In [69]: import tellurium as te
 from urllib.request import urlopen
%matplotlib inline

Roadrunner Methoden

Query an antimony model from model db's:

Load the "Repressilator". Therefore use urlopen() and the methods read().decode('utf-8').

Elowitz, M. B., & Leibler, S. (2000). A synthetic oscillatory network of transcriptional regulators. Nature, 403(6767), 335-338.

In [70]: Repressilator = urlopen('http://antimony.sourceforge.net/examples/biomodels/BIOMD0000000012.txt').read().decode('ut f-8')
 print(Repressilator)

```
// Created by libAntimony v2.8.0
model *BIOMD000000012()
    // Compartments and Species:
    compartment cell:
    substanceOnly species PX in cell, PY in cell, PZ in cell, X in cell, Y in cell;
    substanceOnly species Z in cell;
    // Assignment Rules:
    beta := tau_mRNA/tau_prot;
    alpha0 := (a0_tr*eff*tau_prot)/(ln(2)*KM);
   atpha := (a_tr*eff*tau_prot)/(tn(2)*KM);
alpha := (a_tr*eff*tau_prot)/(ln(2)*KM);
a_tr := (ps_a - ps_0)*60;
t_ave := tau_mRNA/ln(2);
   kd_mRNA := ln(2)/tau_mRNA;
kd_prot := ln(2)/tau_prot;
    k_tl := eff/t_ave;
    // Reactions:
   Reaction1: X => ; kd_mRNA*X;
Reaction2: Y => ; kd_mRNA*Y;
    Reaction3: Z => ; kd_mRNA*Z;
   Reaction1: 2 => ; kd_mmxna*z;
Reaction4: => PX; k_tl*X;
Reaction5: => PY; k_tl*Y;
Reaction6: => PZ; k_tl*Z;
Reaction7: PX => ; kd_prot*PX;
Reaction8: PY => ; kd_prot*PY;
    Reaction9: PZ => ; kd_prot*PZ;
   Reaction10: => X; a0_tr + (a_tr*KM^n)/(KM^n + PZ^n); Reaction11: => Y; a0_tr + (a_tr*KM^n)/(KM^n + PX^n); Reaction12: => Z; a0_tr + (a_tr*KM^n)/(KM^n + PY^n);
    // Species initializations:
   PX = 0;
   PY = 0;
    PZ = 0;
   X = 0;
    Y = 20/cell;
    Z = 0;
    // Compartment initializations:
    cell = 1;
    // Variable initializations:
    tau mRNA = 2;
   tau_prot = 10;
eff = 20;
    KM = 40;
    n = 2;
   ps_a = 0.5;
ps_0 = 0.0005;
    // Other declarations:
   var beta, alpha0, a0_tr, alpha, a_tr, t_ave, kd_mRNA, kd_prot, k_tl; const cell, tau_mRNA, tau_prot, eff, KM, n, ps_a, ps_0;
    // Unit definitions:
    unit volume = 1e-15 litre;
    unit substance = item;
    unit time_unit = 60 second;
   // Display Names:
volume is "cubic microns";
   substance is "item";
time_unit is "minute";
  time_unit is "minute";
PX is "LacI protein";
PY is "TetR protein";
PZ is "cI protein";
X is "LacI mRNA";
Y is "TetR mRNA";
Z is "cI mRNA";
tau_mRNA is "mRNA half life";
tatu_prot is "protein half life";
eff is "translation efficiency";
   eff is "translation efficiency";
t_ave is "average mRNA life time";
ps_a is "tps_active";
ps_0 is "tps_repr";
Reaction1 is "degradation of LacI transcripts";
Reaction2 is "degradation of TetR transcripts";
Reaction3 is "degradation of CI transcripts";
Reaction4 is "translation of LacI";
Reaction5 is "translation of TetR";
Reaction6 is "translation of CI";
Reaction7 is "degradation of CI";
   Reaction is "degradation of LacI";
Reaction8 is "degradation of TetR";
```

By loading a model you similarly generate a roadrunner object. Use loada() from tellurium.

```
In [71]: rr = te.loada(Repressilator)
```

The following section illustrates several methods of roadrunner. For example you can print a model in different formats such as antimony or SBML. For this use getAntimony() or getSBML().

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roadrunner	comn	ΔτΔ
i oaai aiiiici	COLLID	

http://localhost: 8888/nbconvert/html/roadrunner...

In [72]: print(rr.getAntimony())

```
// Created by libAntimony v2.9.4
model *BIOMD000000012()
    // Compartments and Species:
    compartment cell:
    substanceOnly species PX in cell, PY in cell, PZ in cell, X in cell, Y in cell;
    substanceOnly species Z in cell;
    // Assignment Rules:
    beta := tau_mRNA/tau_prot;
   alpha0 := a0_tr*eff*tau_prot/(ln(2)*KM);
a0_tr := ps_0*60;
alpha := a_tr*eff*tau_prot/(ln(2)*KM);
a_tr := (ps_a - ps_0)*60;
t_ave := tau_mRNA/ln(2);
   kd_mRNA := ln(2)/tau_mRNA;
kd_prot := ln(2)/tau_prot;
    k_tl := eff/t_ave;
    // Reactions:
   Reaction1: X => ; kd_mRNA*X;
Reaction2: Y => ; kd_mRNA*Y;
    Reaction3: Z => ; kd_mRNA*Z;
   Reaction1: 2 => ; kd_mmxna*z;
Reaction4: => PX; k_tl*X;
Reaction5: => PY; k_tl*Y;
Reaction6: => PZ; k_tl*Z;
Reaction7: PX => ; kd_prot*PX;
Reaction8: PY => ; kd_prot*PY;
    Reaction9: PZ => ; kd_prot*PZ;
   Reaction10: => X; a0_tr + a_tr*KM^n/(KM^n + PZ^n); Reaction11: => Y; a0_tr + a_tr*KM^n/(KM^n + PX^n); Reaction12: => Z; a0_tr + a_tr*KM^n/(KM^n + PY^n);
    // Species initializations:
   PX = 0;
   PY = 0;
    PZ = 0;
   X = 0;
    Y = 20/cell;
    Z = 0;
    // Compartment initializations:
    cell = 1;
    // Variable initializations:
    tau mRNA = 2;
   tau_prot = 10;
eff = 20;
    KM = 40;
   ps_0 = 0.0005;
   ps_a = 0.5;
    n = 2;
    // Other declarations:
   var beta, alpha0, a0_tr, alpha, a_tr, t_ave, kd_mRNA, kd_prot, k_tl; const cell, tau_mRNA, tau_prot, eff, KM, ps_0, ps_a, n;
    // Unit definitions:
    unit volume = 1e-15 litre;
    unit substance = item;
    unit time_unit = 6e1 second;
   // Display Names:
volume is "cubic microns";
   substance is "item";
time_unit is "minute";
  time_unit is "minute";
PX is "LacI protein";
PY is "TetR protein";
PZ is "cI protein";
X is "LacI mRNA";
Y is "TetR mRNA";
Z is "cI mRNA";
tau_mRNA is "mRNA half life";
tau_prot is "protein half life";
eff is "translation efficiency";
ps A is "ths repr".
   ps_0 is "tps_repr";
ps_a is "tps_active";
t_ave is "average mRNA life time";
   t_ave is "average mkNA LITE time";
Reaction1 is "degradation of LacI transcripts";
Reaction2 is "degradation of TetR transcripts";
Reaction3 is "degradation of CI transcripts";
Reaction4 is "translation of LacI";
Reaction5 is "translation of TetR";
Reaction6 is "translation of CI";
   Reaction is "degradation of LacI";
Reaction8 is "degradation of TetR";
```

```
In [2]: #print(rr.getSBML())
```

Solver Methoden

Attention: resetToOrigin() resets the model somewhat similar to to loada(). But integrator settings are not affected by this. Hence, always use te.loada() for a hard reset!

Use getIntegrator() to display the solver algorithm and solver settings.

Change the solver method from 'CVODE' to 'rk45' and print the settings again. You may notice the default parameters are solver specific. Use methods setIntegrator() and getIntegrator().

For example, use 'CVODE' and plot the model trajectories for different values for the 'relative_tolerance'-parameter.

Change the solver parameters via roadrunner.getIntegrator().setValue().

Steady-State Analysis

```
In [80]: rr = te.loada(Repressilator)
          print(rr.model.getGlobalParameterIds())
          rr.model.setGlobalParameterValues([6],[1])
          print(rr.model.getGlobalParameterValues())
          rr.reset()
          rr.simulate(0,1000,1000)
          rr.plot()
          rr.conservedMoietyAnalysis = True
          rr.model.setGlobalParameterValues([6],[1])
          print(rr.model.getGlobalParameterValues())
          print('Convergence estimator:', rr.steadyState())
          print(rr.steadyStateSelections)
          print(rr.getSteadyStateValues())
          ['tau_mRNA', 'tau_prot', 'eff', 'KM', 'ps_0', 'ps_a', 'n', '
_mRNA', 'kd_prot', 'k_tl']
[2.00000000e+00 1.00000000e+01 2.00000000e+01 4.00000000e+01
                                      'eff', 'KM', 'ps_0', 'ps_a', 'n', 'beta', 'alpha0', 'a0_tr', 'alpha', 'a_tr', 't_ave', 'kd
           5.00000000e-04 5.00000000e-01 1.00000000e+00 2.00000000e-01
           2.16404256e-01 3.00000000e-02 2.16187852e+02 2.99700000e+01
           2.88539008e+00 3.46573590e-01 6.93147181e-02 6.93147181e+00]
```

```
[2.00000000e+00 1.00000000e+01 2.00000000e+01 4.00000000e+01 5.00000000e+0 5.00000000e+01 1.00000000e+00 2.0000000e+01 2.16404256e-01 3.00000000e-02 2.16187852e+02 2.9970000e+01 2.88539008e+00 3.46573590e-01 6.93147181e-02 6.93147181e+00] Convergence estimator: 1.181171963772573e-07 ['[PX]', '[PY]', '[PZ]', '[X]', '[Y]', '[Z]'] [572.96415158 572.96415158 572.96415158 5.72964152 5.72964152
```

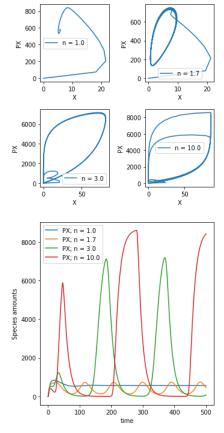
Control Analysis

Roadrunner and your model as an object in Python

From loading a model with loada() an instance of roadrunner is generated. Additionally, the roadrunner object contains a the model as a python-object. Hence, there are i) specific methods for that .model object but also the content of the model can be manipulated. Try it out!

Example - Parameterscan:

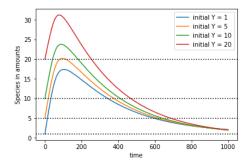
```
In [84]:
          import matplotlib.pyplot as plt
           import numpy as np
           fig_phase = plt.figure(figsize=(5,5))
          rr = te.loada(Repressilator)
for l,i in enumerate([1.0,1.7,3.0,10.]):
               fig_phase.add_subplot(2,2,l+1)
               result = rr.simulate(0,500,500,selections=['time','X','PX'])
               \verb|plt.plot(result['X'], result['PX'], label='n = \$s' \ \$i)|
               plt.xlabel('X')
plt.ylabel('PX')
plt.legend()
           plt.tight layout()
           fig_timecourse= plt.figure(figsize=(5,5))
           rr = te.loada(Repressilator)
          for l,i in enumerate([1.0,1.7,3.0,10.]):
               rr.n = i
               rr.reset()
               result = rr.simulate(0,500,500,selections=['time','X','PX'])
               plt.plot(result['time'], result['PX'], label='PX; n = %s' %i)
               plt.xlabel('time')
plt.ylabel('Species amounts')
plt.legend()
          plt.tight_layout()
```



Example - (Initial value)-scan:

```
In [87]: import matplotlib.pyplot as plt
              import numpy as np
              rr = te.loada(Repressilator)
             print(rr.model.getFloatingSpeciesInitAmountIds())
print(rr.model.getFloatingSpeciesInitAmounts())
              for l,i in enumerate([1,5,10,20]):
                    # There are many possibilites to implement this:
                    # First - wrong
                    #rr.Y=i
                    # Second - wrong
                    #rr.Y=i
                   #rr.reset()
                   # Third - correct, but there are more possibilites... rr.model["init(Y)"] \ = \ i
                    rr.reset()
                    result = rr.simulate(0,10,1000,selections=['Y','PY'])
                   #plt.plot(result[:,0], result['PY'], label='n = %s' %i)
plt.plot(result['Y'], label='initial Y = %s' %i)
plt.xlabel('time')
plt.ylabel('Species in amounts')
plt.axhline(y=i, linestyle = ':', color='black')
                    plt.legend()
```

 $['init(PX)', 'init(PY)', 'init(PZ)', 'init(X)', 'init(Y)', 'init(Z)'] \\ [\ 0. \ 0. \ 0. \ 0. \ 20. \ 0.]$



In []: