

## Review-2 and Practice problems

## 1. Introduction.

$$y' = f(x, y)$$

**Constant solutions** Solve  $f(x, y) = 0$

**Increasing region** Solve  $f(x, y) > 0$

**Decreasing region** Solve  $f(x, y) < 0$

**Euler's Method**

$$\begin{cases} y' = f(x, y) \\ y(a) = y_0 \end{cases}$$

To estimate solution at  $b$ , set  $a = x_0 < x_1 < \cdots < x_n = b$ , where  $x_{i+1} - x_i = \Delta x = (b - a)/n$ ,

$$\begin{cases} x_{i+1} = x_i + \Delta x \\ y_{i+1} = y_i + f(x_i, y_i)\Delta x \end{cases}$$

then  $y_n$  is the approximation of  $y(b)$ .

## 2. Separable DE.

$$\frac{dy}{dx} = \frac{f(x)}{g(y)}$$

$$g(y)dy = f(x)dx$$

$$\int g(y)dy = \int f(x)dx$$

## 3. Applications of separable DE.

**Tank's problem:** Rate of change = Rate in – Rate out.

**Exponential Grow/Decay Model:**

$P$ : population;  $t$ : time;  $k$ : relative growth rate.

$$\begin{cases} P' = kP \\ P(0) = P_0 \end{cases} \rightarrow P(t) = P_0 e^{kt}$$

**Compound interest:**

$P$ : initial investment;  $t$ : time;  $r$ : annual interest rate;  $n$ : the interest is compounded  $n$  times per year.

Regular compound interest:  $A = P \left(1 + \frac{r}{n}\right)^{nt}$

Continuous compounded interest:  $A = Pe^{rt}$

**Newton's Law of heating and cooling:**

$T$ : the temperature of the object;  $t$ : time;  $k$ : positive constant;  $T_m$ : the temperature of surrounding environment.

$$\begin{cases} T' = k(T_m - T) \\ T(0) = T_0 \end{cases}$$

**Logistic Model:**

$P$ : population;  $t$ : time;  $r$ : relative growth rate;  $K$ : maximum supportable population.

$$\begin{cases} P' = rP \left(1 - \frac{P}{K}\right) \\ P(0) = P_0 \end{cases} \rightarrow P(t) = \frac{KP_0}{P_0 + (K - P_0)e^{-rt}}$$

## 4. Second order linear homogeneous DE

$$ay'' + by' + cy = 0$$

**Characteristic Equation:**  $ar^2 + br + c = 0 \rightarrow r_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$

**Case-1**  $b^2 - 4ac > 0$ ,  $r_1 \neq r_2$ :

$$\rightarrow y(x) = C_1 e^{r_1 x} + C_2 e^{r_2 x}$$

**Case-2**  $b^2 - 4ac = 0$ ,  $r_1 = r_2 = r$ :

$$\rightarrow y(x) = C_1 e^{rx} + C_2 x e^{rx}$$

**Case-3**  $b^2 - 4ac < 0$ ,  $r_{1,2} = \alpha \pm \beta i$ :

$$\rightarrow y(x) = e^{\alpha x} \left( C_1 \cos(\beta x) + C_2 \sin(\beta x) \right)$$

## 5. Second order linear non-homogeneous DE

$$ay'' + by' + cy = F(x)$$

**Step-1:** Solve  $ay'' + by' + cy = 0 \rightarrow y_c(x)$

**Step-2:** Find 1 particular solution of  $ay'' + by' + cy = F(x) \rightarrow y_p$

$$F(x) \text{ is a polynomial, ex. } 3x^2 + x + 1 \rightarrow y_p = Ax^2 + BX + C$$

$$F(x) \text{ is a Exp. function, ex. } 10e^{2x} \rightarrow y_p = Ae^{2x}$$

$$F(x) \text{ is a Trig. function, ex. } \sin(3x) \rightarrow y_p = A \sin(3x) + B \cos(3x)$$

$$F(x) \text{ is a polynomial} \times \text{Exp., ex. } x^2 e^{4x} \rightarrow y_p = (Ax^2 + Bx + C)e^{4x}$$

$$F(x) \text{ is } F_1(x) + F_2(x), \text{ ex. } xe^x + \sin(x) \rightarrow y_p = y_{p1} + y_{p2}$$

$$F_1(x) = xe^x \rightarrow y_{p1} = (Ax + B)e^x$$

$$F_2(x) = \sin(x) \rightarrow y_{p2} = A \sin(x) + B \cos(x)$$

**Remark:** If  $F(x)$  is part of  $y_c$ , then the  $y_p$  need to be multiplied by  $x$ . If  $xy_p$  is still part of  $y_c$ , then use  $x^2 y_p$ .

**Step-3:** General solution  $y(x) = y_c(x) + y_p(x)$

## 6. Applications of Second order linear DE.

**Eclectic circuit**

$E$ : Electromotive force;  $R$ : Resistance;  $L$ : Inductor;  $C$ : Capacitor;  $Q(t)$ , the charge in the capacitor at time  $t$ ;  $I(t)$ : the current at time  $t$ ,  $I(t) = Q'(t)$ .

$$LQ'' + RQ' + \frac{1}{C}Q = E$$

**Oscillate spring**

$k$ : Spring constant;  $m$ : the mass of the object;  $x(t)$ : location of the object (when the

spring is of its natural length, the object is at origin.);  $c$  Damping constant;  $F_e$  is the external force.

**Without damping:**

$$mx'' + kx = 0 \rightarrow x(t) = C_1 \cos(\omega t) + C_2 \sin(\omega t) = A \sin(\omega t + \phi)$$

where  $\omega = \sqrt{\frac{k}{m}}$  is the angular frequency,  $A = \sqrt{C_1^2 + C_2^2}$  is the amplitude and  $\phi = \arcsin\left(\frac{C_1}{A}\right)$  is the phase angle.

**With damping:**  $t \rightarrow +\infty, \quad x(t) \rightarrow 0$

$$mx'' + cx' + kx = 0 \rightarrow r_{1,2} = \frac{-c \pm \sqrt{c^2 - 4mk}}{2m}$$

$c^2 - 4mk > 0 \rightarrow$  over-damping;

$c^2 - 4mk = 0 \rightarrow$  critical-damping;

$c^2 - 4mk < 0 \rightarrow$  under-damping;

**With damping and external force:**  $t \rightarrow +\infty, \quad x(t) \rightarrow x_p(t)$

$$mx'' + cx' + kx = F_e \rightarrow x(t) = x_c(t) + x_p(t)$$