

Федеральное государственное бюджетное образовательное учреждение высшего образования
«Сибирский государственный университет телекоммуникаций и информатики»
(СибГУТИ)

Институт информатики и вычислительной техники

09.03.01 "Информатика и вычислительная техника"
профиль "Программное обеспечение средств
вычислительной техники и автоматизированных систем"

Кафедра прикладной математики и кибернетики

Операционные системы реального времени

Лабораторная работа №3

Электростанция

Выполнил:

студент гр.ИП-213

Дмитриев Антон Александрович
ФИО студента

«__» _____ 2025 г.

Проверил:

Преподаватель

ФИО преподавателя

«__» _____ 2025 г.

Оценка _____

Новосибирск 2025 г.

1. Электростанция состоит из следующих элементов: хранилище топлива (1 шт.), транспортное средство (1 шт.), котлы (4 шт.). Элементы станции работают параллельно, каждый по своей программе (что может быть реализовано с помощью нитей). Транспортное средство доставляет топливо из хранилища к котлам. Топливо имеет различные марки (от 1 до 10). Топливо марки 10 горит в котле 10 с (условно), в то время как топливо марки 1 горит всего 1 с. Необходимо написать программу, моделирующую работу электростанции и показывающую на экране процесс ее функционирования.

```
#include <vingraph.h>

#include <pthread.h>

#include <unistd.h>

#include <stdlib.h>

#include <stdio.h>

#include <vector>

#include <cmath>

class Boiler;

struct BurnData {
    Boiler* boiler;
    std::vector<int> fuelBlocks;
    BurnData(Boiler* b, const std::vector<int>& fb) : boiler(b), fuelBlocks(fb) {}
};

class Storage {
public:
    Storage(int x, int y) : x(x), y(y) {
        pthread_mutex_init(&mtx, NULL);
        rect = Rect(x, y, 100, 80, 1, RGB(0, 100, 200));
    }
};
```

```

        fill = Rect(x+2, y+2, 96, 76, 0, RGB(0, 200, 100));

        text = Text(x + 15, y + 35, "FUEL", RGB(255, 255, 255));

        Show(rect);

        Show(fill);

        Show(text);
    }

    int getFuelType() {
        pthread_mutex_lock(&mtx);

        int fuelType = rand() % 10 + 1;

        printf("[Storage] issued fuel type %d\n", fuelType);

        pthread_mutex_unlock(&mtx);

        return fuelType;
    }

    int getX() const { return x; }

    int getY() const { return y; }

private:
    int x, y;

    int rect, fill, text;

    pthread_mutex_t mtx;
};

class Boiler {
public:
    Boiler(int id, int x, int y, int capacity) : id(id), x(x), y(y), capacity(capacity),
        currentFuel(0), burnThread(0) {

        pthread_mutex_init(&burnMtx, NULL);

        rect = Rect(x, y, 100, 80, 1, RGB(200, 150, 0));

        statusRect = Rect(x+2, y+2, 96, 76, 0, RGB(255, 255, 100));

        char title[20];

        sprintf(title, "BOILER %d", id);
    }
};

```

```
text1 = Text(x + 25, y + 20, title, RGB(0, 0, 0));
text2 = Text(x + 25, y + 50, "WAITING", RGB(255, 0, 0));
```

```
Show(rect);
Show(statusRect);
Show(text1);
Show(text2);
}
```

```
~Boiler() {
    if (burnThread) {
        pthread_join(burnThread, NULL);
    }
    pthread_mutex_destroy(&burnMtx);
}
```

```
void fillAndBurn(int fuelType) {
    pthread_mutex_lock(&burnMtx);
    if (currentFuel == 0) {
        currentFuel = capacity;
        currentFuelType = fuelType;

        Delete(text2);
        text2 = Text(x + 25, y + 50, "BURNING", RGB(255, 100, 0));
        Show(text2);

        std::vector<int> fuelBlocks;
        for (int i = 0; i < capacity; i++) {
            int block = Rect(x + 80, y + 10 + (i * 8), 15, 6, 0, RGB(200, 50, 50));
            Show(block);
```

```

        fuelBlocks.push_back(block);

        usleep(200000);
    }

    usleep(500000);

    BurnData* data = new BurnData(this, fuelBlocks);
    pthread_create(&burnThread, NULL, burnHelper, data);
    Delete(text2);
    text2 = Text(x + 25, y + 50, "WORKING", RGB(0, 150, 0));
    Show(text2);
} else {
    Delete(text2);
    text2 = Text(x + 25, y + 50, "WORKING", RGB(0, 150, 0));
    Show(text2);
}
pthread_mutex_unlock(&burnMtx);
}

static void* burnHelper(void* arg) {
    BurnData* data = static_cast<BurnData*>(arg);
    data->boiler->burnInternally(data->fuelBlocks);
    delete data;
    return NULL;
}

void burnInternally(const std::vector<int>& fuelBlocks) {
    pthread_mutex_lock(&burnMtx);
    for (int i = fuelBlocks.size() - 1; i >= 0; i--) {
        Delete(fuelBlocks[i]);
    }
}

```

```

        usleep(currentFuelType * 100000);
    }
    Delete(text2);
    text2 = Text(x + 25, y + 50, "WAITING", RGB(255, 0, 0));
    currentFuel = 0;
    burnThread = 0;
    pthread_mutex_unlock(&burnMtx);
}

```

```

bool isEmpty() const {
    return currentFuel == 0;
}

```

```

int getX() const { return x; }
int getY() const { return y; }

```

private:

```

    int id;
    int x, y;
    int rect, statusRect;
    int text1;
    int text2;
    int capacity;
    int currentFuel;
    int currentFuelType;
    pthread_t burnThread;
    pthread_mutex_t burnMtx;
};

```

```

class Vehicle {

```

public:

```
Vehicle(Storage* storage, std::vector<Boiler*>& boilers, int x, int y, int plantRect)
```

```
: storage(storage), boilers(boilers), x(x), y(y), plantRect(plantRect) {
```

```
    pthread_mutex_init(&moveMtx, NULL);
```

```
}
```

```
~Vehicle() {
```

```
    pthread_mutex_destroy(&moveMtx);
```

```
}
```

```
static void* runHelper(void* arg) { return ((Vehicle*)arg)->runThread(); }
```

```
void* runThread() {
```

```
    int i = 0;
```

```
    while (1) {
```

```
        int fuelType = storage->getFuelType();
```

```
        if (boilers[i]->isEmpty()) {
```

```
            moveToBoiler(storage->getX(), storage->getY() - 50, boilers[i]->getX() + 20,  
boilers[i]->getY() - 50);
```

```
            boilers[i]->fillAndBurn(fuelType);
```

```
            moveToStorage(boilers[i]->getX(), boilers[i]->getY() - 50, storage->getX() +  
20, storage->getY() - 50);
```

```
            usleep(1000000);
```

```
        }
```

```
        i = (i + 1) % boilers.size();
```

```
        usleep(10000);
```

```
    }
```

```
    return NULL;
```

```
}
```

private:

```
void moveToBoiler(int startX, int startY, int endX, int endY) {
```

```

pthread_mutex_lock(&moveMtx);
int steps = 30;
int dx = (endX - startX) / steps;
int dy = (endY - startY) / steps;
MoveTo(startX, startY, plantRect);
for (int step = 1; step <= steps; step++) {
    Move(plantRect, dx, dy);

    Fill(plantRect, RGB(50, 100, 200));
    usleep(15000);
}
pthread_mutex_unlock(&moveMtx);
}

void moveToStorage(int startX, int startY, int endX, int endY) {
    pthread_mutex_lock(&moveMtx);
    int steps = 30;
    int dx = (endX - startX) / steps;
    int dy = (endY - startY) / steps;
    MoveTo(startX, startY, plantRect);
    for (int step = 1; step <= steps; step++) {
        Move(plantRect, dx, dy);

        Fill(plantRect, RGB(150, 50, 200));
        usleep(15000);
    }
    pthread_mutex_unlock(&moveMtx);
}

```

```

Storage* storage;

```

```
std::vector<Boiler*>& boilers;

int x, y;

int plantRect;

pthread_mutex_t moveMtx;

};
```

```
int main() {

    ConnectGraph();
```

```
    int titleBg = Rect(250, 20, 200, 40, 1, RGB(100, 100, 200));
    int electricPlantText = Text(280, 40, "ELECTRIC PLANT", RGB(255, 255, 255));
    Show(titleBg);
    Show(electricPlantText);
```

```
    Storage storage(50, 200);
    Boiler b1(1, 200, 200, 8);
    Boiler b2(2, 350, 200, 8);
    Boiler b3(3, 500, 200, 8);
    Boiler b4(4, 650, 200, 8);
```

```
    std::vector<Boiler*> boilers;
    boilers.push_back(&b1);
    boilers.push_back(&b2);
    boilers.push_back(&b3);
    boilers.push_back(&b4);
```

```
    int vehicleRect = Rect(20, 20, 25, 15, 0, RGB(50, 100, 200));
    Show(vehicleRect);
```

```
Vehicle vehicle(&storage, boilers, 20, 20, vehicleRect);
```

```
pthread_t vehicleThread;
```

```
pthread_create(&vehicleThread, NULL, Vehicle::runHelper, &vehicle);
```

```
int infoText = Text(50, 350, "Press ESC to exit", RGB(150, 150, 150));
```

```
Show(infoText);
```

```
int key = 0;
```

```
bool running = true;
```

```
while (running) {
```

```
    key = InputChar();
```

```
    if (key == 27) {
```

```
        CloseGraph();
```

```
        return 0;
```

```
    }
```

```
}
```

```
pthread_join(vehicleThread, NULL);
```

```
CloseGraph();
```

```
return 0;
```

```
}
```

2. А теперь добавьте второе транспортное средство.

```
#include <vingraph.h>
```

```
#include <pthread.h>
```

```
#include <unistd.h>
```

```
#include <stdlib.h>
```

```
#include <stdio.h>
```

```
#include <vector>
```

```
#include <cmath>
```

```
class Boiler;
```

```
struct BurnData {
```

```
    Boiler* boiler;
```

```
    std::vector<int> fuelBlocks;
```

```
    BurnData(Boiler* b, const std::vector<int>& fb) : boiler(b), fuelBlocks(fb) {}
```

```
};
```

```
class Storage {
```

```
public:
```

```
    Storage(int x, int y) : x(x), y(y) {
```

```
        pthread_mutex_init(&mtx, NULL);
```

```
        rect = Rect(x, y, 100, 80, 1, RGB(0, 100, 200));
```

```
        fill = Rect(x+2, y+2, 96, 76, 0, RGB(0, 200, 100));
```

```
        text = Text(x + 15, y + 35, "FUEL", RGB(255, 255, 255));
```

```
        Show(rect);
```

```

        Show(fill);

        Show(text);
    }

    int getFuelType() {
        pthread_mutex_lock(&mtx);

        int fuelType = rand() % 10 + 1;

        printf("[Storage] issued fuel type %d\n", fuelType);

        pthread_mutex_unlock(&mtx);

        return fuelType;
    }

    int getX() const { return x; }

    int getY() const { return y; }

private:
    int x, y;

    int rect, fill, text;

    pthread_mutex_t mtx;
};

class Boiler {
public:
    Boiler(int id, int x, int y, int capacity) : id(id), x(x), y(y), capacity(capacity),
        currentFuel(0), burnThread(0) {

        pthread_mutex_init(&burnMtx, NULL);

        rect = Rect(x, y, 100, 80, 1, RGB(200, 150, 0));

        statusRect = Rect(x+2, y+2, 96, 76, 0, RGB(255, 255, 100));
    }
};

```

```

    char title[20];

    sprintf(title, "BOILER %d", id);

    text1 = Text(x + 25, y + 20, title, RGB(0, 0, 0));

    text2 = Text(x + 25, y + 50, "WAITING", RGB(255, 0, 0));


    Show(rect);

    Show(statusRect);

    Show(text1);

    Show(text2);
}


~Boiler() {
    if (burnThread) {
        pthread_join(burnThread, NULL);
    }

    pthread_mutex_destroy(&burnMtx);
}


void fillAndBurn(int fuelType) {
    pthread_mutex_lock(&burnMtx);

    if (currentFuel == 0) {
        currentFuel = capacity;

        currentFuelType = fuelType;
    }
}

```

```
Delete(text2);
```

```
text2 = Text(x + 25, y + 50, "BURNING", RGB(255, 100, 0));
```

```
Show(text2);
```

```
std::vector<int> fuelBlocks;
```

```
for (int i = 0; i < capacity; i++) {
```

```
    int block = Rect(x + 80, y + 10 + (i * 8), 15, 6, 0, RGB(200, 50, 50));
```

```
    Show(block);
```

```
    fuelBlocks.push_back(block);
```

```
    usleep(200000);
```

```
}
```

```
usleep(500000);
```

```
BurnData* data = new BurnData(this, fuelBlocks);
```

```
pthread_create(&burnThread, NULL, burnHelper, data);
```

```
Delete(text2);
```

```
text2 = Text(x + 25, y + 50, "WORKING", RGB(0, 150, 0));
```

```
Show(text2);
```

```
} else {
```

```
    Delete(text2);
```

```
    text2 = Text(x + 25, y + 50, "WORKING", RGB(0, 150, 0));
```

```
    Show(text2);
```

```
}
```

```
pthread_mutex_unlock(&burnMtx);
```

```
}
```

```
static void* burnHelper(void* arg) {  
    BurnData* data = static_cast<BurnData*>(arg);  
    data->boiler->burnInternally(data->fuelBlocks);  
    delete data;  
    return NULL;  
}
```

```
void burnInternally(const std::vector<int>& fuelBlocks) {  
    pthread_mutex_lock(&burnMtx);  
    for (int i = fuelBlocks.size() - 1; i >= 0; i--) {  
        Delete(fuelBlocks[i]);  
        usleep(currentFuelType * 100000);  
    }  
    Delete(text2);  
    text2 = Text(x + 25, y + 50, "WAITING", RGB(255, 0, 0));  
    Show(text2);  
    currentFuel = 0;  
    burnThread = 0;  
    pthread_mutex_unlock(&burnMtx);  
}
```

```
bool isEmpty() const {  
    return currentFuel == 0;
```

```
}
```

```
int getX() const { return x; }
```

```
int getY() const { return y; }
```

```
private:
```

```
int id;
```

```
int x, y;
```

```
int rect, statusRect;
```

```
int text1;
```

```
int text2;
```

```
int capacity;
```

```
int currentFuel;
```

```
int currentFuelType;
```

```
pthread_t burnThread;
```

```
pthread_mutex_t burnMtx;
```

```
};
```

```
class Vehicle {
```

```
public:
```

```
    Vehicle(Storage* storage, std::vector<Boiler*>& boilers, int x, int y, int plantRect,  
            int vehicleId)
```

```
        : storage(storage), boilers(boilers), x(x), y(y), plantRect(plantRect),  
          vehicleId(vehicleId) {
```

```
            pthread_mutex_init(&moveMtx, NULL);
```

```
}
```

```

~Vehicle() {

    pthread_mutex_destroy(&moveMtx);

}

static void* runHelper(void* arg) { return ((Vehicle*)arg)->runThread(); }

void* runThread() {

    int i = vehicleId;

    while (1) {

        int fuelType = storage->getFuelType();

        printf("[Vehicle %d] carrying fuel type %d to the boiler %d\n", vehicleId + 1,
fuelType, i + 1);

        if (boilers[i]->isEmpty()) {

            moveToBoiler(storage->getX(), storage->getY() - 50, boilers[i]->getX() +
20, boilers[i]->getY() - 50);

            boilers[i]->fillAndBurn(fuelType);

            moveToStorage(boilers[i]->getX(), boilers[i]->getY() - 50, storage->getX()
+ 20, storage->getY() - 50);

            usleep(1000000);

        } else {

            printf("[Vehicle %d] Boiler %d is not empty, skipping\n", vehicleId + 1, i +
1);

        }

        i = (i + 2) % boilers.size();

        usleep(10000);

    }

    return NULL;
}

```

```
}
```

private:

```
void moveToBoiler(int startX, int startY, int endX, int endY) {  
    pthread_mutex_lock(&moveMtx);  
    int steps = 30;  
    int dx = (endX - startX) / steps;  
    int dy = (endY - startY) / steps;  
    MoveTo(startX, startY, plantRect);  
    for (int step = 1; step <= steps; step++) {  
        Move(plantRect, dx, dy);  
        Fill(plantRect, vehicleId == 0 ? RGB(50, 100, 200) : RGB(200, 100, 50));  
        usleep(15000);  
    }  
    pthread_mutex_unlock(&moveMtx);  
}
```

```
void moveToStorage(int startX, int startY, int endX, int endY) {  
    pthread_mutex_lock(&moveMtx);  
    int steps = 30;  
    int dx = (endX - startX) / steps;  
    int dy = (endY - startY) / steps;  
    MoveTo(startX, startY, plantRect);  
    for (int step = 1; step <= steps; step++) {  
        Move(plantRect, dx, dy);
```

```

        Fill(plantRect, vehicleId == 0 ? RGB(150, 50, 200) : RGB(200, 50, 150));

        usleep(15000);

    }

    pthread_mutex_unlock(&moveMtx);
}

Storage* storage;

std::vector<Boiler*> & boilers;

int x, y;

int plantRect;

int vehicleId;

pthread_mutex_t moveMtx;

};

int main() {

    ConnectGraph();

    int titleBg = Rect(250, 20, 200, 40, 1, RGB(100, 100, 200));

    int electricPlantText = Text(280, 40, "ELECTRIC PLANT", RGB(255, 255, 255));

    Show(titleBg);

    Show(electricPlantText);

    Storage storage(50, 200);

    Boiler b1(1, 200, 200, 8);

    Boiler b2(2, 350, 200, 8);

```

```
Boiler b3(3, 500, 200, 8);
```

```
Boiler b4(4, 650, 200, 8);
```

```
std::vector<Boiler*> boilers;
```

```
boilers.push_back(&b1);
```

```
boilers.push_back(&b2);
```

```
boilers.push_back(&b3);
```

```
boilers.push_back(&b4);
```

```
int vehicleRect1 = Rect(20, 20, 25, 15, 0, RGB(50, 100, 200));
```

```
int vehicleRect2 = Rect(60, 20, 25, 15, 0, RGB(200, 100, 50));
```

```
Show(vehicleRect1);
```

```
Show(vehicleRect2);
```

```
Vehicle vehicle1(&storage, boilers, 20, 20, vehicleRect1, 0);
```

```
Vehicle vehicle2(&storage, boilers, 20, 20, vehicleRect2, 1);
```

```
pthread_t vehicleThread1, vehicleThread2;
```

```
pthread_create(&vehicleThread1, NULL, Vehicle::runHelper, &vehicle1);
```

```
pthread_create(&vehicleThread2, NULL, Vehicle::runHelper, &vehicle2);
```

```
int infoText = Text(50, 350, "Press ESC to exit", RGB(150, 150, 150));
```

```
Show(infoText);
```

```
int key = 0;
```

```
bool running = true;
```

```
while (running) {  
    key = InputChar();  
    if (key == 27) {  
        CloseGraph();  
        return 0;  
    }  
}
```

```
pthread_join(vehicleThread1, NULL);  
pthread_join(vehicleThread2, NULL);
```

```
CloseGraph();  
return 0;  
}
```

3. (использование импульсов) Регулируя скорости работы элементов электростанции, вы можете создать ситуацию, когда котлы будут простаивать из-за низкой скорости подвоза топлива. Создайте такую ситуацию. Теперь сделайте так, чтобы топливо подвозилось к котлам заранее, до момента их полной остановки. Это можно реализовать, если котлы будут сообщать о том, что топливо скоро кончится (например, его осталось на 2 с работы). Ясно, что котлы могут это сделать с помощью импульса, т.к. обычное сообщение их заблокировало бы, в то время как они должны продолжать работать

```
#include <vingraph.h>
```

```
#include <pthread.h>
```

```
#include <unistd.h>
```

```
#include <stdlib.h>
```

```
#include <stdio.h>
```

```
#include <vector>
```

```
class Boiler;
```

```
struct BurnData {
```

```
    Boiler* boiler;
```

```
    std::vector<int> fuelBlocks;
```

```
    BurnData(Boiler* b, const std::vector<int>& fb) : boiler(b), fuelBlocks(fb) {}
```

```
};
```

```
class Storage {
```

```
public:
```

```
    Storage(int x, int y) : x(x), y(y) {
```

```

pthread_mutex_init(&mtx, NULL);

rect = Rect(x, y, 100, 80, 1, RGB(0, 100, 200));

fill = Rect(x+2, y+2, 96, 76, 0, RGB(0, 200, 100));

text = Text(x + 15, y + 35, "FUEL", RGB(255, 255, 255));

Show(rect);

Show(fill);

Show(text);

}

int getFuelType() {
    pthread_mutex_lock(&mtx);

    int fuelType = rand() % 10 + 1;

    printf("[Storage] issued fuel type %d\n", fuelType);

    pthread_mutex_unlock(&mtx);

    return fuelType;
}

int getX() const { return x; }

int getY() const { return y; }

private:
    int x, y;

    int rect, fill, text;

    pthread_mutex_t mtx;
};

class Boiler {
public:
    Boiler(int id, int x, int y, int capacity) : id(id), x(x), y(y), capacity(capacity), currentFuel(0),
    burnThread(0), lowFuel(false) {

        pthread_mutex_init(&burnMtx, NULL);

        rect = Rect(x, y, 100, 80, 1, RGB(200, 150, 0));

        statusRect = Rect(x+2, y+2, 96, 76, 0, RGB(255, 255, 100));

```

```

char title[20];

sprintf(title, "BOILER %d", id);

text1 = Text(x + 25, y + 20, title, RGB(0, 0, 0));
text2 = Text(x + 25, y + 50, "WAITING", RGB(255, 0, 0));


Show(rect);

Show(statusRect);

Show(text1);

Show(text2);

}


~Boiler() {
    if (burnThread) {
        pthread_join(burnThread, NULL);
    }

    pthread_mutex_destroy(&burnMtx);
}


void fillAndBurn(int fuelType) {
    pthread_mutex_lock(&burnMtx);
    if (currentFuel == 0) {
        currentFuel = capacity;
        currentFuelType = fuelType;
        printf("[Boiler %d] Filled with %d liters of fuel type %d\n", id, currentFuel, fuelType);

        Delete(text2);
        text2 = Text(x + 25, y + 50, "BURNING", RGB(255, 100, 0));
        Show(text2);

        std::vector<int> fuelBlocks;

```

```

    for (int i = 0; i < capacity; i++) {
        int block = Rect(x + 80, y + 10 + (i * 8), 15, 6, 0, RGB(200, 50, 50));
        Show(block);
        fuelBlocks.push_back(block);
        usleep(200000);
    }

    usleep(500000);

    BurnData* data = new BurnData(this, fuelBlocks);
    pthread_create(&burnThread, NULL, burnHelper, data);
    Delete(text2);
    text2 = Text(x + 25, y + 50, "WORKING", RGB(0, 150, 0));
    Show(text2);
} else {
    Delete(text2);
    text2 = Text(x + 25, y + 50, "WORKING", RGB(0, 150, 0));
    Show(text2);
    printf("[Boiler %d] Already filled with %d liters, skipping fill\n", id, currentFuel);
}
pthread_mutex_unlock(&burnMtx);
}

static void* burnHelper(void* arg) {
    BurnData* data = static_cast<BurnData*>(arg);
    data->boiler->burnInternally(data->fuelBlocks);
    delete data;
    return NULL;
}

```

```

void burnInternally(const std::vector<int>& fuelBlocks) {
    pthread_mutex_lock(&burnMtx);
    for (int i = fuelBlocks.size() - 1; i >= 0; i--) {
        if (i == 4) {
            lowFuel = true;
            printf("[Boiler %d] Low fuel signal set (remaining %d blocks)\n", id, i + 1);
        }
        Delete(fuelBlocks[i]);
        usleep(currentFuelType * 100000);
    }
    printf("[Boiler %d] has finished burning %d liters\n", id, currentFuel);
    Delete(text2);
    text2 = Text(x + 25, y + 50, "WAITING", RGB(255, 0, 0));
    Show(text2);
    currentFuel = 0;
    burnThread = 0;
    lowFuel = false;
    pthread_mutex_unlock(&burnMtx);
}

bool isEmpty() const {
    return currentFuel == 0;
}

bool isLowFuel() const {
    pthread_mutex_lock(const_cast<pthread_mutex_t*>(&burnMtx));
    bool result = lowFuel;
    pthread_mutex_unlock(const_cast<pthread_mutex_t*>(&burnMtx));
    return result;
}

```

```
int getX() const { return x; }
```

```
int getY() const { return y; }
```

```
private:
```

```
int id;
```

```
int x, y;
```

```
int rect, statusRect;
```

```
int text1;
```

```
int text2;
```

```
int capacity;
```

```
int currentFuel;
```

```
int currentFuelType;
```

```
pthread_t burnThread;
```

```
pthread_mutex_t burnMtx;
```

```
volatile bool lowFuel;
```

```
};
```

```
class Vehicle {
```

```
public:
```

```
    Vehicle(Storage* storage, std::vector<Boiler*>& boilers, int x, int y, int plantRect, int  
    vehicleId)
```

```
        : storage(storage), boilers(boilers), x(x), y(y), plantRect(plantRect), vehicleId(vehicleId) {
```

```
        pthread_mutex_init(&moveMtx, NULL);
```

```
    }
```

```
    ~Vehicle() {
```

```
        pthread_mutex_destroy(&moveMtx);
```

```
    }
```

```
    static void* runHelper(void* arg) { return ((Vehicle*)arg)->runThread(); }
```

```

void* runThread() {
    int i = vehicleId;
    while (1) {
        int fuelType = storage->getFuelType();
        printf("[Vehicle %d] carrying fuel type %d to the boiler %d\n", vehicleId + 1, fuelType, i
+ 1);
        if (boilers[i]->isEmpty() || boilers[i]->isLowFuel()) {
            moveToBoiler(storage->getX(), storage->getY() - 50, boilers[i]->getX() + 20,
boilers[i]->getY() - 50);
            boilers[i]->fillAndBurn(fuelType);
            moveToStorage(boilers[i]->getX(), boilers[i]->getY() - 50, storage->getX() + 20,
storage->getY() - 50);
            usleep(10000);
        } else {
            printf("[Vehicle %d] Boiler %d is not empty, skipping\n", vehicleId + 1, i + 1);
        }
        i = (i + 2) % boilers.size();
        usleep(2000000);
    }
    return NULL;
}

```

private:

```

void moveToBoiler(int startX, int startY, int endX, int endY) {
    pthread_mutex_lock(&moveMtx);
    int steps = 30;
    int dx = (endX - startX) / steps;
    int dy = (endY - startY) / steps;
    MoveTo(startX, startY, plantRect);
    for (int step = 1; step <= steps; step++) {
        Move(plantRect, dx, dy);
    }
}

```

```

        Fill(plantRect, vehicleId == 0 ? RGB(50, 100, 200) : RGB(200, 100, 50));

        usleep(15000);
    }

    pthread_mutex_unlock(&moveMtx);
}

```

```

void moveToStorage(int startX, int startY, int endX, int endY) {
    pthread_mutex_lock(&moveMtx);

    int steps = 30;

    int dx = (endX - startX) / steps;
    int dy = (endY - startY) / steps;

    MoveTo(startX, startY, plantRect);

    for (int step = 1; step <= steps; step++) {
        Move(plantRect, dx, dy);

        Fill(plantRect, vehicleId == 0 ? RGB(150, 50, 200) : RGB(200, 50, 150));

        usleep(15000);
    }

    pthread_mutex_unlock(&moveMtx);
}

```

```

Storage* storage;

std::vector<Boiler*> &boilers;

int x, y;

int plantRect;

int vehicleId;

pthread_mutex_t moveMtx;

};

```

```

int main() {
    ConnectGraph();
}

```

```
int titleBg = Rect(250, 20, 200, 40, 1, RGB(100, 100, 200));
int electricPlantText = Text(280, 40, "ELECTRIC PLANT", RGB(255, 255, 255));
Show(titleBg);
Show(electricPlantText);

Storage storage(50, 200);
Boiler b1(1, 200, 200, 8);
Boiler b2(2, 350, 200, 8);
Boiler b3(3, 500, 200, 8);
Boiler b4(4, 650, 200, 8);

std::vector<Boiler*> boilers;
boilers.push_back(&b1);
boilers.push_back(&b2);
boilers.push_back(&b3);
boilers.push_back(&b4);

int vehicleRect1 = Rect(20, 20, 25, 15, 0, RGB(50, 100, 200));
int vehicleRect2 = Rect(60, 20, 25, 15, 0, RGB(200, 100, 50));
Show(vehicleRect1);
Show(vehicleRect2);

Vehicle vehicle1(&storage, boilers, 20, 20, vehicleRect1, 0);
Vehicle vehicle2(&storage, boilers, 20, 20, vehicleRect2, 1);
pthread_t vehicleThread1, vehicleThread2;
pthread_create(&vehicleThread1, NULL, Vehicle::runHelper, &vehicle1);
pthread_create(&vehicleThread2, NULL, Vehicle::runHelper, &vehicle2);

int infoText = Text(50, 350, "Press ESC to exit", RGB(150, 150, 150));
```

```
Show(infoText);
```

```
int key = 0;
```

```
bool running = true;
```

```
while (running) {
```

```
    key = InputChar();
```

```
    if (key == 27) {
```

```
        CloseGraph();
```

```
        return 0;
```

```
    }
```

```
}
```

```
pthread_join(vehicleThread1, NULL);
```

```
pthread_join(vehicleThread2, NULL);
```

```
CloseGraph();
```

```
return 0;
```

```
}
```

4. А теперь сделайте сетевой вариант разработанной программы. Пусть теперь хранилище работает на одной машине, котлы на другой, а транспортные средства переносят топливо между этими двумя машинами. Вам понадобится разделить вашу программу на две, которые вы будете запускать на разных узлах сети. Чтобы не надоедать соседу с просьбами о запуске вашей программки, которая к тому же будет постоянно подвешивать его компьютер, отладку можно вести на своем компьютере. Напомним, что имя узла содержится в переменной HOSTNAME.

boiler.cpp:

```
#include <vingraph.h>
#include <pthread.h>
#include <unistd.h>
#include <stdlib.h>
#include <stdio.h>
#include <vector>
#include <string>
#include <netinet/in.h>
#include <sys/socket.h>
#include <arpa/inet.h>
#include <cstring>
```

```
class BoilerLocal {
public:
    BoilerLocal(int id) : id(id), fuel(100) {
        pthread_mutex_init(&mtx, NULL);
        rect = Rect(200 + id * 150, 200, 100, 80, 1, RGB(200, 150, 0));
```

```
statusRect = Rect(202 + id * 150, 202, 96, 76, 0, RGB(255, 255, 100));
```

```
char title[20];
```

```
sprintf(title, "BOILER %d", id + 1);
```

```
text = Text(225 + id * 150, 230, title, RGB(0, 0, 0));
```

```
Show(rect);
```

```
Show(statusRect);
```

```
Show(text);
```

```
}
```

```
std::string getStatus() {
```

```
    pthread_mutex_lock(&mtx);
```

```
    std::string status;
```

```
    if (fuel == 0) status = "EMPTY";
```

```
    else if (fuel < 30) status = "LOW";
```

```
    else status = "OK";
```

```
    pthread_mutex_unlock(&mtx);
```

```
    return status;
```

```
}
```

```
void consume() {
```

```
    pthread_mutex_lock(&mtx);
```

```
    if (fuel > 0) fuel--;
```

```
    updateDisplay();
```

```
    pthread_mutex_unlock(&mtx);
```

```
}
```

```

void refuel(int fuelType) {
    pthread_mutex_lock(&mtx);
    fuel = 100;
    updateDisplay();
    printf("[Boiler %d] Refueled with type %d\n", id + 1, fuelType);
    pthread_mutex_unlock(&mtx);
}

```

```

int getFuel() const { return fuel; }
int getId() const { return id; }

```

private:

```

void updateDisplay() {
    int fuelLevel = (fuel * 70) / 100;
    int fuelColor;

    if (fuel < 30) fuelColor = RGB(255, 50, 50);
    else if (fuel < 60) fuelColor = RGB(255, 200, 50);
    else fuelColor = RGB(50, 200, 50);

    Fill(statusRect, fuelColor);

    char fuelText[20];
    sprintf(fuelText, "%d%%", fuel);
    int fuelTextObj = Text(225 + id * 150, 250, fuelText, RGB(0, 0, 0));
    Show(fuelTextObj);
    usleep(50000);
    Delete(fuelTextObj);
}

```

```

    }

    int id;
    int fuel;
    int rect;
    int statusRect;
    int text;
    pthread_mutex_t mtx;
};

void* serverThread(void* arg) {
    std::vector<BoilerLocal*>* boilers =
        static_cast<std::vector<BoilerLocal*>*>(arg);

    int serverSock = socket(AF_INET, SOCK_STREAM, 0);
    if (serverSock < 0) {
        perror("socket");
        return NULL;
    }

    sockaddr_in addr;
    addr.sin_family = AF_INET;
    addr.sin_port = htons(8080);
    addr.sin_addr.s_addr = INADDR_ANY;

    if (bind(serverSock, (sockaddr*)&addr, sizeof(addr)) < 0) {
        perror("bind");
        close(serverSock);
    }
}

```

```

    return NULL;
}

listen(serverSock, 5);

while (1) {
    int clientSock = accept(serverSock, NULL, NULL);
    if (clientSock < 0) continue;

    char buf[1024];
    int len = recv(clientSock, buf, sizeof(buf) - 1, 0);
    if (len > 0) {
        buf[len] = '\0';
        int id, fuelType;

        if (sscanf(buf, "STATUS %d", &id) == 1) {
            if (id >= 0 && id < (int)boilers->size()) {
                std::string status = (*boilers)[id]->getStatus();
                send(clientSock, status.c_str(),
                    status.size(), 0);
            }
        } else if (sscanf(buf, "REFUEL %d %d", &id, &fuelType) == 2) {
            if (id >= 0 && id < (int)boilers->size()) {
                (*boilers)[id]->refuel(fuelType);
                const char* ok = "OK";
                send(clientSock, ok, std::strlen(ok), 0);
            }
        }
    }
}

```

```

    }

    close(clientSock);
}

close(serverSock);
return NULL;
}

void* consumeThread(void* arg) {
    std::vector<BoilerLocal*>* boilers =
        static_cast<std::vector<BoilerLocal*>*>(arg);

    while (1) {
        size_t i;
        for (i = 0; i < boilers->size(); ++i) {
            (*boilers)[i]->consume();
        }
        usleep(500000);
    }
    return NULL;
}

int main() {
    ConnectGraph();

    int titleBg = Rect(250, 20, 200, 40, 1, RGB(100, 100, 200));
    int serverText = Text(280, 40, "BOILER SERVER", RGB(255, 255, 255));
    Show(titleBg);

```

```
Show(serverText);
```

```
BoilerLocal b1(0);
```

```
BoilerLocal b2(1);
```

```
BoilerLocal b3(2);
```

```
BoilerLocal b4(3);
```

```
std::vector<BoilerLocal*> boilers;
```

```
boilers.push_back(&b1);
```

```
boilers.push_back(&b2);
```

```
boilers.push_back(&b3);
```

```
boilers.push_back(&b4);
```

```
int infoText = Text(50, 350, "Press ESC to exit", RGB(150, 150, 150));
```

```
Show(infoText);
```

```
pthread_t srvThread, consThread;
```

```
pthread_create(&srvThread, NULL, serverThread, &boilers);
```

```
pthread_create(&consThread, NULL, consumeThread, &boilers);
```

```
int key = 0;
```

```
while (1) {
```

```
    key = InputChar();
```

```
    if (key == 27) break;
```

```
    usleep(10000);
```

```
}
```

```
pthread_cancel(srvThread);
```

```

pthread_cancel(consThread);

pthread_join(srvThread, NULL);
pthread_join(consThread, NULL);

CloseGraph();

return 0;
}

```

Storage.cpp:

```

#include <vingraph.h>

#include <pthread.h>

#include <unistd.h>

#include <stdlib.h>

#include <stdio.h>

#include <vector>

#include <netinet/in.h>

#include <sys/socket.h>

#include <arpa/inet.h>

#include <cstring>

```

```

class BoilerRemote {

```

```

public:

```

```

    BoilerRemote(int id, const char* host, int port) : id(id), host(host), port(port) {}

```

```

    std::string getStatus() {

```

```

        int sock = socket(AF_INET, SOCK_STREAM, 0);

```

```

        if (sock < 0) return "ERROR";
    }
}

```

```
sockaddr_in addr;
addr.sin_family = AF_INET;
addr.sin_port = htons(port);
inet_pton(AF_INET, host, &addr.sin_addr);
```

```
if (connect(sock, (sockaddr*)&addr, sizeof(addr)) < 0) {
    close(sock);
    return "ERROR";
}
```

```
char buf[1024];
sprintf(buf, "STATUS %d", id);
send(sock, buf, strlen(buf), 0);
```

```
int len = recv(sock, buf, 1024, 0);
buf[len] = '\0';
close(sock);
```

```
return std::string(buf);
}
```

```
void refuel(int fuelType) {
    int sock = socket(AF_INET, SOCK_STREAM, 0);
    if (sock < 0) return;
```

```
    sockaddr_in addr;
    addr.sin_family = AF_INET;
```

```
addr.sin_port = htons(port);  
inet_pton(AF_INET, host, &addr.sin_addr);
```

```
if (connect(sock, (sockaddr*)&addr, sizeof(addr)) < 0) {  
    close(sock);  
    return;  
}
```

```
char buf[1024];  
sprintf(buf, "REFUEL %d %d", id, fuelType);  
send(sock, buf, std::strlen(buf), 0);  
close(sock);  
}
```

```
bool isLowFuelOrEmpty() {  
    std::string status = getStatus();  
    return (status.compare("LOW") == 0) || (status.compare("EMPTY") == 0);  
}
```

```
bool isEmpty() {  
    return getStatus().compare("EMPTY") == 0;  
}
```

```
int getX() const { return 200 + id * 150; }  
int getY() const { return 200; }
```

```
private:
```

```
int id;
```

```
const char* host;

int port;

};
```

```
class Storage {
public:
    Storage(int x, int y) : x(x), y(y) {
        pthread_mutex_init(&mtx, NULL);
        rect = Rect(x, y, 100, 80, 1, RGB(0, 100, 200));
        fill = Rect(x+2, y+2, 96, 76, 0, RGB(0, 200, 100));
        text = Text(x + 15, y + 35, "FUEL", RGB(255, 255, 255));
        Show(rect);
        Show(fill);
        Show(text);
    }
};
```

```
int getFuelType() {
    pthread_mutex_lock(&mtx);
    int f = rand() % 10 + 1;
    printf("[Storage] issued fuel type %d\n", f);
    pthread_mutex_unlock(&mtx);
    return f;
}
```

```
void refreshDisplay() {
    pthread_mutex_lock(&mtx);
    Show(rect);
    Show(fill);
}
```

```

        Show(text);

        pthread_mutex_unlock(&mtx);
    }

```

```

int getX() const { return x; }
int getY() const { return y; }

```

private:

```

    int x, y;

    int rect, fill, text;

    pthread_mutex_t mtx;
};

```

class Vehicle {

public:

```

    Vehicle(Storage* s, std::vector<BoilerRemote*>& bs, int startX, int startY, int id)
        : storage(s), boilers(bs), vehicleId(id) {
        pthread_mutex_init(&moveMtx, NULL);

        vehicleRect = Rect(startX, startY, 25, 15, 0, id == 0 ? RGB(50, 100, 200) :
        RGB(200, 100, 50));

        Show(vehicleRect);
    }

    ~Vehicle() { pthread_mutex_destroy(&moveMtx); }

```

```

static void* runHelper(void* arg) { return ((Vehicle*)arg)->runThread(); }

```

```

void* runThread() {
    int i = vehicleId;

```

```

while (1) {

    int fuel = storage->getFuelType();

    printf("[Vehicle %d] carrying fuel %d to boiler %d\n", vehicleId+1, fuel, i+1);

    if (boilers[i]->isLowFuelOrEmpty()) {

        moveTo(storage->getX(), storage->getY()-50, boilers[i]->getX(), boilers[i]-
>getY()-50);

        while (!boilers[i]->isEmpty()) { usleep(500000); }

        boilers[i]->refuel(fuel);

        moveTo(boilers[i]->getX(), boilers[i]->getY()-50, storage->getX(), storage-
>getY()-50);

    }

    i = (i+1) % boilers.size();

    usleep(2000000);

}
}

```

```

void refreshDisplay() { Show(vehicleRect); }

```

private:

```

void moveTo(int sx, int sy, int ex, int ey) {

    pthread_mutex_lock(&moveMtx);

    int steps = 30;

    int dx = (ex - sx) / steps;

    int dy = (ey - sy) / steps;

    MoveTo(sx, sy, vehicleRect);

    for (int s=0; s<steps; s++) {

        Move(vehicleRect, dx, dy);

        Fill(vehicleRect, vehicleId==0 ? RGB(50, 100, 200) : RGB(200, 100, 50));
    }
}

```

```

        usleep(40000);
    }
    pthread_mutex_unlock(&moveMtx);
}

Storage* storage;
std::vector<BoilerRemote*> boilers;
int vehicleId;
int vehicleRect;
pthread_mutex_t moveMtx;
};

int main() {
    ConnectGraph();

    int titleBg = Rect(250, 20, 200, 40, 1, RGB(100, 100, 200));
    int electricPlantText = Text(280, 40, "ELECTRIC PLANT", RGB(255, 255, 255));
    Show(titleBg);
    Show(electricPlantText);

    Storage storage(50, 200);
    BoilerRemote br1(0, "127.0.0.1", 8080);
    BoilerRemote br2(1, "127.0.0.1", 8080);
    BoilerRemote br3(2, "127.0.0.1", 8080);
    BoilerRemote br4(3, "127.0.0.1", 8080);

    std::vector<BoilerRemote*> boilers;
    boilers.push_back(&br1);

```

```

boilers.push_back(&br2);
boilers.push_back(&br3);
boilers.push_back(&br4);

Vehicle v1(&storage,boilers,20,20,0);
Vehicle v2(&storage,boilers,60,20,1);

int infoText = Text(50, 350, "Press ESC to exit", RGB(150, 150, 150));
Show(infoText);

pthread_t t1,t2;
pthread_create(&t1,NULL,Vehicle::runHelper,&v1);
pthread_create(&t2,NULL,Vehicle::runHelper,&v2);

int key;
while (1) {
    key = InputChar();
    if (key == 27) break;
    storage.refreshDisplay();
    v1.refreshDisplay();
    v2.refreshDisplay();
    usleep(10000);
}

pthread_join(t1,NULL);
pthread_join(t2,NULL);
CloseGraph();
return 0; }

```