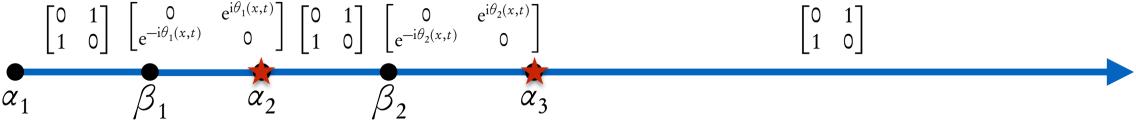
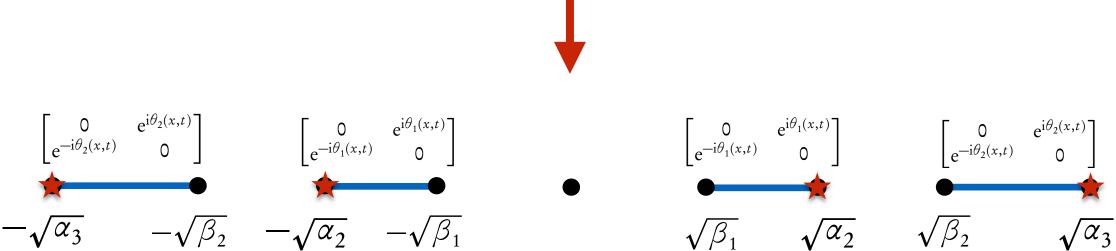


## An example

$$N(z) = \begin{cases} M(z^2) & \text{Im } z > 0, \\ M(z^2) \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} & \text{Im } z < 0. \end{cases}$$



Suppose  $\alpha_1 = 0$ 



The jump matrix J(z) is piecewise constant as a function of z.

T T and B Deconinck. A Riemann-Hilbert problem for the finite-genus solutions of the KdV equation and its numerical solution. Physica D, 251:1-18, 2013

## An example

Suppose 
$$\alpha_1 = 0$$

$$N(z) = \begin{cases} M(z^2) & \text{Im } z > 0, \\ M(z^2) \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} & \text{Im } z < 0. \end{cases}$$

$$\begin{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} e^{-i\theta_i(x,t)} & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} e^{-i\theta_i(x,t)} & e^{i\theta_i(x,t)} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \end{bmatrix}$$

$$\begin{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} & \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_i(x,t)} & 0 \end{bmatrix} \end{bmatrix} \begin{bmatrix} \begin{bmatrix} 0 & e^{i\theta_i(x,t)} \\ e^{-i\theta_$$

The jump matrix J(z) is piecewise constant as a function of z.

T T and B Deconinck. A Riemann–Hilbert problem for the finite-genus solutions of the KdV equation and its numerical solution. Physica D, 251:1–18, 2013



## A singular integral equation

We expect that

$$N(z) = \begin{bmatrix} 1 & 1 \end{bmatrix} + \frac{1}{2\pi i} \int_{\Gamma} \frac{U(z')}{z' - z} dz' = \begin{bmatrix} 1 & 1 \end{bmatrix} + \mathscr{C}_{\Gamma} U(z).$$

Owing to the Plemelj lemma, U will then satisfy

$$U(z) - \mathscr{C}_{\Gamma}^{-}U(z)(J(z) - I) = \begin{bmatrix} 1 & 1 \end{bmatrix}(J(z) - I),$$

$$\mathscr{C}_{\Gamma}^{-}U(z) := \lim_{\epsilon \downarrow 0} \mathscr{C}_{\Gamma}U(z - i\epsilon)$$

