

Using Futhark for a fast, parallel implementation of forward and back projection in algebraic reconstruction methods - A pre-study

Lærke Pedersen and Mette Bjerg Lindhøj

University of Copenhagen

08/11/2018

Solve the problem:

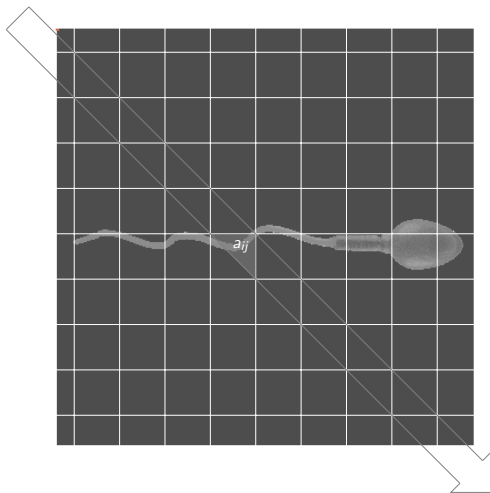
$$\mathbf{f}^* = \operatorname{argmin}_{\mathbf{f}} \|\mathbf{p} - \mathbf{A}\mathbf{f}\| \quad (1)$$

iteratively using this update step:

$$\mathbf{f}^n = \mathbf{f}^{(n-1)} + \mathbf{C}\mathbf{A}^T \mathbf{R}(\mathbf{p} - \mathbf{A}\mathbf{f}^{(n-1)}), \quad (2)$$

where \mathbf{C} and \mathbf{R} are the diagonal matrices containing the inverse column and row sums of the system matrix respectively.

The system matrix



The problem is in the size

- Consider reconstructing a single slice of a volume from a detector of size $n \times n$
- The number of rays is n
- The number of angles is $\frac{n \cdot \pi}{2}$
- A typical value for n is 2048
- In semi sparse format the matrix will take up $2 \cdot 4 \cdot 2048 \cdot \lceil \frac{2048 \cdot \pi}{2} \rceil \cdot (2 \cdot 2048 - 1) \approx 216GB$

System matrix computation

```
1 for ray = 0; ray < numberofrays; ray++ //parallel
2   for pixel = 0; pixel < pixels; pixel++ //parallel
3     if ray intersects pixel:
4       (p1,p2) = intersectionpoints pixel ray
5       A[ray][pixel] = distance p1 p2
```

Figure: $W(r, n) = O(r \cdot n^2)$, $D(r, n) = O(1)$

```
1 for ray in rays //parallel
2   while (isingrid focuspoint) //seq
3     pixel = calculatepixel focuspoint ray
4     nextpoint = findnextpoint focuspoint ray
5     A[ray][pixel] = distance nextpoint focuspoint
6     focuspoint = nextpoint
```

Figure: $W(r, n) = O(r \cdot n)$, $D(r, n) = O(n)$

Flattening

Preliminary results - not good but also we weren't completely done. Also flattening takes up even more space!

Code transformations

- By dumping the compiled code with the `-dump` command and getting the time spend in different kernels with the `-D` option we found that most of the time was spend on calculating the system matrix
- Futhark can not merge a map with a loop
- The code had a lot of branching
- We tried to mitigate this by removing as much from the loop as possible, and reorganising branches.

Changing the algorithm

```
1 for ray in rays //parallel
2   for i=-halfsize; i < halfsize; i++ //parallel
3     (l1,pixel1) = intersection1 ray i
4     (l2,pixel2) = intersection2 ray i
5     A[ray][pixel1] = l1
6     A[ray][pixel2] = l2
```

Figure: $W(r, n) = O(r \cdot n)$, $D(r, n) = O(1)$

Flattening the new algorithm

Show them how its done ;-)



Hao Gao.

Fast parallel algorithms for the x-ray transform and its adjoint.
Medical physics, 39(23127102):7110–7120, November 2012.



Y. Long, J. A. Fessler, and J. M. Balter.

3d forward and back-projection for x-ray ct using separable footprints.
IEEE Transactions on Medical Imaging, 29(11):1839–1850, Nov 2010.



F. Natterer.

The Mathematics of Computerized Tomography.
Society for Industrial and Applied Mathematics, 2001.



Z. Xue, L. Zhang, and J. Pan.

A new algorithm for calculating the radiological path in ct image reconstruction.

In *Proceedings of 2011 International Conference on Electronic Mechanical Engineering and Information Technology*, volume 9, pages 4527–4530, Aug 2011.