

# Tommaso Menara

PhD Candidate at University of California Riverside

## contact

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tommasomenara

## languages

English  
Italian

## programming

C Java  
Matlab & Simulink  
Wolfram (Mathematica)  
Processing (Arduino)

## Education

- 2016–present **Phd** Mechanical Engineering  
Network Neuroscience and Control Theory  
University of California, Riverside
- 2013–2016 **Laurea Magistrale** (Master of Science equivalent)  
Robotics and Control Engineering  
University of Pisa, Italy
- 2010–2013 **Laurea** (Bachelor of Science equivalent)  
Mechatronics Engineering  
University of Padova, Italy

## Publications

### Conference proceedings

- [C3]. T. Menara, V. Katewa, D.S. Bassett, F. Pasqualetti, *The Structured Controllability Radius of Symmetric (Brain) Networks*, IEEE American Control Conference. Milwaukee, USA, June 2018
- [C2]. T. Menara, G. Bianchin, M. Innocenti, F. Pasqualetti, *On the Number of Strongly Structurally Controllable Networks*, IEEE American Control Conference. Seattle, USA, May 2017
- [C1]. M. Laurino, T. Menara, A. Stella, M. Betta, A. Landi, *Procoagulant control strategies for the human blood clotting process*. 37th Annual Conference of the IEEE Engineering in Medicine and Biology Society. Milano Conference Center, Milan, Italy, August 2015

## Experience

- 2016–present **IEEE - IFAC**  
Referee/Reviewer  
University of California, Riverside  
Reviewer for international conferences such as: Conference on Decision and Control (CDC), American Control Conference (ACC), European Control Conference (ECC), International Conference on Control, Decision and Information Technologies (CoDIT), Conference on Control Technologies (CCTA)  
Reviewer for journals such as: IEEE Transactions on Automatic Control (IEEE-TAC), IEEE Transactions on Control of Networked Systems (IEEE-TCNS), IFAC Automatica.
- 2016–2019 **Graduate Students Association**  
Public Relations Officer  
University of California, Riverside  
PR Officer in the Graduate Students Association. Responsible of organizing campus-wide social events. Management of the budget for social events. Vice-chair of the HUB Board of Governors.
- 2017–2018 **Graduate Students Association**  
International Student Affairs Officer  
University of California, Riverside  
ISAO in the Graduate Students Association. Monitoring of campus issues and legislative developments that affect international graduate students. Member of different committees related to international education.

2016–2017	<b>Graduate Students Association</b> <i>MEGSA Representative</i> Mechanical Engineering Representative in the Graduate Students Association.	University of California, Riverside
2015–2016	<b>Mechanical Engineering Department</b> <i>Visiting Scholar</i> Research on strong structural controllability of network systems during a 6-months period.	University of California, Riverside
2013–2015	<b>Department of Information Engineering</b> <i>Student Projects</i> <ul style="list-style-type: none"> <li>• Design, production and coding of an autonomous floor-cleaning robot.</li> <li>• System identification of a Inertially Stabilized Platform (ISP). Developed controllers for the gimbals of the ISP.</li> <li>• Modeled the humanoid robot Walkman (developed by the IIT Genova) in Simulink/Simmechanics. Combined Path Planning, Trajectory Tracking and Motion Control to make the robot achieve tasks while walking. Developed the steering function for a RRT algorithm to decide whether the connection between different states is feasible or not.</li> <li>• Computer Aided Engineering (CAE) Methods: Modeling of mechanical parts and stress simulations using Solidworks.</li> <li>• Identification of Uncertain Systems: Identification and parameter fitting of an electromechanical diesel engine actuator valve.</li> <li>• Real-Time Systems: Developed a C graphic program (Allegro and Pthread libraries) in order to simulate the control of a DC motor controlled by a PID controller.</li> </ul>	University of Pisa, Italy
2012–2013	<b>Freescall Smart Cars Race</b> <i>Embedded Programmer</i> Developed a variable structure PID to control a smart car using the inputs from two linear vision sensors. Design of various modifications to the car chassis, such as camera mounts and LED circuit board to improve performances.	University of Padova, Italy
2012-2013	<b>Lionbridge</b> <i>Internet Assessor</i> Reviewer of the quality of search engines' results.	Work from home job

## Communication skills

2016-present	<b>Oral Presentation</b> Presented the research I conducted for the papers [C2], [C3].	IEEE Conferences
2018	<b>Talk</b> I gave a talk on cluster synchronization on network of Kuramoto oscillators during the Mechanical Engineering Symposium.	University of California, Riverside
2016	<b>Poster</b> I created a poster on structural controllability of anatomical brain networks and presented the results at WUSTL.	Workshop on Brain Dynamics and Neurocontrol Engineering, WUSTL

## Awards

2016	<b>Dean's Distinguished Fellowship</b> Fellowship awarded based on student's academic performance and project proposal. Fellowship guarantees stipend and full coverage of tuition for two years in the Ph.D. program.	University of California, Riverside
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## Interests

I love traveling and discovering different cultures. I like to unwind by performing outdoor activities or trying new foods.

**Hobbies:** passion for technology, neuroscience, cooking, music, philosophy, modern art and camping.

**Sports:** golf, skiing, tennis, swimming, hiking.