# TommasoMenara

PhD Candidate at University of California Riverside

## contact

♥ Bourns College of Engineering, WCH 228, Riverside, CA, 92507

**a** +1 (949) 607-8776

@ tommasomenara.com

~~~

## languages

English Italian

~~~

## programming

C Java Matlab & Simulink

Wolfram (Mathematica)

Processing (Arduino)

# **Education**

2016-present **Phd** Mechanical Engineering

Network Neuroscience and Control Theory

2013–2016 Laurea Magistrale (M.Sc. equivalent)

Robotics and Control Engineering

2010–2013 Laurea (B.Sc. equivalent)

Mechatronics Engineering

University of California, Riverside

University of Pisa, Italy

University of Padova, Italy

## **Publications**

## **Journal papers**

- [J2]. T. Menara, G. Baggio, D.S. Bassett, F. Pasqualetti, Stability Conditions for Cluster Synchronization in Networks of Heterogeneous Kuramoto Oscillators, IEEE Transactions on Control of Network Systems, 2019 (Early Access)
- [J1]. T. Menara, D.S. Bassett, F. Pasqualetti, *Structural Controllability of Symmetric Networks*, IEEE Transactions on Automatic Control, 2018 (Early Access)

## **Conference proceedings**

- [C4]. T. Menara, G. Baggio, D.S. Bassett, F. Pasqualetti, Exact and Approximate Stability Conditions for Cluster Synchronization of Kuramoto Oscillators, IEEE American Control Conference. Philadelphia, USA, July 2019 (Best Student Paper Award Finalist)
- [C3]. T. Menara, V. Katewa, D.S. Bassett, F. Pasqualetti, The Structured Controllability Radius of Symmetric (Brain) Networks, IEEE American Control Conference. Milwaukee, USA, June 2018
- [C2]. T. Menara, G. Bianchin, M. Innocenti, F. Pasqualetti, On the Number of Strongly Structurally Controllable Networks, IEEE American Control Conference. Seattle, USA, May 2017
- [C1]. M. Laurino, T. Menara, A. Stella, M. Betta, A. Landi, Procoagulant control strategies for the human blood clotting process. 37th Annual Conference of the IEEE Engineering in Medicine and Biology Society. Milano Conference Center, Milan, Italy, August 2015

# **Experience**

2016-present IEEE - IFAC

University of California, Riverside

Referee/Reviewer

Reviewer for journals such as: IEEE Transactions on Automatic Control (IEEE-TAC), IEEE Transactions on Control of Networked Systems (IEEE-TCNS), IEEE Control Systems Letters (IEEE L-CSS), IFAC Automatica, SIAM Journal on Control and Optimization.

Reviewer for international conferences such as: Conference on Decision and Control (CDC), American Control Conference (ACC), European Control Conference (ECC), International Conference on Control, Decision and Information Technologies (CODIT), Conference on Control Technologies (CCTA)

#### 2016–2019 **Graduate Students Association**

University of California, Riverside

Public Relations Officer

PR Officer in the Graduate Students Association. Responsible of organizing campus-wide social events. Management of the budget for social events. Vice-chair of the HUB Board of Governors.

#### 2017–2018 Graduate Students Association

University of California, Riverside

International Student Affairs Officer

ISAO in the Graduate Students Association. Monitoring of campus issues and legislative developments that affect international graduate students. Member of different committees related to international education.

### 2016–2017 **Graduate Students Association**

University of California, Riverside

MEGSA Representative

Mechanical Engineering Representative in the Graduate Students Association.

## 2015–2016 Mechanical Engineering Department

University of California, Riverside

Visiting Scholar

Research on strong structural controllability of network systems during a 6-months period.

## 2013–2015 **Department of Information Engineering**

University of Pisa, Italy

Student Projects

- Design, production and coding of an autonomous floor-cleaning robot.
- System identification of a Inertially Stabilized Platform (ISP). Developed controllers for the gimbals of the ISP.
- Modeled the humanoid robot Walkman (developed by the IIT Genova) in Simulink/Simmechanics. Combined Path Planning, Trajectory Tracking and Motion Control to make the robot achieve tasks while walking. Developed the steering function for a RRT algorithm to decide whether the connection between different states is feasible or not.
- Computer Aided Engineering (CAE) Methods: Modeling of mechanical parts and stress simulations using Solidworks.
- Identification of Uncertain Systems: Identification and parameter fitting of an electromechanical diesel engine actuator valve.
- Real-Time Systems: Developed a C graphic program (Allegro and Pthread libraries) in order to simulate the control of a DC motor controlled by a PID controller.

#### 2012–2013 Freescale Smart Cars Race

University of Padova, Italy

Embedded Programmer

Developed a variable structure PID to control a smart car using the inputs from two linear vision sensors. Design of various modifications to the car chassis, such as camera mounts and LED circuit board to improve performances.

## 2012-2013 **Lionbridge**

Work from home job

Internet Assessor

Reviewer of the quality of search engines' results.

# **Communication skills**

## 2016-present Oral Presentation

IEEE Conferences

Presented the research I conducted for the papers [C2], [C3].

2018 **Poste** 

Computational Neuroimaging and Neuroengineering Symposium, UCR

I presented my results on cluster synchronization of Kuramoto oscillators.

2018 **Talk** 

University of California, Riverside

I gave a talk on cluster synchronization on network of Kuramoto oscillators during the Mechanical Engineering Symposium.

2016 **Poster** Workshop on Brain Dynamics and Neurocontrol Engineering, WUSTL I presented my results on structural controllability of anatomical brain networks.

# **Awards**

2019	Best Student Paper Award Finalist	American Automatic Control Council
	I was selected as one of five finalists for the Best Student Paper Award at the	
	2019 IEEE American Control Conference.	
2017	IEEE Student Travel Award	IEEE
	I was awarded a student travel award to attend the 2017 IEEE American Control	
	Conference.	
2016	Dean's Distinguished Fellowship	University of California, Riverside
	Fellowship awarded based on student's academic performance and project	
	proposal. Fellowship guarantees stipend and full coverage of tuition for two	
	years in the Ph.D. program.	

# **Interests**

I love traveling and learning about different cultures. I like to de-stress by performing outdoor activities or trying new foods.

**Hobbies**: passion for technology, cooking, jazz music, philosophy, architecture and camping. **Sports**: golf, skiing, tennis, swimming, hiking.