

Chapter 2

Instructions: Language of the Computer

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HW#1 & Project #1

- Programming merge sort in MIPS assembly
- Due on Sept. 28 (Fri.)
- Project#1 posted

Synchronization

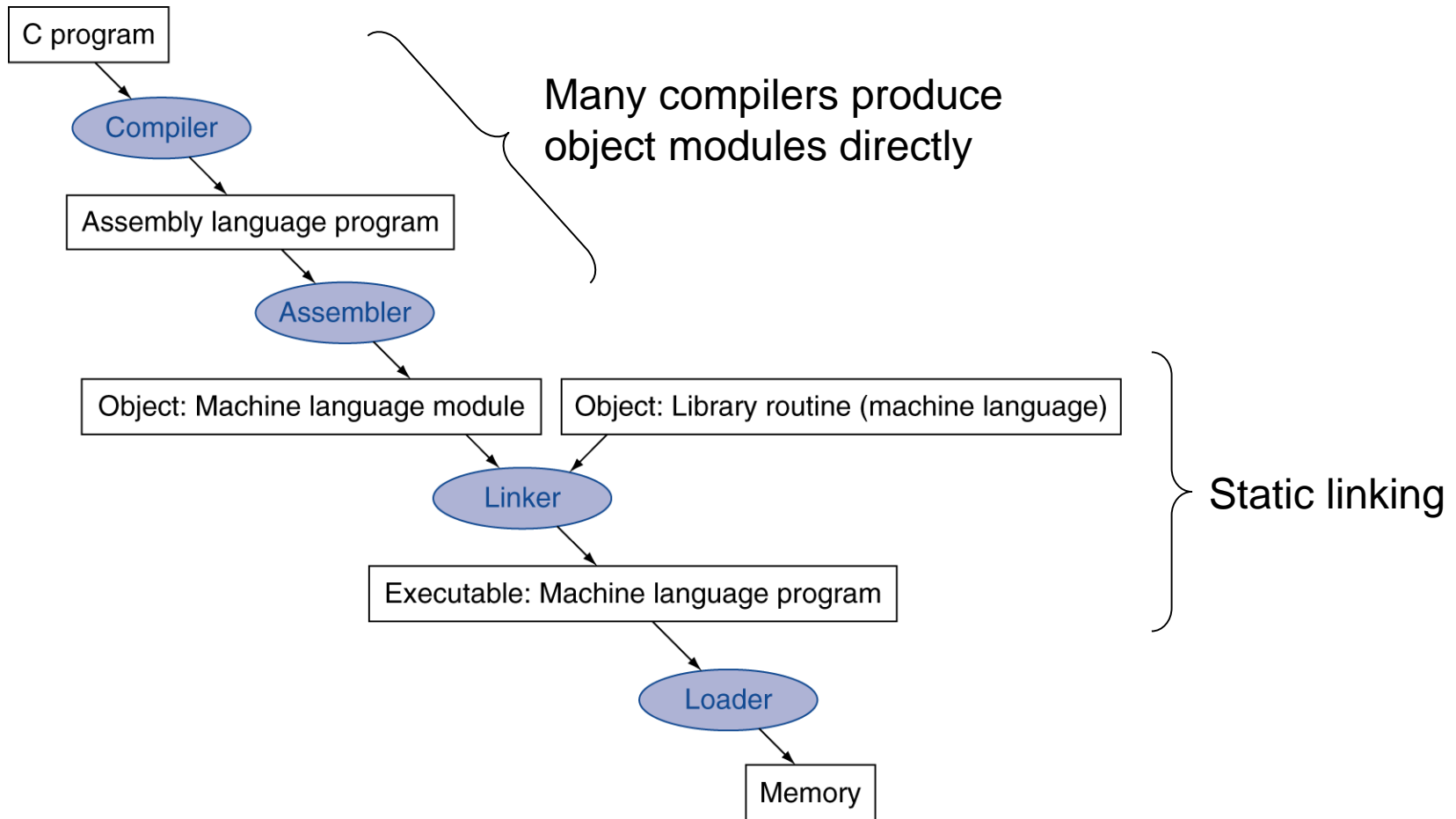
- Two processors sharing an area of memory
 - P1 writes, then P2 reads same location for cooperation
 - Data race if P1 and P2 don't synchronize
 - Result depends on order of accesses
- Hardware support required for lock/unlock
 - Atomic read/write memory operation
 - No other access to the location allowed between the read and write
 - Atomic exchange or swap
 - E.g., atomic swap of register \leftrightarrow memory
 - Or an atomic pair of instructions

Synchronization in MIPS

- Load linked: `ll rt, offset(rs)`
- Store conditional: `sc rt, offset(rs)`
 - Succeeds if location not changed since the `ll`
 - Returns 1 in `rt`
 - Fails if location is changed
 - Returns 0 in `rt`
- Example: atomic swap (to test/set lock variable)

```
try: add $t0,$zero,$s4 ;copy exchange value
      ll $t1,0($s1)      ;load linked
      sc $t0,0($s1)      ;store conditional
      beq $t0,$zero,try ;branch store fails
      add $s4,$zero,$t1 ;put load value in $s4
```

Translation and Startup



Assembler Pseudoinstructions

- Most assembler instructions represent machine instructions one-to-one
- Pseudoinstructions: figments of the assembler's imagination

`move $t0, $t1` \rightarrow `add $t0, $zero, $t1`

`blt $t0, $t1, L` \rightarrow `slt $at, $t0, $t1`
 `bne $at, $zero, L`

- `$at` (register 1): assembler temporary

Producing an Object Module

- Assembler (or compiler) translates program into machine instructions
- Object file provides information for building a complete program from the pieces
 - Header: describes contents of object module
 - Text segment: translated instructions
 - Static data segment: data allocated for the life of the program
 - Relocation info: for contents that depend on absolute location of loaded program
 - Symbol table: global definitions and external refs
 - Debug info: for associating with source code

Linking Object Modules

- Produces an executable image
 1. Merges segments
 2. Resolve labels (determine their addresses)
 3. Patch location-dependent and external refs

Loading a Program

- Load from image file on disk into memory
 1. Read header to determine segment sizes
 2. Create virtual address space
 3. Copy text and initialized data into memory
 4. Set up arguments on stack
 5. Initialize registers (including `$sp`, `$fp`, `$gp`)
 6. Jump to startup routine
 - Copies arguments to `$a0`, ... and calls `main`
 - When `main` returns, do `exit` syscall

Dynamic Linking

- Only link/load library procedure when it is called
 - Requires procedure code to be relocatable
 - Avoids image bloat caused by static linking of all (transitively) referenced libraries
 - Automatically picks up new library versions

C Sort Example

- Illustrates use of assembly instructions for a C bubble sort function
- Swap procedure (leaf)

```
void swap(int v[], int k)
{
    int temp;
    temp = v[k];
    v[k] = v[k+1];
    v[k+1] = temp;
}
```

- v in \$a0, k in \$a1, temp in \$t0

The Procedure Swap

swap: sll \$t1, \$a1, 2	# \$t1 = k * 4
add \$t1, \$a0, \$t1	# \$t1 = v+(k*4)
	# (address of v[k])
lw \$t0, 0(\$t1)	# \$t0 (temp) = v[k]
lw \$t2, 4(\$t1)	# \$t2 = v[k+1]
sw \$t2, 0(\$t1)	# v[k] = \$t2 (v[k+1])
sw \$t0, 4(\$t1)	# v[k+1] = \$t0 (temp)
jr \$ra	# return to calling routine

The Sort Procedure in C

- Non-leaf (calls swap)

```
void sort (int v[], int n)
{
    int i, j;
    for (i = 0; i < n; i += 1) {
        for (j = i - 1;
             j >= 0 && v[j] > v[j + 1];
             j -= 1) {
            swap(v, j);
        }
    }
}
```

- v in \$a0, n in \$a1, i in \$s0, j in \$s1

The Full Procedure

sort:	addi \$sp,\$sp, -20	# make room on stack for 5 registers
	sw \$ra, 16(\$sp)	# save \$ra on stack
	sw \$s3,12(\$sp)	# save \$s3 on stack
	sw \$s2, 8(\$sp)	# save \$s2 on stack
	sw \$s1, 4(\$sp)	# save \$s1 on stack
	sw \$s0, 0(\$sp)	# save \$s0 on stack
...		# procedure body
...		
exit1:	lw \$s0, 0(\$sp)	# restore \$s0 from stack
	lw \$s1, 4(\$sp)	# restore \$s1 from stack
	lw \$s2, 8(\$sp)	# restore \$s2 from stack
	lw \$s3,12(\$sp)	# restore \$s3 from stack
	lw \$ra,16(\$sp)	# restore \$ra from stack
	addi \$sp,\$sp, 20	# restore stack pointer
	jr \$ra	# return to calling routine

The Procedure Body

	move \$s2, \$a0	# save \$a0 into \$s2	Move params
	move \$s3, \$a1	# save \$a1 into \$s3	
	move \$s0, \$zero	# i = 0	Outer loop
for1tst:	slt \$t0, \$s0, \$s3	# \$t0 = 0 if \$s0 ≥ \$s3 (i ≥ n)	
	beq \$t0, \$zero, exit1	# go to exit1 if \$s0 ≥ \$s3 (i ≥ n)	Inner loop
	addi \$s1, \$s0, -1	# j = i - 1	
for2tst:	slti \$t0, \$s1, 0	# \$t0 = 1 if \$s1 < 0 (j < 0)	
	bne \$t0, \$zero, exit2	# go to exit2 if \$s1 < 0 (j < 0)	
	sll \$t1, \$s1, 2	# \$t1 = j * 4	
	add \$t2, \$s2, \$t1	# \$t2 = v + (j * 4)	
	lw \$t3, 0(\$t2)	# \$t3 = v[j]	
	lw \$t4, 4(\$t2)	# \$t4 = v[j + 1]	
	slt \$t0, \$t4, \$t3	# \$t0 = 0 if \$t4 ≥ \$t3	Pass params & call
	beq \$t0, \$zero, exit2	# go to exit2 if \$t4 ≥ \$t3	
	move \$a0, \$s2	# 1st param of swap is v (old \$a0)	
	move \$a1, \$s1	# 2nd param of swap is j	Inner loop
	jal swap	# call swap procedure	
	addi \$s1, \$s1, -1	# j -= 1	Outer loop
	j for2tst	# jump to test of inner loop	
exit2:	addi \$s0, \$s0, 1	# i += 1	Outer loop
	j for1tst	# jump to test of outer loop	

Arrays vs. Pointers

- Array indexing involves
 - Multiplying index by element size
 - Adding to array base address
- Pointers correspond directly to memory addresses
 - Can avoid indexing complexity

Example: Clearing and Array

```
clear1(int array[], int size) {  
    int i;  
    for (i = 0; i < size; i += 1)  
        array[i] = 0;  
}
```

```
        move $t0,$zero    # i = 0  
loop1:  sll $t1,$t0,2      # $t1 = i * 4  
        add $t2,$a0,$t1   # $t2 =  
                                # &array[i]  
        sw $zero, 0($t2)  # array[i] = 0  
        addi $t0,$t0,1    # i = i + 1  
        slt $t3,$t0,$a1   # $t3 =  
                                # (i < size)  
        bne $t3,$zero,loop1 # if (...)  
                                # goto loop1
```

```
clear2(int *array, int size) {  
    int *p;  
    for (p = &array[0]; p < &array[size];  
        p = p + 1)  
        *p = 0;  
}
```

```
        move $t0,$a0      # p = & array[0]  
        sll $t1,$a1,2      # $t1 = size * 4  
        add $t2,$a0,$t1    # $t2 =  
                                # &array[size]  
loop2:  sw $zero,0($t0)    # Memory[p] = 0  
        addi $t0,$t0,4     # p = p + 4  
        slt $t3,$t0,$t2    # $t3 =  
                                # (p<&array[size])  
        bne $t3,$zero,loop2 # if (...)  
                                # goto loop2
```

Comparison of Array vs. Ptr

- Multiply “strength reduced” to shift
- Array version requires shift to be inside loop
 - Part of index calculation for incremented i
 - c.f. incrementing pointer
- Compiler can achieve same effect as manual use of pointers
 - Induction variable elimination
 - Better to make program clearer

ARM & MIPS Similarities

- ARM: the most popular embedded core
- Similar basic set of instructions to MIPS

	ARM	MIPS
Date announced	1985	1985
Instruction size	32 bits	32 bits
Address space	32-bit flat	32-bit flat
Data alignment	Aligned	Aligned
Data addressing modes	9	3
Registers	15 × 32-bit	31 × 32-bit
Input/output	Memory mapped	Memory mapped

Compare and Branch in ARM

- Uses condition codes for result of an arithmetic/logical instruction
 - Negative, zero, carry, overflow
 - Compare instructions set condition codes without keeping the result
- Each instruction can be conditional
 - Top 4 bits of instruction word: condition value
 - Can avoid branches over single instructions

ARM v8 Instructions

- In moving to 64-bit, ARM did a complete overhaul
- ARM v8 resembles MIPS
 - Changes from v7:
 - No conditional execution field
 - Immediate field is 12-bit constant
 - Dropped load/store multiple instructions
 - PC is no longer a GPR
 - GPR set expanded to 32 —
 - Addressing modes work for all word sizes
 - Divide instruction included
 - Branch if equal/branch if not equal instructions added