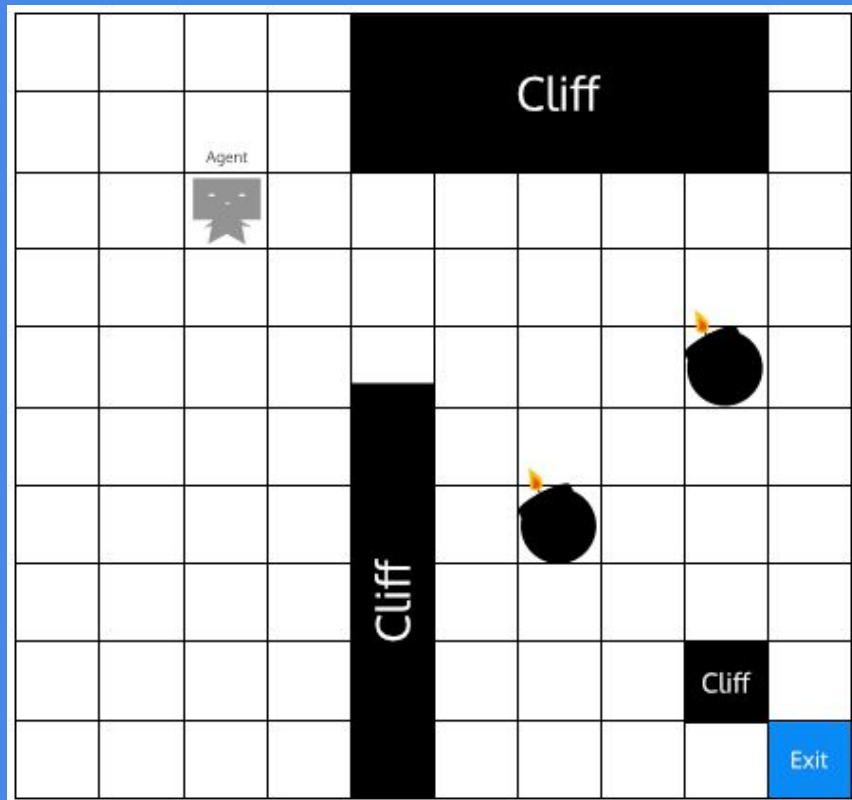


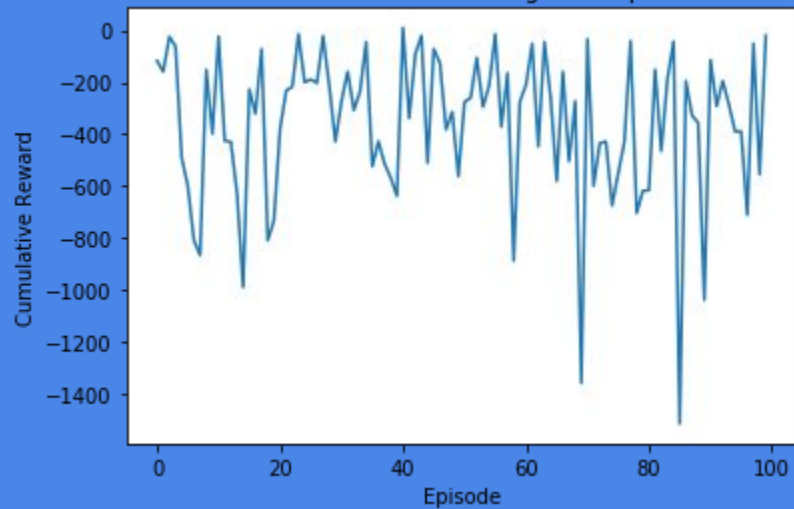
# Practice Reinforcement learning



Dumb Agent -> random walk

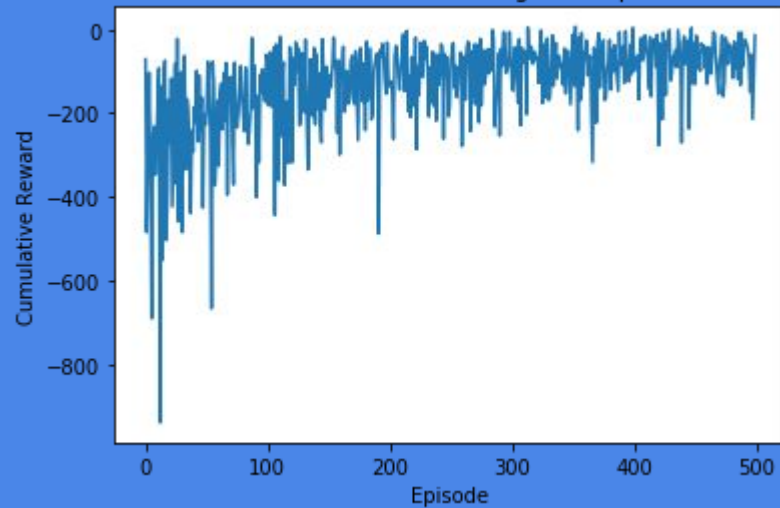
Q-Agent -> generate Q-table to keep  $Q(S,A)$

The Sum of Reward During Each Episode



Dumb Agent

The Sum of Reward During Each Episode



Q-Agent