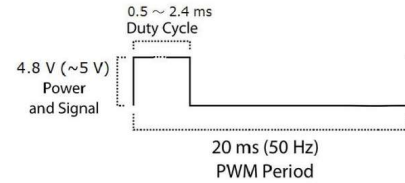


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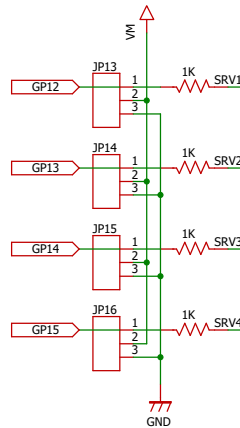
マイクロサーボモーターを使う



PWM=Orange (⌋⌋)  
 Vcc = Red (+)  
 Ground=Brown (-)



Position "0" (1.45 ms pulse) is middle, "90" (~2.4 ms pulse) is all the way to the right, "-90" (~0.5 ms pulse) is all the way left.



```
from machine import Pin, PWM
from utime import sleep
msb = machine.PWM(machine.Pin(12))
msb.freq(50)
# dutyの設定は、0-65536の範囲
# 0°:4751
```

```
while True:
    msb.duty_u16(1638) # 0°
    sleep(1)
    msb.duty_u16(4751) # 90°
    sleep(1)
    msb.duty_u16(7864) # 180°
    sleep(1)
```

-90°から90°まで、10°ずつ変えたときの設定値を計算した

// 中心位置	0 1638
1.45/20 = X/65536	10 1984
x = 1.45/20 * 65536	20 2330
	30 2676
// -90°	40 3022
x1 = 0.5/20 * 65536	50 3367
	60 3713
// 90°	70 4059
x2 = 2.4 /20 * 65536	80 4405
	90 4751
x = 4751	100 5097
x1 = 1638	110 5443
x2 = 7864	120 5789
	130 6135
	140 6480
	150 6826
	160 7172
	170 7518
	180 7864

