

```

clear
clc
close all

syms N_b Omega R c theta C_la C_d rho y dy
assume(N_b>0);
assume(Omega>0);
assume(R>0);
assume(c>0);
assume(theta>0);
assume(C_la>0);
assume(C_d>0);
assume(rho>0);
assume(y>0);
assume(dy>0);

r = y / R ;
dr = dy / R ;

```

## Assumptions

```

syms lambda_c lambda_i mu beta betadot psi theta_0 sigma sigma_0
assume(lambda_c>0);
assume(lambda_i>0);
assume(mu>0);
assume(beta>0);
assume(betadot>0);
assume(psi>0);
assume(theta_0>0);
assume(sigma>0);
assume(sigma_0>0);

beta = 0; % Assuming NO blade flapping
betadot = 0; % Assuming NO blade dynamics
mu = 0; % Assuming NO forward flight
theta = theta_0; % Assuming constant pitch
sigma = sigma_0; % Assuming constant solidity

arg1 = ( sigma*C_la/16 - lambda_c/2);
arg2 = sigma*C_la*theta*r/8;
lambda_BEMT = sqrt( arg1^2 + arg2 ) - arg1;
lambda = lambda_BEMT; % Assuming BEMT inflow
% lambda = lambda_c + lambda_i; % Assuming vetical flighth

lambda

```

lambda =

$$\frac{\lambda_c}{2} + \sqrt{\left(\frac{\lambda_c}{2} - \frac{C_{la}\sigma_0}{16}\right)^2 + \frac{C_{la}\sigma_0\theta_0 y}{8R} - \frac{C_{la}\sigma_0}{16}}$$

```

U_T = (Omega*R) * ( r + mu*sin(psi) );
U_P = (Omega*R) * ( lambda + r*betadot/Omega + mu*beta*cos(psi) );
U_R = (Omega*R) * ( mu*cos(psi) );

phi = U_P / U_T;
alpha = theta - phi; % sectional angle of attack

q = 0.5*rho*U_T^2; % dynamic pressure
Cl = C_la*(alpha); % lift coefficient
dL = q*c*Cl*dy; % sectional lift
dD = q*c*C_d*dy; % sectional drag

dT = N_b * ( dL ); % sectional thrust
dQ = N_b * ( phi*dL + dD ) * y; % sectional torque
dP = dQ * Omega; % sectional power

% sectional thrust
dT = simplify(dT)

```

dT =

$$\frac{C_{la} N_b \Omega^2 c \, dy \, \rho \, y^2 \left( \theta_0 - \frac{R \left( \frac{\lambda_c}{2} + \sqrt{\left( \frac{\lambda_c}{2} - \frac{C_{la} \sigma_0}{16} \right)^2 + \frac{C_{la} \sigma_0 \theta_0 y}{8 R} - \frac{C_{la} \sigma_0}{16}} \right)}{y} \right)}{2}$$

```

% sectional power
dP = simplify(dP)

```

dP =

$$N_b \Omega y \left( \frac{C_d \Omega^2 c \, dy \, \rho \, y^2}{2} + \frac{C_{la} \Omega^2 R c \, dy \, \rho \, y \left( \theta_0 - \frac{R \sigma_1}{y} \right) \sigma_1}{2} \right)$$

where

$$\sigma_1 = \frac{\lambda_c}{2} + \sqrt{\left( \frac{\lambda_c}{2} - \frac{C_{la} \sigma_0}{16} \right)^2 + \frac{C_{la} \sigma_0 \theta_0 y}{8 R} - \frac{C_{la} \sigma_0}{16}}$$

```

% Integrate along the blade
T_psi = int(dT, y, 0, R)

```

T\_psi =

$$\frac{C_{la}^2 N_b \Omega^2 R^3 c \, dy \, \rho \, \sigma_0}{64} + \frac{C_{la} N_b \Omega^2 R c \, dy \, \rho \left( \frac{R^2 \sigma_1^{3/2} (768 \sigma_1 - 320 \lambda_c^2 - \sigma_3 + 80 C_{la} \lambda_c \sigma_0)}{\sigma_2} - \frac{R^2 \left( \sigma_1 + \frac{C_{la}}{16} \right)}{2} \right)}{2}$$

where

$$\sigma_1 = \left( \frac{\lambda_c}{2} - \frac{C_{la} \sigma_0}{16} \right)^2$$

$$\sigma_2 = 30 C_{la}^2 \sigma_0^2 \theta_0^2$$

$$\sigma_3 = 5 C_{la}^2 \sigma_0^2$$

```
% Integrate along the blade
```

```
P_psi = int(dP, y, 0, R)
```

```
P_psi =
```

$$\frac{N_b \Omega^3 R^4 c \, dy \, \rho \left( 573440 \lambda_c^4 \sigma_1^{3/2} - 2752512 \lambda_c^2 \sigma_1^{5/2} - 819200 \lambda_c^4 \sqrt{\sigma_2^6} + 2752512 \lambda_c^2 \sqrt{\sigma_2^{10}} + 3932160 \right)}{64}$$

where

$$\sigma_1 = \sigma_2^2 + \frac{C_{la} \sigma_0 \theta_0}{8}$$

$$\sigma_2 = \frac{\lambda_c}{2} - \frac{C_{la} \sigma_0}{16}$$

```
% Integrate along the azimuth
```

```
dy = 1;
```

```
T_psi = subs(T_psi);
```

```
P_psi = subs(P_psi);
```

```
T_tot= int(T_psi, psi, 0, 2*pi)
```

```
T_tot =
```

$$\frac{\pi C_{la}^2 N_b \Omega^2 R^3 c \rho \sigma_0}{32} + \pi C_{la} N_b \Omega^2 R c \rho \left( \frac{R^2 \sigma_1^{3/2} (768 \sigma_1 - 320 \lambda_c^2 - \sigma_3 + 80 C_{la} \lambda_c \sigma_0)}{\sigma_2} - \frac{R^2 \left( \sigma_1 + \frac{C_{la} \sigma_0}{8} \right)}{\sigma_2} \right)$$

where

$$\sigma_1 = \left( \frac{\lambda_c}{2} - \frac{C_{la} \sigma_0}{16} \right)^2$$

$$\sigma_2 = 30 C_{la}^2 \sigma_0^2 \theta_0^2$$

$$\sigma_3 = 5 C_{la}^2 \sigma_0^2$$

```
% Integrate along the azimuth
P_tot = int(P_psi, psi, 0, 2*pi)
```

$$P_{tot} = \frac{\pi N_b \Omega^3 R^4 c \rho (573440 \lambda_c^4 \sigma_1^{3/2} - 2752512 \lambda_c^2 \sigma_1^{5/2} - 819200 \lambda_c^4 \sqrt{\sigma_2^6} + 2752512 \lambda_c^2 \sqrt{\sigma_2^{10}} + 3932160 \sigma_1 \sigma_2^3)}{32}$$

where

$$\sigma_1 = \sigma_2^2 + \frac{C_{la} \sigma_0 \theta_0}{8}$$

$$\sigma_2 = \frac{\lambda_c}{2} - \frac{C_{la} \sigma_0}{16}$$

```
% Normalize to a1
% a1 = subs( ( pi*N_b*rho*c*Omega^2*C_la*R^3 )/6 );
% a1 = subs( ( pi*N_b*rho*c*C_la*R^3 )/6 );
% T_tot = simplify( subs(T_tot / a1) )
% P_tot = simplify( subs(P_tot / a1) )
```

## Analysis on a 0.25m blade

```
N_b = 2;
R = 1/4; % m
c = 0.1/4; % m
rho = 1.225; % kg/m3
C_la = 2*3.14;
theta_0 = 20*3.14/180; % rad
C_d = C_la*theta_0 / 10;
sigma_0 = N_b*c*R/(pi*R^2);

T_tot = vpa(eval(subs(T_tot)), 2)
```

T\_tot =

$$2.4\text{e-}3 \Omega^2 - 4.7\text{e-}3 \Omega^2 \lambda_c - 0.3 \Omega^2 (0.11 (\sigma_1 + 0.017)^{3/2} (32.0 \lambda_c + 777.0 \sigma_1 - 322.0 \lambda_c^2 + 13.0) - 0.11 \sigma_1^{3/2})$$

where

$$\sigma_1 = (0.5 \lambda_c - 0.025)^2$$

$$P_{\text{tot}} = \text{vpa}(\text{eval}(\text{subs}(P_{\text{tot}})), 2)$$

$$P_{\text{tot}} =$$

$$2.3\text{e-}5 \Omega^3 (17.0 \lambda_c + 577.0 \lambda_c \sigma_2^{3/2} - 11.0 \sigma_2^{3/2} + 6.9\text{e+}3 \sigma_2^{5/2} + 3.9\text{e+}6 \sigma_2^{7/2} - 455.0 \lambda_c \sigma_1 - 8.6\text{e+}3 \lambda_c^2 \sigma_2^{3/2})$$

where

$$\sigma_1 = \sqrt{(0.5 \lambda_c - 0.025)^6}$$

$$\sigma_2 = (0.5 \lambda_c - 0.025)^2 + 0.017$$

$$\sigma_3 = \sqrt{(0.5 \lambda_c - 0.025)^{10}}$$

## BEMT inflow dependance on climb velocity

```
% Integrate along the blade
avg_lambda = int(lambda, y, 0, R) / R;
avg_lambda = vpa(eval(subs(avg_lambda)), 2)
```

$$\text{avg\_lambda} = 0.5 \lambda_c + 38.0 ((0.5 \lambda_c - 0.025)^2 + 0.017)^{3/2} - 38.0 ((0.5 \lambda_c - 0.025)^2)^{3/2} - 0.025$$

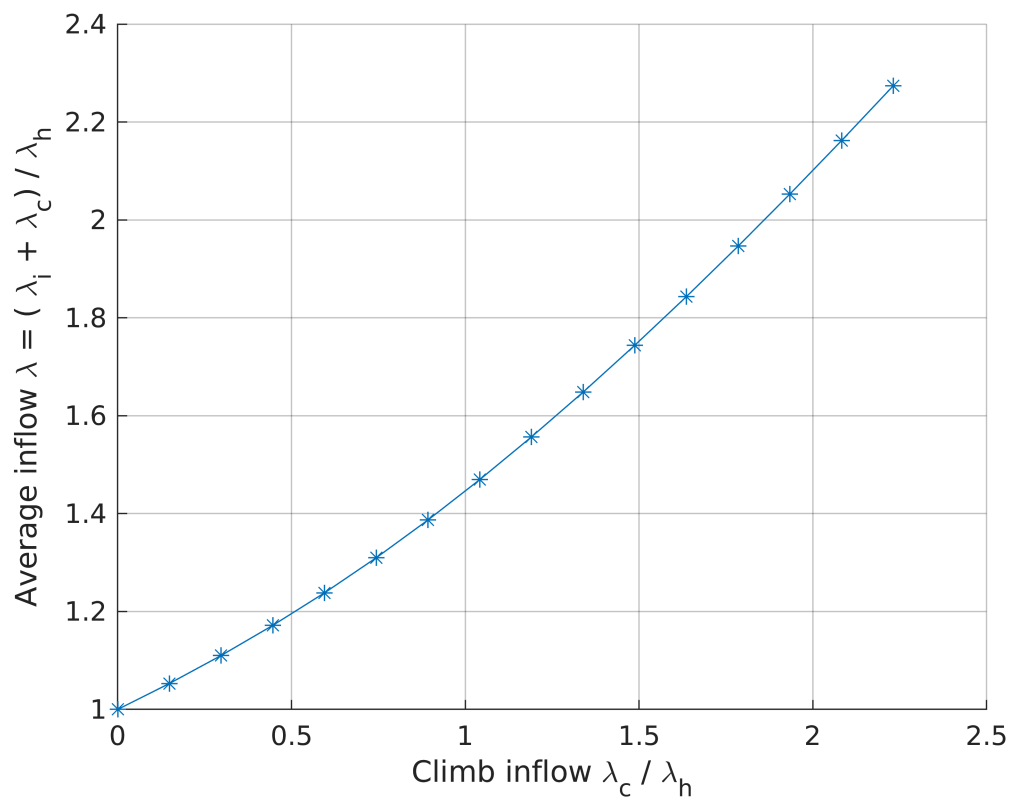
```
lambda_c_arr = 0:0.01:0.15;
ns = length(lambda_c_arr);

avg_lambda_arr = zeros(ns, 1);
avg_lambda_i_arr = zeros(ns, 1);
for i = 1:ns
    lc = lambda_c_arr(i); % / (Omega*R);
    avg_lambda_arr(i) = subs(avg_lambda, lambda_c, lc);
    avg_lambda_i_arr(i) = avg_lambda_arr(i) - lc;
end

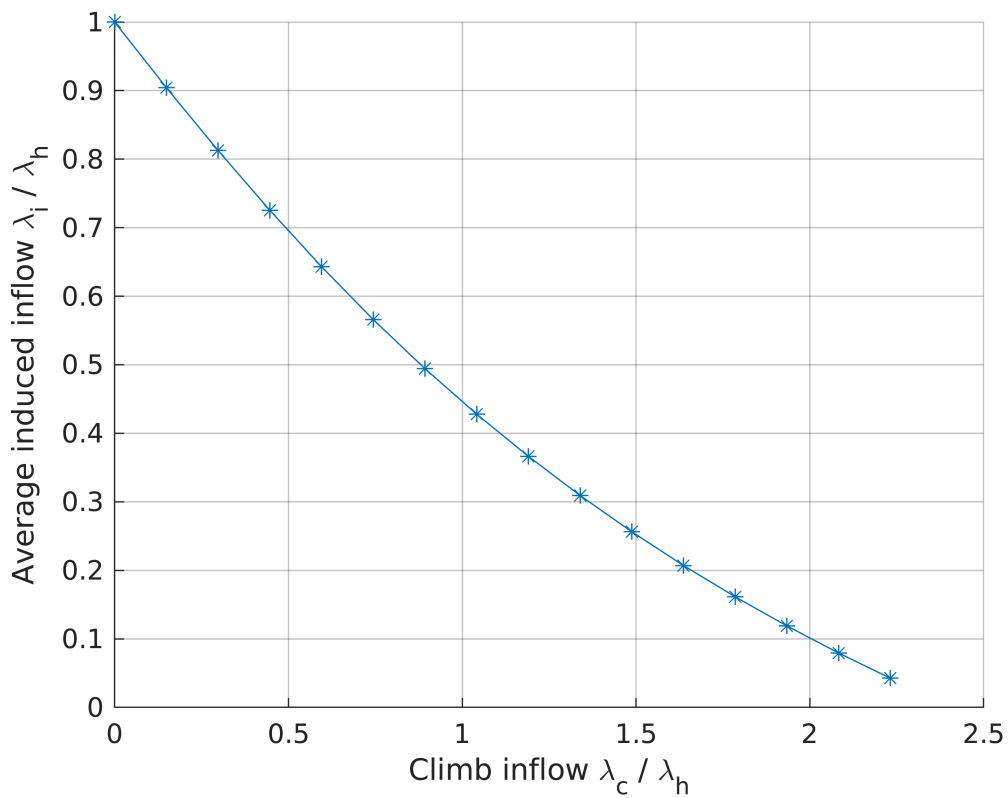
lh = avg_lambda_arr(1)
```

$$lh = 0.0672$$

```
figure;
hold on;
grid on;
plot(lambda_c_arr./lh, avg_lambda_arr./lh, '-*')
% legend('isolation', 'interference')
xlabel('Climb inflow \lambda_c / \lambda_h')
ylabel('Average inflow \lambda = ( \lambda_i + \lambda_c ) / \lambda_h')
```



```
figure;
hold on;
grid on;
plot(lambda_c_arr./lh, avg_lambda_i_arr./lh, '-*')
% legend('isolation', 'interference')
xlabel('Climb inflow \lambda_c / \lambda_h')
ylabel('Average induced inflow \lambda_i / \lambda_h')
```



## Thrust dependance on climb velocity (at fixed RPM)

```

lambda_c_arr = 0:0.01:0.15;
ns = length(lambda_c_arr);

Omega_arr = zeros(ns, 1);
T_arr = zeros(ns, 1);
P_arr = zeros(ns, 1);
for i = 1:ns
    lc = lambda_c_arr(i);
    T_i = subs(T_tot, lambda_c, lc);
    P_i = subs(P_tot, lambda_c, lc);

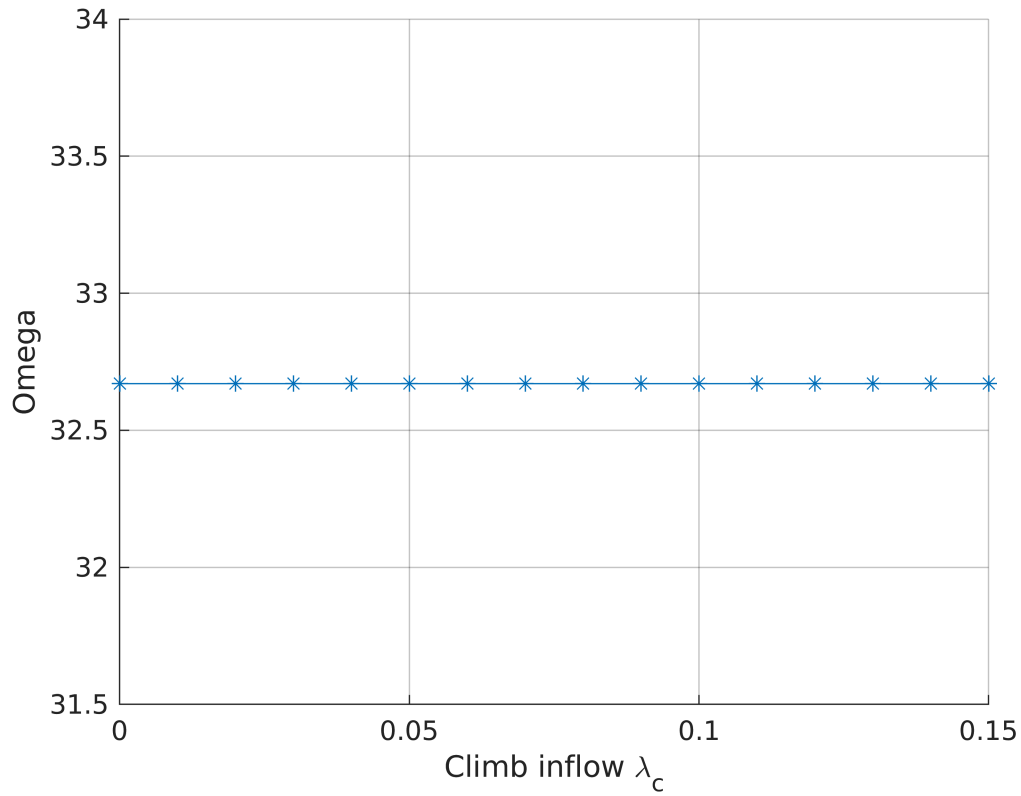
    Omega_0 = 32.6702;    % Hz
    solx = Omega_0;

    Omega_arr(i) = solx;
    T_arr(i) = subs(T_i, Omega, solx);
    P_arr(i) = subs(P_i, Omega, solx);
end

figure;
hold on;
grid on;
plot(lambda_c_arr, Omega_arr, '-*')
% legend('isolation', 'interference')
xlabel('Climb inflow \lambda_c')

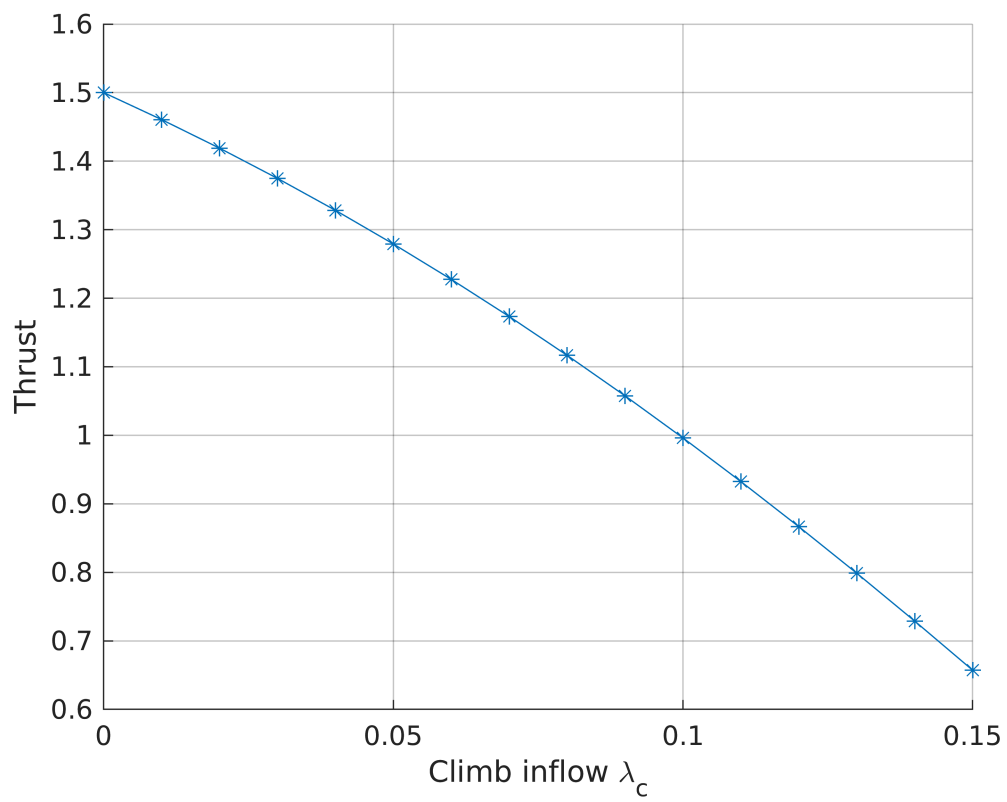
```

```
ylabel('Omega')
```

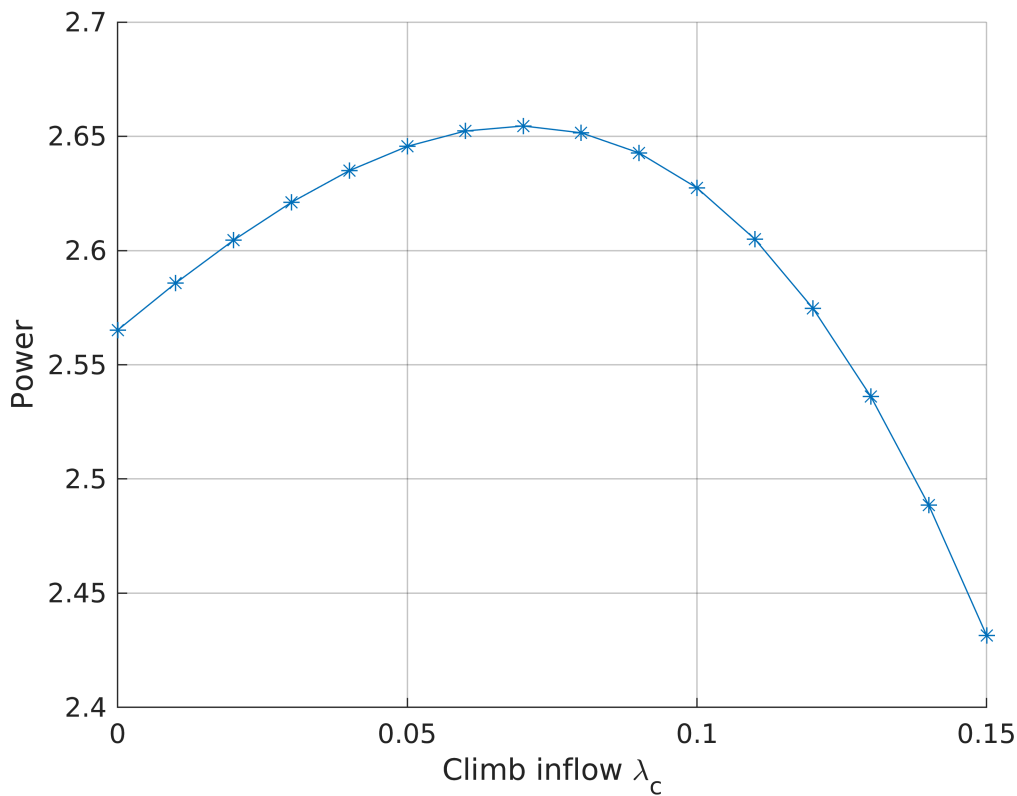


```
figure;  
hold on;  
grid on;  
plot(lambda_c_arr, T_arr, '-*')  
% legend('isolation', 'interference')  
xlabel('Climb inflow \lambda_c')  
ylabel('Thrust')
```





```
figure;  
hold on;  
grid on;  
plot(lambda_c_arr, P_arr, '-*')  
% legend('isolation', 'interference')  
xlabel('Climb inflow \lambda_c')  
ylabel('Power')
```



## Power dependance on climb velocity (at fixed Thrust)

```

lambda_c_arr = 0:0.01:0.15;
ns = length(lambda_c_arr);

Omega_arr = zeros(ns, 1);
T_arr = zeros(ns, 1);
P_arr = zeros(ns, 1);
for i = 1:ns
    lc = lambda_c_arr(i);
    T_i = subs(T_tot, lambda_c, lc);
    P_i = subs(P_tot, lambda_c, lc);

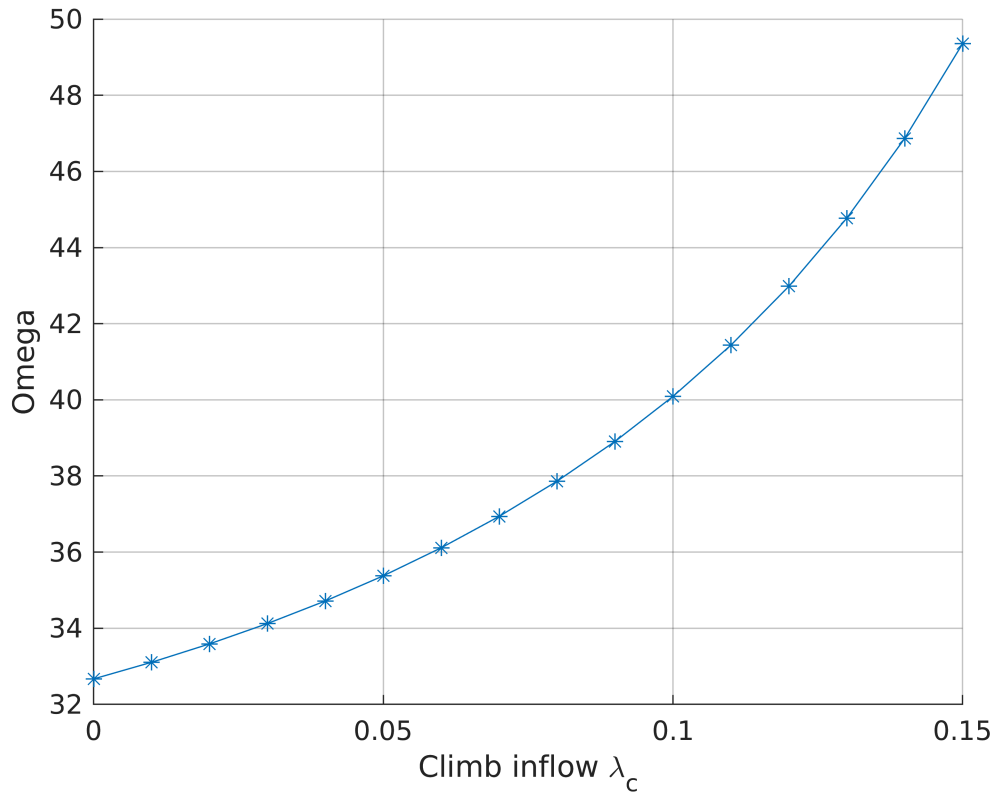
    T_0 = 1.5;
    [solx, parameters, conditions] = solve(T_i == T_0, Omega, 'ReturnConditions', true)

    Omega_arr(i) = solx;
    T_arr(i) = subs(T_i, Omega, solx);
    P_arr(i) = subs(P_i, Omega, solx);
end

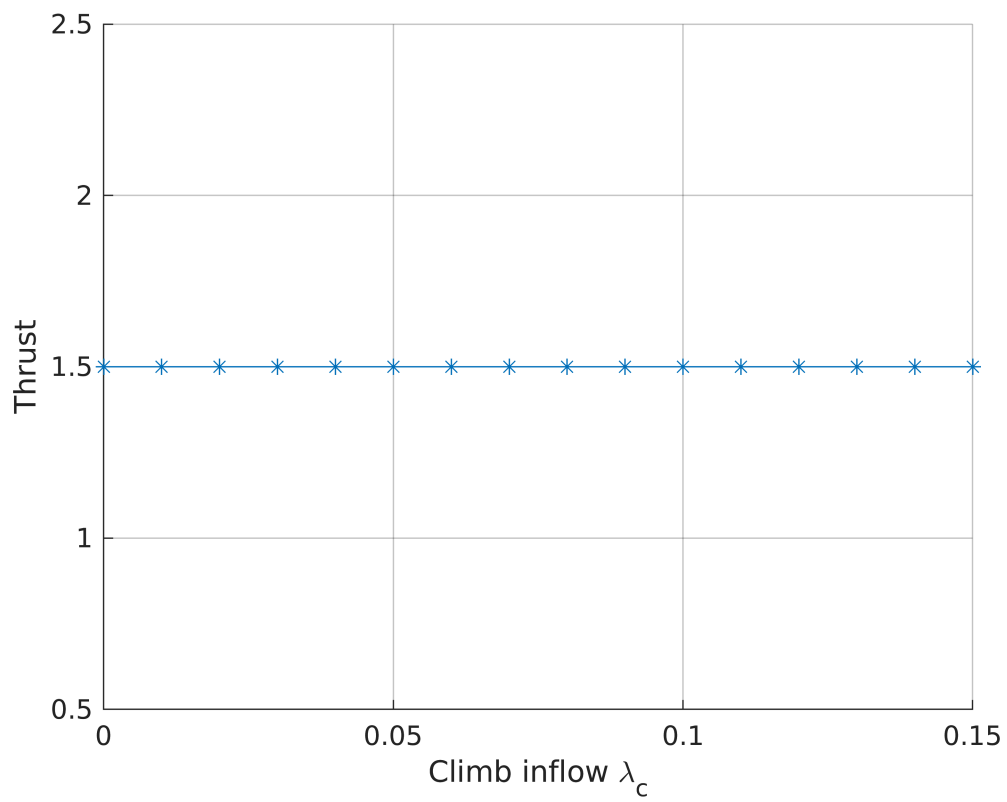
figure;
hold on;
grid on;
plot(lambda_c_arr, Omega_arr, '-*')
% legend('isolation', 'interference')
xlabel('Climb inflow \lambda_c')

```

```
ylabel('Omega')
```



```
figure;  
hold on;  
grid on;  
plot(lambda_c_arr, T_arr, '-*')  
% legend('isolation', 'interference')  
xlabel('Climb inflow \lambda_c')  
ylabel('Thrust')
```



```
figure;  
hold on;  
grid on;  
plot(lambda_c_arr, P_arr, '-*')  
% legend('isolation', 'interference')  
xlabel('Climb inflow \lambda_c')  
ylabel('Power')
```

