# **ALGEBRA AND FUNCTIONS**

#### **Partial fractions:**

Methods for dealing with degree of numerator ≥ degree of denominator

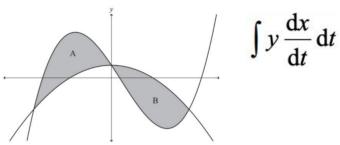
E.g. Partial fractions of the form
$$A \quad B \quad C \quad A \quad B \quad C \quad A \quad B \quad C$$

# $\frac{2x+3}{x(x-1)(2x+1)} \equiv \frac{A}{x} + \frac{B}{x-1} + \frac{C}{2x+1} \text{ and } \frac{5-x}{(x+2)(x-3)^2} \equiv \frac{A}{x+2} + \frac{B}{x-3} + \frac{C}{(x-3)^2}$

# **COORDINATE GEOMETRY**

Changing equations of curves between Cartesian and parametric form

# Finding area under curve:



# **SEQUENCES AND SERIES**

Expansion of (ax + b) n for any rational n and for  $|x| < \underline{b}$ , using:

$$(1+x)^{n} = 1 + nx + {n \choose 2}x^{2} + \dots + {n \choose r}x^{r} + \dots + x^{n} = 1 + nx + \frac{n(n-1)}{2!}x^{2} + \frac{n(n-1)(n-2)}{3!} + \dots + x^{n}$$

where 
$${}^{n}C_{r} = \frac{n!}{r!(n-r)!}$$

## **DIFFERENTIATION**

- Implicit and parametric differentiation including applications to tangents and normals
- Exponential growth and decay

$$\frac{\mathrm{d}(a^x)}{\mathrm{d}x} = a^x \ln a$$

• Formation of differential equations

# **INTEGRATION**

- Integration by substitution
- Integration by parts
- Integration of other trig functions can be found in formula book
- Volume: Use  $\int \pi y^2$  when rotating about x-axis

$$\int e^{x} dx = e^{x} + c \qquad \int e^{kx} dx = \frac{1}{k} e^{kx} + c$$

$$\int \frac{1}{x} dx = \ln|x| + c \qquad \int \frac{1}{ax} dx = \int \frac{1}{a} \cdot \frac{1}{x} dx = \frac{1}{a} \ln|x| + c_{1} \quad \text{or} \quad \int \frac{1}{ax} dx = \frac{1}{a} \ln|ax| + c_{2}$$

$$\int \cos kx dx = \frac{1}{k} \sin kx + c \qquad \int \sin kx dx = -\frac{1}{k} \cos kx + c \qquad \int \sec^{2}kx dx = \frac{1}{k} \tan kx + c$$

Use of 
$$\int \frac{f'(x)}{f(x)} dx = \ln |f(x)| + c$$
 and  $\int f'(x) [f(x)]^n dx = \frac{[f(x)]^{n+1}}{n+1} + c$ 

• Use of partial fractions in integration

Differential equations: first order separate variables

e.g. 
$$f(x)g(y)\frac{dy}{dx} = h(x)k(y)$$
  $\Rightarrow \int \frac{g(y)}{k(y)} dy = \int \frac{h(x)}{f(x)} dx$ 

Trapezium rule (expanded)

$$\int_{a}^{b} f(x) dx \approx \frac{1}{2} h[y_0 + y_n + 2(y_1 + ... + y_{n-1})] \quad \text{where } y_i = f(a + ih) \quad \text{and} \quad h = \frac{b - a}{n}$$

## **VECTORS**

If 
$$\mathbf{a} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$$
,  $|\mathbf{a}| = \sqrt{(x^2 + y^2 + z^2)}$ 

If  $\mathbf{a} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$ , the unit vector in the direction of  $\mathbf{a}$  is  $[(x\mathbf{i} + y\mathbf{j} + z\mathbf{k}) \div \sqrt{(x^2 + y^2 + z^2)}]$ 

### Scalar product

If 
$$\mathbf{OP} = \mathbf{p} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$$
 and  $\mathbf{OQ} = \mathbf{q} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$  and  $\angle POQ = \theta$ , then

$$\mathbf{p.q} = |\mathbf{p}||\mathbf{q}|\cos\theta$$
 and  $\mathbf{p.q} = (x\mathbf{i} + y\mathbf{j} + z\mathbf{k}) \cdot (a\mathbf{i} + b\mathbf{j} + c\mathbf{k}) = xa + by + cz$ 

If OP and OQ are perpendicular,  $\mathbf{p.q} = 0$ 

Vector equation of line where **a** is the position vector of a point on the line and **m** is a vector parallel to the line:

 $r = a + \lambda m$ 

Vector equation of line where **a** and **b** are the position vectors of points on the line:

$$r = a + \lambda(b - a)$$