

Метод на най-малките квадрати (МНМК)

Генериране на данни

$$x_t = 5 - t(0.13), \quad t = -3, 15$$

$$f(x) = 2\cos(2x-2)$$

$$y = f(x_t)$$

Линейна регресия

$$P_1(x) = a_1x + a_0$$

$$a_1, a_0 = ?$$

Квадратична регресия

$$P_2(x) = a_0 + a_1x + a_2x^2$$

$$a_0, a_1, a_2 = ?$$

Генериране на данни

```
In[621]:=
  xt = Table[5 + t * 0.13, {t, -3, 15}]

Out[621]=
  {4.61, 4.74, 4.87, 5., 5.13, 5.26, 5.39, 5.52, 5.65,
   5.78, 5.91, 6.04, 6.17, 6.3, 6.43, 6.56, 6.69, 6.82, 6.95}

In[622]:=
  f[x_] := 2 Cos[2 x - 2]
  yt = f[xt]

Out[623]=
  {1.18471, 0.730649, 0.22747, -0.291, -0.789909, -1.23572,
   -1.59847, -1.85376, -1.98445, -1.98174, -1.84582, -1.58583,
   -1.21923, -0.770676, -0.270319, 0.24821, 0.750054, 1.20148, 1.57214}

In[624]:=
  P = Length[xt]

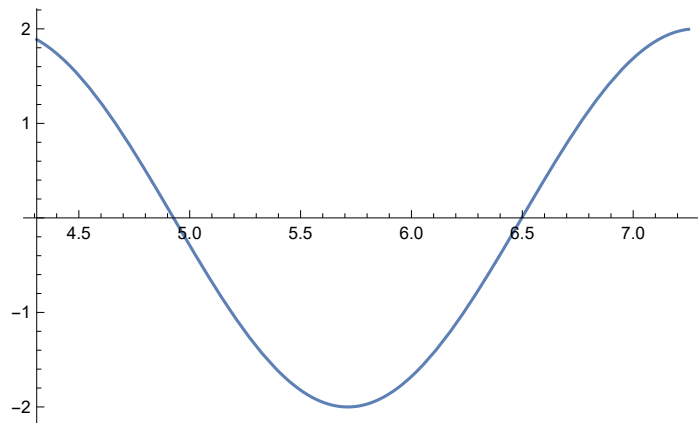
Out[624]=
  19
```

Визуализация

In[625]:=

```
grf = Plot[f[x], {x, xt[[1]] - 0.3, xt[[P]] + 0.3}]
```

Out[625]=



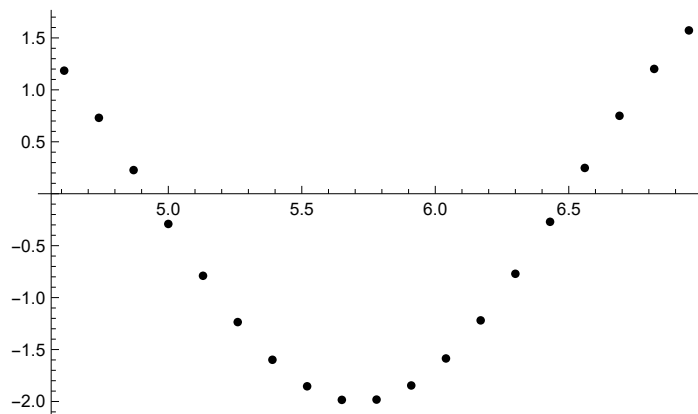
In[626]:=

```
points = Table[{xt[[i]], yt[[i]]}, {i, 1, P}];
```

In[627]:=

```
grp = ListPlot[points, PlotStyle -> Black]
```

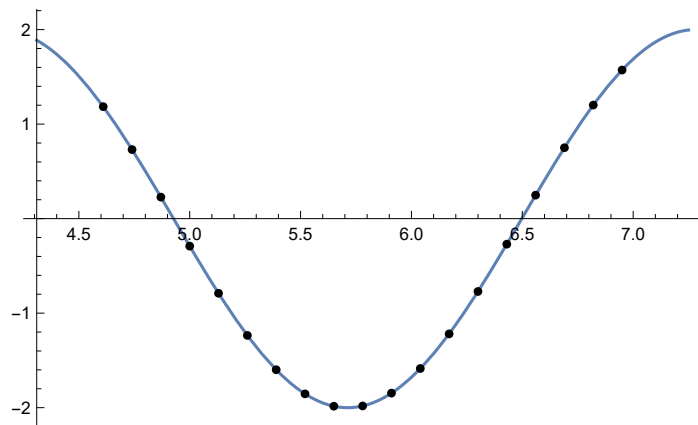
Out[627]=



In[628]:=

```
Show[grf, grp]
```

Out[628]=



Линейна регресия

Попълваме таблицата

In[629]:=

$$xt^2$$

Out[629]=

{21.2521, 22.4676, 23.7169, 25., 26.3169, 27.6676, 29.0521, 30.4704, 31.9225, 33.4084, 34.9281, 36.4816, 38.0689, 39.69, 41.3449, 43.0336, 44.7561, 46.5124, 48.3025}

In[630]:=

$$yt * xt$$

Out[630]=

{5.46153, 3.46328, 1.10778, -1.455, -4.05223, -6.49989, -8.61573, -10.2328, -11.2121, -11.4545, -10.9088, -9.57838, -7.52264, -4.85526, -1.73815, 1.62826, 5.01786, 8.19409, 10.9264}

Намиране на сумите

In[631]:=

$$\sum_{i=1}^p xt[i]$$

Out[631]=

109.82

In[632]:=

$$\sum_{i=1}^p yt[i]$$

Out[632]=

-9.51221

In[633]:=

$$\sum_{i=1}^p xt[i]^2$$

Out[633]=

644.393

In[634]:=

$$\sum_{i=1}^p yt[i] * xt[i]$$

Out[634]=

-52.3263

Решаваме системата

In[635]:=

$$A = \begin{pmatrix} 19 & 109.82 \\ 109.82 & 644.393 \end{pmatrix}; \quad b = \{-9.512, -52.326\};$$

In[636]:=

LinearSolve[A, b]

Out[636]=

 $\{-2.09264, 0.275433\}$

Съставяме полинома

In[637]:=

P1[x_] := -2.093 + 0.275 x

Таен коз (възможност за самопроверка)

In[638]:=

Fit[points, {1, x}, x]

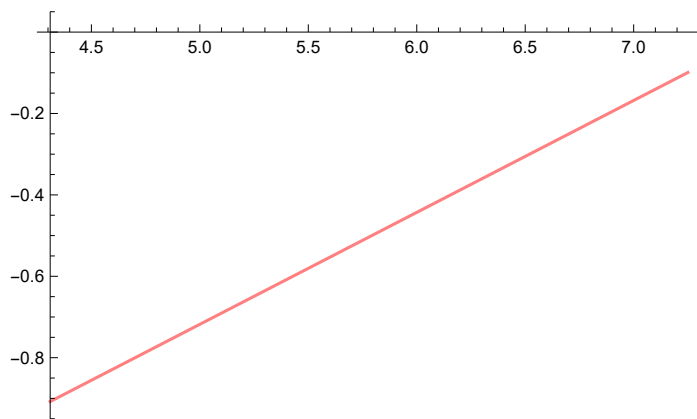
Out[638]=

 $-2.09324 + 0.275535 x$

In[639]:=

grfP1 = Plot[P1[x], {x, xt[[1]] - 0.3, xt[[P]] + 0.3}, PlotStyle -> Pink]

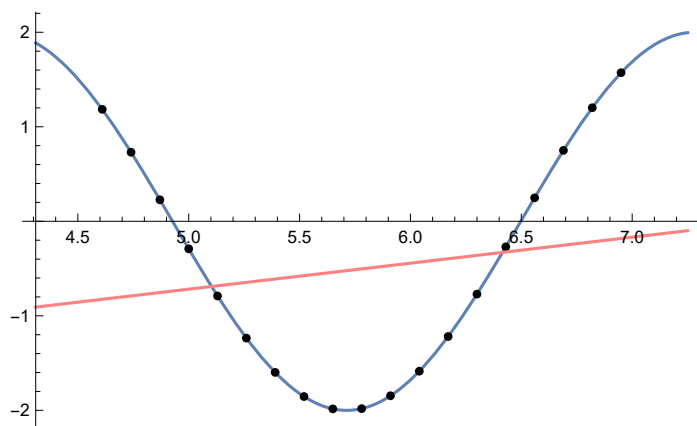
Out[639]=



In[640]:=

Show[grf, grp, grfP1]

Out[640]=



Намиране на приближена стойност (апроксимация)

In[641]:=

P1[4]

Out[641]=

 -0.993

За сравнение истинската стойност

In[642]:=

f[4.]

Out[642]=

1.92034

Оценка на грешката

Теоретична грешка (средноквадратична)

In[643]:=

$$\sqrt{\sum_{i=1}^P (y_t[i] - P1[x_t[i]])^2}$$

Out[643]=

5.02027

Истинска грешка

In[644]:=

Abs[f[4.] - P1[4.]]

Out[644]=

2.91334

Квадратична регресия

Попълваме таблицата

In[645]:=

xt²

Out[645]=

{21.2521, 22.4676, 23.7169, 25., 26.3169, 27.6676, 29.0521, 30.4704, 31.9225, 33.4084,
34.9281, 36.4816, 38.0689, 39.69, 41.3449, 43.0336, 44.7561, 46.5124, 48.3025}

In[646]:=

yt * xt

Out[646]=

{5.46153, 3.46328, 1.10778, -1.455, -4.05223, -6.49989,
-8.61573, -10.2328, -11.2121, -11.4545, -10.9088, -9.57838,
-7.52264, -4.85526, -1.73815, 1.62826, 5.01786, 8.19409, 10.9264}

In[647]:=

xt³

Out[647]=

{97.9722, 106.496, 115.501, 125., 135.006, 145.532, 156.591, 168.197, 180.362, 193.101,
206.425, 220.349, 234.885, 250.047, 265.848, 282.3, 299.418, 317.215, 335.702}

In[648]:=

$$\mathbf{x}t^4$$

Out[648]=

{451.652, 504.793, 562.491, 625., 692.579, 765.496, 844.025, 928.445, 1019.05, 1116.12, 1219.97, 1330.91, 1449.24, 1575.3, 1709.4, 1851.89, 2003.11, 2163.4, 2333.13}

In[649]:=

$$\mathbf{y}t * \mathbf{x}t^2$$

Out[649]=

{25.1777, 16.4159, 5.39488, -7.275, -20.788, -34.1894, -46.4388, -56.4849, -63.3486, -66.2069, -64.4711, -57.8534, -46.4147, -30.5881, -11.1763, 10.6814, 33.5695, 55.8837, 75.9383}

Намиране на сумите

In[650]:=

$$\sum_{i=1}^P \mathbf{x}t[[i]]$$

Out[650]=

109.82

In[651]:=

$$\sum_{i=1}^P \mathbf{y}t[[i]]$$

Out[651]=

-9.51221

In[652]:=

$$\sum_{i=1}^P \mathbf{x}t[[i]]^2$$

Out[652]=

644.393

In[653]:=

$$\sum_{i=1}^P \mathbf{y}t[[i]] * \mathbf{x}t[[i]]$$

Out[653]=

-52.3263

In[654]:=

$$\sum_{i=1}^P \mathbf{x}t[[i]]^3$$

Out[654]=

3835.95

In[655]:=

$$\sum_{i=1}^P \mathbf{x}t[[i]]^4$$

Out[655]=

23146.

In[656]:=

$$\sum_{i=1}^P y_t[i] * x_t[i]^2$$

Out[656]=

- 282.174

Решаваме системата

In[657]:=

$$A = \begin{pmatrix} 19 & 109.82 & 644.393 \\ 109.82 & 644.393 & 3835.95 \\ 644.393 & 3835.95 & 23146 \end{pmatrix}; \quad b = \{-9.512, -52.326, -282.174\};$$

In[658]:=

LinearSolve[A, b]

Out[658]=

{80.6781, -28.8073, 2.51589}

Записваме в общ вид

In[659]:=

$$A = \begin{pmatrix} P & \sum_{i=1}^P x_t[i] & \sum_{i=1}^P x_t[i]^2 \\ \sum_{i=1}^P x_t[i] & \sum_{i=1}^P x_t[i]^2 & \sum_{i=1}^P x_t[i]^3 \\ \sum_{i=1}^P x_t[i]^2 & \sum_{i=1}^P x_t[i]^3 & \sum_{i=1}^P x_t[i]^4 \end{pmatrix};$$

$$b = \left\{ \sum_{i=1}^P y_t[i], \sum_{i=1}^P y_t[i] * x_t[i], \sum_{i=1}^P y_t[i] * x_t[i]^2 \right\};$$

In[660]:=

a = LinearSolve[A, b]

Out[660]=

{80.7295, -28.8245, 2.5173}

Съставяме полинома

In[661]:=

$$P2[x_] := 80.678 - 28.807 x + 2.516 x^2$$

In[662]:=

$$P2[x_] := a[[1]] + a[[2]] x + a[[3]] x^2$$

$$P2[x]$$

Out[663]=

$$80.7295 - 28.8245 x + 2.5173 x^2$$

Таен коз (възможност за самопроверка)

In[664]:=

$$\text{Fit}[\text{points}, \{1, x, x^2\}, x]$$

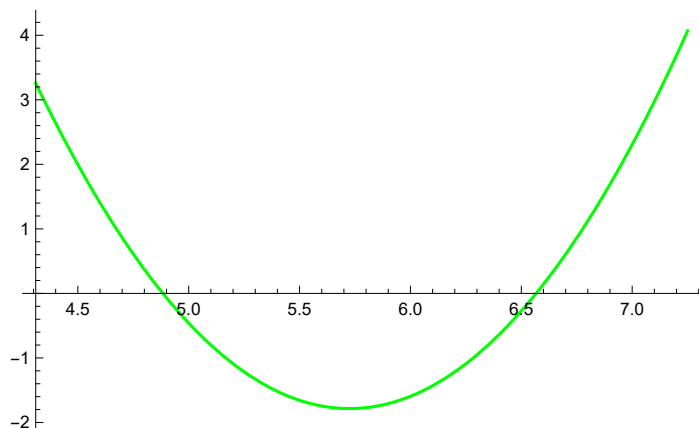
Out[664]=

$$80.7295 - 28.8245 x + 2.5173 x^2$$

In[665]:=

```
grfP2 = Plot[P2[x], {x, xt[[1]] - 0.3, xt[[P]] + 0.3}, PlotStyle -> Green]
```

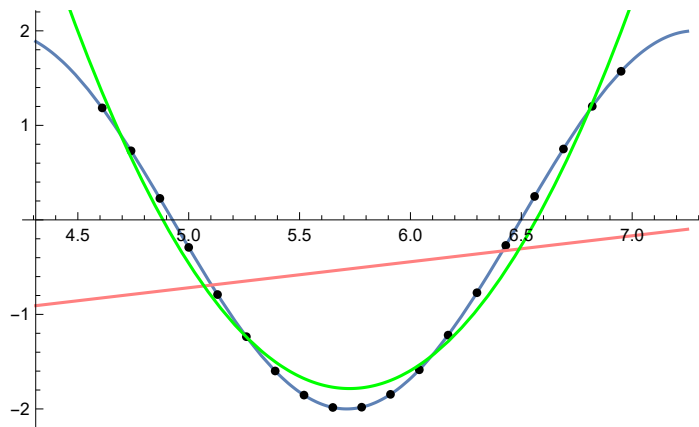
Out[665]=



In[666]:=

```
Show[grf, grp, grfP1, grfP2]
```

Out[666]=



Намиране на приближена стойност (апроксимация)

Стойност извън разглеждания интервал

In[667]:=

```
P2[4]
```

Out[667]=

```
5.70845
```

За сравнение истинската стойност

In[668]:=

```
f[4.]
```

Out[668]=

```
1.92034
```


Намиране на приближена стойност (апроксимация)

Стойност вътре в разглеждания интервал

In[669]:= **P2[5.3]**

Out[669]=
- 1.32918

За сравнение истинската стойност

In[670]:= **f[5.3]**

Out[670]=
- 1.35744

Оценка на грешката

Теоретична грешка (средноквадратична)

In[671]:=
$$\sqrt{\sum_{i=1}^p (yt[[i]] - P2[xt[[i]])^2}$$

Out[671]=
0.806493

Истинска грешка

In[672]:= **Abs[f[4.] - P2[4.]]**

Out[672]=
3.78811

In[673]:= **Abs[f[5.3] - P2[5.3]]**

Out[673]=
0.0282553

Кубична регресия

Попълваме таблицата

In[674]:= **xt²**

Out[674]=
{ 21.2521, 22.4676, 23.7169, 25., 26.3169, 27.6676, 29.0521, 30.4704, 31.9225, 33.4084,
34.9281, 36.4816, 38.0689, 39.69, 41.3449, 43.0336, 44.7561, 46.5124, 48.3025 }

In[675]:=

yt * xt

Out[675]=

```
{ 5.46153, 3.46328, 1.10778, -1.455, -4.05223, -6.49989,
  -8.61573, -10.2328, -11.2121, -11.4545, -10.9088, -9.57838,
  -7.52264, -4.85526, -1.73815, 1.62826, 5.01786, 8.19409, 10.9264 }
```

In[676]:=

xt³

Out[676]=

```
{ 97.9722, 106.496, 115.501, 125., 135.006, 145.532, 156.591, 168.197, 180.362, 193.101,
  206.425, 220.349, 234.885, 250.047, 265.848, 282.3, 299.418, 317.215, 335.702 }
```

In[677]:=

xt⁴

Out[677]=

```
{ 451.652, 504.793, 562.491, 625., 692.579, 765.496, 844.025, 928.445, 1019.05, 1116.12,
  1219.97, 1330.91, 1449.24, 1575.3, 1709.4, 1851.89, 2003.11, 2163.4, 2333.13 }
```

In[678]:=

yt * xt²

Out[678]=

```
{ 25.1777, 16.4159, 5.39488, -7.275, -20.788, -34.1894,
  -46.4388, -56.4849, -63.3486, -66.2069, -64.4711, -57.8534,
  -46.4147, -30.5881, -11.1763, 10.6814, 33.5695, 55.8837, 75.9383 }
```

Допълваме необходимото

Намиране на сумите

In[679]:=

$$\sum_{i=1}^P \mathbf{xt}[[i]]$$

Out[679]=

109.82

In[680]:=

$$\sum_{i=1}^P \mathbf{yt}[[i]]$$

Out[680]=

-9.51221

In[681]:=

$$\sum_{i=1}^P \mathbf{xt}[[i]]^2$$

Out[681]=

644.393

In[682]:=

$$\sum_{i=1}^P \mathbf{yt}[[i]] * \mathbf{xt}[[i]]$$

Out[682]=

-52.3263

In[683]:=

$$\sum_{i=1}^P x_t[i]^3$$

Out[683]=

3835.95

In[684]:=

$$\sum_{i=1}^P x_t[i]^4$$

Out[684]=

23 146.

In[685]:=

$$\sum_{i=1}^P y_t[i] * x_t[i]^2$$

Out[685]=

- 282.174

Допълваме необходимото

Решаваме системата

In[686]:=

$$A = \begin{pmatrix} 19 & 109.82 & 644.393 \\ 109.82 & 644.393 & 3835.95 \\ 644.393 & 3835.95 & 23\,146 \end{pmatrix}; \quad b = \{-9.512, -52.326, -282.174\};$$

In[687]:=

LinearSolve[A, b]

Out[687]=

{80.6781, -28.8073, 2.51589}

Записваме в общ вид

In[688]:=

$$A = \begin{pmatrix} P & \sum_{i=1}^P x_t[i] & \sum_{i=1}^P x_t[i]^2 & \sum_{i=1}^P x_t[i]^3 \\ \sum_{i=1}^P x_t[i] & \sum_{i=1}^P x_t[i]^2 & \sum_{i=1}^P x_t[i]^3 & \sum_{i=1}^P x_t[i]^4 \\ \sum_{i=1}^P x_t[i]^2 & \sum_{i=1}^P x_t[i]^3 & \sum_{i=1}^P x_t[i]^4 & \sum_{i=1}^P x_t[i]^5 \\ \sum_{i=1}^P x_t[i]^3 & \sum_{i=1}^P x_t[i]^4 & \sum_{i=1}^P x_t[i]^5 & \sum_{i=1}^P x_t[i]^6 \end{pmatrix};$$

$$b = \left\{ \sum_{i=1}^P y_t[i], \sum_{i=1}^P y_t[i] * x_t[i], \sum_{i=1}^P y_t[i] * x_t[i]^2, \sum_{i=1}^P y_t[i] * x_t[i]^3 \right\};$$

In[689]:=

a = LinearSolve[A, b] **LinearSolve:** Result for LinearSolve of badly conditioned matrix

{{19., 109.82, 644.393, 3835.95}, {109.82, 644.393, 3835.95, 23146.}, {644.393, 3835.95, 23146., 141427.}, {3835.95, 23146., 141427., 874141.}} may contain significant numerical errors.

Out[689]=

{128.634, -54.1524, 6.93941, -0.255023}

Съставяме полинома

In[690]:=

```
P3[x_] := a[[1]] + a[[2]] x + a[[3]] x^2 + a[[4]] x^3
P3[x]
```

Out[691]=

$$128.634 - 54.1524 x + 6.93941 x^2 - 0.255023 x^3$$

Таен код (възможност за самопроверка)

In[692]:=

```
Fit[points, {1, x, x^2, x^3}, x]
```

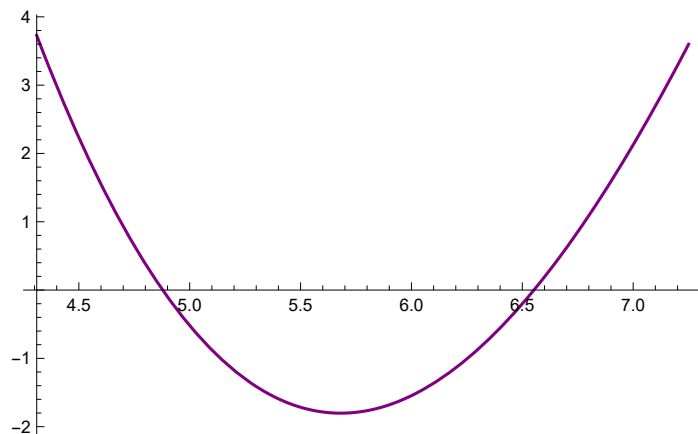
Out[692]=

$$128.634 - 54.1524 x + 6.93941 x^2 - 0.255023 x^3$$

In[693]:=

```
grfP3 = Plot[P3[x], {x, xt[[1]] - 0.3, xt[[P]] + 0.3}, PlotStyle -> Purple]
```

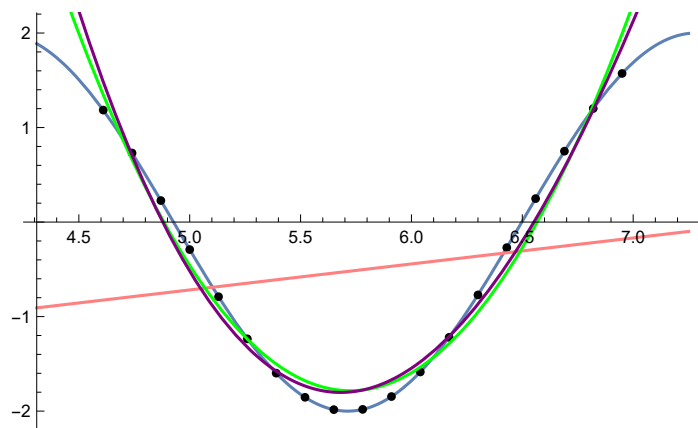
Out[693]=



In[694]:=

```
Show[grf, grp, grfP1, grfP2, grfP3]
```

Out[694]=



Намиране на приближена стойност (апроксимация)

Стойност извън разглеждания интервал

In[695]:=

P3[4]

Out[695]=

6.73399

За сравнение истинската стойност

In[696]:=

f[4.]

Out[696]=

1.92034

Намиране на приближена стойност (апроксимация)

Стойност вътре в разглеждания интервал

In[697]:=

P3[5.3]

Out[697]=

-1.41228

За сравнение истинската стойност

In[698]:=

f[5.3]

Out[698]=

-1.35744

Оценка на грешката

Теоретична грешка (средноквадратична)

In[699]:=

$$\sqrt{\sum_{i=1}^p (yt[[i]] - P3[xt[[i]])^2}$$

Out[699]=

0.744355

Истинска грешка

In[700]:=

Abs[f[4.] - P3[4.]]

Out[700]=

4.81364

```
In[701]:=
```

```
Abs[f[5.3] - P3[5.3]]
```

```
Out[701]=
```

```
0.0548399
```