

Simulating a 28 GHz antenna for a UAV

For complex antennas, it is often necessary to perform detailed EM simulations in third-party software such as HFSS and then import the results into MATLAB for analysis. In this lab, we will import HFSS simulation data for a 28 GHz antenna designed for a UAV (unmanned aerial vehicle or drone). Antenna modeling is particularly important for mmWave aerial links since the directivity gain is necessary to overcome the high isotropic path loss of mmWave frequencies. Also, UAVs can be an arbitrary orientation and it is important to model the cases when the UAV is out of the beamwidth of the antenna.

In going through this lab, you will learn to:

- Import data from an EM simulation data given as a [MATLAB table object](#).
- Compute directivity from E-field values
- Create custom arrays in MATLAB's phased array toolbox
- Display 2D and 3D antenna patterns
- Compute the half-power beamwidth (HPBW) of an antenna
- Compute fractions of power in angular areas
- Estimate the path loss along a path

Submission: Complete all the sections marked TODO, and run the cells to make sure your script is working. When you are satisfied with the results, [publish your code](#) to generate an html file. Print the html file to PDF and submit the PDF.

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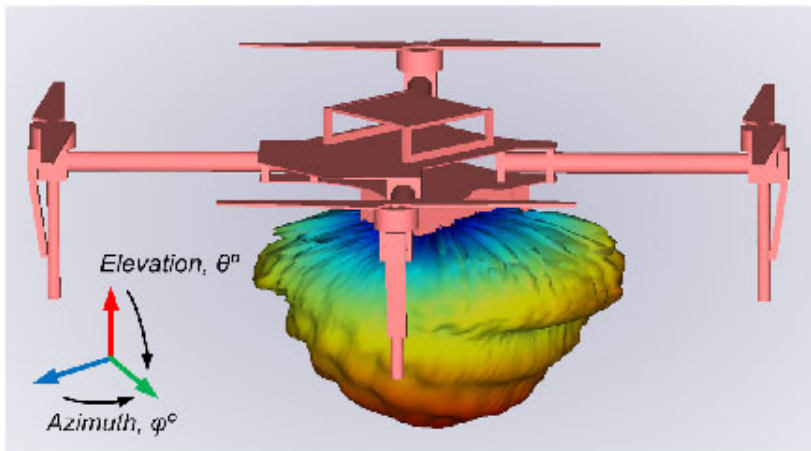
Load the data

The data for this lab was generously donated by Vasilii Semkin of VTT and taken from the paper:

- W Xia, V. Semkin, M. Mezzavilla, G. Loianno, S. Rangan, Multi-array Designs for MmWave and Sub-THz Communication to UAVs, 2020

The paper performs EM simulations on a circularly polarized 28 GHz antenna mounted to the bottom of a commercial DJI Matrice 100 quadcopter. An image of the drone with the antenna and its pattern is shown in the following picture.

```
A = imread('./CP_patch_downwards_m100_3D_coord.png');  
imshow(A, 'InitialMagnification', 40);
```



We will first load the data with the following command.

```
load patch_bottom_data.mat
```

Running the above command should create an object, `data_table`, in your workspace. The `data_table` object is a MATLAB table, which is like a SQL table. Run the following command to see the first five rows. You should see the fields in each table entry including the azimuth and elevation and the corresponding V and H fields.

```
data_table(1:5,:)
```

ans =

5×9 table

x_AngleIndex	Elevation	Azimuth	Frequency	TotVReal	TotVImag	TotHReal	TotHImag	Var9
0	-90	0	2.8e+10	0.018862	0.037489	0.02257	0.019296	{0×0 char}
1	-90	2	2.8e+10	0.019638	0.03814	0.021898	0.017976	{0×0 char}
2	-90	4	2.8e+10	0.020391	0.038744	0.021199	0.016634	{0×0 char}
3	-90	6	2.8e+10	0.021118	0.039301	0.020475	0.015272	{0×0 char}
4	-90	8	2.8e+10	0.02182	0.03981	0.019725	0.013891	{0×0 char}

Reading and the data table

We can read the table columns into MATLAB arrays with commands such as,

```
col = data_table(:,{column_name}).Variables;
```

```
% TODO: Read the 'Elevation' and 'Azimuth' columns into matlab arrays
% e1 and az.
e1 = data_table(:,{'Elevation'}).Variables;
az = data_table(:,{'Azimuth'}).Variables;
```

In this simulation, the antenna was pointed upwards, meaning that the boresight is at an elevation of 90 degrees. But, since we want to simulate antenna pointing downwards, we need to switch the signs of the elevation angles.

```
% TODO: Switch the elevation angles with el = -el;
el = -el;
```

Getting the E-field

Most EM simulations produce outputs as E-field at some distance from the antenna. The E-field is represented by two complex values, one for the H polarization and for the V polarization.

```
% TODO: Read the complex E-fields from the data_table object. Store them
% in variables EH and EV.

EV = data_table(:, {'TotVReal'}).Variables + ...
    1i*data_table(:, {'TotVImag'}).Variables;
EH = data_table(:, {'TotHReal'}).Variables + ...
    1i*data_table(:, {'TotHImag'}).Variables;
```

Recall that the radiation intensity and any point is proportional to the E-field power,

$$W = E_{\text{pow}}/\eta, \quad E_{\text{pow}} = |EH|^2 + |EV|^2.$$

where η is characteristic impedance. This is the power flux that can be received by an antenna exactly aligned in polarization with the E-field.

```
% TODO: Compute the E-field power, Epow = |EH|^2 + |EV|^2.
% Remember to use the MATLAB abs() command.
Epow = abs(EH).^2 + abs(EV).^2;
```

Compute the directivity

We next compute the directivity of the antenna. The directivity of the antenna is given by,

$$\text{dir} = U / P_{\text{tot}}$$

where P_{tot} is the total radiated power and U is the far-field radiation density

$$U = r^2 W = r^2 E_{\text{pow}} / \eta$$

Hence, the directivity (in linear scale) is:

$$\text{dir} = c * E_{\text{pow}}$$

for some constant c . To compute the constant c , we know that the average of the directivity $\text{dir} * \cos(\text{el})$ over a spherical integral must be one. Hence, if we take mean over the discrete values, you should have that:

$$\text{mean}(\text{dir} * \cos(\text{el})) / \text{mean}(\cos(\text{el})) = 1$$

You can use this relation to find the scale factor, c .

TODO: Compute a vector, dir , with the directivity of each point in dBi. Remember, MATLAB's $\cos()$ function takes the argument in radians.

```
el_rad = deg2rad(el);
c = mean(cos(el_rad))/mean(Epow.*cos(el_rad));
dir = c*Epow;
```

```

ratio = mean(dir.*cos(el_rad)) / mean(cos(el_rad));

% TODO: Print the maximum gain.
maxD = max(dir);
maxD_dBi = 10*log10(maxD);
fprintf(1, 'maximum gain = %f\n', maxD);
fprintf(1, 'maximum gain [dBi] = %f\n', maxD_dBi);

```

```

maximum gain = 5.646113
maximum gain [dBi] = 7.517496

```

Plotting the 3D antenna pattern

To plot the antenna pattern, we will create a CustomAntennaObject in MATLAB's phased array toolbox. However, to use the CustomAntennaObject, we need to re-format the directivity vector into a matrix. The process is tedious, but conceptually simple. What we need to do is create a matrix, `dirMat`, with values, `dirMat(i,j)` is the directivity at (elevation, azimuth) angles (`elval(i)`, `azval(j)`).

```

elvals = (-90:2:90)';
azvals = (-180:2:180)';
nel = length(elvals);
naz = length(azvals);
disp(naz*nel);
fprintf(1, '# elevation angles = %f\n', nel);
fprintf(1, '# azimuth angles = %f\n', naz);

```

```

16471

```

```

# elevation angles = 91.000000
# azimuth angles = 181.000000

```

If you have done everything correctly up to now, you will have a vector, `dir`, that is should be `naz*nel x 1`. To convert this to the `dirMat` matrix, you can do the following:

- Reshape the vector, `dir`, into a directory `dirMat` of size `naz x nel`. Take the transpose of the matrix so it is `nel x naz`.
- Circularly shift (using the MATLAB command `circshift`) so that the first column of `dirMat` is moved to the position corresponding to `az=0`. We do this since the angles in `dirMat` go from 0 to 360, not -180 to 180
- Flip the `dirMat` vertically with the MATLAB command `flipud`. We do this since we want to look at an antenna pattern facing downwards

TODO: Create `dirMat` as above

```

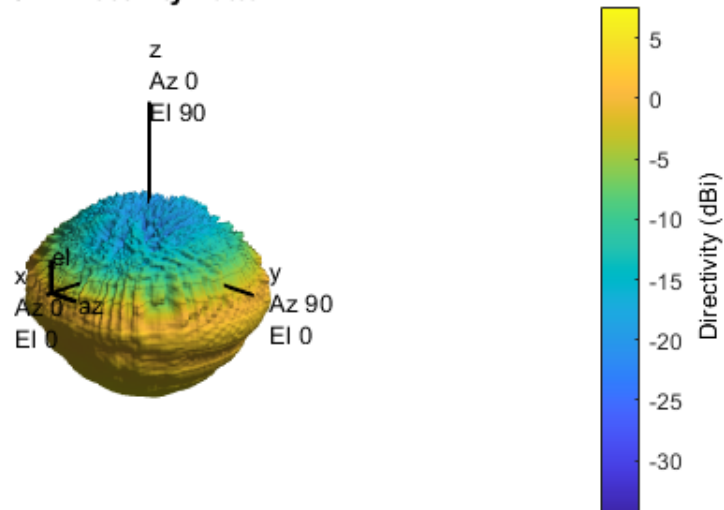
dirMat = reshape(dir,[naz,nel]).';
first = dirMat(:,1);
I = find(azvals == 0);
dirMat = circshift(dirMat,I,2);
dirMat = flipud(dirMat);
% TODO: Now, create the antenna object with the correct parameters
% Use an all zero phasePattern.

phasePattern = zeros(size(dirMat));
ant = phased.CustomAntennaElement(...
    'AzimuthAngles', azvals, ...
    'ElevationAngles', elvals, ...
    'MagnitudePattern', 10*log10(dirMat), ...
    'PhasePattern', phasePattern);

```

```
% TODO: Plot the antenna pattern with the ant.pattern() command
fc = 28e9;
ant.pattern(fc);
```

3D Directivity Pattern

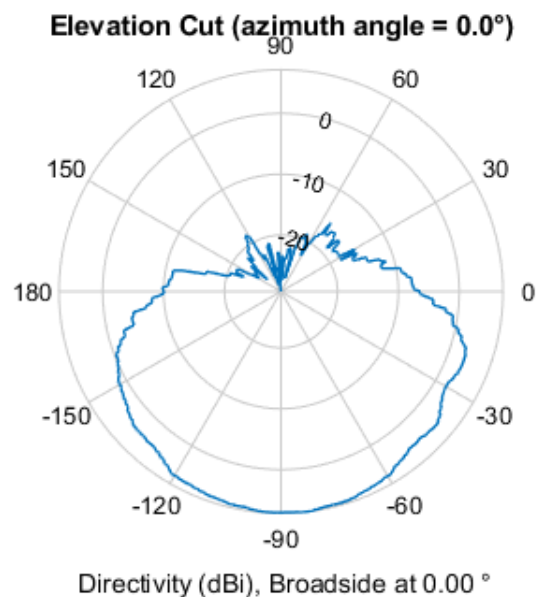


Plot a polar 2D plot

We next plot a 2D antenna pattern

TODO: Use the `ant.patternElevation(...)` to plot the antenna cut at `azPlot = 0` degrees

```
azPlot = 0;
patternElevation(ant, fc);
```



Computing the half-power beamwidth

The half-power beamwidth is a common value in describing the directivity of an antenna. We show how this quantity can be computed. First, get the numerical values of the directivity along a cut at `azPlot = 0`. We do this with the same command as above, but with an output argument:

```

% TODO: Run the clf('reset') command. This is needed since the last plot
% was a pattern plot,
clf('reset');
% TODO:
dircut = ant.patternElevation(fc);

% This returns the directivity along elevation angles elcut
elcut = (-180:180)';

```

The HPBW is the range of angles that correspond to the directivity 3 dB below the peak.

```

dir_range = maxD_dBi-3;
I = find(dircut >= 10^(dir_range/10));
hpbw_angles = elcut(I);
% TODO: Use the dircut and elcut vectors to find and print the HPBW.
max_an = max(hpbw_angles);
min_an = min(hpbw_angles);
HPBW = abs(max_an-min_an);
fprintf(1, 'The HPBW is %f\n', HPBW);

```

The HPBW is 104.000000

Computing power fractions.

Often we are interested in finding the fraction of radiated power in some angular region. The fraction of power radiated in any region is proportional to the sum of values $E_{\text{pow}}(i) \cdot \cos(\text{el}(i))$ for all points i in the region.

```

tot_power = sum(Epow.*cos(el_rad));
% TODO: Use this relation to print the fraction of power radiated in
% the upper hemisphere. This should be small, since most of the
% power is radiated downwards.
dircut_upper = dircut(181:end);
%upper_power = sum((dircut_upper/c).*cos());
% TODO: Print the power fraction within the HPBW:

```

Computing the path loss along a path

```

% Following the code in the demo, plot the path loss (omni and
% with element gain) of a UAV RX flying from (0,0,30) to (500,0,30)
% in a linear path. Assume the TX is at (0,0,0).
%
% TODO: Plot the omni and directional path loss vs. x position.
%
% You should see initially that you obtain significant antenna gain
% since the antenna is facing downwards to the TX. But, as you fly
% the antenna gain decreases and becomes negative. Before plotting you
% will want to run the command, clf('reset'). This is necessary since the
% pattern plots above screw up later figures.
clf('reset');
c=physconst('Lightspeed');
lambda = c/fc;
x = linspace(0,500,1000);
y = zeros(1,1000);
z = linspace(30,30,1000);

% plotting the UAV path
plot3(x,y,z); hold on;
plot3(0,0,0, 'x', 'MarkerSize',10); hold on;
plot3(0,0,30, 'o', 'MarkerSize',10); hold on;
plot3(500,0,30, 'd', 'MarkerSize',10);
xlabel('x');ylabel('y');zlabel('z');
grid();
title('UAV Flying Path');
legend('UAV path','TX position','UAV start','UAV end',...
      'Location','southoutside','Orientation','horizontal');

% the azimuth az0 is 0 since the UAV is moving along the x axis.
[az0, el0, rad0] = cart2sph(x, y, z);
az0 = rad2deg(az0)';
el0 = rad2deg(el0)';
[new_dir,new_az,new_el] = ant.pattern(fc, 'Type', 'Directivity');
F = griddedInterpolant({new_el,new_az},new_dir);
dirGain = F(-el0, az0)';

plOmni = fspl(rad0, lambda);
plDir = plOmni - dirGain;

figure;
plot(x,plOmni,'LineWidth',2); hold on;
plot(x,plDir,'LineWidth',2);
title('Omni vs Directional Path loss');
legend('Omni','Directional');
xlabel('Distance on x axis [m]');
ylabel('Path Loss [dB]');
grid();

```

