Backpropagation

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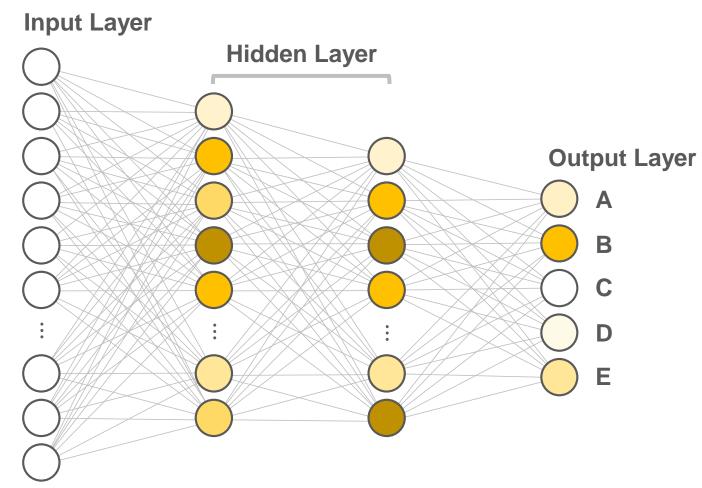
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Outline

- Forward and Back Propagation
- Chain Rule
- $\partial C(\theta)/\partial w_{ij}^l$
- $\partial C(\theta)/\partial z_i^l$
- $\partial C(\theta)/\partial z_i^l = \delta_i^l$
- Back Propagation
- Summary

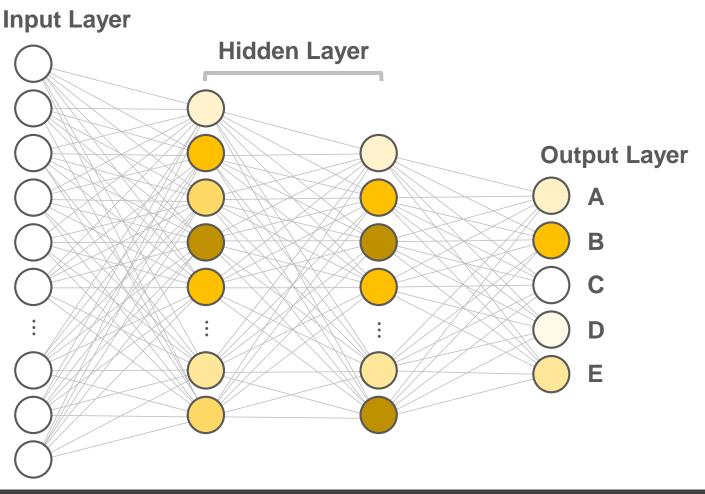
Forward Propagation

- Forward propagation is the process of calculating the output of a neural network given an input. In other words, it is the process of feeding input data through the network's layers in a forward direction to produce an output.
- During forward propagation, each neuron in a layer receives input from the previous layer and applies an activation function to produce an output, which is then passed to the next layer. The output of the final layer is the predicted output of the neural network.



Back Propagation

 Backpropagation computes the gradient of the loss function with respect to the weights of the network for a single input-output example, and does so efficiently, unlike a naive direct computation of the gradient with respect to each weight individually.



Chain Rule

$$\frac{\Delta w \to \Delta x \to \Delta y \to \Delta z}{\partial z} = \frac{\partial z}{\partial y} \frac{\partial y}{\partial x} \frac{\partial x}{\partial w}$$
$$= f'(y)f'(x)f'(w)$$

Forward propagation for computing the cost

$$= f'\left(f(f(w))\right)f'(f(w))f'(w)$$

Back propagation for computing the **gradient**

Looking Back – Gradient Decsent

$$y = f(x) = \sigma(W^{L} \dots \sigma(W^{2}\sigma(W^{1}x + b^{1}) + b^{2}) \dots + b^{L})$$

$$\theta = \{W^{1}, b^{1}, W^{2}, b^{2}, \dots, W^{L}, b^{L}\}$$

$$W^{l} = \begin{bmatrix} w_{11}^{l} & w_{12}^{l} & \cdots \\ w_{21}^{l} & w_{22}^{l} & \cdots \\ \vdots & \vdots & \ddots \end{bmatrix}, b^{l} = \begin{bmatrix} \vdots \\ b_{l}^{l} \\ \vdots \end{bmatrix}$$

$$\nabla C(\theta) = \begin{bmatrix} \frac{\partial}{\partial C(\theta)} \\ \frac{\partial}{\partial w_{ij}^{l}} \\ \vdots \\ \frac{\partial}{\partial C(\theta)} \\ \frac{\partial}{\partial t^{l}} \end{bmatrix}$$

$$\begin{cases} Algorithm \\ Initialization \\ while (\theta^{(i)}) \\ \{ \\ compute \\ update \\ \theta^{i+1} \leftarrow \\ \} \end{cases}$$

Algorithm

```
Initialization: start at \theta^0
while (\theta^{(i+1)} \neq \theta^i)
   compute the gradients at \theta^i
  update parameters
  \theta^{i+1} \leftarrow \theta^i - \eta \nabla_{\theta} C(\theta^i)
```

$$\partial C(\theta)/\partial w_{ij}^l$$

Layer l-1Layer *l* w_{i1}^l N_l nodes N_{l-1} nodes Bias

$$\frac{\partial C(\theta)}{\partial w_{ij}^l} = \frac{\partial C(\theta)}{\partial z_i^l} \frac{\partial z_i^l}{\partial w_{ij}^l}$$

$$\partial z_i^l/\partial w_{ij}^l \ (l>1)$$

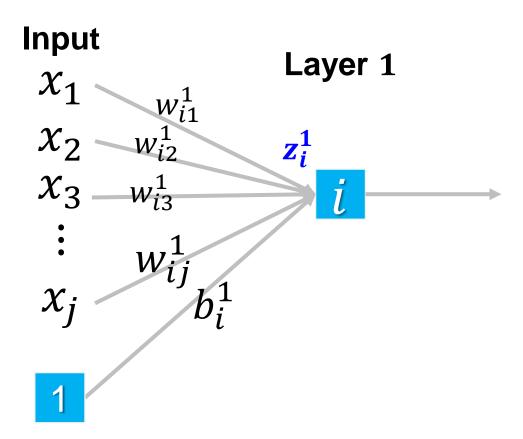
Layer l-1Layer *l* N_l nodes N_{l-1} nodes Bias

$$z^{l} = W^{l}a^{l-1} + b^{l}$$

$$z^{l}_{i} = \sum_{j} w^{l}_{ij}a^{l-1}_{j} + b^{l}_{i}$$

$$\frac{\partial z^{l}_{i}}{\partial w^{l}_{ij}} = a^{l-1}_{j}$$

$$\partial z_i^l/\partial w_{ij}^l \ (l=1)$$

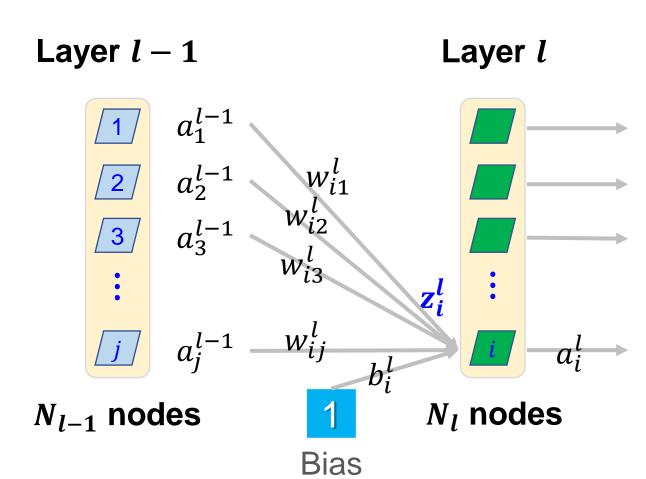


$$z^{1} = W^{1}x + b^{1}$$

$$z^{1}_{i} = \sum_{j} w^{1}_{ij} x_{j} + b^{1}_{i}$$

$$\frac{\partial z^{1}_{i}}{\partial w^{1}_{ij}} = x_{j}$$

$$\partial C(\theta)/\partial w_{ij}^{l}$$

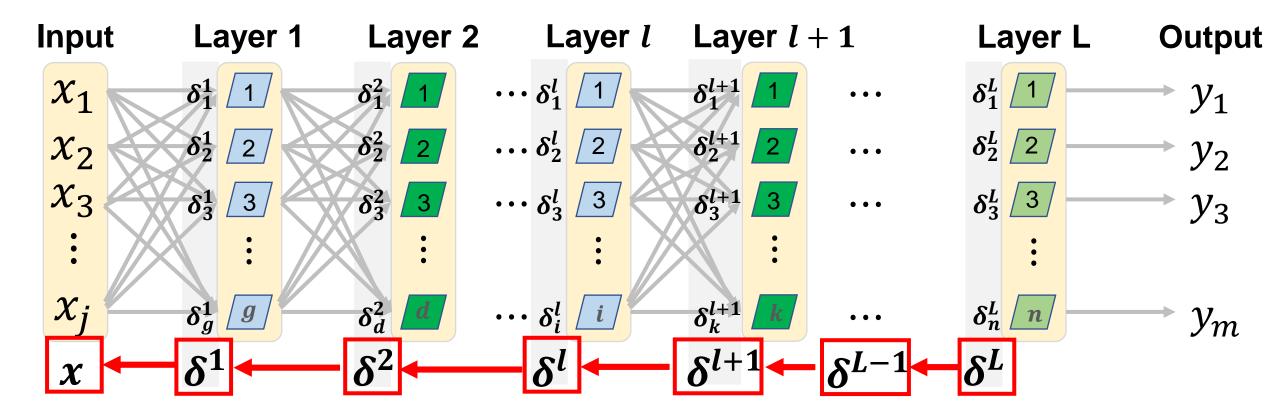


$$egin{aligned} rac{\partial \mathcal{C}(heta)}{\partial w_{ij}^l} &= rac{\partial \mathcal{C}(heta)}{\partial z_i^l} rac{\partial z_i^l}{\partial w_{ij}^l} \ rac{\partial z_i^l}{\partial w_{ij}^l} &= egin{cases} a_j^{l-1} &, l > 1 \ x_j &, l = 1 \end{cases} \end{aligned}$$

$$\partial C(\theta)/\partial z_i^l$$

$$\partial C(\theta)/\partial z_i^l \frac{\partial C(\theta)}{\partial w_{ij}^l} = \frac{\partial C(\theta)}{\partial z_i^l} \frac{\partial z_i^l}{\partial w_{ij}^l}$$

 δ_i^l : the propagated gradient corresponding to the l-th layer



$$\partial \mathcal{C}(\theta)/\partial z_i^l = \delta_i^l$$

- Procedure: from layer L to layer 1
- 1. Initialization: compute δ^L

$$\delta_i^L = \frac{\partial c}{\partial z_i^L} = \frac{\partial c}{\partial y_i} \frac{\partial y_i}{\partial z_i^L}, \quad \frac{\partial c}{\partial y_i} \text{ depends on the loss function}$$

$$\Delta z_i^L \to \alpha_i^L = \Delta y_i \to \Delta C$$

2. Compute δ^L based on δ^{l+1}

$$\partial \mathcal{C}(\theta)/\partial z_i^l = \delta_i^l$$

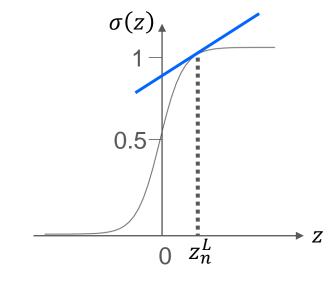
- Procedure: from layer L to layer 1
- 1. Initialization: compute δ^L
- 2. Compute δ^L based on δ^{l+1}

$$\Delta z_i^L \to \Delta a_i^L = \Delta y_i \to \Delta C$$

$$\delta_i^L = \frac{\partial C}{\partial z_i^L}$$

$$\delta_i^L = \frac{\partial C}{\partial y_i} \frac{\partial y_i}{\partial z_i^L} = \frac{\partial C}{\partial y_i} \sigma'(z_i^L),$$

where
$$y_i = a_i^L = \sigma(z_i^L)$$

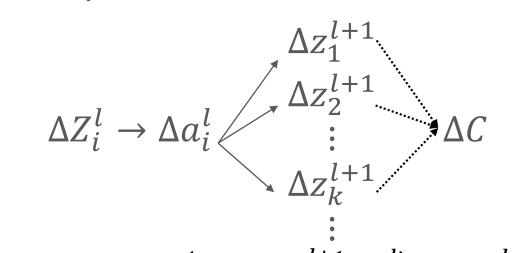


$$\sigma'(z^{L}) = \begin{bmatrix} \sigma'(z_{1}^{L}) \\ \sigma'(z_{2}^{L}) \\ \vdots \\ \sigma'(z_{i}^{L}) \\ \vdots \end{bmatrix}, \nabla C(y) = \begin{bmatrix} \overline{\partial y_{1}} \\ \overline{\partial C} \\ \overline{\partial y_{2}} \\ \vdots \\ \overline{\partial C} \\ \overline{\partial y_{i}} \end{bmatrix}$$

$$\boldsymbol{\delta}^L = \boldsymbol{\sigma}'\big(\mathbf{z}^L\big) \odot \boldsymbol{\nabla} \boldsymbol{C}(\boldsymbol{y})$$

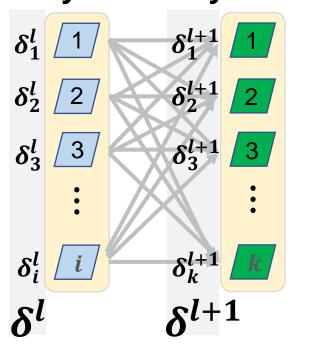
$$\partial C(\theta)/\partial z_i^l = \delta_i^l$$

- Procedure: from layer L to layer 1
- 1. Initialization: compute δ^L
- 2. Compute δ^L based on δ^{l+1}



$$\delta_{i}^{l} = \frac{\partial C}{\partial z_{i}^{l}} = \sum_{k} \left(\frac{\partial C}{\partial z_{k}^{l+1}} \frac{\partial z_{k}^{l+1}}{\partial a_{i}^{l}} \frac{\partial a_{i}^{l}}{\partial z_{i}^{l}} \right) = \frac{\partial a_{i}^{l}}{\partial z_{i}^{l}} \sum_{k} \left(\frac{\partial C}{\partial z_{k}^{l+1}} \frac{\partial z_{k}^{l+1}}{\partial a_{i}^{l}} \frac{\partial z_{k}^{l+1}}{\partial a_{i}^{l}} \right)$$

Layer l Layer l+1



$$\partial \mathcal{C}(\theta)/\partial z_i^l = \delta_i^l$$

- Procedure: from layer L to layer 1
- 1. Initialization: compute δ^L
- 2. Compute δ^L based on δ^{l+1}

$$\delta_{i}^{l} = \frac{\partial a_{i}^{l}}{\partial z_{i}^{l}} \sum_{k} \frac{\partial z_{k}^{l+1}}{\partial a_{i}^{l}} \delta_{k}^{l+1}$$

$$\delta_{i}^{l} = \sigma'(z_{i}) \sum_{k} \frac{\partial z_{k}^{l+1}}{\partial a_{i}^{l}} \delta_{k}^{l+1}$$

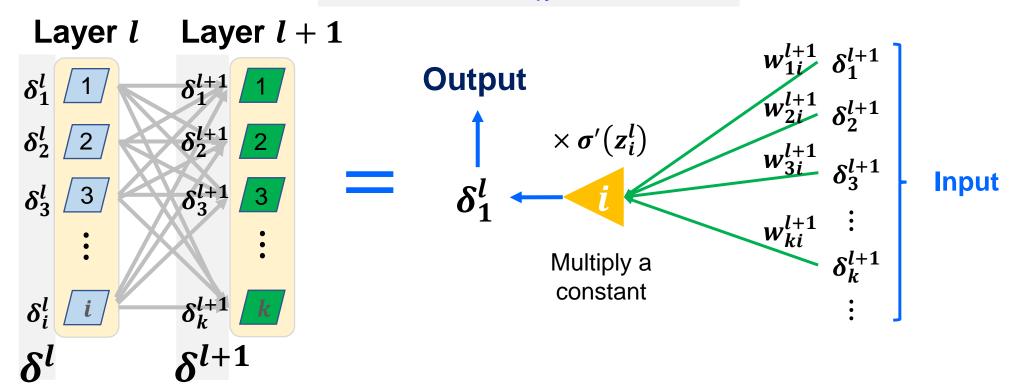
$$= \sum_{i} w_{ki}^{i+1} a_{i}^{l} + b_{k}^{l+1}$$

$$\delta_{i}^{l} = \sigma'(z_{i}) \sum_{k} w_{ki}^{l+1} \delta_{k}^{l+1}$$

$$\delta_{i}^{l} = \sigma'(z_{i}) \sum_{k} w_{ki}^{l+1} \delta_{k}^{l+1}$$

$$\partial \mathcal{C}(\theta)/\partial z_i^l = \delta_i^l$$

• The propagation:
$$\delta_i^l = \sigma'(z_i) \sum_k w_{ki}^{l+1} \delta_k^{l+1}$$

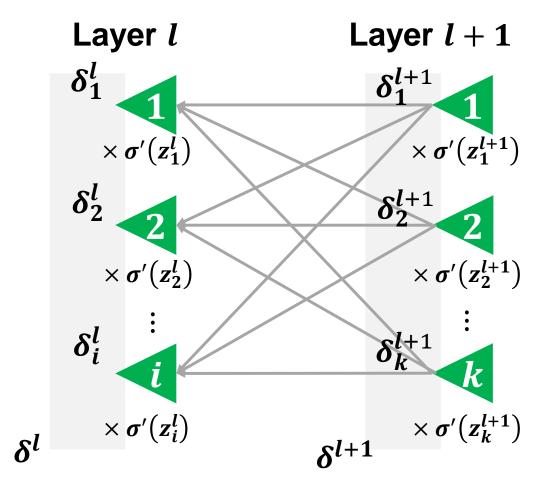


$$\partial C(\theta)/\partial z_i^l = \delta_i^l$$

$$\delta_{i}^{l} = \sigma'(z_{i}) \sum_{k} w_{ki}^{l+1} \delta_{k}^{l+1}$$

$$\sigma'(z^{l}) = \begin{bmatrix} \sigma'(z_{1}^{l}) \\ \sigma'(z_{2}^{l}) \\ \vdots \\ \sigma'(z_{i}^{l}) \end{bmatrix}$$

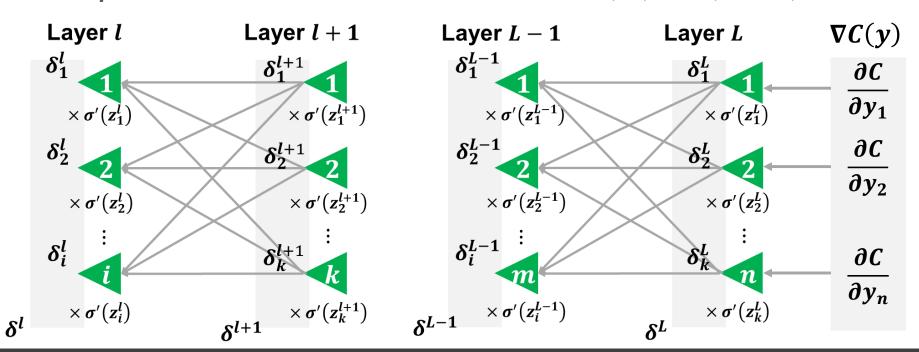
$$\delta^{l} = \sigma'(z^{l}) \odot (W^{l+1})^{T} \delta^{l+1}$$



$$\partial C(\theta)/\partial z_i^l = \delta_i^l$$

$$\frac{\partial C(\theta)}{\partial w_{ij}^l} = \frac{\partial C(\theta)}{\partial z_i^l} \frac{\partial z_i^l}{\partial w_{ij}^l}$$

- Procedure: from layer L to layer 1
- 1. Initialization: compute δ^L $\delta^L = \sigma'(z^L) \odot \nabla C(y)$ 2. Compute δ^{l-1} based on δ^l $\delta^l = \sigma'(z^l) \odot (W^{l+1})^T \delta^{l+1}$



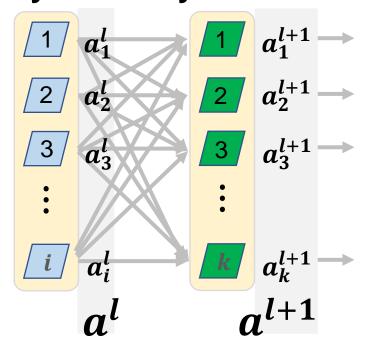
Back Propagation

$$\frac{\delta z_i^i}{\partial w_{ij}^l} = \begin{cases} a_j^{l-1} & , l > 1 \\ x_j & , l = 1 \end{cases}$$

Forward Direction $z^1 = W^1 x + b^1$ $a^1 = \sigma(z^1)$ \vdots $z^l = W^l x^{l-1} + b^l$ $a^l = \sigma(z^l)$

$$\frac{\partial C(\theta)}{\partial w_{ij}^l} = \frac{\partial C(\theta)}{\partial z_i^l} \frac{\partial z_i^l}{\partial w_{ij}^l}$$

Layer l Layer l+1



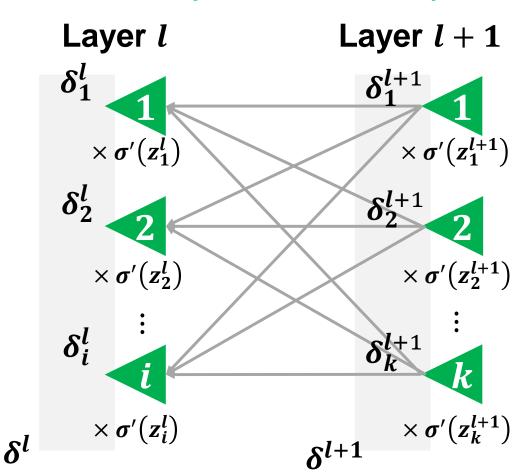
Back Propagation

$$\frac{\partial C(\theta)}{\partial z_i^l} = \delta_i^l$$

Backward Direction

$$egin{aligned} \delta^L &= \sigma'ig(z^Lig) \odot
abla \mathcal{C}(y) \ \delta^{L-1} &= \sigma'ig(z^{L-1}ig) \odot ig(W^Lig)^T \delta^L \ &dots \ \delta^l &= \sigma'ig(z^lig) \odot ig(W^{l+1}ig)^T \delta^{l+1} \ &dots \end{aligned}$$

$$\frac{\partial C(\theta)}{\partial w_{ij}^l} = \frac{\partial C(\theta)}{\partial z_i^l} \frac{\partial z_i^l}{\partial w_{ij}^l}$$



Gradient Descent

$$y = f(x) = \sigma(W^L \dots \sigma(W^2 \sigma(W^1 x + b^1) + b^2) \dots + b^L)$$

$$\theta = \{W^1, b^1, W^2, b^2, \dots, W^L, b^L\}$$

$$W^l = \begin{bmatrix} w_{11}^l & w_{12}^l & \dots \\ w_{21}^l & w_{22}^l & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}, b^l = \begin{bmatrix} \vdots \\ b_l^l \\ \vdots \end{bmatrix}$$

$$\nabla C(\theta) = \begin{bmatrix} \frac{\partial}{\partial C(\theta)} \\ \frac{\partial}{\partial w_{ij}^l} \\ \vdots \\ \frac{\partial}{\partial C(\theta)} \\ \frac{\partial}{\partial b_l^l} \end{bmatrix}$$
Gradient descent in neural network requires to update millions of parameters $\theta^{i+1} \leftarrow \theta^i - \eta \nabla_\theta C(\theta^i)$
However, it is time-consuming and an inefficient process...
Therefore, we will introduce another solution – backpropagation.

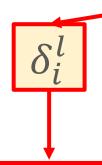
Summary

Layer l - 1 Layer l









Forward Direction

$$z^{1} = W^{1}x + b^{1} \qquad a^{1} = \sigma(z^{1})$$

$$\vdots \qquad \vdots$$

$$z^{l} = W^{l}x^{l-1} + b^{l} \qquad a^{l} = \sigma(z^{l})$$

$$\frac{\partial C(\theta)}{\partial w_{ij}^l} = \frac{\partial C(\theta)}{\partial z_i^l} \frac{\partial z_i^l}{\partial w_{ij}^l}$$

$$\begin{cases} a_j^{l-1} & , l > 1 \\ x_j & , l = 1 \end{cases}$$

Backward Direction

$$egin{align*} oldsymbol{\delta^L} &= oldsymbol{\sigma'}(oldsymbol{z^L}) \odot oldsymbol{
abla} C(y) \ oldsymbol{\delta^{L-1}} &= oldsymbol{\sigma'}(oldsymbol{z^{L-1}}) \odot oldsymbol{(W^L)}^T oldsymbol{\delta^L} \ & dots \ oldsymbol{\delta^l} &= oldsymbol{\sigma'}(oldsymbol{z^l}) \odot oldsymbol{(W^{l+1})}^T oldsymbol{\delta^{l+1}} \ & dots \ \end{pmatrix}$$

References

- 臺大電機系李宏毅教授講義
- 臺大資工系陳縕儂教授講義
- NVIDIA Deep Learning Tutorial

