

Condition Numbers for the Cube.

I: Univariate Polynomials and Hypersurfaces

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This presentation is about the accepted paper

Condition Numbers for the Cube.

I: Univariate Polynomials and Hypersurfaces

authored by

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Complexity of numerical algorithms

Numerical algorithms

What do characterize numerical algorithms?

- Inexact input data
- Approximate operations with numbers

Which problems arise when working with numerical algorithms?

- Behaviour is not uniform
- Some inputs (*ill-posed*) are intractable

Why do we want numerical algorithms?

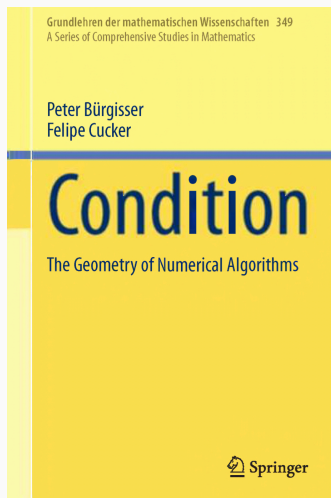
- More stable, i.e., robust with respect errors
- They can be faster in practice

ALL INPUTS ARE EQUAL
BUT SOME INPUTS ARE MORE EQUAL
THAN OTHERS

Condition number

- Measure of the numerical sensitivity
 - The bigger the worse!
 - It depends on the metric!
- Controls the complexity. This is what happens in:
 - Linear algebra
 - Linear programming and optimization
 - Algebraic geometry

Details in the Book!



...and some other papers!

Uniform complexity of numerical algorithms I

Worst-case complexity analysis:

What is the worst running time?

Average complexity analysis:

What is the expectation of the running time on a random input?

Smoothed complexity analysis: (Spielman, Teng; 2002)

What is the worst running time after perturbing the input with a random perturbation (with weight σ)?

Smoothed lies between worst-case and average complexity

- $\sigma \rightarrow 0$: We recover worst-case complexity
- $\sigma \rightarrow \infty$: We recover average analysis

Uniform complexity of numerical algorithms II

Worst-case complexity analysis:

Infinite for numerical algorithms!

Average complexity analysis: (Goldstein & von Neumann, Demmel, Smale)

It allows to derive complexity estimates that do not depend on the condition number

Smoothed complexity analysis:

Explains the success of numerical algorithms in practice

The long-term goal

Better algorithms in real numerical algebraic geometry!

Algorithms are faster and simpler on the cube,
but geometry is easier on the sphere!

Example:

Covering the cube efficiently is easy,
but covering the sphere is not so easy.

Cubes are better for subdivisions!



Geometry on the sphere	=	Euclidean norm	$\ x\ := \sqrt{\sum_i x_i ^2}$
Geometry on the cube	=	∞ -norm	$\ x\ _\infty := \max_i x_i $

Goal:

Geometry on the sphere	→	Geometry on the cube
Euclidean norm	→	∞ -norm

Warning: The ∞ -norm does not come from an inner product!

Hopes:

- Better complexity estimates
- Faster algorithms
- Better understanding of subdivision methods

Antecedent exploring other norms: (Cucker, Ergür, T.C.; SIAM AG'19)

Our local achievement

- Condition theory for hypersurfaces in the cube
- Gaussian polynomials
- Polynomials with restricted support (up to assumptions)

We showcase our results with:

- Separation bounds for roots of univariate polynomials in $(0, 1)$
- Plantinga-Vegter algorithm

Let's see some details!

Polynomial inequalities and condition

Some notation

$\mathcal{P}_{n,d}$: Polynomials of degree $\leq d$ in the variables X_1, \dots, X_n

B_n : Euclidean ball in \mathbb{R}^n

I^n : Unit ∞ -ball $([-1, 1]^n)$ in \mathbb{R}^n

$$f = \sum_{\alpha} f_{\alpha} X^{\alpha} \in \mathcal{P}_{n,d}, x \in \mathbb{R}^n$$

$\|f\|_W$: Weyl norm, given by $\sqrt{\sum_{\alpha} \binom{d}{\alpha, d-|\alpha|}^{-1/2} f_{\alpha}}$

$\|f\|_1$: 1-norm, given by $\sum_{\alpha} |f_{\alpha}|$

$f(x)$: Evaluation of f at x

∇f : Formal gradient of f , element of $\mathcal{P}_{n,d-1}^n$

$\nabla_x f$: Gradient vector of f at x

Idea: Controlling size of evaluation

Proposition

Let $f \in \mathcal{P}_{n,d}$ and $x \in B_n$. Then $|f(x)| \leq \|f\|_w \|(1, x)\|^d$.

Proof.

$$\begin{aligned} |f(x)| &= \left| \left\langle \left(\binom{d}{\alpha, d-|\alpha|}^{-1/2} f_\alpha \right), \left(\binom{d}{\alpha, d-|\alpha|}^{1/2} x_\alpha \right) \right\rangle \right| \\ &\leq \left\| \left(\binom{d}{\alpha, d-|\alpha|}^{-1/2} f_\alpha \right) \right\| \left\| \left(\binom{d}{\alpha, d-|\alpha|}^{1/2} x_\alpha \right) \right\| \\ &= \|f\|_w \sqrt{\sum_{\alpha} \binom{d}{\alpha, d-|\alpha|} x^{2\alpha}} \\ &= \|f\|_w \sqrt{(1 + \sum_i x_i^2)^d} \\ &= \|f\|_w \|(1, x)\|^d \end{aligned}$$



Idea: Controlling size of evaluation

Proposition

Let $f \in \mathcal{P}_{n,d}$, $x \in B_{q,n}$ and $p, q \geq 1$ such that $1/p + 1/q = 1$. Then

$$|f(x)| \leq \|f\|_{w,p} \|(1, x)\|_q^d.$$

Proof.

$$\begin{aligned} |f(x)| &= \left| \left\langle \left(\binom{d}{\alpha, d-|\alpha|}^{1/p-1} f_\alpha \right), \left(\binom{d}{\alpha, d-|\alpha|}^{1/q} x_\alpha \right) \right\rangle \right| \\ &\leq \left\| \left(\binom{d}{\alpha, d-|\alpha|}^{1/p-1} f_\alpha \right) \right\|_p \left\| \left(\binom{d}{\alpha, d-|\alpha|}^{1/q} x_\alpha \right) \right\|_q \\ &= \|f\|_{w,p} \sqrt[q]{\sum_{\alpha} \binom{d}{\alpha, d-|\alpha|} x^{q\alpha}} \\ &= \|f\|_{w,p} \sqrt[q]{(1 + \sum_i x_i^q)^d} \\ &= \|f\|_{w,p} \|(1, x)\|_q^d \end{aligned}$$



Idea: Controlling size of evaluation

Taking $p = 1$ and $q = \infty$...

Proposition

Let $f \in \mathcal{P}_{n,d}$, $x \in I^n$. Then $|f(x)| \leq \|f\|_1$.

This, by duality, justifies our use of the 1-norm for polynomials when we use the ∞ -norm for points.

In a similar way...

$$f \in \mathcal{P}_{n,d}, x \in I^n, v \in \mathbb{R}^n$$

- Control of the derivative I:

$$\|\langle \nabla f, v \rangle\|_1 \leq d \|f\|_1 \|v\|_\infty$$

- Control of the derivative II:

$$\|\nabla_x f\|_1 \leq d \|f\|_1$$

- Lipschitz properties for f and its derivatives

Definition

Let $f \in \mathcal{P}_{n,d}$ and $x \in I^n$, the *local condition number of f at x* is the quantity

$$C(f, x) := \frac{\|f\|_1}{\max \left\{ |f(x)|, \frac{1}{d} \|\nabla_x f\|_1 \right\}}.$$

Important observation: $C(f, x) = \infty$ iff x is a singular zero of f

Properties of the local condition number

- 1st Lipschitz property

$$f \mapsto \|f\|_1 / \mathcal{C}(f, x) \text{ is 1-Lipschitz}$$

- 2nd Lipschitz property

$$I^n \ni x \mapsto 1 / \mathcal{C}(f, x) \text{ is } d\text{-Lipschitz}$$

- Condition Number Theorem

$$\|f\|_1 / \text{dist}_1(f, \Sigma_x) \leq \mathcal{C}(f, x) \leq 2d \|f\|_1 / \text{dist}_1(f, \Sigma_x)$$

where $\Sigma_x := \{g \in \mathcal{P}_{n,d} \mid x \text{ is a singular zero of } f\}$

- Higher Derivative Estimate. If $\mathcal{C}(f, x) f(x) / \|f\|_1 < 1$, then

$$\gamma(f, x) \leq \frac{1}{2} (d-1) \sqrt{n} \mathcal{C}(f, x).$$

where $\gamma(f, x)$ is Smale's γ

All we need for complexity analyses!

Application 1: Separation of roots

Separation of roots

Recall...

$$\Delta_{\alpha}(f) := \text{dist}(\alpha, f^{-1}(0) \setminus \{\alpha\})$$

Theorem

Let $f \in \mathcal{P}_{1,d}$. Then, for every complex $\alpha \in f^{-1}(0)$ such that $\text{dist}(\alpha, I) \leq 1/(3(d-1) C(f))$,

$$\Delta_{\alpha}(f) \geq \frac{1}{16(d-1) C(f)}$$

where

$$C(f) := \sup_{x \in I} C(f, x).$$

I.e., the condition number controls the separation of the roots

Probabilistic results

Randomness model I: Two properties

- (SG) We call a random variable \mathfrak{x} *subgaussian*, if there exist a $K > 0$ such that for all $t \geq K$,

$$\mathbb{P}(|\mathfrak{x}| > t) \leq 2 \exp(-t^2/K^2).$$

The smallest such K is the *subgaussian constant* of \mathfrak{x} .

- (AC) A random variable \mathfrak{x} has the *anti-concentration property*, if there exists a $\rho > 0$, such that for all $\varepsilon > 0$,

$$\max\{\mathbb{P}(|\mathfrak{x} - u| \leq \varepsilon) \mid u \in \mathbb{R}\} \leq 2\rho\varepsilon.$$

The smallest such ρ is the *anti-concentration constant* of \mathfrak{x} .

Randomness model II: Zintzo random polynomials I

Definition

Let $M \subseteq \mathbb{N}^n$ be a finite set such that $0, e_1, \dots, e_n \in M$. A *zintzo random polynomial* supported on M is a random polynomial

$$f = \sum_{\alpha \in M} f_{\alpha} X^{\alpha} \in \mathcal{P}_{n,d}$$

such that the coefficients f_{α} are independent subgaussian random variables with the anti-concentration property.

Note: ‘zintzo’, from Basque, means honest, upright, righteous.

Observation: No scaling in the coefficients, as it happens with dobro random polynomials (Cucker, Ergür, TC; ISSAC’19)

Randomness model II: Zintzo random polynomials II

For \mathbf{f} a zintzo random polynomial, we define:

1. the *subgaussian constant* of \mathbf{f} which is given by

$$K_{\mathbf{f}} := \sum_{\alpha \in M} K_{\alpha}, \quad (5.1)$$

where K_{α} is the subgaussian constant of \mathbf{f}_{α} , and

2. the *anti-concentration constants* of \mathbf{f} which is given by

$$\rho_{\mathbf{f}} := \sqrt[n+1]{\rho_0 \rho_{e_1} \cdots \rho_{e_n}}, \quad (5.2)$$

where ρ_0 is the anti-concentration constant of \mathbf{f}_0 and for each i , ρ_{e_i} is the anti-concentration constant of \mathbf{f}_{e_i} .

$K_{\mathbf{f}}$ and $\rho_{\mathbf{f}}$ will control the complexity estimates

Randomness model II: Zintzo random polynomials III

Let $M \subseteq \mathbb{N}^n$ be such that it contains $0, e_1, \dots, e_n$. These are two important cases of zintzo random polynomials:

G A *Gaussian polynomial supported on M* is a zintzo random polynomial f supported on M , the coefficients of which are i.i.d. Gaussian random variables.

In this case, $\rho_f = 1/\sqrt{2\pi}$ and $K_f \leq |M|$.

U A *uniform random polynomial supported on M* is a zintzo random polynomial f supported on M , the coefficients of which are i.i.d. uniform random variables on $[-1, 1]$.

In this case, $\rho_f = 1/2$ and $K_f \leq |M|$.

Randomness model III: Smoothed case

Proposition

Let \mathfrak{f} be a zintzo random polynomial supported on M , $f \in \mathcal{P}_{n,d}$ a polynomial supported on M , and $\sigma > 0$. Then,

$$\mathfrak{f}_\sigma := f + \sigma \|f\|_1 \mathfrak{f}$$

is a zintzo random polynomial supported on M such that

$$K_{\mathfrak{f}_\sigma} \leq \|f\|_1 (1 + \sigma K_{\mathfrak{f}}) \text{ and } \rho_{\mathfrak{f}_\sigma} \leq \rho_{\mathfrak{f}} / (\sigma \|f\|_1).$$

In particular,

$$K_{\mathfrak{f}_\sigma} \rho_{\mathfrak{f}_\sigma} = (K_{\mathfrak{f}} + 1/\sigma) \rho_{\mathfrak{f}}.$$

I.e., the smoothed case is included in our average case!

Theorem

Let $f \in \mathcal{P}_{n,d}$ a zintzo random polynomial supported on M . Then for all $t \geq e$,

$$\mathbb{P}(C(f, x) \geq t) \leq \sqrt{nd}^n |M| (8K_f \rho_f)^{n+1} \frac{\ln^{\frac{n+1}{2}} t}{t^{n+1}}.$$

Corollary

Let $f \in \mathcal{P}_{n,d}$ be a zintzo random polynomial supported on M . Then, for all $t > 2e$,

$$\mathbb{P}(C(f) \geq t) \leq \frac{1}{4} \sqrt{nd}^{2n} |M| (64K_f \rho_f)^{n+1} \frac{\ln^{\frac{n+1}{2}} t}{t}.$$

Application 2: Plantinga-Vegter algorithm

Setting

What do we have?

- An implicit curve C inside $[-1, 1]^2$ given by a C^1 function $f: [-1, 1]^2 \rightarrow \mathbb{R}$
- Interval approximations $\square f$ of f and $\square \nabla f$ of ∇f

What do we want?

- Piecewise-linear approximation L of C in $[-1, 1]^2$ such that $([-1, 1]^2, C)$ and $([-1, 1]^2, L)$ are isotopic

Any assumptions?

- C smooth
- C Intersects the boundary of $[-1, 1]^2$ transversely

Plantinga-Vegter algorithm for curves I

Algorithm: PV Algorithm for curves (Plantinga, Vegter; 2004)

Input: $f : \mathbb{R}^2 \rightarrow \mathbb{R}$

with interval approximations $\square[f]$ and $\langle \square[\nabla f], \square[\nabla f] \rangle$

SUBDIVISION:

Starting with the trivial subdivision $\mathcal{S} := \{[-1, 1]^n\}$, repeatedly subdivide each $J \in \mathcal{S}$ into 4 squares until for all $J \in \mathcal{S}$,

$$0 \notin \square f(J) \text{ or } 0 \notin \langle \square \nabla f(J), \square \nabla f(J) \rangle$$

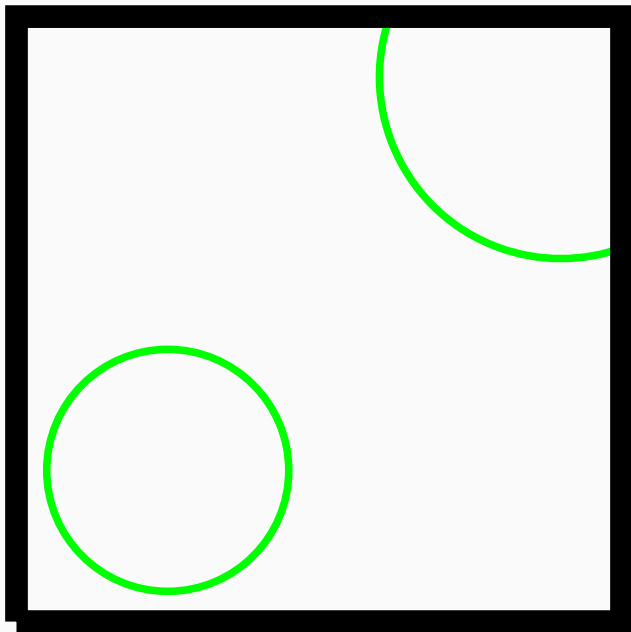
CONSTRUCTION:

Construct piecewise-linear curve L

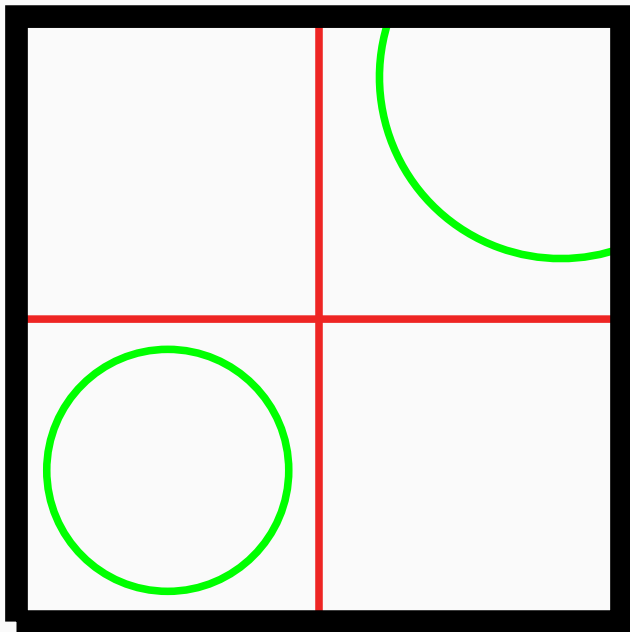
joining the midpoints of “small” edges of each $J \in \mathcal{S}$ with opposite f -signs at their vertices

Output: Piecewise-linear approximation L of $C = f^{-1}(0) \cap [-a, a]^2$ isotopic to it

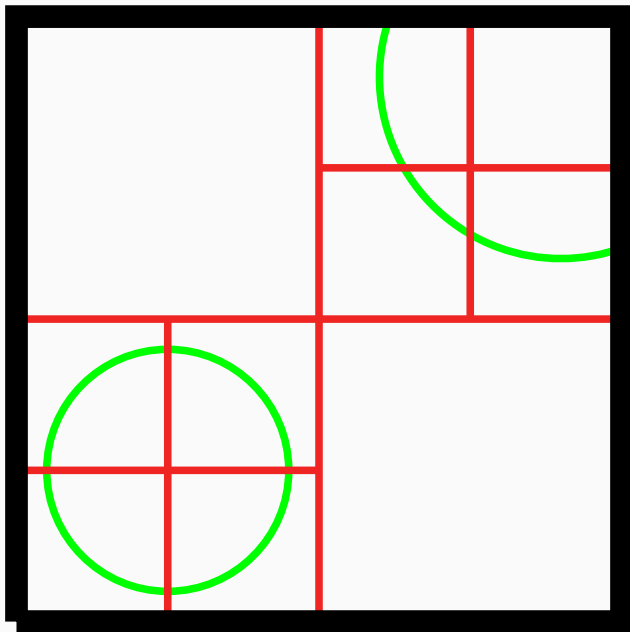
Plantinga-Vegter algorithm for curves II: Example



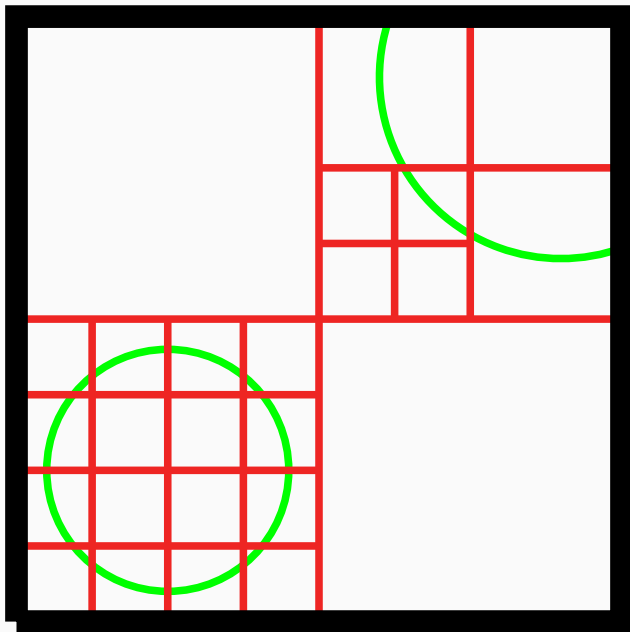
Plantinga-Vegter algorithm for curves II: Example



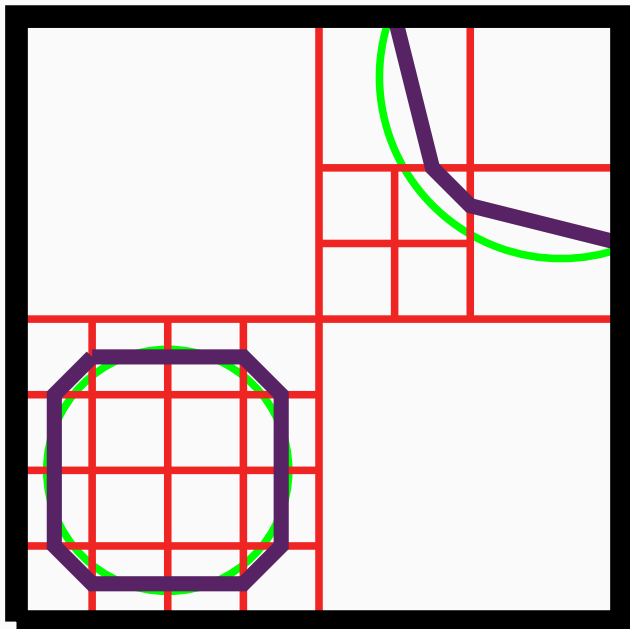
Plantinga-Vegter algorithm for curves II: Example



Plantinga-Vegter algorithm for curves II: Example



Plantinga-Vegter algorithm for curves II: Example



Plantinga-Vegter algorithm in higher dimensions

1. Plantinga-Vegter algorithm can be generalized to produce isotopic approximations of surfaces (Plantinga, Vegter; 2004)

This is really why is called Plantinga-Vegter!

Very efficient in practice

2. The subdivision method can be generalized to higher dimensions (Burr, Gao, Tsigaridas; ISSAC2017)

We will focus on the later, since...

complexity of the algorithm is mainly that of the subdivision part

We will mainly count the number of subdivisions, because...

$\text{cost}(\text{subdivision algorithm}) \sim \#(\text{subdivisions}) \cdot \text{cost}(\text{evaluations})$

Subdivision in Plantinga-Vegter algorithm

Algorithm: Subdivision of PV Algorithm (Burr, Gao, Tsigaridas; ISSAC'17)

Input: $f : \mathbb{R}^n \rightarrow \mathbb{R}$

with interval approximations $\square[hf]$ and $\square[h'\nabla f]$

for some functions $h, h' : \mathbb{R}^n \rightarrow (0, \infty)$

Starting with the trivial subdivision $\mathcal{S} := \{[-a, a]^n\}$, repeatedly subdivide each $J \in \mathcal{S}$ into 2^n cubes until the condition

$$C_f(J) : 0 \notin \square[hf](J) \text{ or } 0 \notin \langle \square[h'\nabla f], \square[h'\nabla f] \rangle$$

holds for all $J \in \mathcal{S}$

Output: Subdivision $\mathcal{S} \subseteq \mathcal{I}_n$ of $[-a, a]^n$
such that for all $J \in \mathcal{S}$, $C_f(J)$ is true

h, h' depend on the setting and the interval arithmetic one uses

The complexity estimate

We had...

Theorem (Cucker, Ergür, T.C.; ISSAC'19)

Let $f \in \mathcal{P}_{n,d}$ be a dobro random polynomial with parameters K and ρ .
The average number of boxes of the final subdivision of PV algorithm on input f is at most

$$d^{\frac{n^2+3n}{2}} 2^{\frac{n^2+16n \log(n)}{2}} (c_1 c_2 K \rho)^{n+1}.$$

We get...

Theorem (T.C., Tsigaridas; ISSAC'20)

Let $f \in \mathcal{P}_{n,d}$ be a zintzo random polynomial supported on M . The average number of boxes of the final subdivision of PV algorithm on input f is at most

$$n^{\frac{3}{2}} d^{2n} |M| \left(80 \sqrt{n(n+1)} K_f \rho_f \right)^{n+1}.$$

Corollary (T.C., Tsigaridas; ISSAC'20)

Let $f \in \mathcal{P}_{n,d}$ be a random polynomial supported on M . The average number of boxes of the final subdivision of PV algorithm on input f is at most

$$n^{\frac{3}{2}} \left(40 \sqrt{n(n+1)} \right)^{n+1} d^{2n} |M|^{n+2}$$

if f is Gaussian or uniform.

Bere arretagatik eskerrik asko!
Merci pour votre attention!

Galderak?
Des questions?