



AMERICAN
UNIVERSITY of BEIRUT
MAROUN SEMAAN FACULTY OF
ENGINEERING & ARCHITECTURE

American University of Beirut
Maroun Semaan Faculty of Engineering and Architecture
Department of Electrical and Computer Engineering

EECE 321: Computer Organization
Datapath Design Project
Floating Point Unit

Professor: Mazen Saghir

Team Members: Serena Stephan, Tony Abi Haidar, Joud Senan

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1. The Tool and Prompts Used to Implement, Refine, and Test the FPU:

For the Floating-Point Unit (FPU) implementation, we used Xilinx Vivado 2023.1. The editing tool used is Vivado built-in text editor, Vivado Synthesis for synthesis, and Vivado XSim Simulator for simulation.

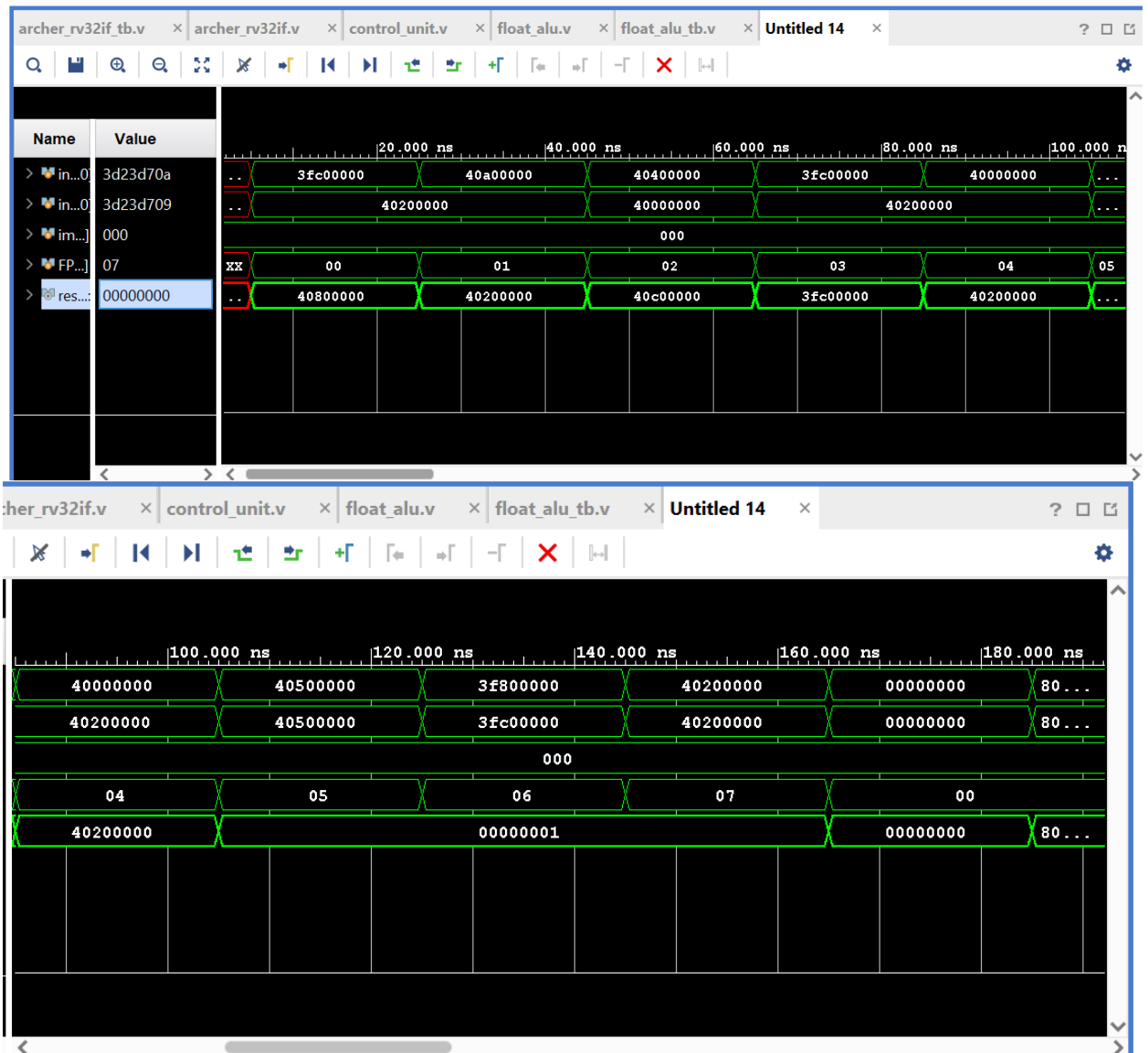
Description of our Approach:

- We modularized the FPU into blocks: fpu.v containing add_fp, sub_fp, mul_fp, max_fp, min_fp, le_fp, lt_fp, and eq_fp.
- We refined floating-point addition and multiplication to handle corner cases: exact zeros, NaNs, $\pm\infty$, and normalized/subnormal numbers.
- For testing the fpu code, we got a Verilog Testbench generated by ChatGPT (fpu_tb.v) providing hexadecimal IEEE-754 inputs and verified outputs against expected values.
- We revised all the other codes to check for consistency including: mux2to1, sram, lmb, branch_cmp, alu, immgen, rom, add4, and pc.
- We designed a dedicated Control Unit (control_unit.v) to generate all necessary control signals for both integer and floating-point instructions. It dynamically detects floating-point operations based on the funct7 and funct3 fields and issues the appropriate FPUOp, FPStart, FPRegWrite, and FPToReg signals alongside classical RV32I control signals.
- We implemented two register files (regfile.v and float_regfile.v) to separately manage general-purpose integer registers and floating-point registers. The integer register file ensures x0 remains hardwired to zero, while the floating-point register file handles independent floating-point storage without enforcing f0 = 0, as per RISC-V convention and as instructed in this project.
- During simulation, the control unit properly selects whether operations were integer-based or floating-point-based, and the datapath dynamically routes reads/writes to either the integer or float register file accordingly.
- We tested the fpu logic using a standalone testbench (mentioned above).
- **Test Cases:**

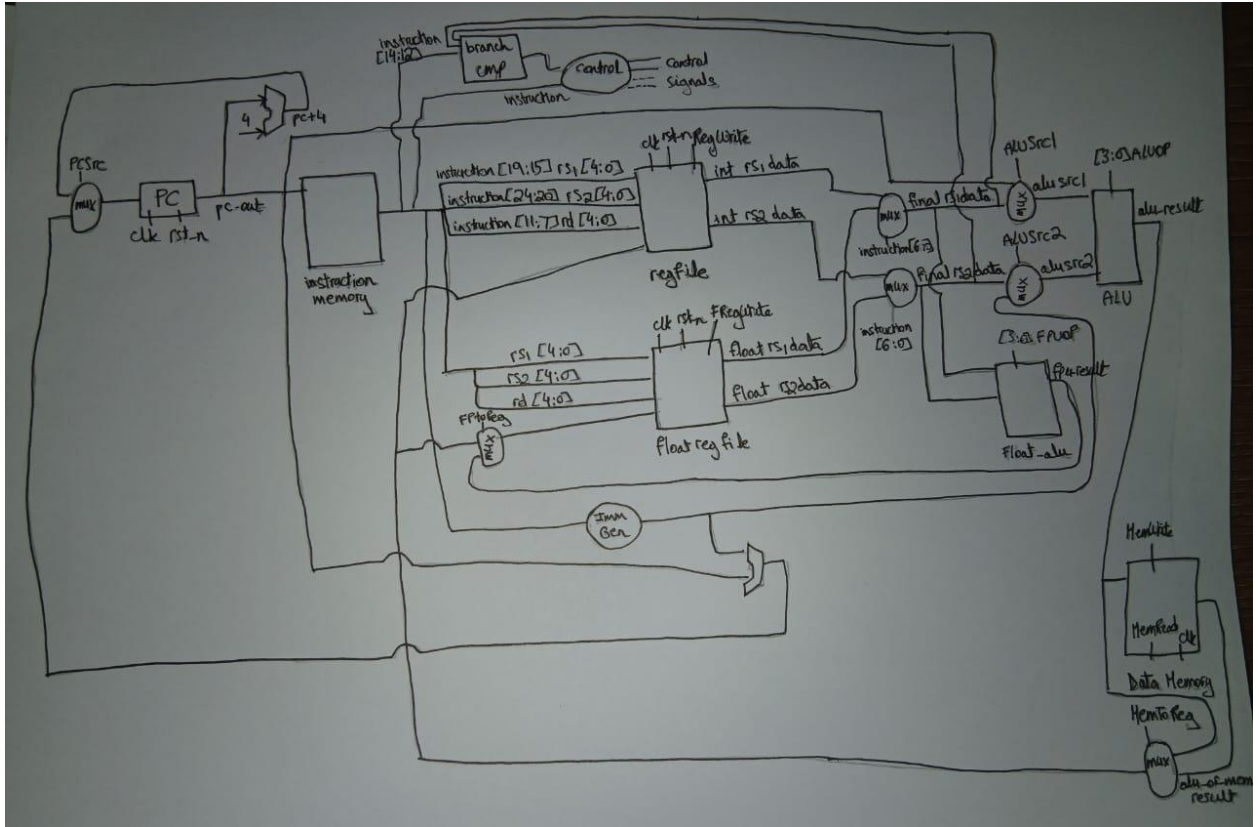
| Operation | Inputs | Output |
|--------------------|--------------|----------|
| Addition | 1.1 + 1.15 | 40800000 |
| Subtraction | 5.0 - 2.5 | 40200000 |
| Multiplication | 3.0 * 2.0 | 40c00000 |
| Min | (1.5, 2.5) | 3fc00000 |
| Max | (2.0, 2.5) | 40200000 |
| Equality Check | 3.25 == 3.25 | 1 |
| Less Than | 1.0 < 1.5 | 1 |
| Less Than or Equal | 2.5 <= 2.5 | 1 |
| Special Case | +0.0 + +0.0 | 00000000 |
| Special Case | -0.0 + -0.0 | 80000000 |
| Special Case | +Inf + +Inf | 7f800000 |
| Special Case | +Inf + -Inf | 7fc00000 |
| Special Case | NaN + 2.0 | 7fc00000 |

| | | |
|-------------------------------|-----------------------|----------|
| Special Case | $0 * 0$ | 00000000 |
| Special Case | $\text{Inf} * 0$ | 7fc00000 |
| Special Case | $+0.0 == -0.0$ | 1 |
| Add Small Fractions | $1.1 + 1.15$ | 3fa00000 |
| Subtract tiny numbers | | 2f000000 |
| MUL tiny fraction | $0.7 * 1.2$ | 3f570a3d |
| MIN negative small | $(-0.2, -0.5)$ | bf000000 |
| MAX tiny positive vs negative | $(1e-7, -1e-7)$ | 33d6bf95 |
| LE close decimals | $0.04 \leq 0.0399999$ | 0 |

2. *Vivado simulator waveforms demonstrating successful testing of FPU functionality including operations involving exact zero, $\pm\infty$, and NaN:*



3. Detailed Datapath Block Diagram:



4. Short Description of Input Ports, Output Ports and Block Functionality for New/Modified Datapath Blocks:

Control Unit:

Input Ports:

- instruction (32 bits): Fetched instruction word containing opcode, funct3, funct7, rs1, rs2, rd...
- BranchCond (1 bit): Result of branch comparison (1 = branch taken, 0 = branch not taken).

Output Ports:

- Jump (1 bit): High when instruction is jal or jalr, indicating an unconditional jump.
- Lui (1 bit): High is the instruction is lui.
- PCSrc (1 bit): Selects program counter source: (branch target / jump address) or PC+4 (sequential).
- RegWrite (1 bit): Enables write operation in the integer register file.
- ALUSrc1 (1 bit): Selects first ALU operand: PC (ALUSrc1=1) or register data (ALUSrc1=0).

- ALUSrc2 (1 bit): Selects second ALU operand: immediate (ALUSrc2=1) or register data (ALUSrc2=0).
- ALUOp (4 bits): The opcode which specifies which ALU operation to perform.
- MemWrite (1 bit): Enables memory write.
- MemRead (1 bit): Enables memory read.
- MemToReg (1 bit): Selects memory output as data to write back to register file.
- FPRegWrite (1 bit): Enables write operation in the floating-point register file.
- FPToReg (1 bit): Selects floating-point load result for writing back into the register file.
- FPUOp (4 bits): The opcode which specifies which floating point operation to perform.
- FPStart (1 bit): Start signal for floating-point operations.

Block Functionality:

The Control Unit decodes the 32-bit instruction input based on the opcode field and generates all necessary control signals for the datapath. It uses BranchCond signal for branching instructions and sets PCSrc accordingly. It handles arithmetic and logic instructions, memory instructions, jump instructions, and floating-point instructions.

○ ***Floating-Point Unit:***

Input Ports:

inputA (32 bits): First input operand in IEEE-754 single-precision floating-point format.

inputB (32 bits): Second input operand in IEEE-754 single-precision floating-point format.

imm (12 bits): Immediate field.

FPU_OP (5 bits): Control signal selecting the floating-point operation.

Output Ports:

result (32 bits): Computed result of the selected floating-point operation in IEEE-754 format.

Block Functionality:

The FPU performs single-precision (32-bit) floating-point operations based on IEEE-754 standard. Operations supported are the following: addition, subtraction, multiplication, minimum, maximum, equal comparison, less than comparison, and less than or equal comparison. The FPU extracts the sign, exponent, and mantissa from both input operands. It can also handle special cases like addition and multiplication involving zero, infinity handling, and NaN for invalid operations.

The output result is formatted back to the IEEE-754 single-precision 32-bit floating-point format.

○ ***Top-Level Datapath (archer_rv32if.v):***

Input Ports:

- clk (1 bit): System clock signal.
- rst_n (1 bit): Active-low reset signal to reset the processor components.

Block Functionality:

It implements a single cycle RV32IF processor with support for floating-point operations. It fetches instructions from Instruction Memory, the rom, decodes them using the control unit, and processes integer and floating-point operations through the separate ALU and FPU units.

We included 2 register files: regfile for integer registers and float_regfile for floating-point registers.

lmb, connected to sram, handles load and store operations.

branch_cmp and control unit handle branch decisions.

The program counter value (pc) is managed by branching, jumping, or sequential incrementation (add4).

○ ***Floating-Point Register File:***

Input Ports:

- clk (1 bit): clock signal for synchronous writes.
- rst_in (1 bit): active-low reset signal to initialize all floating-point registers.
- FRegWrite (1 bit): write enable signal for the floating-point register file.
- rs1 (5 bits): source register 1 address.
- rs2 (5 bits): source register 2 address.
- rd (5 bits): destination register address.
- datain (32 bits): data to be written into the register file at address rd.

Output Ports:

- regA (32 bits): data read from register at address rs1.
- regB (32 bits): data read from register at address rs2.

Block Functionality:

It implements a 32-entry floating-point register file. When `rst_n` is de-asserted, all floating-point registers are cleared to 0. There is no special handling to prevent writing `f0` unlike `x0` in regfile which is for integers.

Note: We added to `archerdefs` the definitions that we needed in these new files accounting for floating-point operations.

5. *Description of the assembly code used to test the floating-point instructions and the corresponding Vivado simulator waveforms demonstrating successful tests:*

- We also assembled RV32I assembly code (`RV32IFtest.s`) and loaded it into the ROM, executing floating-point instructions at runtime to verify FPU behavior inside the system. Here are the details:

Floating-Point Test Program:

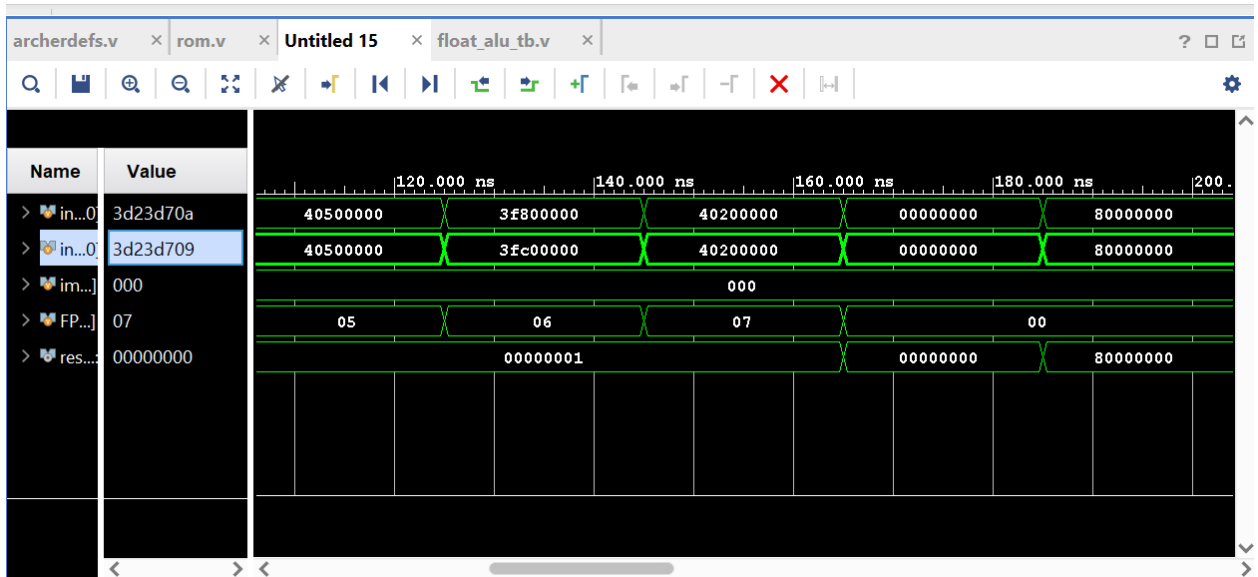
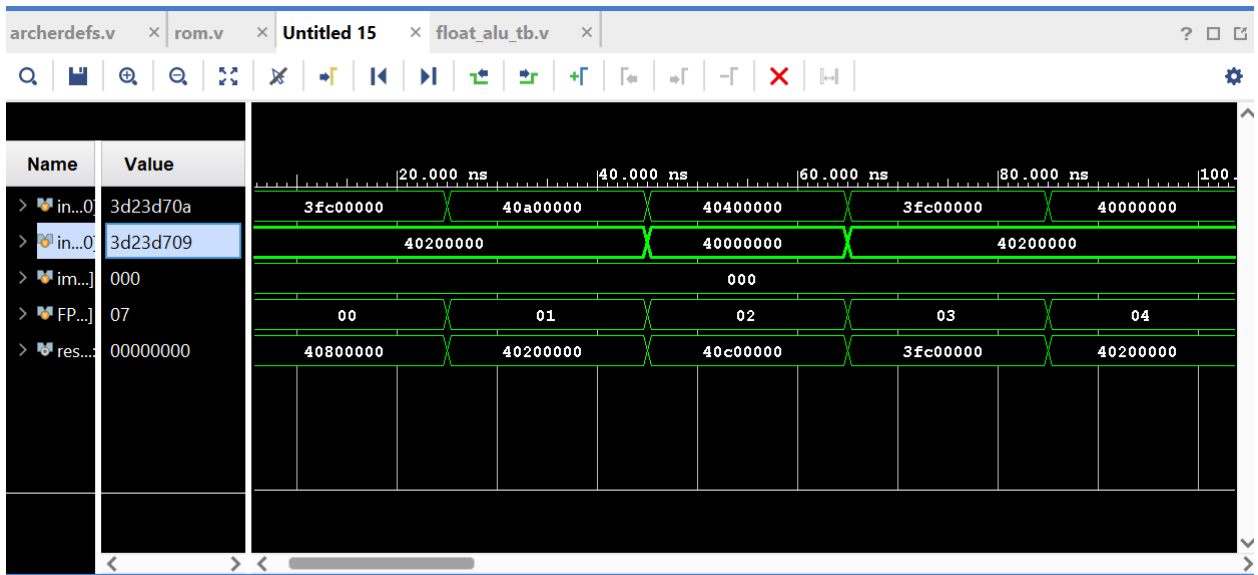
A test program was developed to validate the floating-point instructions in the expanded RV32IF datapath. It includes:

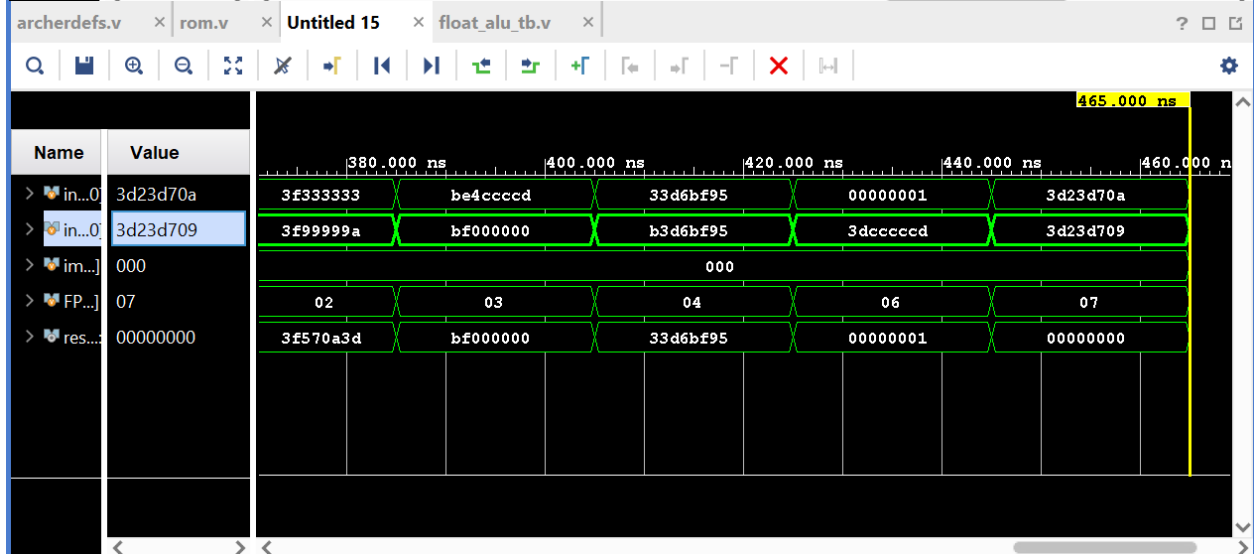
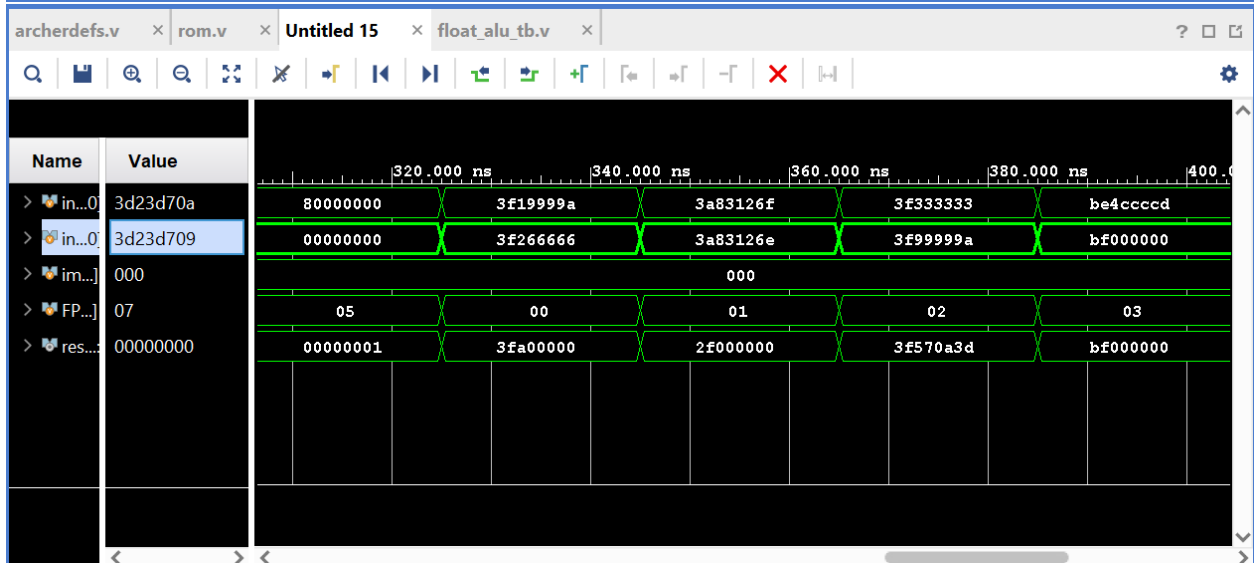
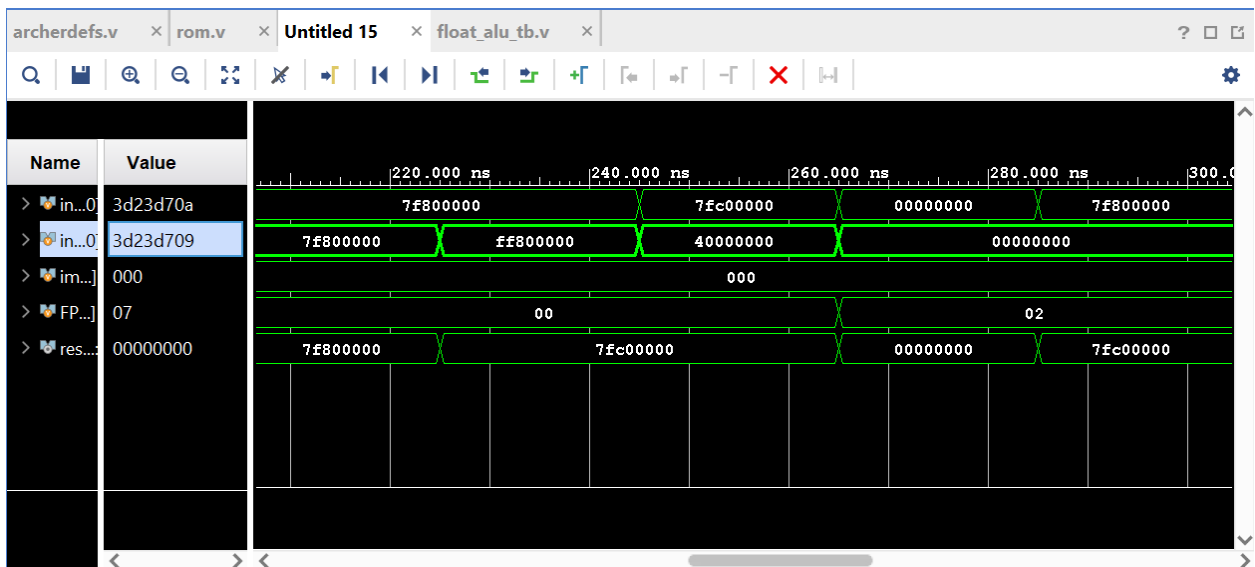
- **RV32IFtest.s:** RISC-V assembly code that tests floating-point operations across different cases, including zeros, NaNs, and infinities.
- **RV32IFtest.o:** Machine code generated from the assembly file using Venus Simulator.
- **RV32IF_test_rom.v:** A Verilog ROM model that stores the machine code for processor simulation.

Tools Used:

- Venus Simulator
- Vivado software

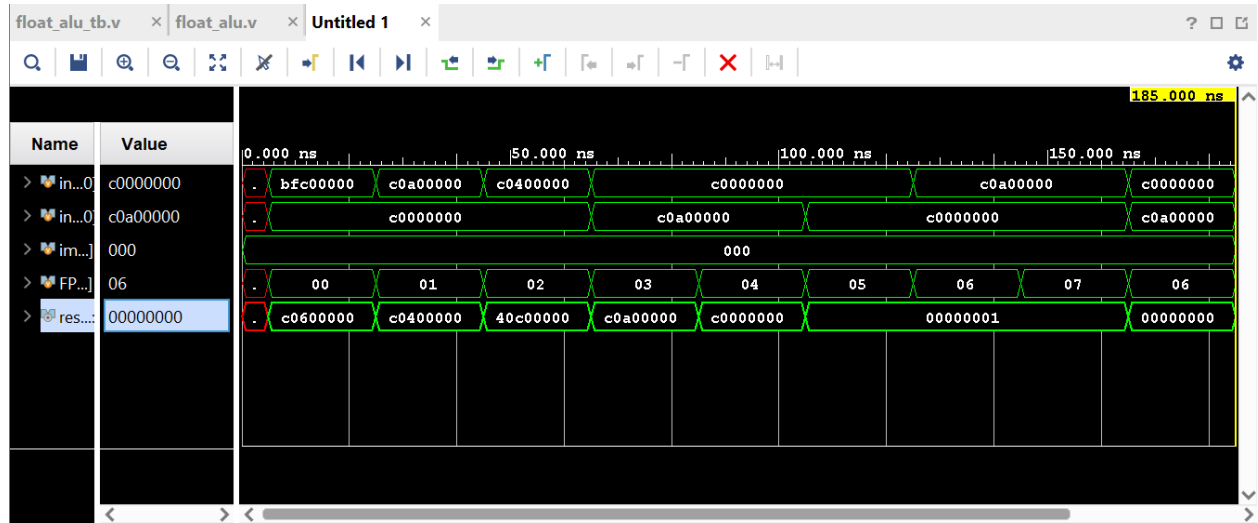
Waveforms:





One more thing:

We checked if our fpu can handle operations on negative numbers in a separate test bench, and it worked perfectly! Below is a screenshot of the correctness:



6. Contributions of Each Team Member:

Joud Senan:

- Wrote control_unit.v and archer_rv32if.v
- Wrote the details regarding the implementation and content of the codes in the report.

Serena Stephan:

- Wrote the code of “float_alu”
- Sketched a diagram of the datapath

Tony Abi Haidar:

- Test program (all three versions)
- Modified: archerdefs.v, float_regfile.v

Group contributions:

- Testbenches
- Integrating files
- Debugging