Note on Minka "Estimating a Dirichlet distribution"

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1 Estimating a Dirichlet distribution

1.1 Basic setting

Let **p** denote a random vector each of which elements sum to 1 and α a parameter vector of the Dirichlet distribution.

$$P(\mathbf{p}|\boldsymbol{\alpha}) \sim \mathcal{D}(\alpha_1, \dots, \alpha_K) = \frac{\Gamma(\sum_{k=1}^K \alpha_k)}{\prod_{k=1}^K \Gamma(\alpha_k)} \prod_{k=1}^K p_k^{\alpha_k - 1}$$
(1)

where
$$\sum_{k=1}^{n} p_k = 1$$
 and $p_k > 0$ (2)

We maximize $p(D|\boldsymbol{\alpha}) = \prod_{i=1}^{N} p(\mathbf{p}_i|\boldsymbol{\alpha})$ where $D = \{\mathbf{p}_1, \cdots, \mathbf{p}_N\}$.

$$\log p(D|\alpha) = \log \left(\prod_{i=1}^{N} p(\mathbf{p}_i|\alpha) \right)$$
(3)

$$= \sum_{i=1}^{N} \log \left(\frac{\Gamma(\sum_{k=1}^{K} \alpha_k)}{\prod_{k=1}^{K} \Gamma(\alpha_k)} \prod_{k=1}^{K} p_{ik}^{\alpha_k - 1} \right)$$

$$\tag{4}$$

$$= \sum_{i=1}^{N} \left\{ \log \left(\Gamma(\sum_{k=1}^{K} \alpha_k) \right) - \log \left(\prod_{k=1}^{K} \Gamma(\alpha_k) \right) + \log \left(\prod_{k=1}^{K} p_{ik}^{\alpha_k - 1} \right) \right\}$$
 (5)

$$= N \log \left(\Gamma(\sum_{k=1}^{K} \alpha_k) \right) - N \sum_{k=1}^{K} \log \left(\Gamma(\alpha_k) \right) + \sum_{i=1}^{N} \sum_{k=1}^{K} (\alpha_k - 1) \log p_{ik}$$
 (6)

$$= N \log \left(\Gamma(\sum_{k=1}^{K} \alpha_k) \right) - N \sum_{k=1}^{K} \log \left(\Gamma(\alpha_k) \right) + N \sum_{k=1}^{K} (\alpha_k - 1) \log \bar{p_k}$$
 (7)

where
$$\log \bar{p_k} = \frac{1}{N} \sum_{i=1}^{N} \log p_{ik}$$
 (8)

The objective function $p(D|\alpha)$ is convex in α since the Dirichlet distribution is in the exponential family. This implies that the likelihood function is unimodal and the maximum can be found by a simple search.

1.2 Estimate α by MLE (1): A fixed-point iteration

The gradient of the log-likelihood with respect to each α_k can be written as follows.

$$g_k = \frac{\partial \log p(D|\alpha)}{\partial \alpha_k} \tag{9}$$

$$= N \frac{\partial}{\partial \alpha_k} \log \left(\Gamma(\sum_{k=1}^K \alpha_k) \right) - N \frac{\partial}{\partial \alpha_k} \sum_{k=1}^K \log \left(\Gamma(\alpha_k) \right) + N \frac{\partial}{\partial \alpha_k} \sum_{k=1}^K (\alpha_k - 1) \log \bar{p_k}$$
 (10)

$$= N \left\{ \Psi(\sum_{k=1}^{K} \alpha_k) - \Psi(\alpha_k) + \log \bar{p_k} \right\}$$
(11)

where
$$\Psi(x) = \frac{\partial \log \Gamma(x)}{\partial x}$$
 (12)

Recall that $\frac{\partial}{\partial x_i} \sum_{i=1}^N x_i = x_i$ since all factors in $\sum_{i=1}^N x_i$ other than x_i disappear when you take derivative with respect to x_i .

We want to show $\Psi(\alpha_k^{new}) = \Psi(\sum_{k=1}^K \alpha_k^{old}) + \log \bar{p_k}$. Using the inequality in Appendix A in Minka's technical report to the first factor of (7), we obtain following inequality. Note that here we regard α_k^{old} constant here.

$$\frac{\log p(D|\alpha)}{N} \tag{13}$$

$$= \log \left[\Gamma \left(\sum_{k=1}^{K} \alpha_k^{old} \right) \exp \left\{ \sum_{k=1}^{K} (\alpha_k - \alpha_k^{old}) \Psi \left(\sum_{k=1}^{K} \alpha_k^{old} \right) \right\} \right] - \sum_{k=1}^{K} \log \Gamma(\alpha_k) + \sum_{k=1}^{K} (\alpha_k - 1) \log \bar{p_k}$$
 (14)

$$= \left(\sum_{k=1}^{K} \alpha_k\right) \Psi\left(\sum_{k=1}^{K} \alpha_k^{old}\right) - \sum_{k=1}^{K} \log \Gamma(\alpha_k) + \sum_{k=1}^{K} (\alpha_k - 1) \log \bar{p_k} + \operatorname{const}(\alpha_k^{old})$$
(15)

By taking derivative respect to α_k and set to zero to obtain the equation above.

$$\frac{\partial}{\partial \alpha_k} \left[\left(\sum_{k=1}^K \alpha_k \right) \Psi \left(\sum_{k=1}^K \alpha_k^{old} \right) - \sum_{k=1}^K \log \Gamma(\alpha_k) + \sum_{k=1}^K (\alpha_k - 1) \log \bar{p_k} + \operatorname{const}(\alpha_k^{old}) \right]$$
(16)

$$=\Psi\left(\sum_{k=1}^{K}\alpha_{k}^{old}\right) - \Psi(\alpha_{k}) + \log \bar{p_{k}} = 0 \tag{17}$$

$$\therefore \quad \Psi(\alpha_k^{new}) = \Psi(\sum_{k=1}^K \alpha_k^{old}) + \log \bar{p_k}$$
 (18)

$$\Leftrightarrow \alpha_k^{new} = \Psi^{-1} \left(\Psi(\sum_{k=1}^K \alpha_k^{old}) + \log \bar{p_k} \right)$$
 (19)

1.3 Estimate α by MLE (2): Newton iteration

Newton itertion is a method to obtain x which satisfies f(x) = 0. The second order of Taylor expansion of f(x) at x^* is

$$f(x) = f(x^*) + \frac{\partial f(x^*)}{\partial x}(x - x^*) + O((x - x^*)^2).$$
 (20)

Ignoring the second order degree and higher, and inputing f(x) = 0, we obtain following equation, which is the update equation for Newton iteration method.

$$0 = f(x^*) + \frac{\partial f(x^*)}{\partial x}(x - x^*) \tag{21}$$

$$\Leftrightarrow x = x^* - \left(\frac{\partial f(x^*)}{\partial x}\right)^{-1} f(x^*) \tag{22}$$

In the following procedure f(x) is equivalent to $\frac{\partial \log p(D|\alpha)}{\partial \alpha}$.

First, we take the second-derivatives (Hessian matrix) of the loglikelihood (which is equivalent to $\frac{\partial f(x)}{\partial x}$) since our target function is $\frac{\partial \log p(D|\boldsymbol{\alpha})}{\partial \alpha}$ and we want to obtain α with $\frac{\partial \log p(D|\boldsymbol{\alpha})}{\partial \alpha}=0$.

$$\frac{\partial^{2} \log p(D|\alpha)}{\partial^{2} \alpha_{k}} = N \left\{ \Psi' \left(\sum_{k=1}^{K} \alpha_{k} \right) - \Psi' \left(\alpha_{k} \right) \right\}$$
 (23)

$$\frac{\partial^2 \log p(D|\alpha)}{\partial \alpha_k \partial \alpha_j} = N \Psi' \left(\sum_{k=1}^K \alpha_k \right) \quad \text{where } k \neq j$$
 (24)

or

$$\frac{\partial^2 \log p(D|\alpha)}{\partial \alpha_k \partial \alpha_j} = \underbrace{N\Psi'\left(\sum_{k=1}^K \alpha_k\right)}_{(a)} \underbrace{-N\Psi'\left(\alpha_k\right)\delta(j-k\right)}_{(b)} \tag{25}$$

Note that Ψ' is known as the trigamma function and δ as the indicator function. We define each component of the Hessian as $h_{kj} = \frac{\partial^2 \log p(D|\alpha)}{\partial \alpha_k \partial \alpha_j}$ and $g_k = \frac{\partial \log p(D|\alpha)}{\partial \alpha_k}$. The Hessian can be written in matrix form as follows.

$$\mathbf{H} = \mathbf{Q} + \mathbf{1}\mathbf{1}^{\mathsf{T}}z\tag{26}$$

$$q_{jk} = -N\Psi'(\alpha_k)\delta(j-k)$$
 (b) in the equation (25)

$$z = N\Psi'(\sum_{k=1}^{K} \alpha_k)$$
 (a) in the equation (25)

Using the equation (22),

$$\alpha^{new} = \alpha^{old} - \mathbf{H}^{-1}\mathbf{g} \tag{29}$$

We examine second part in the right side of the equation (29). Note that **H** and **g** are function of α^{old} .

$$\mathbf{H}^{-1}\mathbf{g} = (\mathbf{Q} + \mathbf{1}\mathbf{1}^{\mathsf{T}}z)^{-1}\mathbf{g} \tag{30}$$

$$= \mathbf{Q}^{-1} \mathbf{g} - \frac{\mathbf{Q}^{-1} \mathbf{1} \mathbf{1}^{\mathsf{T}} \mathbf{Q}^{-1} \mathbf{g}}{\frac{1}{z} + \mathbf{1}^{\mathsf{T}} \mathbf{Q}^{-1} \mathbf{1}}$$
(31)

$$= \mathbf{Q}^{-1}\mathbf{g} - \mathbf{Q}^{-1}\mathbf{1} \left(\frac{\mathbf{1}^{\top} \mathbf{Q}^{-1} \mathbf{g}}{\frac{1}{\epsilon} + \mathbf{1}^{\top} \mathbf{Q}^{-1} \mathbf{1}} \right)$$
(32)

$$=\mathbf{Q}^{-1}(\mathbf{g}-\mathbf{1}b)\tag{33}$$

where

$$b = \frac{\mathbf{1}\mathbf{Q}^{-1}\mathbf{g}}{\frac{1}{z} + \mathbf{1}^{\top}\mathbf{Q}^{-1}\mathbf{1}} = \frac{\sum_{j=1}^{J} \frac{g_j}{q_{jj}}}{\frac{1}{z} + \sum_{j=1}^{J} \frac{1}{q_{jj}}}$$
(34)

From (30) to (31), we utilize following matrix property,

$$(\mathbf{A} + \mathbf{B}\mathbf{C}^{\mathsf{T}})^{-1} = \mathbf{A}^{-1} - \frac{\mathbf{A}^{-1}\mathbf{B}\mathbf{C}^{\mathsf{T}}\mathbf{A}^{-1}}{1 + \mathbf{C}^{\mathsf{T}}\mathbf{A}^{-1}\mathbf{B}}$$
(35)

where **A** as a $p \times p$ regular matrix and **B** and **C** as $p \times 1$ vectors which compose a regular matrix $\mathbf{A} + \mathbf{B}^{\top} \mathbf{C}$. Each component of $\mathbf{H}^{-1}\mathbf{g}$ can be written as follows.

$$[\mathbf{H}^{-1}\mathbf{g}]_k = [\mathbf{Q}^{-1}(\mathbf{g} - \mathbf{1}b)]_k \tag{36}$$

$$=\sum_{j=1}^{J} q_{kj}^{-1}(g_k - b) \tag{37}$$

$$=\sum_{j=1}^{J} \frac{\delta(j-k)}{-N\Psi'(\alpha_k)} (g_k - b)$$
(38)

$$=\frac{g_k - b}{-N\Psi'(\alpha_k)} \tag{39}$$

2 Appendix

2.1 Useful property of inverse of digamma function

To compute a high-accuracy solution to $\Psi(x) = y$, use following formula.

$$\Psi^{-1}(y) \approx \begin{cases} \exp(y) + \frac{1}{2} & \text{if } y \ge -2.22\\ -\frac{1}{y - \Psi(1)} & \text{if } y \le -2.22 \end{cases}$$
(40)

Then, you implement the Newton method using the following equation.

$$x^{new} = x^{old} = \frac{\Psi(x) - y}{\Psi'(x)} \tag{41}$$

Note that Ψ' is known as a trigamma function.

3 Useful reference

- https://endymecy.gitbooks.io/spark-ml-source-analysis/content/%E8%81%9A%E7%B1%BB/LDA/docs/dirichlet.pdf
- https://qiita.com/research-PORT-INC/items/9e83a49f9b07eaccef6b (Japanese)