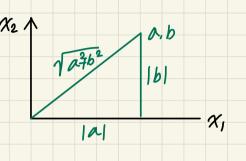
* fully annected layous. **एकाइला**न y1 = W1. x1 + W2. x2 + W3. x3 ft if y, = 1.x, - 1.y2, 刊180, 强剂 80 岁,=100 7 100 35711 10 91 = 11 neto-one.

$$-\underline{u} \cdot \underline{v} = \underline{u}^{T}\underline{v} = \underline{v} \cdot \underline{u}$$

$$-(\underline{n+\underline{n}})\cdot\underline{m}=\underline{n\cdot\underline{m}}+\underline{n\cdot\underline{m}}$$

$$= C_1 \left(\underline{u_1 \cdot w} \right) + C_2 \left(\underline{u_2 \cdot w} \right) + \cdots C_p \left(\underline{u_p \cdot w} \right).$$

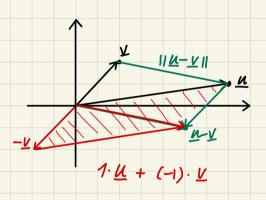
•
$$||V|| = \sqrt{V_1^2 + V_2^2 + V_n^2}$$



Vector's norm
$$\rightarrow \frac{\text{Vector}}{\text{norm}} \cdot \frac{1}{||V||} \frac{V}{||V||}$$

* distance betw Vectors.

$$\begin{bmatrix} 3 \\ 4 \end{bmatrix} \longleftrightarrow \begin{bmatrix} 1 \\ 5 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix} \cdot \underbrace{12\frac{2}{16}}$$



* angle between vectors.

* orthogonal vectors.

orthogonal u, v, $u \cdot v = 0$.

* Over determined system.

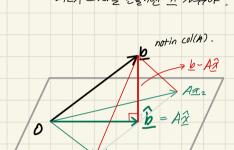
" Which one is a better solution?

Better Solution

B-A2

$$\hat{X} = \underset{\underline{x}}{\text{arg min } 11 \underline{b} - \underline{A} \underline{x} 11}.$$

$$\Rightarrow \underline{x}$$



$$(b-A\hat{x})\perp(x_1a_1+x_2a_2+x_3a_3)$$

$$\Rightarrow dot-p=0.$$

· am = 0 .

$$b-A\hat{x} \cdot a_1 = 0 \longrightarrow \underline{a_1}^{\mathsf{T}} (b-A\hat{x}) = 0 = A^{\mathsf{T}} (b-A\hat{x})$$

$$b-A\hat{x} \cdot a_2 = 0 \qquad b_2^{\mathsf{T}} = 0$$

 $A_{\underline{x}} = (x_1 \ \underline{a_1}) + (x_2 \ \underline{a_2}) + (x_3 \ \underline{a_3})$

$$A^{T}(b-A\hat{a})=0$$

$$\Rightarrow A^T A \hat{\alpha} = A^T \underline{b}$$

$$\widehat{X} = (A^T A)^T A^T \underline{b}$$

$$\begin{array}{c}
\circ f(\underline{x}) = \underline{a^{T}}\underline{x} \\
= \begin{bmatrix} 3 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 3x_1 + 2x_2 .
\end{array}$$

$$\frac{df}{dx} \Rightarrow 3x_1 + 2x_2 = \begin{bmatrix} 3\\2 \end{bmatrix}$$

$$\therefore \frac{df}{d\underline{x}} \underline{\alpha}^{\mathsf{T}} \underline{x} = \underline{a} = \frac{df}{d\underline{x}} \underline{x}^{\mathsf{T}} \underline{a}$$

* Another Derivation of normal equation.

$$arg \min_{\underline{x}} \|\underline{b} - \underline{A}\underline{x}\| = arg \min_{\underline{x}} \|\underline{b} - \underline{A}\underline{x}\|^2$$

$$\|\underline{x}\|^2 = \underline{x}^T\underline{x}$$
 ... $\underset{\underline{x}}{\operatorname{arg\,min}} (\underline{b} - \underline{A}\underline{\alpha})^T(\underline{b} - \underline{A}\underline{\alpha})$

$$= \underline{b^{T}b} - \underline{x^{T}A^{T}b}, -\underline{b^{T}Ax} + \underline{x^{T}A^{T}Ax}, \underline{x^{T}(A^{T}Ax)}$$

$$= \underline{x^{T}A^{T}b} \quad \underline{\underline{d(x^{T}(A^{T}Ax))}}$$

$$= \underline{A^{T}Ax} + \underline{A^{T}Ax}$$

$$= \underline{A^{T}Ax} + \underline{A^{T}Ax}$$

$$\frac{\partial \operatorname{arg min} ||b - Ax||}{\partial x} = 0 - A^{T}b - A^{T}b + A^{T}Ax + A^{T}Ax$$

$$\Rightarrow 2 A^{T}\underline{b} = 2 A^{T}\underline{A}\underline{x}$$

$$\Rightarrow \text{ normal equation.}$$

$$\underline{x} = (A^{T}A)^{-1}A^{T}\underline{b}$$

* Orthogonal projection.

normal equations.

$$\widehat{b} = f(\underline{b}) = A\widehat{x} = A(A^TA)^{-1}A^T\underline{b}$$

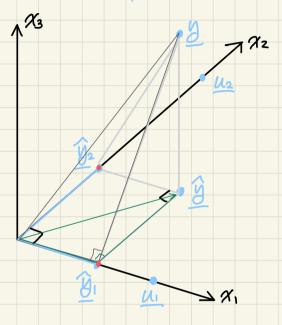
ex)
$$y = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$
, $L = \text{Span } \left\{ \begin{bmatrix} -1 \\ 2 \end{bmatrix} \right\} \left(\frac{1}{1^2 + (1)^{\frac{3}{2}} 2^2} \right)$

$$y \circ u = \frac{1-2+6}{16} = \frac{5}{16} = \frac{1}{46}$$

$$\frac{\partial}{\partial x} \times \underline{u} = \frac{1}{16} \left[\frac{1}{16} \right] = \hat{y}$$

$$\frac{3}{3} \qquad \frac{1}{3} \qquad \frac{1$$

W = Span & U1, U23



$$\frac{\hat{y}}{y} = \frac{y \cdot u_1}{u_1 \cdot u_2} \frac{u_1}{u_2} + \frac{y \cdot u_2}{u_2 \cdot u_2} \frac{u_2}{u_2}$$

$$=$$
 $\widehat{y}_1 + \widehat{y}_2$

- on each orthogonal basis vector.