Location Agnostic Adaptive Rain Precipitation Prediction using Deep Learning

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Abstract—Rain precipitation prediction is a challenging task as it depends on weather and meteorological features which vary from location to location. As a result, a prediction model that performs well at one location does not perform well at other locations due to the distribution shifts. In addition, due to global warming, the weather patterns are changing very rapidly year by year which creates the possibility of ineffectiveness of those models even at the same location as time passes. In our work, we have proposed an adaptive deep learning-based framework in order to provide a solution to the aforementioned challenges. Our method can generalize the model for the prediction of precipitation for any location where the methods without adaptation fail. Our method has shown 43.51%, 5.09%, and 38.62% improvement after adaptation using a deep neural network for predicting the precipitation of Paris, Los Angeles, and Tokyo, respectively.

Index Terms—weather, precipitation, deep learning, domain adaptation

I. INTRODUCTION

Weather forecasting [1] plays an essential role in numerous applications related to hydrology such as flood control [2], reduction of impact from disaster [3] from climate change, and so on. Accurate prediction of rain precipitation is very important for planning and decision-making to minimize loss from any potential occurrence of a disaster. However, predicting accurate rain precipitation is an arduous task due to the complex nature of weather features and the sparsity of weather data across different locations [4].

The accessibility of meteorological and climate data gathered from a variety of sensors [5] and weather stations [6] has significantly increased due to new developments in data collection technologies. The possibility to increase the precision of rain precipitation forecast over time is made possible by this enormous volume of data. However, the availability and distribution of meteorological data vary greatly among geologically unique locations, making it challenging to create prediction models that can successfully generalize across various kinds of regions. Moreover, the recent climate change pattern has had a great impact on precipitation as global warming and rainfall are deeply inter wined.

Furthermore, global warming can cause shifts in precipitation patterns, both in terms of spatial distribution and seasonal timing. While some regions may experience increased rainfall, others may be subject to frequent droughts[7].

Recently, deep learning-based approaches have been very useful tools in multi-modal learning [8], [9], optimization [10]–[12], domain generalization [13]. Hence being inspired by [14]–[16], a potential solution to the challenges of precipitation prediction that are posed by diverse weather patterns in various regions can be data-driven generalization also known as domain adaptation [17]. Through the use of domain adaptation techniques [18], models trained on one source domain can be adapted to perform successfully in a target domain where a significant domain shift is evident. Domain adaptation increases prediction accuracy by transferring important insights to the target domain where the pre-trained model of the source fails

The application of domain adaptation in the context of rain precipitation prediction is a relatively new research area. Most existing studies in rain precipitation prediction have focused on specific locations or regions, neglecting the cross-domain differences in weather patterns. This limitation calls for the development of generalized adaptive rain precipitation prediction models that can effectively adapt to varying weather patterns without being limited to specific locations.

In this paper, we propose a novel deep learning-based precipitation prediction approach that can adapt to changes in weather features such as temperature, wind flow, humidity, and so on. Our approach aims to overcome the limitations of traditional prediction models that solely rely on target domain data by leveraging the knowledge and insights gained from various source domains. By adapting the prediction models to the target domain, we aim to improve the accuracy of rain precipitation prediction for diverse locations with different weather patterns.

The contributions of this study include the development of a domain adaptation framework specifically tailored for rain precipitation prediction and the exploration of locationagnostic adaptive models that can adapt to varying weather patterns. We conduct extensive experiments and evaluations

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to demonstrate the effectiveness of our proposed approach and compare it with alternative methods.

The remainder of this paper is organized as follows. Section II provides a comprehensive review of the related literature, discussing previous studies on rain precipitation prediction and domain adaptation. Section III presents the methodology and framework of our proposed location-agnostic adaptive rain precipitation prediction approach. In Section IV, we present the dataset, experimental setup, and results of our experiments. Finally, Section V concludes the paper, highlighting the key findings and suggesting future research directions.

II. RELATED WORKS

Several studies have focused on the development of techniques for adaptive rain precipitation prediction. These works take into account the issues posed by changing climates and the necessity for accurate forecasting in a variety of applications. This section provides an overview of relevant research that has explored different approaches to tackle these challenges.

Numerous research has been conducted to examine the effectiveness of various AI algorithms for rainfall prediction in specific areas. Pham et al.[19] investigated ANFIS, ANN, and SVM models for forecasting daily precipitation in Vietnam's Hoa Binh region, and reported that SVM produced the best forecasts across the models tested. Diez-Sierra and Jesus [20] evaluated K-means clustering, K-nearest neighbors (K-NN), SVM, random-forest (RF), and NN for long-term forecasts of rainfall on the Spanish island of Tenerife, concluding that neural network models outperformed SVM, indicating their potential for adaptive rain precipitation prediction. Tang et al. [21] recently suggested a data augmentation strategy for expanding precipitation series data that is based on the Kmeans clustering algorithm and the synthetic minority oversampling technique (SMOTE). They assessed the performance of shallow ML models (RF, extreme gradient boosting) and deep learning models (recurrent neural network, long shortterm memory) before and after the expansion of precipitation data from the Danjiangkou River Basin in China. Their findings indicated that data augmentation has the potential to improve the accuracy of medium- and long-term precipitation prediction.

Recent studies have investigated the use of hybrid models to predict precipitation. For example, Xiang et al. [22] suggested a hybrid model for short and long-term precipitation prediction in Bangladesh's northern region using support vector regression (SVR) and artificial neural network (ANN). In their work, they used an ensemble empirical mode decomposition (EEMD) [23] for early data decomposition. Di Nunno et al. [24] proposed a model for precipitation forecasting that incorporates M5P and SVR. Their hybrid model exhibited superior performance with high R^2 values, suggesting its efficacy in predicting precipitation. Danandeh Mehr et al. [25] examined monthly precipitation prediction in a semiarid region by integrating SVR with the Fire-Fly algorithm. The

hybrid model was compared with SVR and multigene genetic programming (MGGP) algorithms. The results showed that the hybrid SVR-FFA model outperformed the standalone SVR, while the MGGP approach exceeded it. Utilizing preprocessing techniques such as discrete-wavelet-transform and seasonal decomposition, Tran Anh et al. [26] implemented a hybrid model to predict monthly precipitation. They incorporated two feed-forward neural networks, namely artificial neural networks and seasonal artificial neural networks, in their models and produced the most satisfactory simulation of rainfall prediction using wavelet transform.

Additionally, Ghamariadyan and Imteaz [27] developed a medium-term (1, 3, 6, and 12 months lead time) prediction model using a hybrid wavelet artificial neural network (WANN). Their comparative analysis shows that the WANN outperformed ANN, ARIMA, multiple linear regression (MLR), and the current prediction system for Queensland, Australia, providing more precise rainfall predictions.

These related works demonstrate the significance of adopting various technique-based approaches, including machine learning models and hybrid methods, for adaptive rain precipitation prediction. The studies highlight the potential of these approaches in improving accuracy, computational efficiency, and the ability to capture different components and patterns in rainfall time series. Building upon these previous findings, this paper proposes a novel Location Agnostic Adaptive Rain Precipitation Prediction approach, aiming to address the challenges associated with changing climate conditions and improve the accuracy of rainfall forecasts across different locations.

III. METHODOLOGY

In this paper, we use a deep learning model for rain precipitation prediction based on meteorological data as features. To make the model adaptive across spatial variation we leverage the domain adaptation approach. For domain adaptation, we need data from two domains which are termed as source domain and target domain. The source domain is the domain where the deep learning model will be trained primarily. The target domain is the domain where the trained model by the source data will be adapted. In our work, the source domain is the weather data of the city of Dhaka. The target domains are the weather data of cities - Tokyo, Paris, and Los Angeles. In each experiment, only one of these cities will be considered as the target domain. The total workflow is shown in the Fig 1. At first, we shall train a deep learning network using the source data from scratch. Then we shall use data from both the source and target domain for adaptation.

A. Training the Source Model

We shall train a deep neural network using the source data. We know that neural networks can be trained for two types of problems which are classification and regression. We formulate our problem as a regression problem as we want to predict the value of precipitation. A feed-forward deep neural network of Fig. 1a comprising 2 stages of hidden layers is

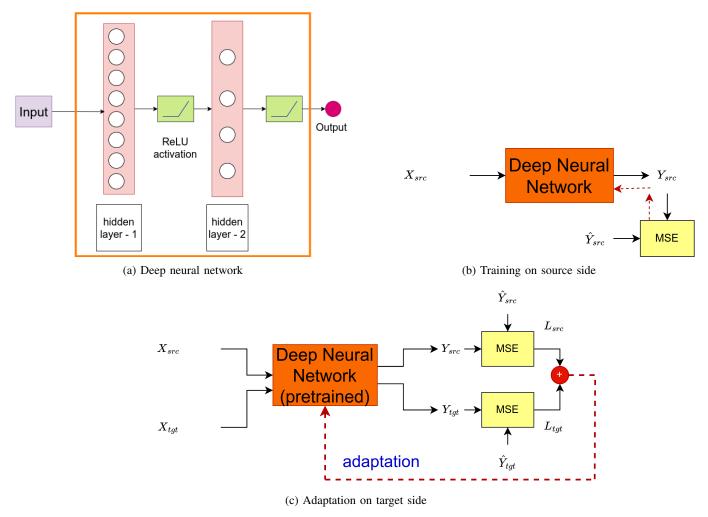


Fig. 1: The total workflow is shown in this figure. (a) The deep neural network that is used for training. We formulate our problem as a regression problem. Hence there is only one output node. (b) Training on the source side. X_{src} is the source data (weather features) and \hat{Y}_{src} is the ground truth data of the target value (precipitation). The training is guided by the mean square error (MSE) loss. (c) The adaptation on the target side is guided by MSE loss using both source and target data.

used for training. The output layer has one node in order to facilitate regression. If the output of the network (predicted precipitation) is Y_{src} and the ground truth value is \hat{Y}_{src} , the mean square error (MSE) loss function can be expressed by

$$L_{src} = \frac{1}{N} \sum_{i=1}^{N} (Y_{src} - \hat{Y}_{src})^2$$
 (1)

where N indicates the number of samples in training.

B. Adaptation for Target Domain

The target domain data is split into two portions, namely adaptation data and test data. The adaptation split of the target domain and the train split of the source domain are used for adapting the network for the target domain. The loss function which is used for the adaptation is expressed by

$$L_{total} = \lambda_1 L_{src} + \lambda_2 L_{tgt} \tag{2}$$

where L_{src} and L_{tgt} both are MSE loss and λ_1 and λ_2 are non negative weight coefficients.

IV. EXPERIMENTS AND RESULTS

A. Dataset

Our findings from this dataset provide valuable insights into the relationships between different weather variables and offer valuable information for weather forecasting and understanding weather patterns in the Dhaka, Los Angeles, Paris, and Tokyo regions. We collected weather data from NASA Power [28] and conducted an extensive analysis of 20 years' worth of weather data, spanning from January 1, 2003, to January 1, 2023. The extracted features include air temperature, dew point, wet point, specific humidity, relative humidity, atmospheric pressure, and wind speed. (summarized in TABLE I)

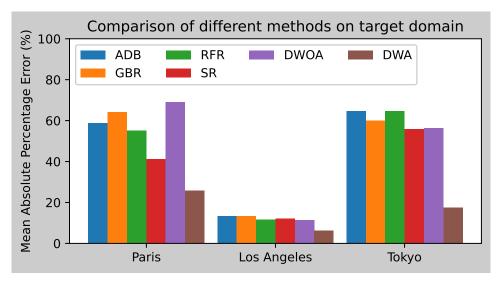


Fig. 2: Performance comparison on predicting precipitation of different methods by training them on the weather data of Dhaka city and using the pre-trained model for testing on Paris, Los Angeles, and Tokyo. ADB, GRB, RFR, SR, DWOA, and DWA indicate Adaboost, Gradient Boosting Regressor, Random Forest Regressor, Stacking Regressor, Deep learning WithOut Adaptation, and Deep learning With Adaptation, respectively. We see that Deep learning with adaptation outperforms all other methods by securing the lowest Mean Absolute percentage error.

TABLE I: Features Used in the Dataset

Features	Description	
T2M	Average air temperature at 2 meters	
T2MDEW	Dew point at 2 meters	
T2MWET	Wet point at 2 meters	
TS	Earth Skin Temperature	
T2M RANGE	Merra-2 Temperature at 2 meters range	
T2M MAX	Maximum temperature at 2 meters	
T2M MIN	Minimum temperature at 2 meters	
QV2M	Specific Humidity at 2 meters	
RH2M	Relative Humidity at 2 meters	
PRECTOT	Bias-corrected total precipitation at 2 meters	
PS	Average surface pressure at surface	
WS10M RANGE	Average wind speed 10 meters range	
WS10M	Average wind speed 10 meters high	
WD10M	Average wind direction 10 meters high	
WS10M MAX	maximum wind speed 10 meters	
WS10M MIN	Minimum wind speed 10 meters	

B. Results

In the result section, we shall demonstrate the training performance of the deep neural network on source data, then show how the adaptive algorithm works in reducing mean square error and running time.

1) Training Performance on Source Domain: We present the performance of deep neural networks on training source

TABLE II: Training on source data using different techniques

Method	Mean Square Error
Adaboost	96.7630
Gradient Boosting Regressor	102.7857
Random Forest Regressor	85.8252
Stacking Regressor	112.3288
Deep Neural Network	79.8080

data. We compare the performance of deep neural networks with some ensembling machine learning techniques such as Adaboost [29], Gradient Boosting Regressor [30], Random Forest Regressor [31] and Stacking Regressor [32]. TABLE II shows that Deep Neural Network performs the best (with the lowest MSE) compared to other ensembling machine learning techniques.

2) Performance of Adaptation on Target Domain: In our work, we have used 'Dhaka' as our source domain. Tokyo, Los Angeles, and Paris have been selected as the target domain. The cities of the target domain have significant domain shifts compared to the source domain. TABLE III shows when a deep neural network is trained on 'Dhaka' and used in other cities without adaptation it exhibits high values of mean absolute error (MAE) in percentage. On the other hand, when adaptation is introduced, the MAE percentage decreases significantly. From TABLE III we see, 43.51%, 5.09%, and 38.62% improvement in MAE for cities Paris, Los Angeles, and Tokyo, respectively.

Fig. 2 illustrates how deep learning with adaptation on the target domain outperforms all other ensembling machine learning methods. It is evident that adaptation is essential if

TABLE III: Comparing the inference performance in terms of Mean Absolute Percentage Error for Deep Learning Network on other cities before and after adaptation. Here the city Dhaka is the source domain and Paris, Tokyo and Los Angeles are considered as the target domain.

City	Before Adaptation	After Adaptation
	MAE	MAE
Paris	69.0626 %	25.8855%
Los Angeles	11.3367 %	6.3358 %
Tokyo	56.2065 %	17.5864 %

we want to generalize our model.

V. CONCLUSION AND FUTURE DIRECTION

This paper proposes a deep neural network-based adaptive technique in rain precipitation prediction. We have shown the comparison of different approaches on the target domain where our adaptive deep neural network outperforms other methods such as Adaboost, Gradient Boosting Regressor, Random Forest Regressor, and Stacking Regressor. Moreover the performance difference between before adaptation and after adaption is huge in the target domain area which satisfies our motivation. In the future, we will extend our work to fit the model using fewer features for different locations in order to make the approach computation and storage efficient. In addition, we shall focus on adaptation in an unsupervised manner.

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