Deformations

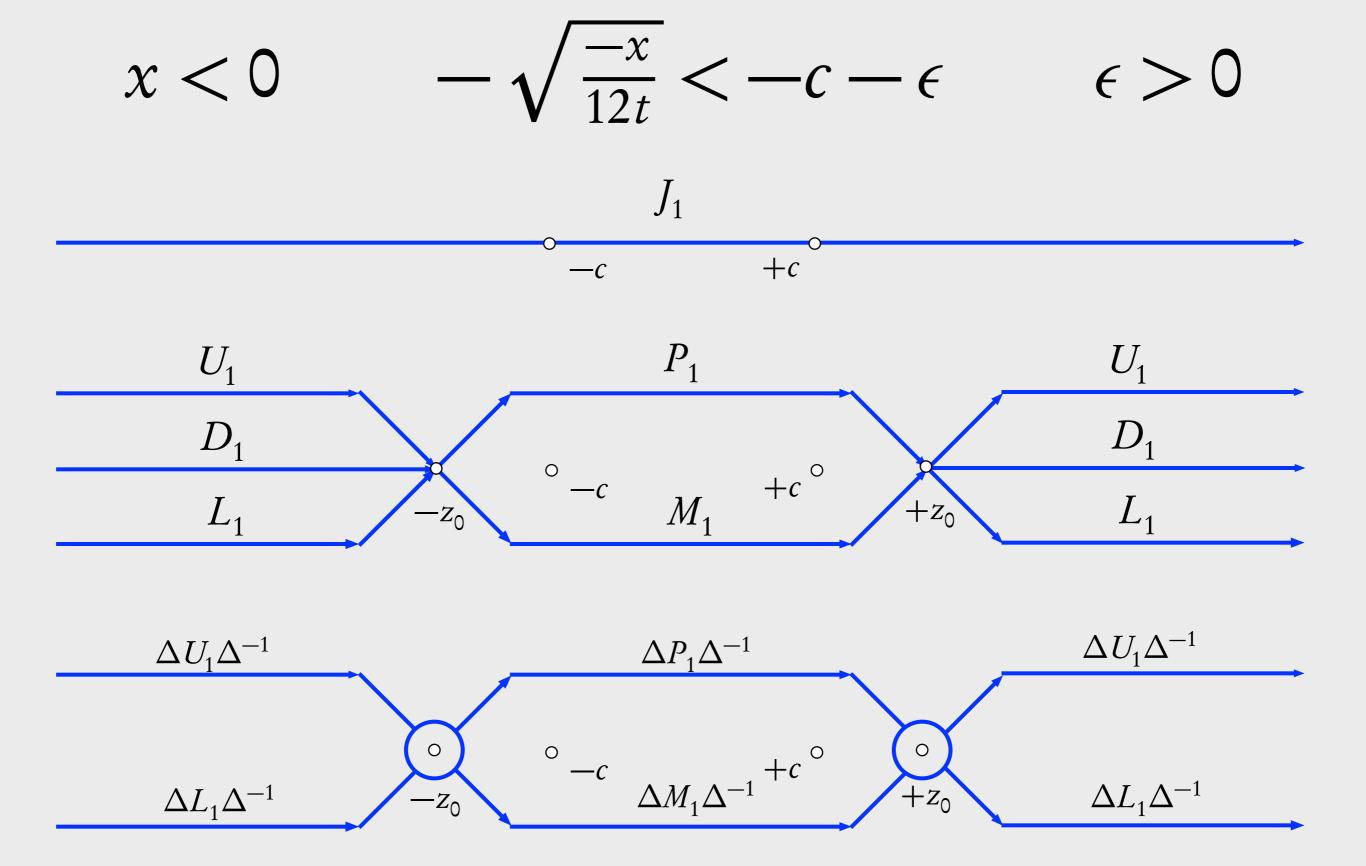
We have not implemented all the deformations that are required to compute q(x, t) for all (x, t).

Two deformations allow us to compute the solution for all x and small time, 0 < t < 2.

More to come, including $t \to \infty$!

All deformations are performed assuming $u_0 \in L^1(\mathbb{R}, e^{\delta|x|} dx)$ for some $\delta > 0$.





The LDU-factorization fails on [-c, c].

