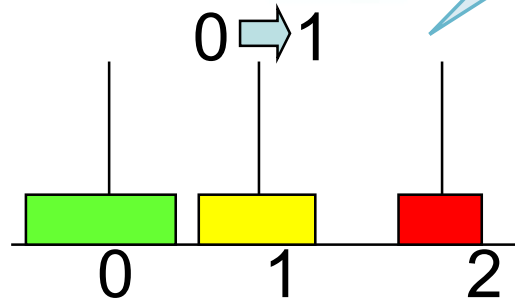
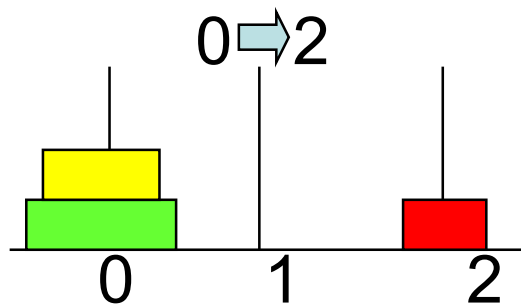
- Move just 1 disk

Example



All disks
from 0 to
2

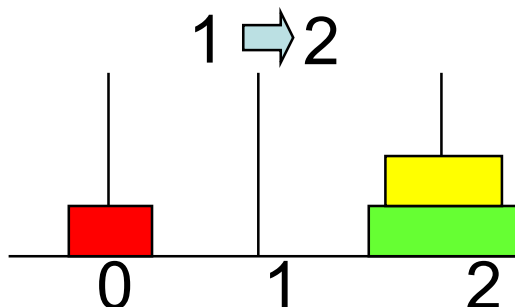
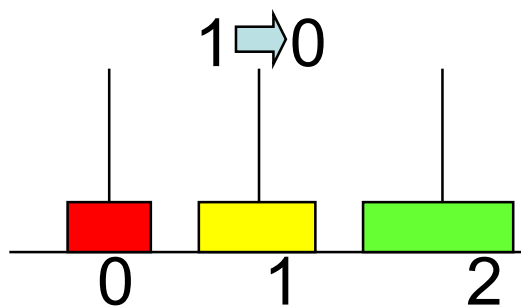
Medium
and small
disks from
0 to 1



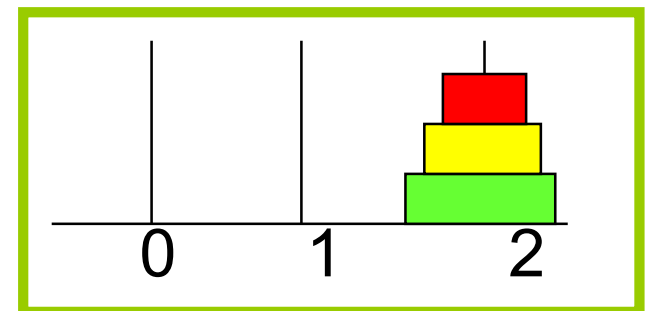
0 → 2

Large
disk from
0 to 2

Medium and
small disks
from 1 to 2



0 → 2



Solution

Move 3 disks from per
0 to peg 2

```
int main (void) {
    hanoi (3, 0, 2);
    return;
}
```

Output

```
Disk 1 from peg 0 to 2
Disk 2 from peg 0 to 1
Disk 1 from peg 2 to 1
Disk 3 from peg 0 to 2
Disk 1 from peg 1 to 0
Disk 2 from peg 1 to 2
Disk 1 from peg 0 to 2
```

```
void hanoi (int n, int src, int dest) {
    int aux;

    if (n <= 0) {
        return;
    }
    aux = 3 - (src + dest);
    hanoi (n-1, src, aux);
    printf("Disk %d from peg %c to %c\n", n, src, dest);
    hanoi (n-1, aux, dest);

    return;
}
```

Termination
condition

Divide

Move

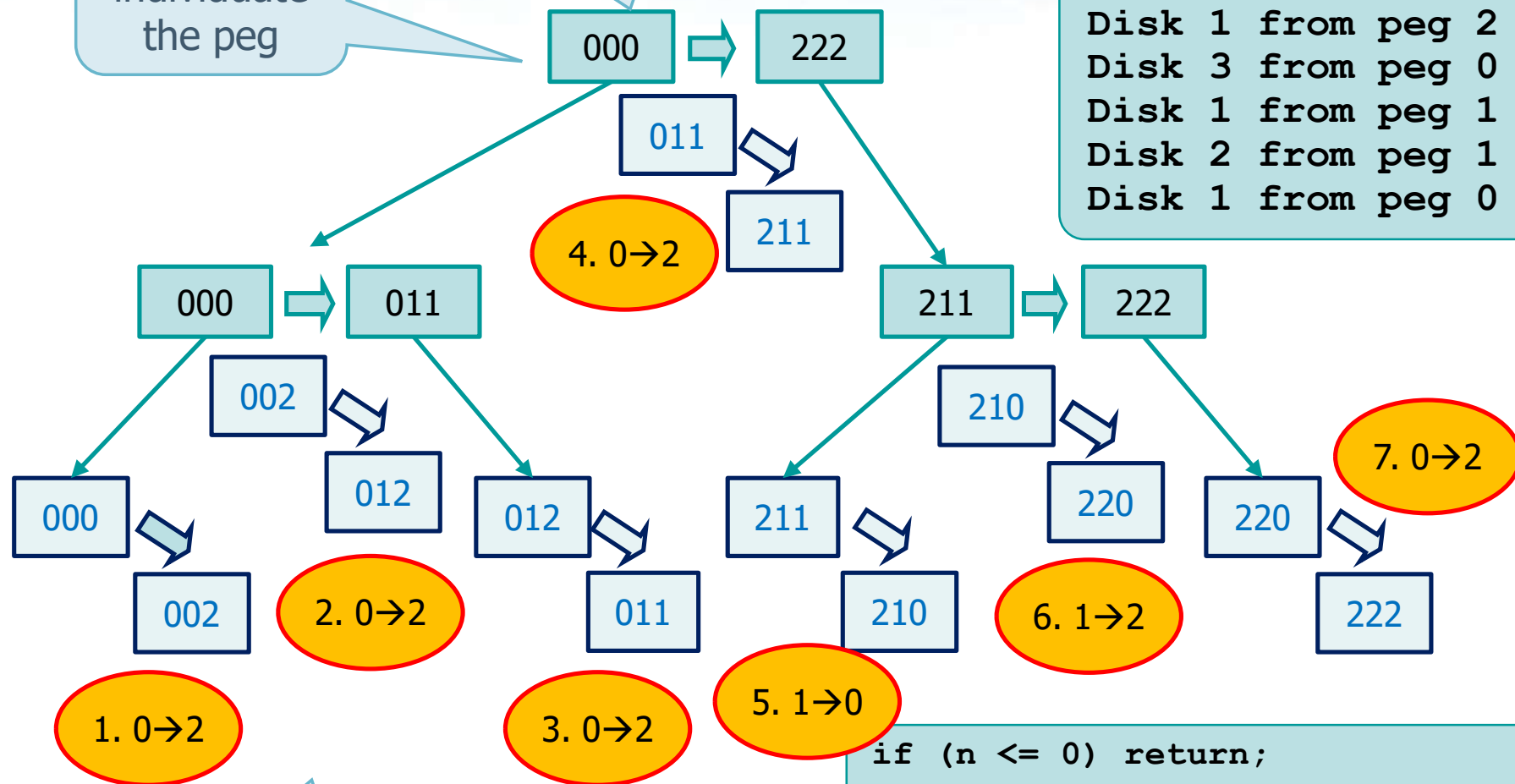
Divide

Recursion tree

XXX stands for Large-Medium-Small disk

0,1,2
individuate
the peg

```
Disk 1 from peg 0 to 2
Disk 2 from peg 0 to 1
Disk 1 from peg 2 to 1
Disk 3 from peg 0 to 2
Disk 1 from peg 1 to 0
Disk 2 from peg 1 to 2
Disk 1 from peg 0 to 2
```



Order and Move

```
if (n <= 0) return;
...
hanoi (n-1, src, aux);
printf(...);
hanoi (n-1, aux, dest);
```

Complexity Analysis

Divide and conquer problem

Number of subproblems	$a = 2$
Reduction factor	$k_i = 1$
Division cost	$D(n) = \Theta(1)$
Recombination cost	$C(n) = \Theta(1)$

$$T(n) = D(n) + \sum_{i=0}^{a-1} T(n - k_i) + C(n)$$

$$T(n) = \Theta(1) \quad \begin{matrix} n > 1 \\ n \leq 1 \end{matrix}$$

$$T(n) = 1 + 2 \cdot T(n - 1)$$

$$T(1) = 1$$

As for
Fibonacci ...

$$T(n) = O(2^n)$$

```
void hanoi(...) {
    int aux;
    aux = 3 - (src + dest);
    if (n == 1) {
        printf(...);
        return;
    }
    hanoi(n-1, src, aux);
    printf(...);
    hanoi(n-1, aux, dest);
    return;
}
```