# Condition Numbers for the Cube.

# I: Univariate Polynomials and Hypersurfaces

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This presentation is about the accepted paper

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I: Univariate Polynomials and Hypersurfaces
authored by

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The long-term goal

# Grid and subdivision methods: What are they for?

#### Grid methods:

- Feasibility of real polynomial systems (Cucker & Smale; 1999)
- Approximating and counting real zeros (Cucker, Krick, Malajovich & Wschebor; 2008, 2009, 2012)
- · Homology of real algebraic sets (Cucker, Krick & Shub; 2012)
- Homology of semialgebraic sets (Bürgisser, Cucker & Lairez; 2018) (Bürgisser, Cucker & T.-C.; ISSAC'19, 2020+)

#### Subdivision methods:

- Root isolation of univariate polynomials (Pan, Davenport, Yap, Sagraloff, Mehlhorn, Rouillier, Mourrain, Yakoubsohn...) Too many to write them all!
- Root isolation of polynomial systems (Dedieu & Yakoubsohn; 1991) (Mourrain& Pavone; 2009) (Mantzaflaris, Mourrain & Tsigaridas; 2011)
- PL approximation of curves and surfaces (Plantinga & Vegter; 2004) (Galehouse; 2009) (Burr, Gao & Tsigaridas; ISSAC'17)

#### Grid and subdivision methods: What is their complexity?

#### Techniques for controlling complexity:

- Root separation bounds (Davenport, Mahler & Mignotte) (Emiris, Mourrain & Tsigaridas; ISSAC'10) → Bit-complexity bounds
- Variety separation bounds (D'Andrea, Krick & Sombra; 2013)
   (Burr, Gao & Tsigaridas; ISSAC'17) → Bit-complexity bounds
- Continuous amortization (Burr, Krahmer & Yap; 2009) (Burr; 2016)
   + Condition-based complexity + Probabilistic analysis (Cucker, Ergür & T.-C.; ISSAC'19, 2020+) → Average and smoothed complexity bounds

# Condition-based complexity

Average and smoothed complexity bounds!

MAIN ISSUE:

Condition numbers are designed for the sphere, but the algorithms work in the cube!

Example:

Covering the cube efficiently is easy, but covering the sphere is not so easy.

# Condition numbers for the cube? THAT IS OUR OBJECTIVE!



#### The plan

Geometry on the sphere 
$$=$$
 Euclidean norm  $\|x\| := \sqrt{\sum_i |x_i|^2}$   
Geometry on the cube  $=$   $\infty$ -norm  $\|x\|_{\infty} := \max_i |x_i|$ 

Goal:

Geometry on the sphere 
$$\rightarrow$$
 Geometry on the cube Euclidean norm  $\rightarrow$   $\infty$ -norm

Warning: The  $\infty$ -norm does not come from an inner product! Hopes:

- Better complexity estimates
- Faster algorithms
- · Better understanding of subdivision methods

Antecedent exploring other norms: (Cucker, Ergür & T.-C.; SIAM AG'19)

## Results of the accepted paper

- · Condition theory for hypersurfaces in the cube
- · Gaussian polynomials
- Polynomials with restricted support (up to assumptions)

#### We showcase our results with:

- Separation bounds for roots of univariate polynomials in (0,1)
- · Plantinga-Vegter algorithm

Polynomial inequalities

and condition

#### Idea

Norm for polynomials control evaluations, variations...



Condition-based complexity theory

Our choice:

$$||f||_1 := \sum_{\alpha} |f_{\alpha}|$$

the 1-norm for polynomials

Why?:  $||f||_1$  behaves live the dual of  $||x||_{\infty}$ 

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## Polynomial inequalities

$$f \in \mathcal{P}_{n,d} := \{g \in \mathbb{R}[X_1, \dots, X_n] \mid \deg g \le d\}, x, y \in I^n := [-1, 1]^n, v \in \mathbb{R}^n$$

Control of the evaluation

$$|f(x)| \le ||f||_1$$

Control of the derivative I

$$\|\langle \nabla f, v \rangle\|_1 \le d\|f\|_1 \|v\|_{\infty}$$

Control of the derivative II

$$\|\nabla_{x}f\|_{1} \leq d\|f\|_{1}$$

Lipschitz properties for f and its derivatives

$$|f(x) - f(y)| \le d||f||_1 ||x - y||_{\infty}$$
  
$$||\nabla_x f - \nabla_y f||_1 \le d(d - 1)||f||_1 ||x - y||_{\infty}$$

g

#### Local condition number

#### Definition (T.-C., Tsigaridas; ISSAC'20)

Let  $f \in \mathcal{P}_{n,d}$  and  $x \in I^n$ , the local condition number of f at x is the quantity

$$C(f,x) := \frac{\|f\|_1}{\max\{|f(x)|, \frac{1}{d}\|\nabla_x f\|_1\}}.$$

Important observation:  $C(f,x) = \infty$  iff x is a singular zero of f

## Properties of the local condition number

- Regularity inequality either  $|f(x)|/\|f\|_1 \ge 1/C(f,x)$  or  $\|\nabla_x f\|_1/(d\|f\|_1) \ge 1/C(f,x)$ .
- 1st Lipschitz property

$$f \mapsto ||f||_1 / C(f, x)$$
 is 1-Lipschitz

· 2nd Lipschitz property

$$I^n \ni x \mapsto 1/C(f,x)$$
 is d-Lipschitz

Condition Number Theorem

$$||f||_1/\mathrm{dist}_1(f,\Sigma_x) \le C(f,x) \le 2d ||f||_1/\mathrm{dist}_1(f,\Sigma_x)$$

where  $\Sigma_{x} := \{g \in \mathcal{P}_{n,d} \mid x \text{ is a singular zero of } f\}$ 

• Higher Derivative Estimate. If  $C(f,x)|f(x)|/||f||_1 < 1$ , then

$$\gamma(f,x) \leq \frac{1}{2}(d-1)\sqrt{n} C(f,x).$$

where  $\gamma(f, x)$  is Smale's  $\gamma$ 

All we need for condition-based complexity analyses!

# \_\_\_\_

Application 1:

Separation of roots

# Separation of roots

Recall...

$$\Delta_{\alpha}(f) := \operatorname{dist}(\alpha, f^{-1}(0) \setminus \{\alpha\})$$

Theorem (T.-C. & Tsigaridas; ISSAC'20) Let  $f \in \mathcal{P}_{1,d}$ . Then, for every complex  $\alpha \in f^{-1}(0)$  such that  $\operatorname{dist}(\alpha, l) \leq 1/(3(d-1)C(f))$ ,

$$\Delta_{\alpha}(f) \geq \frac{1}{16(d-1) C(f)}$$

where

$$C(f) := \sup_{x \in I} C(f, x).$$

I.e., the condition number controls the separation of the roots

# Probabilistic results

## Randomness model I: Two properties

(SG) We call a random variable  $\mathfrak x$  subgaussian, if there exist a K>0 such that for all  $t\geq K$ ,

$$\mathbb{P}(|\mathfrak{x}| > t) \le 2 \exp(-t^2/K^2).$$

The smallest such K is the subgaussian constant of  $\mathfrak{x}$ .

(AC) A random variable  $\mathfrak x$  has the anti-concentration property, if there exists a  $\rho > 0$ , such that for all  $\varepsilon > 0$ ,

$$\max\{\mathbb{P}\left(|\mathfrak{x}-u|\leq\varepsilon\right)\mid u\in\mathbb{R}\}\leq2\rho\varepsilon.$$

The smallest such  $\rho$  is the anti-concentration constant of  $\mathfrak{x}$ .

#### Randomness model II: Zintzo random polynomials I

#### Definition (T.-C. & Tsigaridas; ISSAC'20)

Let  $M \subseteq \mathbb{N}^n$  be a finite set such that  $0, e_1, \dots, e_n \in M$ . A zintzo random polynomial supported on M is a random polynomial

$$\mathfrak{f} = \sum_{\alpha \in M} \mathfrak{f}_{\alpha} X^{\alpha} \in \mathcal{P}_{n,d}$$

such that the coefficients  $\mathfrak{f}_{\alpha}$  are independent subgaussian random variables with the anti-concentration property.

Note: 'zintzo', from Basuqe, means honest, upright, righteous.

Observation: No scaling in the coefficients, as it happens with dobro random polynomials (Cucker, Ergür & T.-C.; ISSAC'19)

#### Randomness model II: Zintzo random polynomials II

For  $\mathfrak{f}$  a zintzo random polynomial, we define:

1. the subgaussian constant of f which is given by

$$K_{\mathfrak{f}} := \sum_{\alpha \in M} K_{\alpha}, \tag{4.1}$$

where  $K_{\alpha}$  is the subgaussian constant of  $\mathfrak{f}_{\alpha}$ , and

2. the anti-concentration constants of f which is given by

$$\rho_{\mathfrak{f}} := \sqrt[n+1]{\rho_0 \rho_{e_1} \cdots \rho_{e_n}}, \tag{4.2}$$

where  $\rho_0$  is the anti-concentration constant of  $\mathfrak{f}_0$  and for each i,  $\rho_{e_i}$  is the anti-concentration constant of  $\mathfrak{f}_{e_i}$ .

 $K_{\rm f}\rho_{\rm f}$  will control the complexity estimates

#### Randomness model II: Zintzo random polynomials III

Let  $M \subseteq \mathbb{N}^n$  be such that it contains  $0, e_1, \dots, e_n$ . These are two important cases of zintzo random polynomials:

- G A Gaussian polynomial supported on M is a zintzo random polynomial  $\mathfrak f$  supported on M, the coefficients of which are i.i.d. Gaussian random variables. In this case,  $\rho_{\mathfrak f}=1/\sqrt{2\pi}$  and  $K_{\mathfrak f}\leq |M|$ .
- U A uniform random polynomial supported on M is a zintzo random polynomial  $\mathfrak f$  supported on M, the coefficients of which are i.i.d. uniform random variables on [-1,1]. In this case,  $\rho_{\mathfrak f}=1/2$  and  $K_{\mathfrak f}\leq |M|$ .

#### Randomness model III: Smoothed case

#### Proposition (T.-C. & Tsigaridas; ISSAC'20)

Let  $\mathfrak f$  be a zintzo random polynomial supported on  $M, f \in \mathcal P_{n,d}$  a polynomial supported on M, and  $\sigma > 0$ . Then,

$$\mathfrak{f}_{\sigma} := f + \sigma ||f||_1 \mathfrak{f}$$

is a zintzo random polynomial supported on M such that

$$K_{\mathfrak{f}_{\sigma}} \leq ||f||_1 (1 + \sigma K_{\mathfrak{f}}) \text{ and } \rho_{\mathfrak{f}_{\sigma}} \leq \rho_{\mathfrak{f}}/(\sigma ||f||_1).$$

In particular,

$$K_{\mathfrak{f}_{\sigma}}\rho_{\mathfrak{f}_{\sigma}}=(K_{\mathfrak{f}}+1/\sigma)\rho_{\mathfrak{f}}.$$

I.e., the smoothed case is included in our average case!

#### Probabilistic bound

#### Theorem (T.-C. & Tsigaridas; ISSAC'20)

Let  $\mathfrak{f} \in \mathcal{P}_{n,d}$  a zintzo random polynomial supported on M. Then for all  $t \geq e$ ,

$$\mathbb{P}(C(\mathfrak{f},x)\geq t)\leq \sqrt{n}d^n|M|\left(8K_{\mathfrak{f}}\rho_{\mathfrak{f}}\right)^{n+1}\frac{\ln^{\frac{n+1}{2}}t}{t^{n+1}}.$$

#### Corollary (T.-C. & Tsigaridas; ISSAC'20)

Let  $\mathfrak{f} \in \mathcal{P}_{n,d}$  be a zintzo random polynomial supported on M. Then, for all t>2e,

$$\mathbb{P}(C(\mathfrak{f}) \geq t) \leq \frac{1}{4} \sqrt{n} d^{2n} |M| \left(64 K_{\mathfrak{f}} \rho_{\mathfrak{f}}\right)^{n+1} \frac{\ln^{\frac{n+1}{2}} t}{t}.$$

# Application 2: Plantinga-Vegter algorithm

# The complexity estimate

We had...

**Theorem (Cucker, Ergür & T.-C.; ISSAC'19, 2020+)** Let  $\mathfrak{f} \in \mathcal{P}_{n,d}$  be a dobro random polynomial with parameters K and  $\rho$ . The average number of boxes of the final subdivision of Plantinga-Vegter algorithm on input  $\mathfrak{f}$  is at most

$$d^n N^{\frac{n+1}{2}} 2^{15n \log n + 12} (K\rho)^{n+1}$$

where  $N := \dim \mathcal{P}_{n,d}$ .

We get...

**Theorem (T.-C. & Tsigaridas; ISSAC'20, 2020+)** Let  $\mathfrak{f} \in \mathcal{P}_{n,d}$  be a zintzo random polynomial supported on M. The average number of boxes of the final subdivision of the Plantinga-Vegter algorithm on input  $\mathfrak{f}$  is at most

$$n^2d^{2n}|M|\left(4\sqrt{n+1}\,K_{\mathfrak{f}}\rho_{\mathfrak{f}}\right)^{n+1}.$$

## An specific bound

Corollary (T.-C. & Tsigaridas; ISSAC'20, 2020+)

Let  $\mathfrak{f} \in \mathcal{P}_{n,d}$  be a random polynomial supported on M. The average number of boxes of the final subdivision of Plantinga-Vegter algorithm on input  $\mathfrak{f}$  is at most

$$n^{2} \left(2\sqrt{n+1}\right)^{n+1} d^{2n} |M|^{n+2}$$

if f is Gaussian or uniform.

# Bere arretagatik eskerrik asko! Ευχαριστω για την προσοχη σας!

Galderak? Καμιά ερώτηση?