

# ADL HW1-TIMIT Report

b03705012 資管四 張晉華

## 1. Model description

- RNN

Layer (type)	Output Shape	Param #
bidirectional_1 (Bidirection	(None, 776, 1000)	1620000
bidirectional_2 (Bidirection	(None, 776, 1000)	4503000
time_distributed_1 (TimeDist	(None, 776, 1000)	1001000
dropout_1 (Dropout)	(None, 776, 1000)	0
time_distributed_2 (TimeDist	(None, 776, 1000)	1001000
dropout_2 (Dropout)	(None, 776, 1000)	0
time_distributed_3 (TimeDist	(None, 776, 39)	39039
Total params: 8,164,039		
Trainable params: 8,164,039		
Non-trainable params: 0		

(Model Summary)

- 兩層的 Bidirectional GRU: Units = 500, dropout = 0.5, activation = ReLU
- 兩層 TimeDistributed Dense: Units = 1000, activation = ReLU, 加上 TimeDistributed 讓 Output Shape 維持 776(frames)\*1000
- 最後一層 TimeDistributed Dense 作為 Output Layer: Units = 39(事先用 48\_39.map, 48phone\_char.map 將 label mapping 成 char 了), activation = Softmax, 加上 TimeDistributed 一樣為了讓 Output Shape 維持 776(frames)\*39(probability of per label)

- RNN+CNN

Layer (type)	Output Shape	Param #
conv1d_1 (Conv1D)	(None, 776, 800)	1217600
time_distributed_1 (TimeDist	(None, 776, 39)	31239
bidirectional_1 (Bidirection	(None, 776, 1000)	1620000
bidirectional_2 (Bidirection	(None, 776, 1000)	4503000
bidirectional_3 (Bidirection	(None, 776, 500)	1876500
bidirectional_4 (Bidirection	(None, 776, 500)	1126500
time_distributed_2 (TimeDist	(None, 776, 39)	19539
Total params: 10,394,378		
Trainable params: 10,394,378		
Non-trainable params: 0		

(Model Summary)

- 一層的 Conv1d:Filters = 800, Filters Shape = (39)
- 兩層的 Bidirectional GRU:Units = 500, dropout = 0.3, activation = ReLU
- 兩層的 Bidirectional GRU:Units = 250, dropout = 0.3, activation = ReLU
- 最後一層 TimeDistributed Dense 作為 Output Layer: Units = 39(事先用 48\_39.map,48phone\_char.map 將 label mapping 成 char 了), activation = Softmax, 加上 TimeDistributed 一樣為了讓 Output Shape 維持 776(frames)\*39(probability of per label)

## 2.How to improve your performance

- Standardize

先將 mfcc 的 data 做標準化，將他整理成每個 column 都是標準差為 1，平均為 0 的資料。（由於 mfcc 是 1 個對數能量和 12 個倒頻譜參數再加上差量運算和差差量運算所形成的 39 維資料，因此以 column 做標準化單位而不用 row)

- 加深 RNN

增加 RNN 的深度，增加前後相關性的判斷能力

- Compare(2 層 GRU → 4 層 GRU)
  - before:11.02824(Kaggle Public Score)
  - after:10.14124(Kaggle Public Score)

- Output Filter

由於最後 performance 的評估方式是以 edit distance 來做評價，所以我決定忽略 frame 的連續數量不足的 label，只輸出連續數量含或超過 2 個以上的 label。

- Compare(以同一模型做比較)
  - before:10.14124(Kaggle Public Score)
  - after:9.27118(Kaggle Public Score)

- Ensemble

將 3 個不同的模型做 ensemble，以避免個別模型的 bias，有實作過 voting 跟 average 兩種作法。

- Compare(Before 是以單一模型的最高分為準)
  - Voting
    - before:9.27118(Kaggle Public Score)
    - after:9.25988(Kaggle Public Score)
  - Average
    - before:9.27118(Kaggle Public Score)
    - after:8.44632(Kaggle Public Score)

### **3.Experimental results and settings**

- Compare and analyze the results between RNN and CNN
  - Compare

- RNN:11.31638(Kaggle Public Score)
- CNN+RNN:12.01129(Kaggle Public Score)
- Analyze
  - CNN+RNN 在 training 時收斂速度比 RNN 還快但容易 overfit
  - CNN+RNN 由於 frame 的 feature 在 CNN 時先通過了 Filters，因此到 RNN 時對前後相關性的判斷資訊稍微不足，因此綜合的結果表現比起純 RNN 略差。
- Compare and analyze the results with other models
  - SimpleRNN 和 GRU 的比較

在同樣的架構下 GRU 的表現比 RNN 好，收斂速度也較快
  - 4 層 GRU 和 2 層 GRU+2 層 Dense 的比較

4 層 GRU 對於前後相關性的判斷能力比起 2 層 GRU+2 層 Dense 來的好一些，雖然計算時間較久但最後的 Performance 較好。

    - 4 層 GRU:10.14124(Kaggle Public Score)
    - 2 層 GRU+2 層 Dense:11.02824(Kaggle Public Score)