COMS 4771 Lecture 22

1. Markov models

A sequence model (or time series model) is a family of probability distributions for (possibly infinite) sequences of random variables $\{X_t\}_{t\in\mathcal{T}}$.

▶ $\{X_t\}_{t \in \mathcal{T}}$ is a **stochastic process** indexed by the totally-ordered set \mathcal{T} (e.g., $\mathcal{T} = \mathbb{N}$ for discrete time series).

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Sequence / time series modeling is an entire subfield in statistics, largely due to the plethora of sequence / time series data in applications:

- ► Economic / financial data over time
- ▶ Climate science
- ► Genomic sequences
- ► Speech and natural language
- **>** ...

A stochastic process $\{X_t\}_{t\in\mathbb{N}}$ has the **Markov property** if the conditional distribution of the next state X_{t+1} given all previous states $\{X_\tau: \tau \leq t\}$ only depends on the value of the current state X_t .

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If the X_t are discrete-valued, then the Markov property means that

$$\Pr(X_{t+1} = x_{t+1} \mid X_1 = x_1, \dots, X_t = x_t) = \Pr(X_{t+1} = x_{t+1} \mid X_t = x_t).$$

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MARKOV MODELS

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A stochastic process with the Markov property is called a Markov chain.

A sequence model for a Markov chain is called a Markov model.

Markov Chain distributions

To specify a Markov chain (MC):

- ightharpoonup Specify the distribution of the initial state X_1 .
- ▶ Specify a transition kernel: $\Pr(X_{t+1} = x' \mid X_t = x)$ for all (x, x'). (Nothing to do with *kernels* as in SVMs/kernel trick/RKHS.)

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▶ Transition kernel can be written as a $d \times d$ matrix A

Great!!!

$$A_{i,j} = \Pr(X_{t+1} = j | X_t = i)$$

(rows of A are probability vectors).

Also called a transition matrix or (right) stochastic matrix.

State space: $\{1, 2\}$.

Parameters:

$$m{\pi} = rac{ ext{state 1}}{ ext{state 2}} egin{pmatrix} 0.1 \ 0.9 \end{pmatrix}, & m{A} = rac{ ext{state 1}}{ ext{state 2}} egin{pmatrix} 0.3 & 0.7 \ 0.6 & 0.4 \end{pmatrix}.$$
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A random state sequence drawn from this MC:

What is the probability of this sequence?

 π_2

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$$\pi_2 \times A_{2,2}$$

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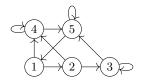
finite machine

A random state sequence drawn from this MC:

$$\pi_2 \times A_{2,2} \times A_{2,2} \times A_{2,1} \times A_{1,1} \times A_{1,2} \times A_{2,2} \times A_{2,1} = 0.00435456$$

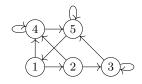
EXAMPLE: RANDOM WALK ON A DIRECTED GRAPH

Consider a directed graph G=(V,E) over $\vert V \vert = d$ vertices (self-loops ok).



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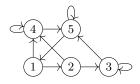
MC for random walk on G:

$$\pi_i = \mathbb{1}\{\text{start vertex is } i\}, \quad A_{i,j} = \frac{\mathbb{1}\{(i,j) \in E\}}{\operatorname{out degree}(i)}.$$

	state 1	state 2	state 3	state 4	state 5
state 1	0	0.5	0	0.5	0
state 2	0	0	0.5	0.5	0
state 3	0	0	0.5	0	0.5
state 4	0	0	0	0.5	0.5
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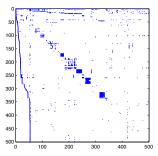
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? is there are weight difference on each edge?

The non-zero pattern of A gives the adjacency structure of G (vertices = states).

Web graph G = (V, E):

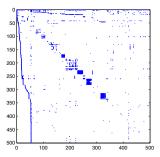
Vertices are webpages, directed edges are hyperlinks between webpages.



Adjacency matrix of the web graph for 500 web pages.

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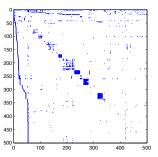


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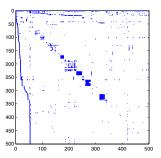
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Adjacency matrix of the web graph for 500 web pages.

How popular is webpage i?

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$$\Pr(X_t = i)$$
 for large t . may converge

Markov Chain State distributions

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$$Pr(X_{2} = j) = \sum_{i=1}^{d} Pr(X_{1} = i, X_{2} = j)$$
$$= \sum_{i=1}^{d} Pr(X_{1} = i) \cdot Pr(X_{2} = j | X_{1} = i)$$

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$$= \sum_{i=1}^{d} \pi_{i} \cdot A_{i,j}$$

What is the marginal distribution of X_2 in terms of π and A?

$$\begin{split} \Pr(X_2 = j) &= \sum_{i=1}^d \Pr(X_1 = i, \ X_2 = j) \\ &= \sum_{i=1}^d \Pr(X_1 = i) \cdot \Pr(X_2 = j \mid X_1 = i) \\ &= \sum_{i=1}^d \pi_i \cdot A_{i,j} & \text{Great thinking!!!} \\ &= j\text{-th entry of } \boldsymbol{\pi}^\top \boldsymbol{A}. \end{split}$$

What is the marginal distribution of X_3 in terms of π and A?

What is the marginal distribution of X_3 in terms of ${m \pi}$ and ${m A}$? For each $k \in [d]$,

$$Pr(X_3 = k) = \sum_{i=1}^{d} \sum_{j=1}^{d} Pr(X_1 = i, X_2 = j, X_3 = k)$$

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$$= \sum_{i=1}^{d} \sum_{j=1}^{d} \pi_{i} \cdot A_{i,j} \cdot A_{j,k}$$
magic matrix!!!

It's great!

For any $t \in \mathbb{N}$, the marginal distribution of X_t in terms of π and A is

$$\Pr(X_t = k) = k$$
-th entry of $\boldsymbol{\pi}^{\top} \underbrace{\boldsymbol{A} \boldsymbol{A} \cdots \boldsymbol{A}}_{t-1 \text{ times}}$.

POWERS OF THE TRANSITION MATRIX

The
$$(i,j)$$
-th entry of ${m A}^p = \underbrace{{m A}{m A} \cdots {m A}}_{p \text{ times}}$ is the p -step transition matrix
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Example: State space:
$$\{1,2\}$$
. Parameters: $\boldsymbol{\pi} = \begin{pmatrix} 0.1 \\ 0.9 \end{pmatrix}$, $\boldsymbol{A} = \begin{pmatrix} 0.3 & 0.7 \\ 0.6 & 0.4 \end{pmatrix}$

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$$\boldsymbol{\pi}^{\top} \boldsymbol{A}^{5} = \begin{pmatrix} 0.1 & 0.9 \end{pmatrix} \begin{pmatrix} 0.46023 & 0.53977 \\ 0.46266 & 0.53734 \end{pmatrix} = \begin{pmatrix} 0.462417 & 0.537583 \end{pmatrix}$$

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Convergence?

The
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Convergence? Doesn't even seem to matter what π is!

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try to find out the q!!!

i.e.,

$$\boldsymbol{q}^{\top} \boldsymbol{A} = \boldsymbol{q}^{\top}. \tag{\star}$$

A solution q to (\star) , is called a **stationary distribution**.

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Law of Large Numbers for MCs.

not like cherf

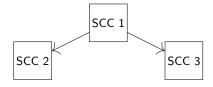
as the size of n growing

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When does a MC even have a unique stationary distribution?

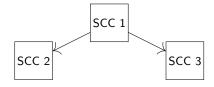
WHAT CAN GO WRONG

1. Directed graph underlying A has more than one strongly connected component "sinks" \longrightarrow stationary distribution may not be unique.



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Markov chains with only one strongly connected component are called **irreducible**.

What can go wrong

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If start at state 1, then never at state 1 on even time steps.

Markov chains without such oscillation are called aperiodic.

(Formally: there exists p_0 s.t. for all $p \geq p_0$, $[{m A}^p]_{i,i} > 0$ for all $i \in [d]$.)

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(Formally: here exists p_0 s.t. for all $p \geq p_0$, $[{m A}^p]_{i,j} > 0$ for all $i \in [d]$.)

If every state $i \in [d]$ has $A_{n,n} > 0$, then aperiodicity is guaranteed.

CONDITIONS FOR UNIQUE STATIONARY DISTRIBUTION

Theorem: If MC with transition matrix A is *irreducible* and *aperiodic*, then

lacktriangle There is a unique stationary distribution q (which satisfies $q^ op A = q^ op$).

$$lackbox{igspace}{egin{array}{ll} \displaystyle \lim_{p o\infty} oldsymbol{A}^p &= egin{pmatrix} --- & oldsymbol{q}^ op & --- \ & dots \ --- & oldsymbol{q}^ op & --- \end{pmatrix}}.$$

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Direct method: Find any vector in *left null space* of A-I

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Power method:

initialize q arbitrarily. repeat $q^\top := q^\top A$. A is usually sparse until bored. return q.

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- definitely not irreducible,
 (some pages have no links to other pages);
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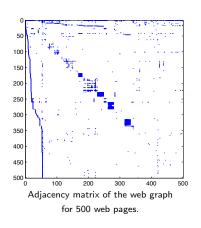
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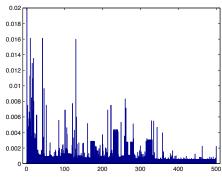
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too many sinks~

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 ${\sf PageRank\ scores} = {\sf stationary\ distribution\ of\ this\ new\ MC}.$





PageRank distribution.

(From K. Murphy, "Machine Learning", MIT Press 2012.)

Have some labeled data $(x_1,y_1),(x_2,y_2),\ldots,(x_m,y_m)$ from $\mathcal{X}\times\{\pm 1\}$, and also many unlabeled data $x_{m+1},x_{m+1},\ldots,x_{m+n}$ from \mathcal{X} .

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[Zhu, Ghahramani, and Lafferty, 2003]

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- $V = \{1, 2, \dots, m+n\}.$
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U : unlabel data

[Zhu, Ghahramani, and Lafferty, 2003]

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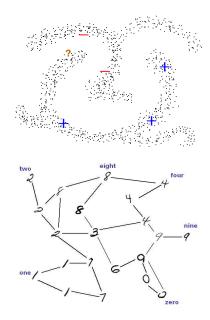
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 normalize (equal to 0)

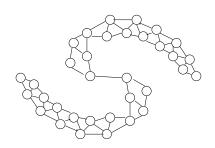
the large the distance, the smaller the weight

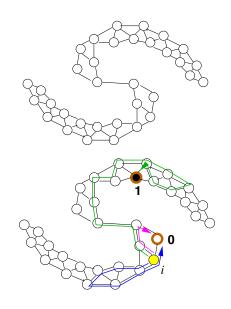
Start weighted random walk starting from unlabeled point x_{m+i} . If first labeled point reached has label $y \in \{\pm 1\}$, then use $\hat{y}_{m+i} := y$ as the label for x_{m+i} .

(Can actually compute, in closed form, the probabilities of $\hat{y}_{m+i} = y$ for each y.)



Example: Semi-supervised learning





RECAP

- Markov property: past and future are conditionally independent given the present.
- ► Transition matrix: the conditional next-state distributions for each state.
- Random walk on graphs: extremely important process, very well-studied, many applications (including in ML, statistics, etc).
- Irreducible and aperiodic Markov chains have limiting behavior: doesn't matter where you start, eventually marginal state distribution is the stationary distribution.
 - Some qualities similar to iid processes, some rather different.
 - Related to eigenvectors/eigenvalues, computation via power method.
- ► Forms the basis of PageRank.