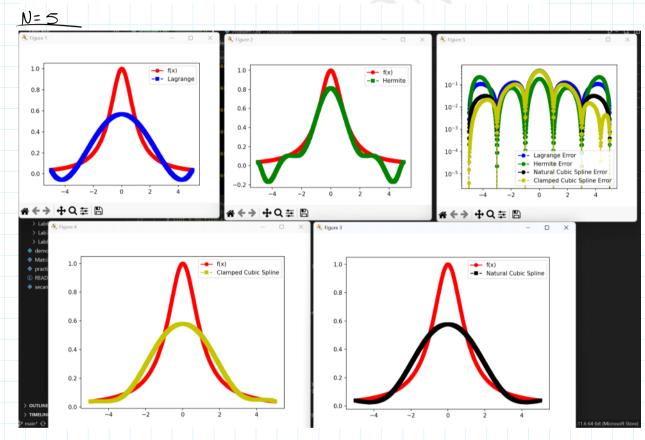
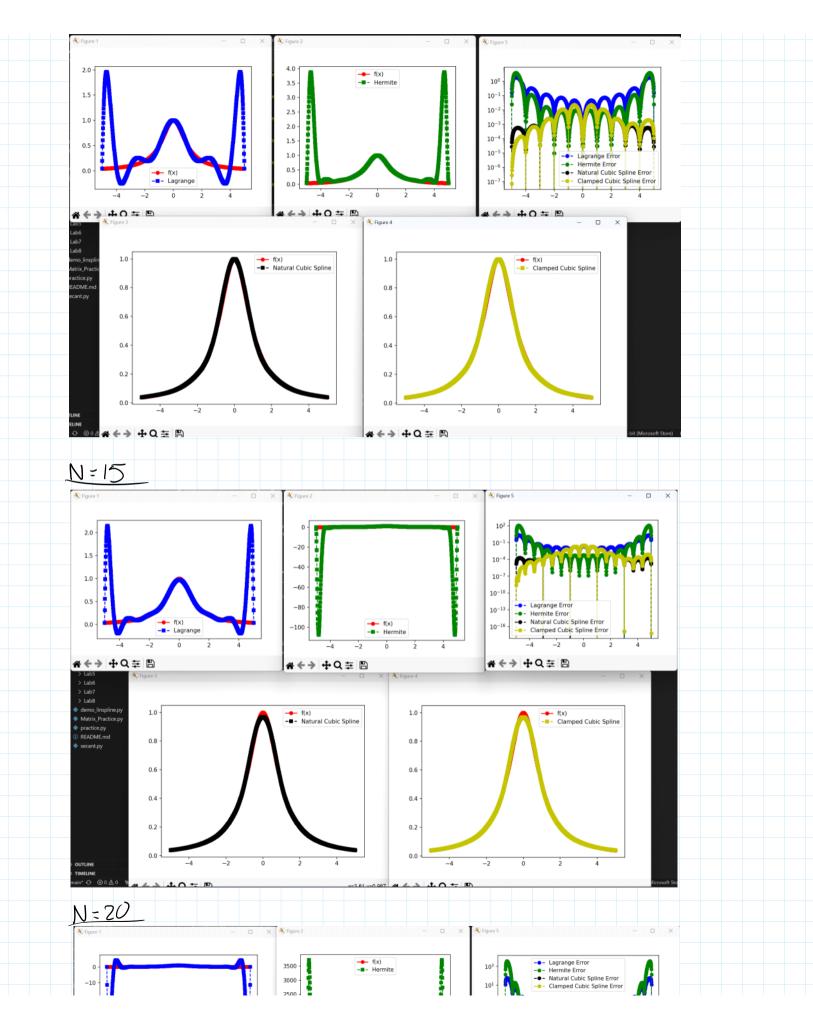
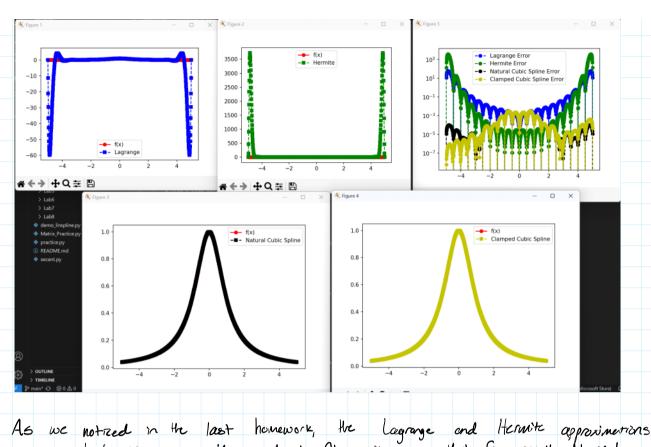
- 1. Consider the task of interpolating the function $f(x) = \frac{1}{1+x^2}$ on the interval [-5,5]. Using equispaced nodes with n = 5, 10, 15 and 20, interpolate the function using the methods below:
 - (a) Lagrange interpolation.
 - (b) Hermite interpolation.
 - (c) Natural Cubic spline.
 - (d) Clamped Cubic spline.

Which method performs best? Do you have an intiution why?







As we notized in the last homework, the lagrange and Iterative approximations experience high error near the endpoints. Also, it appears that for small N values, the Hermite approximation most closely marches the shape of F(x).

2.) 2. Repeat the experiment from the previous problem but with Chebychev nodes. How does this impact the performance of the different interpolation techniques?

On an interval [a,6], the Chebyshev nodes are given by:

$$X_j = \frac{1}{2}(\alpha+b) + \frac{1}{2}(b-\alpha) \cdot \cos\left(\frac{Z_{j-1}}{2n}\pi\right), \text{ for } j=1,...,n$$

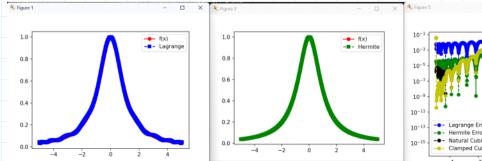
In Python, over the interval [-5,5], the nodes ever given as follows:

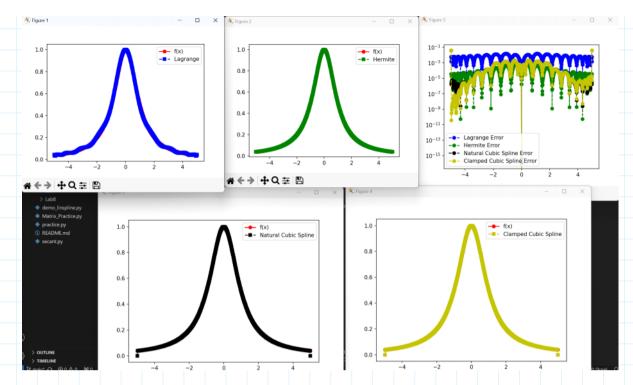
Note: as mentioned in the class announcement, the ordering of the Chelogohev nodes

need to be flipped for the cubic spline interpolations.

j = np.array(range(1,N+2))
xint = 5*np.cos(np.pi*(2*j -1)/(2*(N+1)))
xint = np.flip(xint)

Using the above nodes and the same code as used above, I found the following for N = 15:





As we found before, the use of the Chebyshev nades helped to decreuse the error at the endpoints for the Lagrange and Iterative Approximations. It appears that it did add one point with larger error right at the end of the cubic spline approximations. This could be a result of the conditioning of the splines and how the endpoints are defined.

3.) 3. Consider the task of approximating a periodic function such as $f(x) = \sin(10x)$ on the interval $[0, 2\pi]$ using the cubic spline. How do you modify the end point conditions on the coefficients so that the spline is naturally periodic?

To ensure that the spline will properly approximate only finetics f(k), we observedly specify that the spline is continuous, and that the first two observed of the spline are continuous. That is, we need to setting the following conditions:

$$S_{i}(x_{i}) = f(x_{i})$$

$$S_{i}(x_{i+1}) = f(x_{i+1})$$

$$S_{i}(x_{i+1}) = S_{i+1}(x_{i+1})$$

$$S_{i}(x_{i+1}) = S_{i+1}(x_{i+1})$$

To ensure that the spline is necturally periodic, we wast aso satisfy the condition that the endpoints, and their derivatives, are also equivalent. That is to say:

For some S_i evaluated at X_i , where i = 0, 1, 2, ..., n $S_o(x_o) = S_n(x_n)$, $S_o'(x_o) = S_n'(x_n)$, and $S_o''(x_o) = S_n''(x_n)$