





# THOMAS TRAN

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## EDUCATION

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### University of Michigan College of Engineering

Ann Arbor, MI

*Bachelors of Science in Computer and Electrical Engineering*

*Aug. 2023 - May. 2026*

- **Selected Coursework:** Advanced Embedded Systems, Embedded Control Systems, Control Systems Design
- **Campus Involvement:** Michigan Aeronautical Science Association(MASA) Avionics Project Member, VSA

## EXPERIENCE

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### University of Michigan - CAEN

Ann Arbor, MI

*Classroom Technology Maintenance Technician*

*Aug. 2025 - Present*

- Serving as technical resource for maintaining integrated AV systems, diagnosing faults in signal and control hardware
- Identified and resolved system-level connectivity issues by analyzing signal paths and verifying network configurations for AV control hardware
- Performed routine maintenance and diagnostics on over 70+ multimedia classrooms to maintain system reliability

### Michigan Aeronautical Science Association(MASA)

Ann Arbor, MI

*Avionics Subteam Project Lead*

*Sept. 2024 - Present*

- Driving development of 2.4GHz LoRa-based telemetry system in a 10+ person Avionics team for real-time rocket flight data transmission, using dual-antenna ground station to enhance signal reception at altitudes up to 75,000 feet
- Orchestrating integration of radio systems with microcontroller firmware to achieve 40Kbps telemetry data rate
- Conducting RF link budget analysis and optimization to achieve -123.9 dBm received power sensitivity at 20km range

## PROJECTS

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### Multi-Modal Robotic Gantry Control System

- Engineered a real-time STM32 control system for a 2-axis gantry, achieving multi-modal operation by integrating a vision system (SPI) and a custom wireless Wii remote (I2C/UART)
- Authored interrupt-driven firmware to manage asynchronous data and hardware safety, achieving low-latency motor control and failsafe operation via GPIO limit switch interrupts
- Optimized the SPI communication link using a logic analyzer to verify data integrity, enabling high-throughput data transfer from the vision system to the microcontroller

### Model-Based Adaptive Cruise Control & Autonomous Steering

- Developed a multi-mode ACC system in Simulink for an NXP S32K144, deploying control logic via Stateflow to maintain set speeds and safe following distances
- Engineered C-based S-Functions to process CAN bus data from 6 vehicles, enabling robust lead-vehicle detection for the ACC state machine
- Tuned a PD controller for autonomous steering, achieving stable lane-keeping at 30 m/s and providing realistic force feedback through a haptic steering wheel

### 8-Bit Dual-Mode Ripple-Carry Adder

- Fabricated an 8-bit dual-mode ripple-carry adder using pass transistor logic in Cadence Virtuoso using Differential Cascode Voltage Switch Logic for high-speed operation, achieving 1GHz clock frequency at low power consumption
- Designed synchronous reset logic and dual operating modes, performing extensive timing verification and power analysis

## CERTIFICATIONS

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- Control Systems Analysis: Modeling of Dynamic Systems, *University of Colorado Boulder (Coursera)*, Issued July 2025
- Electric Power Systems, *University at Buffalo (Coursera)*, Issued June 2025
- C Programming for Embedded Applications, *LinkedIn Learning*, Issued June 2025

## SKILLS

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**Languages:** C, C++, Python, Verilog, ARM Assembly

**Hardware & Platforms:** Embedded Systems, FPGAs (Intel/Altera), Microcontrollers (STM32, NXP S32K144), RPi

**Software & Tools:** MATLAB/Simulink, Cadence Virtuoso, ModelSim, Quartus, Altium Designer, SPICE, NXP S32 Design Studio, VS Code, Git, STM32CubeIDE