

- 1.) 1. Find the least squares solution to the overdetermined linear system

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

Theorem The vector \bar{x} that minimizes $\|A\bar{x} - b\|_2$ where $A \in \mathbb{R}^{n \times m}$, $n > m$ is given by the solution of $A^T A \bar{x} = A^T b$

$$\therefore \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \Rightarrow \boxed{\begin{matrix} u = 1 \\ v = 1/2 \end{matrix}}$$

- 2.) 2. Find the vector
- x
- that minimizes the quantity
- $E^2 = b_1^2 + 4b_2^2 + 25b_3^2 + 9b_4^2$
- , when it holds that

$$\begin{bmatrix} 1 & 3 \\ 6 & -1 \\ 4 & 0 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$$

Hint: When we solve a linear system of equations $Ax = b$, multiplication from the left with a nonsingular matrix will leave the solution unchanged. This is **not** the case when finding the least squares solution to an overdetermined system. Exploit this and multiply the system above with a suitable diagonal matrix, so that the problem becomes a regular least squares problem (for which we can apply the normal equation approach.)

Given that we want to minimize the quantity $E^2 = b_1^2 + 4b_2^2 + 25b_3^2 + 9b_4^2$, it would seem suitable to multiply the system by the diagonal matrix where the entries are the coefficients of E .

$$\text{i.e. } E = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 5 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

$$\therefore \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 5 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 6 & -1 \\ 4 & 0 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 5 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} b_1 \\ 2b_2 \\ 5b_3 \\ 3b_4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 \\ 12 & -2 \\ 20 & 0 \\ 6 & 21 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \\ 15 \\ 12 \end{bmatrix} = \begin{bmatrix} b_1 \\ 2b_2 \\ 5b_3 \\ 3b_4 \end{bmatrix}$$

Using the Theorem from problem 1, we can use the least squares method to solve

$$\begin{bmatrix} 1 & 12 & 20 & 6 \\ 3 & -2 & 0 & 21 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 12 & -2 \\ 20 & 0 \\ 6 & 21 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & 12 & 20 & 6 \\ 3 & -2 & 0 & 21 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \\ 15 \\ 12 \end{bmatrix}$$

$$\begin{bmatrix} 581 & 105 \\ 105 & 454 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 421 \\ 247 \end{bmatrix}$$

Now solving this linear system for \bar{x} using $\bar{x} = A^{-1}b$,

we arrive at $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0.6536 \\ 0.3929 \end{bmatrix} \Rightarrow \boxed{x_1 = 0.6536, x_2 = 0.3929}$

MATLAB Code:

```
4 %% Main Script
5 A = [1 3;
6      6 -1;
7      4 0;
8      2 7];
9 C = [1 2 3 4]';
10
11 E = [1 0 0 0;
12      0 2 0 0;
13      0 0 5 0;
14      0 0 0 3];
15
16 Aadj = E*A
17 Cadj = E*C
18
19 Atrans = Aadj';
20
21
22 M = Atrans*Aadj
23 Cnew = Atrans*Cadj
24
25 M\Cnew
```

MATLAB Output:

```
Aadj =
     1     3
    12    -2
    20     0
     6    21

Cadj =
     1
     4
    15
    12

M =
    581    105
    105    454

Cnew =
    421
    247

ans =
    0.6536
    0.3929
```

3.) 3. If a function is identically zero over an interval, all its derivatives must also be identically zero over the same interval. Based on this observation:

- Prove that $\{1, x, x^2, \dots, x^n\}$ are linearly independent.
- Show that the function set

$$\{1, \cos(x), \cos(2x), \dots, \cos(nx), \sin(x), \dots, \sin(nx)\}$$

is linearly independent (also over any interval).

(a) Prove that $\{1, x, x^2, \dots, x^n\}$ are linearly independent

Take the Wronskian of the above vector:

$$W = \begin{vmatrix} 1 & x & x^2 & x^3 & \dots & x^n \\ 0 & 1 & 2x & 3x^2 & \dots & nx^{n-1} \\ 0 & 0 & 2 & 6x & \dots & n(n-1)x^{n-2} \\ 0 & 0 & 0 & 6 & \dots & n! \end{vmatrix}$$

$$W \text{ is a triangular matrix} \Rightarrow \det(W) = \prod_{i=1}^n w_{ii}$$

$$\therefore \det(W) = n!(n-1)! \dots 1 \neq 0$$

$$W = \begin{bmatrix} 0 & 0 & 2 & 6 \times n(n-1)x^{n-2} \\ 0 & 0 & 0 & 6 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & n! \end{bmatrix}$$

$$\therefore \det(W) = n!(n-1)! \dots 1 \neq 0$$

Since $\det(W) \neq 0$, the set is linearly independent.

$$(b) \{1, \cos(x), \cos(2x), \dots, \cos(nx), \sin(x), \sin(2x), \dots, \sin(nx)\}$$

To show linear independence, we have to show that

$$a_0 \cos(0x) + a_1 \cos(x) + a_2 \cos(2x) + \dots + a_n \cos(nx) + b_0 \sin(0x) + b_1 \sin(x) + \dots + b_n \sin(nx) \equiv 0$$

Taking n derivatives of the above functions will result in the multiplication of each term by n^n i.e. $a_1 \cdot 1^n \cos(x) + a_2 \cdot 2^n \cos(2x) + \dots + a_n n^n \cos(nx) + \dots + b_n n^n \sin(nx)$ which would result in

$$a_n \cos(nx) + b_n \sin(nx) \equiv 0$$

and if we create the Wronskian:

$$\begin{bmatrix} \cos(nx) & \sin(nx) \\ -n \sin(nx) & n \cos(nx) \end{bmatrix}, \det(W) = n \cos^2(nx) - (-n \sin^2(nx)) = n(\cos^2(nx) + \sin^2(nx)) = n \neq 0$$

\therefore these are linearly independent vectors.

Extending this from the $n-1, n-2, \dots, 1, 0$ satisfies

$$a_0 \cos(0x) + a_1 \cos(x) + a_2 \cos(2x) + \dots + a_n \cos(nx) + b_0 \sin(0x) + b_1 \sin(x) + \dots + b_n \sin(nx) \equiv 0,$$

meaning that $\{1, \cos(x), \cos(2x), \dots, \cos(nx), \sin(x), \sin(2x), \dots, \sin(nx)\}$ is indeed a linearly independent set of vectors.

4.) 4. Prove the three-term recursion formula for orthogonal polynomials:

$$\phi_k(x) = (x - b_k)\phi_{k-1}(x) - c_k\phi_{k-2}(x)$$

where

$$b_k = \frac{\langle x\phi_{k-1}, \phi_{k-1} \rangle}{\langle \phi_{k-1}, \phi_{k-1} \rangle} \quad c_k = \frac{\langle x\phi_{k-1}, \phi_{k-2} \rangle}{\langle \phi_{k-2}, \phi_{k-2} \rangle}$$

Hint: Since $\phi_k(x)$ is a polynomial of degree k and of the form $\phi_k = x^k + \{\text{lower order terms}\}$, we can clearly select b_k and c_k so that the right hand side (RHS) of (1) matches $\phi_k(x)$ for powers x^k, x^{k-1} and x^{k-2} . We have no obvious reason to expect that the two sides will match the other lower order terms. Hence, we would expect to need to include a lot more terms in the RHS to get the two sides to become equal:

$$\phi_k(x) = (x - b_k)\phi_{k-1}(x) - c_k\phi_{k-2}(x) - \{a_{k-3}\phi_{k-3}(x) + a_{k-4}\phi_{k-4}(x) + \dots + a_0\phi_0(x)\} \quad (1)$$

We now need to show that all these a 's are in fact zero. To show that $a_j = 0, j \leq k-3$, we form the scalar product of (1) with $\phi_j(x)$ for $j = 0, \dots, k-1$. You need to show that everything in (1) apart from $a_j \langle \phi_j, \phi_j \rangle$ then vanishes, thereby showing that $a_j = 0, j \leq k-3$. After that, it remains to determine the values of b_k and c_k . These coefficients follow by again forming suitable scalar products.

From the hint:

$$\phi_k(x) = (x - b_k)\phi_{k-1}(x) - c_k\phi_{k-2}(x) - \{a_{k-3}\phi_{k-3}(x) + a_{k-4}\phi_{k-4}(x) + a_0\phi_0(x)\}$$

$$\phi_k(x) = (x - b_k)\phi_{k-1}(x) - c_k\phi_{k-2}(x) - \sum_{i=0}^{k-3} a_i \phi_i(x)$$

$$\phi_k(x) = (x - b_k) \phi_{k-1}(x) - c_k \phi_{k-2}(x) - \sum_{i=0}^{k-3} a_i \phi_i(x)$$

To show $\alpha_j = 0$, $j \leq k-3$, form a scalar product of ϕ_k and ϕ_j , for $j = 0, \dots, k-1$

$$\therefore \langle \phi_k, \phi_j \rangle = \langle \phi_{k-1}, x \phi_j \rangle - b_k \langle \phi_{k-1}, \phi_j \rangle - c_k \langle \phi_{k-2}, \phi_j \rangle - \sum_{i=0}^{k-3} a_i \langle \phi_i, \phi_j \rangle, \quad j = 0, \dots, k-3$$

$x \phi_j(x)$ is a polynomial of degree $j+1$, so we can rewrite as $x \phi_j(x) = \sum_{i=0}^{j+1} d_i \phi_i(x)$

$$\therefore 0 = \sum_{i=0}^{j+1} d_i \langle \phi_i, \phi_{k-1} \rangle - 0 - 0 - a_j \langle \phi_j, \phi_j \rangle, \quad j \leq k-3$$

$j+1 \leq k-2 \Rightarrow$ every term w/in the sum is 0

$$\therefore 0 = a_j \langle \phi_j, \phi_j \rangle, \quad j \leq k-3$$

Now we can solve for b_k and c_k .

Take the inner product of ϕ_k and ϕ_{k-1} :

$$\langle \phi_k, \phi_{k-1} \rangle = \langle x \phi_{k-1}, \phi_{k-1} \rangle - b_k \langle \phi_{k-1}, \phi_{k-1} \rangle - c_k \langle \phi_{k-2}, \phi_{k-1} \rangle$$

$$0 = \langle x \phi_{k-1}, \phi_{k-1} \rangle - b_k \langle \phi_{k-1}, \phi_{k-1} \rangle - 0$$

$$\Rightarrow b_k = \frac{\langle x \phi_{k-1}, \phi_{k-1} \rangle}{\langle \phi_{k-1}, \phi_{k-1} \rangle} \quad \checkmark$$

Take the inner product of ϕ_k and ϕ_{k-2} :

$$\langle \phi_k, \phi_{k-2} \rangle = \langle x \phi_{k-1}, \phi_{k-2} \rangle - b_k \langle \phi_{k-1}, \phi_{k-2} \rangle - c_k \langle \phi_{k-2}, \phi_{k-2} \rangle$$

$$0 = \langle x \phi_{k-1}, \phi_{k-2} \rangle - 0 - c_k \langle \phi_{k-2}, \phi_{k-2} \rangle$$

$$\Rightarrow c_k = \frac{\langle x \phi_{k-1}, \phi_{k-2} \rangle}{\langle \phi_{k-2}, \phi_{k-2} \rangle} \quad \checkmark$$

5.) 5. One of the many formulas for computing the Chebychev polynomials $T_n(x)$ is

$$T_n(x) = \frac{1}{2} \left(z^n + \frac{1}{z^n} \right), \quad (2)$$

where z is implicitly defined through x via $x = \frac{1}{2} \left(z + \frac{1}{z} \right)$. Confirm that the formula (2) indeed generates the same polynomials as the standard definition of the Chebychev polynomials.

Hint: One way would be to verify that it produces the correct result for T_0 and T_1 and that it satisfies the 3 term recursion.

$$T_n(x) = \frac{1}{2} \left(z^n + \frac{1}{z^n} \right), \quad \text{where } z \text{ is defined implicitly through } x \text{ via } x = \frac{1}{2} \left(z + \frac{1}{z} \right)$$

The standard 3-term recursion for the Chebychev polynomials is defined as

$$T_0 = 1$$

$$T_0 = 1$$

$$T_1 = x$$

$$T_{n+1}(x) = 2x \cdot T_n(x) - T_{n-1}(x) \Rightarrow T_{n+1}(x) + T_{n-1}(x) = 2x \cdot T_n(x)$$

Given formula (2) as defined above, implicit definition of x

$$\frac{1}{z} \left(z^{n+1} + \frac{1}{z^{n+1}} \right) + \frac{1}{z} \left(z^{n-1} + \frac{1}{z^{n-1}} \right) = z \cdot \frac{1}{z} \left(z + \frac{1}{z} \right) \cdot \frac{1}{z} \left(z^n + \frac{1}{z^n} \right)$$

$$\frac{1}{z} \left[z^n \cdot z^1 + z^{-n} \cdot z^{-1} + z^n \cdot z^{-1} + z^{-n} \cdot z^1 \right] = \frac{1}{z} \left[z^1 \cdot z^n + z^{-1} z^n + z^1 z^{-n} + z^{-1} z^{-n} \right]$$

$$\frac{1}{z} \left[z^{n+1} + z^{-(n+1)} + z^{n-1} + z^{-(n-1)} \right] = \frac{1}{z} \left[z^{n+1} + z^{-(n+1)} + z^{n-1} + z^{-(n-1)} \right] \quad \checkmark$$

Therefore, formula (2) as given in the problem statement indeed satisfies the standard 3-term recursion.