



command_interfaces
effector_joint/position
finger_left_joint/position
finger_right_joint/position
fore_arm_joint/position
middle_arm_joint/position
shoulder_joint/position
upper_arm_joint/position

state_interfaces
effector_joint/acceleration
effector_joint/position
effector_joint/velocity
finger_left_joint/acceleration
finger_left_joint/position
finger_left_joint/velocity
finger_right_joint/acceleration
finger_right_joint/position
finger_right_joint/velocity
fore_arm_joint/acceleration
fore_arm_joint/position
fore_arm_joint/velocity
middle_arm_joint/acceleration
middle_arm_joint/position
middle_arm_joint/velocity
shoulder_joint/acceleration
shoulder_joint/position
shoulder_joint/velocity
upper_arm_joint/acceleration
upper_arm_joint/position
upper_arm_joint/velocity

joint_state_broadcaster
effector_joint/acceleration
effector_joint/position
effector_joint/velocity
finger_left_joint/acceleration
finger_left_joint/position
finger_left_joint/velocity
finger_right_joint/acceleration
finger_right_joint/position
finger_right_joint/velocity
fore_arm_joint/acceleration
fore_arm_joint/position
fore_arm_joint/velocity
middle_arm_joint/acceleration
middle_arm_joint/position
middle_arm_joint/velocity
shoulder_joint/acceleration
shoulder_joint/position
shoulder_joint/velocity
upper_arm_joint/acceleration
upper_arm_joint/position
upper_arm_joint/velocity

joint_trajectory_position_controller
middle_arm_joint/position
middle_arm_joint/velocity
shoulder_joint/position
shoulder_joint/velocity
upper_arm_joint/position
upper_arm_joint/velocity