Requirements

To configure the hardware and software necessary to connect a controller to a host PC. The host PC must support the motion controls to be sent over wireless to a BeagleBone Black. Supported controls include thrust, yaw, pitch and roll. The host PC must display assign specific controls to adjust these measurements and display the current value for all controls.

Hardware Architecture Controller Layout



Homework 4 – Motion Controls

Parts List

- Sony PlayStation 3 Controller
- Asus Eee PC 1215b
 - o Broadcom Azurewave AW-CE123H Wireless/Bluetooth Adapter

Software Implementation

Python along with additional libraries are used as the development language for implementing the controls. The PyGame library allows interaction with an attached joystick and supports the Sony PS3 controller. PyGTK library along with the Glade RAD tool are used to create and manipulate the graphical user interface (GUI) that display the controller values. The SciPy library is used in order to map the controller analog stick axes values from the range -1 to 1 to the range -100 to 100.

The program consists of two threads, the main GTK thread that displays the GUI and a thread that updates GUI labels representing the control values. The controller thread that handles retrieving the values from the controller also stores the labels from the GUI that are to be updated. Whenever these labels are updated a function is called stating that the controller thread is entering the GTK thread and likewise when the controller thread leaves the GTK thread. An exception try-catch clause surrounds the loop block since occasionally the controller needs to be reinitialized to continue retrieving values through PyGame.

The controller thread handles retrieving values through a continuous loop. For the thrust, yaw, pitch, and roll, the thread retrieves the raw value from the controller, maps the value to the correct range, and then sets the label value. There are two states for the controls, armed and disarmed. When disarmed the values are fixed at 0 even if the controller is being used. When armed the control values are updated based on the state of the controller.

The analog sticks do not always give an absolute zero value when centered. Therefore, the value retrieved is first checked against a minimum deviation of .0005 from zero. If the value is found to be within this deviation the control label is updated to zero. The trim values are set to increment by .1 whenever pressed during each controller thread iteration. Trim values have a maximum and minimum threshold of 100 and -100 respectively. This value may be reset to zero by pressing the correct button described in the Controller Layout section on the previous page.

```
1 '''
 2 Homework 4 - Motion Controls
 3 <u>Joseph</u> DiMarino
4 Retrieves values from an attached <u>Playstation</u> 3 controller and maps
 5 to values used to represent Quad-Copter controls. Displays the values
6 of the controls through a Graphical User Interface.
 7 ' '
8 import gtk
9 import pygame, sys, time
10 from pygame.locals import *
11 from scipy.interpolate import interp1d
12 import pygtk
13 import threading
14 import gobject
15 pygtk.require('2.0')
16
17# Reads in values from the attached controller
18 def readController(ControllerThread):
19
      pygame.init()
20
      pygame.joystick.init()
21
      joystick = pygame.joystick.Joystick(0)
22
      joystick.init()
23
      armed = False
24
25
      # Refresh values from controller every 100th of a second
26
      interval = 0.01
27
      # get count of joysticks=1, axes=27, buttons=19 for DualShock 3
28
29
      numJoysticks = pygame.joystick.get_count()
30
      numAxes = joystick.get_numaxes()
31
      numButtons = joystick.get_numbuttons()
32
33
      # Initialize values and display control specs
34
      ControllerThread.initValues(numButtons, numJoysticks, numAxes)
35
36
      # Function that maps controller values to the range of [-100, 100]
37
      valueMap = interp1d([-1,1],[-100,100])
38
39
      resetThrustTrim = False
                                   # L1 pressed, reset thrust trim to 0
                                   # L2 pressed, reset yaw trim to 0
40
      resetYawTrim = False
41
      resetPitchTrim = False
                                   # left analog pressed, reset pitch trim to 0
42
      resetRollTrim = False
                                   # right analog pressed, reset roll trim to 0
43
44
      while ControllerThread.running:
45
          try:
46
               # Arm/Disarm when start/select/ZL/ZR are pressed
47
               if joystick.get button(6) and joystick.get button(7) \
               and joystick.get_button(8) and joystick.get_button(9):
48
49
                   armed = False if armed else True
50
                   time.sleep(1)
               # L1 pressed, reset thrust trim to 0
51
               if joystick.get_button(4):
52
53
                   resetThrustTrim = True
54
               # L2 pressed, reset yaw trim to 0
55
              if joystick.get button(5):
56
                   resetYawTrim = True
57
              # left analog pressed, reset pitch trim to 0
58
              if joystick.get_button(10):
59
                   resetPitchTrim = True
60
              # right analog pressed, reset roll trim to 0
61
               if joystick.get button(11):
                   resetRollTrim = True
62
```

```
63
 64
               # Retrieve axes values
 65
               thrustRaw = -joystick.get_axis(1)
 66
               yawRaw = joystick.get_axis(0)
 67
               pitchRaw = -joystick.get_axis(3)
 68
               rollRaw = joystick.get axis(2)
 69
 70
               # Retrieve currently displayed trim values
 71
               gtk.threads enter()
 72
               curThrustTrim = float(ControllerThread.thrustTrim.get_text())
 73
               curYawTrim = float(ControllerThread.yawTrim.get text())
 74
               curPitchTrim = float(ControllerThread.pitchTrim.get_text())
 75
               curRollTrim = float(ControllerThread.rollTrim.get text())
               gtk.threads_leave()
 76
 77
 78
               # Determine if trust trim buttons are pressed down
 79
               thrustTrimUpPressed = joystick.get_button(3)
 80
               yawTrimUpPressed = joystick.get_button(0)
 81
               pitchTrimUpPressed = True if (joystick.get_hat(0)[0] == -1) \
 82
                                     and (joystick.get_hat(0)[1] == 0) else False
 83
               rollTrimUpPressed = True if (joystick.get_hat(0)[0] == 0) \
 84
                                    and (joystick.get_hat(0)[1] == 1) else False
 85
               thrustTrimDownPressed = joystick.get_button(2)
               yawTrimDownPressed = joystick.get_button(1)
86
               pitchTrimDownPressed = True if (joystick.get_hat(0)[0] == 0) \
 87
 88
                                       and (joystick.get_hat(0)[1] == -1) else False
 89
               rollTrimDownPressed = True if (joystick.get_hat(0)[0] == 1) \
 90
                                      and (joystick.get_hat(0)[1] == 0) else False
 91
92
               # Calculate new axes values
 93
               # Map from [-1, 1] to [-100, 100]
               # If within a .0005 deviation from zero then set value to zero
 94
95
               # Use calculated value if armed, use zero otherwise
96
               thrust = (valueMap(thrustRaw)
 97
                          if (thrustRaw > .0005 or thrustRaw < -.0005)</pre>
98
                          else 0) if armed else 0
99
               yaw = (valueMap(yawRaw)
100
                       if (yawRaw > .0005 or yawRaw < -.0005) else 0) if armed else 0
101
               pitch = (valueMap(pitchRaw)
102
                         if (pitchRaw > .0005 or pitchRaw < -.0005)</pre>
103
                         else 0) if armed else 0
104
               roll = (valueMap(rollRaw)
105
                        if (rollRaw > .0005 or rollRaw < -.0005) else 0) if armed else 0
106
107
               # calculate new trim values
108
               # Increment by .1 if up button pressed, decrement otherwise
109
               # Set to zero if not armed
               thrustTrim = max(min((curThrustTrim + .1 if thrustTrimUpPressed \
110
111
                             else (curThrustTrim - .1 if thrustTrimDownPressed \
                                   else curThrustTrim)) if armed else 0, 100), -100)
112
               yawTrim = max(min((curYawTrim + .1 if yawTrimUpPressed \
113
                          else (curYawTrim - .1 if yawTrimDownPressed \
114
                                else curYawTrim)) if armed else 0, 100), -100)
115
116
               pitchTrim = max(min((curPitchTrim + .1 if pitchTrimUpPressed \
                            else (curPitchTrim - .1 if pitchTrimDownPressed \
117
118
                                else curPitchTrim)) if armed else 0, 100), -100)
119
               rollTrim = max(min((curRollTrim + .1 if rollTrimUpPressed \
120
                           else (curRollTrim - .1 if rollTrimDownPressed \
121
                                else curRollTrim)) if armed else 0, 100), -100)
122
123
               # Reset trim button pressed, set to zero
               if resetThrustTrim:
124
```

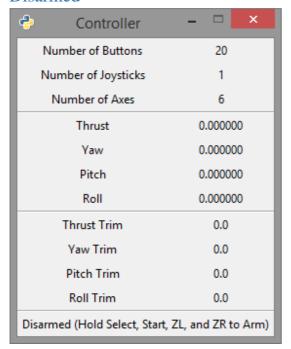
```
125
                    thrustTrim = 0
126
                    resetThrustTrim = False
127
               if resetYawTrim:
128
                   yawTrim = 0
129
                    resetYawTrim = False
130
               if resetPitchTrim:
131
                   pitchTrim = 0
                   resetPitchTrim = False
132
133
               if resetRollTrim:
134
                   rollTrim = 0
135
                    resetRollTrim = False
136
137
               # Update values to display
138
               ControllerThread.updateValues(thrust, yaw, pitch, roll, thrustTrim,
139
                    yawTrim, pitchTrim, rollTrim,
140
                    "Armed (Hold Select, Start, ZL, and ZR to Disarm)" if armed else
141
                    "Disarmed (Hold Select, Start, ZL, and ZR to Arm)")
142
143
               # Handle controller update events
144
               for event in pygame.event.get():
                    if event.type == QUIT:
145
146
                        loopQuit = True
147
                    elif event.type == pygame.KEYDOWN:
                        if event.key == pygame.K_ESCAPE:
148
149
                            loopQuit = True
150
151
               # sleep for .01 seconds
152
               time.sleep(interval)
153
           # Occasionally the controller must be reinitialized
154
           except:
155
               if ControllerThread.running:
156
                    joystick.init()
157
158 # Thread dedicated to handling retrieving values from controller and
159 # updating GUI labels with new values
160 class ControllerThread(threading.Thread):
       # Initialize thread
161
       def __init__(self, numButtons, numJoysticks, numAxes, thrust, yaw,
162
163
                     pitch, roll, thrustTrim, yawTrim, pitchTrim, rollTrim, arm):
164
           super(ControllerThread, self).__init__()
165
           self.numButtons = numButtons
166
           self.numJoystick = numJoysticks
167
           self.numAxes = numAxes
168
           self.thrust = thrust
169
           self.yaw = yaw
170
           self.pitch = pitch
171
           self.roll = roll
172
           self.thrustTrim = thrustTrim
173
           self.yawTrim = yawTrim
174
           self.pitchTrim = pitchTrim
           self.rollTrim = rollTrim
175
           self.arm = arm
176
177
           self.running = True
178
179
       # Initialize to initial values
180
       def initValues(self, numButtons, numJoysticks, numAxes):
181
           gtk.threads_enter()
           self.numButtons.set_text("%d" % numButtons)
182
           self.numJoystick.set_text("%d" % numJoysticks)
183
184
           self.numAxes.set_text("%d" % numAxes)
185
           self.thrustTrim.set text("0")
186
           self.yawTrim.set_text("0")
```

```
self.pitchTrim.set_text("0")
187
188
           self.rollTrim.set_text("0")
189
           self.arm.set_text("%s"
                              % "Disarmed (Hold Select, Start, ZL, and ZR to Arm)")
190
191
           gtk.threads leave()
192
           return False
193
       # Update values based on controller's state determined from controller
194
195
       # read function
       def updateValues(self, thrust, yaw, pitch, roll, thrustTrim, yawTrim,
196
197
                         pitchTrim, rollTrim, arm):
198
199
           self.thrust.set text("%f" % thrust)
200
           self.yaw.set_text("%f" % yaw)
           self.pitch.set_text("%f" % pitch)
201
202
           self.roll.set_text("%f" % roll)
           self.thrustTrim.set_text("%.1f" % thrustTrim)
203
204
           self.yawTrim.set_text("%.1f" % yawTrim)
           self.pitchTrim.set_text("%.1f" % pitchTrim)
205
206
           self.rollTrim.set_text("%.1f" % rollTrim)
           self.arm.set_text("%s" % arm)
207
208
           gtk.threads leave()
209
           return False
210
       # Call controller read function when thread is run
211
212
       def run(self):
213
           readController(self)
214
215
       def exit(self):
216
           self.running = False
217
           pygame.quit()
218
219 def delete_event(*args):
       gtk.main_quit(*args)
221
222 # Creates/runs threads and handles the GUI
223 def main():
224
       # Use GTK threads
225
       gobject.threads init()
226
227
       # construct GUI from glade file
228
       builder = gtk.Builder()
229
       builder.add_from_file("interface.glade")
230
231
       # retrieve window from constructed GUI
232
       window = builder.get_object("window1")
233
       window.connect("delete_event", delete_event)
234
       # display window
235
       window.show_all()
236
       # retrieve labels that will be updated from controller thread
237
       numButtons = builder.get_object("numButtons")
238
239
       numJoysticks = builder.get object("numJoysticks")
240
       numAxes = builder.get_object("numAxes")
241
       thrust = builder.get_object("thrust")
242
       yaw = builder.get_object("yaw")
243
       pitch = builder.get_object("pitch")
244
       roll = builder.get_object("roll")
       thrustTrim = builder.get_object("thrustTrim")
245
246
       yawTrim = builder.get_object("yawTrim")
247
       pitchTrim = builder.get object("pitchTrim")
       rollTrim = builder.get_object("rollTrim")
```

```
249
       arm = builder.get_object("arm")
250
251
      # construct controller thread, passing in labels to manipulate
       t = ControllerThread(numButtons, numJoysticks, numAxes, thrust, yaw, pitch,
252
                            roll, thrustTrim, yawTrim, pitchTrim, rollTrim, arm)
253
254
       # start controller thread
255
256
       t.start()
257
258
       # start GUI thread
259
       gtk.threads_enter()
260
       gtk.main()
       gtk.threads_leave()
261
262
263
       t.exit()
264
       sys.exit(-1)
265
266
267 # call main
268 if __name__ == "__main__":
269
      main()
270
```

Graphical User Interface Results

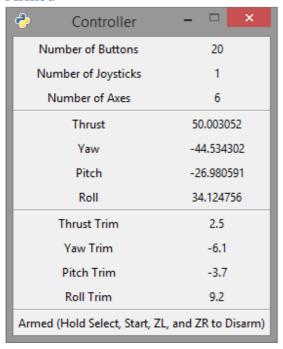
Disarmed



This displays the user interface while the controls are in a disarmed state. During this time the controller's state is ignored and values displayed are fixed at zero except for the controller specifications. These specifications include the number of buttons, joysticks, and axes retrieved from PyGame. The PS3 controller is viewed as a single joystick with 6 axes comprised of the two analog sticks and the Z triggers. In total there are 20 buttons, all used by the controller program.

Homework 4 - Results

Armed

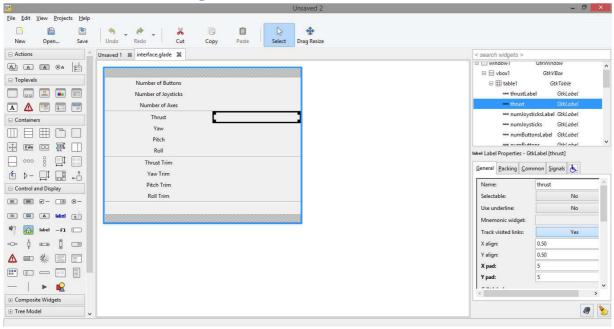


This displays the user interface while the controls are in a disarmed state. During this time the controller's current values are retrieved, mapped from the range [-1, 1] to [-100, 100], and sent to the appropriate label on the GTK interface thread.

From this point the values would be sent to the BeagleBone Black over wireless.

Homework 4 - Results

Glade Interface Designer



The Glade Interface Designer was used to construct the gtkbuilder xml file that represents the static location of the GUI widgets. This allowed for rapid development of the interface and simplified python code that would otherwise require manually boxing the interface elements.

The next page displays the XML generated by Glade.

```
<?xml version="1.0" encoding="UTF-8"?>
   <interface>
      <requires lib="gtk+" version="2.24"/>
      <!-- interface-naming-policy project-wide -->
4
      <object class="GtkWindow" id="window1">
5
        cproperty name="can focus">False</property>
6
        cproperty name="title" translatable="yes">Controller
7
        cproperty name="resizable">False</property>
8
        <child>
          <object class="GtkVBox" id="vbox1">
10
            cproperty name="visible">True</property>
            cproperty name="can_focus">False</property>
12
13
              <placeholder/>
14
15
           </child>
           <child>
16
              <object class="GtkTable" id="table1">
17
                cproperty name="visible">True</property>
18
                cproperty name="can_focus">False
19
                cproperty name="n rows">13</property>
20
                cproperty name="n_columns">2</property>
21
                <child>
22
                  <object class="GtkLabel" id="thrustLabel">
23
                    cproperty name="visible">True</property>
24
                    cproperty name="can_focus">False</property>
25
                    cproperty name="xpad">5</property>
26
                    cproperty name="ypad">5</property>
27
                    cproperty name="label" translatable="yes">Thrust
28
                  </object>
29
                  <packing>
30
                    cproperty name="top attach">4</property>
                    cproperty name="bottom_attach">5</property>
32
                  </packing>
33
34
                </child>
                <child>
35
                  <object class="GtkLabel" id="thrust">
36
                    cproperty name="visible">True
37
                    cproperty name="can focus">False/property>
38
                    cproperty name="xpad">5</property>
39
                    cproperty name="ypad">5
40
                    cproperty name="width chars">10</property>
41
                  </object>
42
                  <packing>
43
                    cproperty name="left attach">1
44
                    cproperty name="right_attach">2</property>
45
                    cproperty name="top attach">4</property>
46
                    cproperty name="bottom attach">5</property>
47
                  </packing>
48
                </child>
49
                <child>
50
                  <object class="GtkLabel" id="numJoysticksLabel">
```

```
cproperty name="visible">True</property>
52
                     cproperty name="can focus">False/property>
53
                     cproperty name="xpad">5
54
                     cproperty name="ypad">5
55
                     cproperty name="label" translatable="yes">Number of
56
    Joysticks</property>
                  </object>
57
                  <packing>
58
                     cproperty name="top_attach">1</property>
59
                     cproperty name="bottom_attach">2</property>
60
61
                  </packing>
                </child>
62
                <child>
63
                  <object class="GtkLabel" id="numJoysticks">
                     cproperty name="visible">True</property>
65
                     cproperty name="can_focus">False</property>
66
                     cproperty name="xpad">5</property>
67
                     cproperty name="ypad">5
68
                     cproperty name="width_chars">10</property>
69
                  </object>
70
                  <packing>
71
                     cproperty name="left_attach">1</property>
72
                     cproperty name="right attach">2</property>
73
                     cproperty name="top_attach">1</property>
74
                     cproperty name="bottom_attach">2</property>
75
                  </packing>
76
                </child>
77
                <child>
78
                  <object class="GtkLabel" id="numButtonsLabel">
79
                     cproperty name="visible">True/property>
80
                     cproperty name="can focus">False/property>
81
                     cproperty name="xpad">5
82
                     cproperty name="ypad">5</property>
83
                     cproperty name="label" translatable="yes">Number of
84
    Buttons</property>
                  </object>
85
                </child>
86
87
                <child>
                  <object class="GtkLabel" id="numButtons">
88
                     cproperty name="visible">True</property>
89
                     cproperty name="can focus">False/property>
90
                     cproperty name="xpad">5
91
                     cproperty name="ypad">5</property>
92
                     cproperty name="width chars">10
93
                  </object>
94
                  <packing>
95
                     cproperty name="left attach">1
96
                     cproperty name="right_attach">2</property>
97
                  </packing>
98
                </child>
99
                 <child>
100
```

```
<object class="GtkLabel" id="numAxesLabel">
101
                     cproperty name="visible">True</property>
102
                     cproperty name="can focus">False
103
                     cproperty name="xpad">5
104
                     cproperty name="ypad">5
105
                     cproperty name="label" translatable="yes">Number of
106
     Axes</property>
                   </object>
107
108
                   <packing>
                     cproperty name="top_attach">2</property>
109
                     cproperty name="bottom_attach">3</property>
110
                   </packing>
111
                 </child>
112
                 <child>
113
                   <object class="GtkLabel" id="numAxes">
114
                     cproperty name="visible">True</property>
115
116
                     cproperty name="can focus">False/property>
                     cproperty name="xpad">5</property>
117
                     cproperty name="ypad">5</property>
118
                     cproperty name="width_chars">10</property>
119
                   </object>
120
                   <packing>
121
                     cproperty name="left attach">1
122
                     cproperty name="right_attach">2
123
                     cproperty name="top_attach">2</property>
124
                     cproperty name="bottom attach">3</property>
125
                   </packing>
126
                 </child>
127
                 <child>
128
                   <object class="GtkLabel" id="yawLabel">
129
                     cproperty name="visible">True</property>
130
                     cproperty name="can_focus">False</property>
131
                     cproperty name="xpad">5</property>
132
133
                     cproperty name="ypad">5</property>
                     cproperty name="label" translatable="yes">Yaw</property>
134
135
                   </object>
                   <packing>
136
                     cproperty name="top_attach">5</property>
137
                     cproperty name="bottom_attach">6</property>
138
                     cproperty name="x_options">GTK_FILL</property>
139
                   </packing>
140
                 </child>
141
                 <child>
142
                   <object class="GtkLabel" id="yaw">
143
                     cproperty name="visible">True</property>
144
                     cproperty name="can_focus">False
145
                     cproperty name="xpad">5</property>
146
                     cproperty name="ypad">5
147
                     cproperty name="width_chars">10</property>
148
                   </object>
149
                   <packing>
150
```

```
cproperty name="left_attach">1</property>
151
                     cproperty name="right_attach">2</property>
152
                     cproperty name="top attach">5</property>
153
                     cproperty name="bottom_attach">6</property>
154
                   </packing>
155
                 </child>
156
                 <child>
157
                   <object class="GtkLabel" id="pitchLabel">
158
                     cproperty name="visible">True</property>
159
                     cproperty name="can focus">False/property>
160
                     cproperty name="xpad">5
161
                     cproperty name="ypad">5
162
                     cproperty name="label" translatable="yes">Pitch</property>
163
                   </object>
164
165
                   <packing>
                     cproperty name="top_attach">6</property>
166
167
                     cproperty name="bottom_attach">7</property>
168
                   </packing>
                 </child>
169
                 <child>
170
                   <object class="GtkLabel" id="pitch">
171
                     cproperty name="visible">True</property>
172
                     cproperty name="can focus">False
173
                     cproperty name="xpad">5</property>
174
                     cproperty name="ypad">5
175
                     cproperty name="width chars">10</property>
176
                   </object>
177
178
                   <packing>
                     cproperty name="left_attach">1</property>
179
                     cproperty name="right_attach">2</property>
180
                     cproperty name="top attach">6</property>
                     cproperty name="bottom_attach">7</property>
182
                   </packing>
183
184
                 </child>
                 <child>
185
                   <object class="GtkLabel" id="roll">
186
                     cproperty name="visible">True
187
                     cproperty name="can_focus">False
188
                     cproperty name="xpad">5</property>
189
                     cproperty name="ypad">5</property>
190
                     cproperty name="width chars">10
191
                   </object>
192
                   <packing>
193
                     cproperty name="left attach">1
194
                     cproperty name="right_attach">2</property>
195
                     cproperty name="top attach">7</property>
196
                     cproperty name="bottom_attach">8</property>
197
                   </packing>
198
                 </child>
199
                 <child>
200
                   <object class="GtkLabel" id="rollLabel">
201
```

```
cproperty name="visible">True</property>
202
                     cproperty name="can_focus">False</property>
203
                     cproperty name="xpad">5</property>
204
                      cproperty name="ypad">5
205
                      cproperty name="label" translatable="yes">Roll/property>
206
                   </object>
207
                   <packing>
208
                      cproperty name="top_attach">7</property>
209
                      cproperty name="bottom_attach">8</property>
210
                   </packing>
211
                 </child>
212
                 <child>
213
                   <object class="GtkLabel" id="yawTrimLabel">
214
                      cproperty name="visible">True</property>
215
                     cproperty name="can_focus">False</property>
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