

# 1 Generic Numeric Programming

Generic numeric programming employs templates to use the same code for different floating-point types and functions. Consider the area of a circle  $a$  of radius  $r$ , given by

$$a = \pi r^2. \quad (1)$$

The area of a circle can be computed in generic programming using Boost.Math as shown below.

---

```
#include <boost/math/constants/constants.hpp>
```

```
using boost::math::constants::pi;
```

```
template<typename T>
inline T area_of_a_circle(T r)
{
    return pi<T>() * (r * r);
}
```

---

It is possible to use `area_of_a_circle()` with built-in floating-point types as well as floating-point types from Boost.Multiprecision. In particular, consider a system with 4-byte single-precision **float**, 8-byte double-precision **double** and also the `cpp_dec_float_50` data type from Boost.Multiprecision with 50 decimal digits of precision.

We can compute and print the approximate area of a circle with radius 123/100 for **float**, **double** and `cpp_dec_float_50` with the program below.

---

```
#include <iostream>
#include <iomanip>
#include <boost/multiprecision/cpp_dec_float.hpp>

using boost::multiprecision::cpp_dec_float_50;

int main(int, char**)
{
    const float r_f(float(123) / 100);
    const float a_f = area_of_a_circle(r_f);

    const double r_d(double(123) / 100);
    const double a_d = area_of_a_circle(r_d);

    const cpp_dec_float_50 r_mp(cpp_dec_float_50(123) / 100);
    const cpp_dec_float_50 a_mp = area_of_a_circle(r_mp);

    // 4.75292
```

```

std::cout
    << std::setprecision(std::numeric_limits<float>::digits10)
    << a_f
    << std::endl;

// 4.752915525616
std::cout
    << std::setprecision(std::numeric_limits<double>::digits10)
    << a_d
    << std::endl;

// 4.7529155256159981904701331745635599135018975843146
std::cout
    << std::setprecision(std::numeric_limits<cpp_dec_float_50>::digits10)
    << a_mp
    << std::endl;
}

```

---

Let's add even more power to generic numeric programming using not only different floating-point types but also function objects as template parameters. Consider some well-known central difference rules for numerically computing the first derivative of a function  $f'(x)$  with  $x \in \mathbb{R}$ .

$$\begin{aligned}
 f'(x) &\approx m_1 + O(dx^2) \\
 f'(x) &\approx \frac{4}{3}m_1 - \frac{1}{3}m_2 + O(dx^4) \\
 f'(x) &\approx \frac{3}{2}m_1 - \frac{3}{5}m_2 + \frac{1}{10}m_3 + O(dx^6), \tag{2}
 \end{aligned}$$

where the difference terms  $m_n$  are given by

$$\begin{aligned}
 m_1 &= \frac{f(x+dx) - f(x-dx)}{2dx} \\
 m_2 &= \frac{f(x+2dx) - f(x-2dx)}{4dx} \\
 m_3 &= \frac{f(x+3dx) - f(x-3dx)}{6dx}, \tag{3}
 \end{aligned}$$

and  $dx$  is the step-size of the derivative.

The third formula in Equation 2 is a three-point central difference rule. It calculates the first derivative of  $f(x)$  to  $O(dx^6)$ , where  $dx$  is the given step-size. For example, if the step-size is 0.01 this derivative calculation has about 6 decimal digits of precision—just about right for the 7 decimal digits of single-precision **float**.

Let's make a generic template subroutine using this three-point central difference rule. In particular,

---

```

template<typename value_type,
        typename function_type>
value_type derivative(const value_type x,
                    const value_type dx,
                    function_type func)
{
    // Compute d/dx[func(*first)] using a three-point
    // central difference rule of  $O(dx^6)$ .

    const value_type dx1 = dx;
    const value_type dx2 = dx1 * 2;
    const value_type dx3 = dx1 * 3;

    const value_type m1 = ( func(x + dx1)
                          - func(x - dx1)) / 2;
    const value_type m2 = ( func(x + dx2)
                          - func(x - dx2)) / 4;
    const value_type m3 = ( func(x + dx3)
                          - func(x - dx3)) / 6;

    const value_type fifteen_m1 = 15 * m1;
    const value_type six_m2      = 6 * m2;
    const value_type ten_dx1     = 10 * dx1;

    return ((fifteen_m1 - six_m2) + m3) / ten_dx1;
}

```

---

The `derivative()` template function can be used to compute the first derivative of any function to  $O(dx^6)$ . For example, consider the first derivative of  $\sin x$  evaluated at  $x = \pi/3$ . In other words,

$$\left. \frac{d}{dx} \sin x \right|_{x=\frac{\pi}{3}} = \cos \frac{\pi}{3} = \frac{1}{2}. \quad (4)$$

The code below computes the derivative in Equation 4 for **float**, **double** and boost's multiple-precision type `cpp_dec_float_50`. The code uses the `derivative()` function in combination with a lambda expression.

---

```

#include <iostream>
#include <iomanip>
#include <boost/multiprecision/cpp_dec_float.hpp>
#include <boost/math/constants/constants.hpp>

using boost::math::constants::pi;
using boost::multiprecision::cpp_dec_float_50;

```

[illegible]

The expected value of the derivative is 0.5. This central difference rule in this example is ill-conditioned, meaning it suffers from slight loss of precision. With that in mind, the results agree with the expected value of 0.5.

A generic numerical integration template similar to the `derivative()` template is shown below.

---

```

template<typename value_type,
          typename function_type>
inline value_type integral(const value_type a,
                           const value_type b,
                           const value_type tol,
                           function_type func)
{
    unsigned n = 1U;

    value_type h = (b - a);
    value_type I = (func(a) + func(b)) * (h / 2);

    for(unsigned k = 0U; k < 8U; k++)
    {
        h /= 2;

        value_type sum(0);
        for(unsigned j = 1U; j <= n; j++)
        {
            sum += func(a + (value_type((j * 2) - 1) * h));
        }

        const value_type I0 = I;
        I = (I / 2) + (h * sum);

        const value_type ratio    = I0 / I;
        const value_type delta    = ratio - 1;
        const value_type delta_abs = ((delta < 0) ? -delta : delta);

        if((k > 1U) && (delta_abs < tol))
        {
            break;
        }

        n *= 2U;
    }

    return I;
}

```

---