

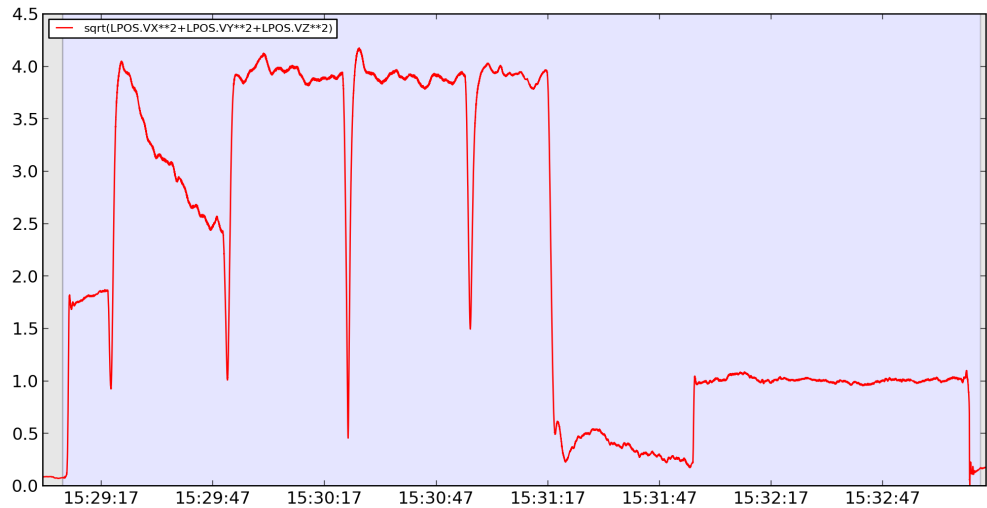
Upload News About

Other /

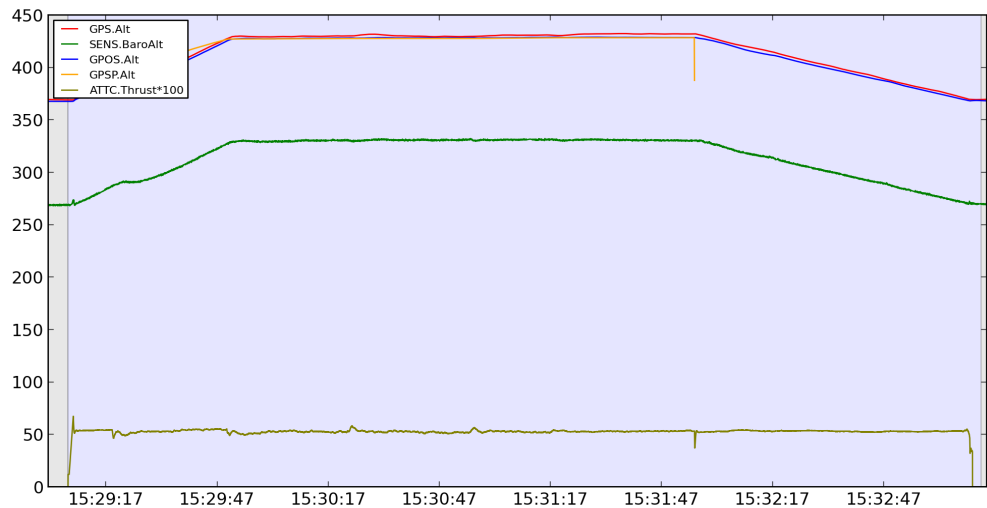
Map [\[link | top\]](#)

Disabled due to licensing issues.

Airspeed Estimate [\[link | top\]](#)



Altitude Estimate [\[link | top\]](#)



- General
- Parameters
 - Map

- Attitude
- Pitch Angle
 - Pitch Angular Rate
 - Roll Angle
 - Roll Angular Rate
 - Yaw / Heading Angle
 - Yaw Angular Rate

- Speed / Acceleration
- Airspeed
 - Raw Angular Speed
 - Raw Acceleration

- Position
- Altitude
 - Local Position (X)
 - Local Position (Y)
 - Local Position (Z)
 - Velocity

- GPS
- GPS Uncertainty
 - GPS Noise and Jamming

- Inputs/Outputs
- Raw RC Inputs
 - Actuator Outputs
 - Actuator AUX Outputs

- Magnetic
- Magnetic Field Strength
 - Thrust and Magnetic Field

- Distance
- Distance Sensor
 - Laser Landing

- System
- Power

- TECS
- Outer Loop
 - Inner Loop
 - Airspeed
 - Airspeed Derivative
 - Actuators
 - F

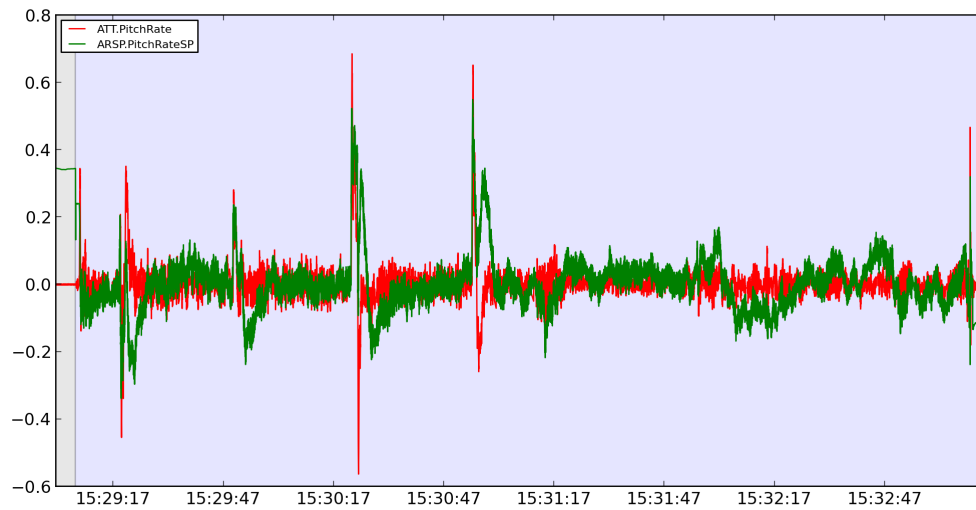
- Environment
- Wind

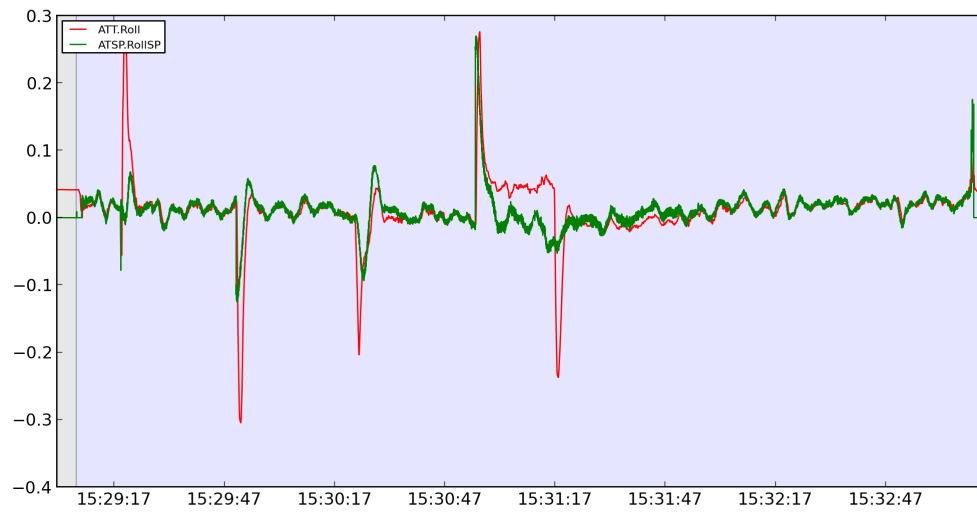
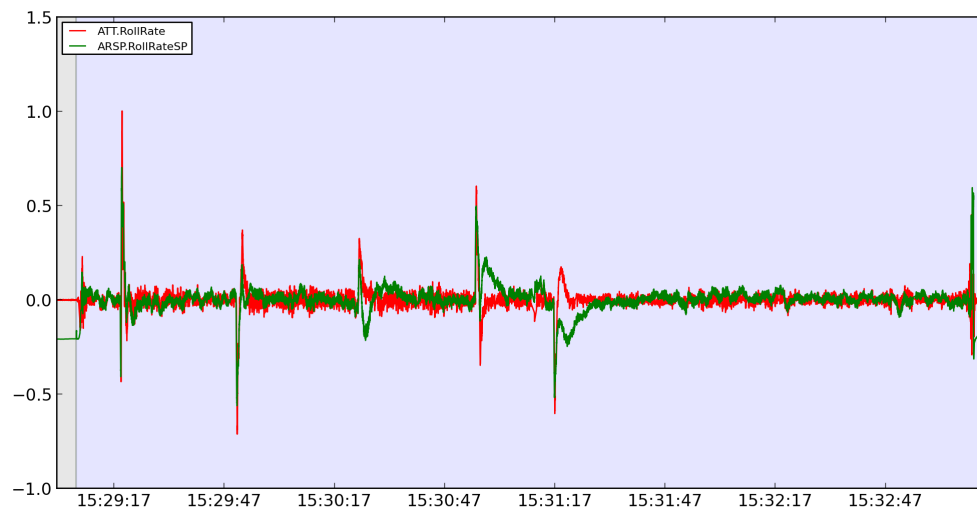
- Monitoring
- Filter Watchdog

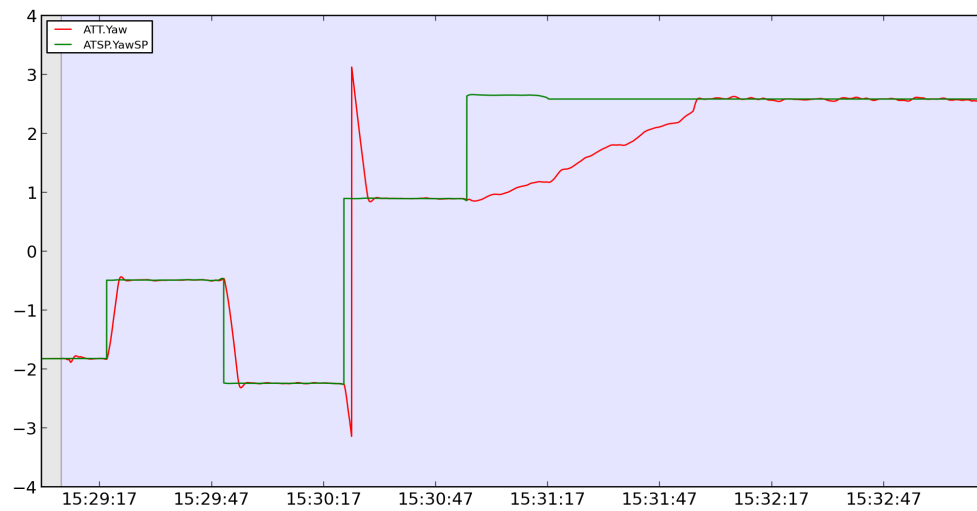
- Downloads
- Raw Log File
 - KML File

Pitch Angle [[link](#) | [top](#)]**Debugging**[LogMuncher Log](#)**Plot Legend**

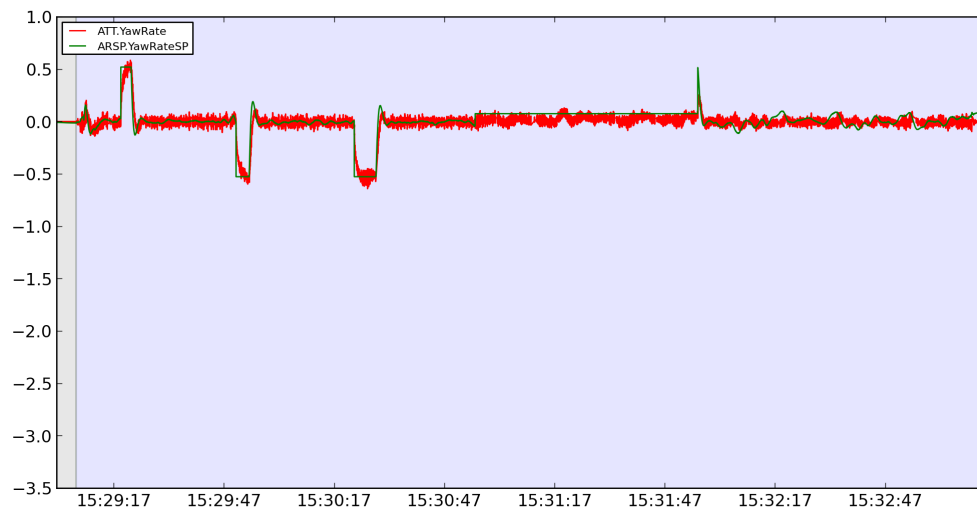
- ☐ Manual
- ☐ Stabilised
- ☐ AltCtl
- ☐ PosCtl
- ☐ Auto

Pitch Angular Rate [[link](#) | [top](#)]**Roll Angle** [[link](#) | [top](#)]

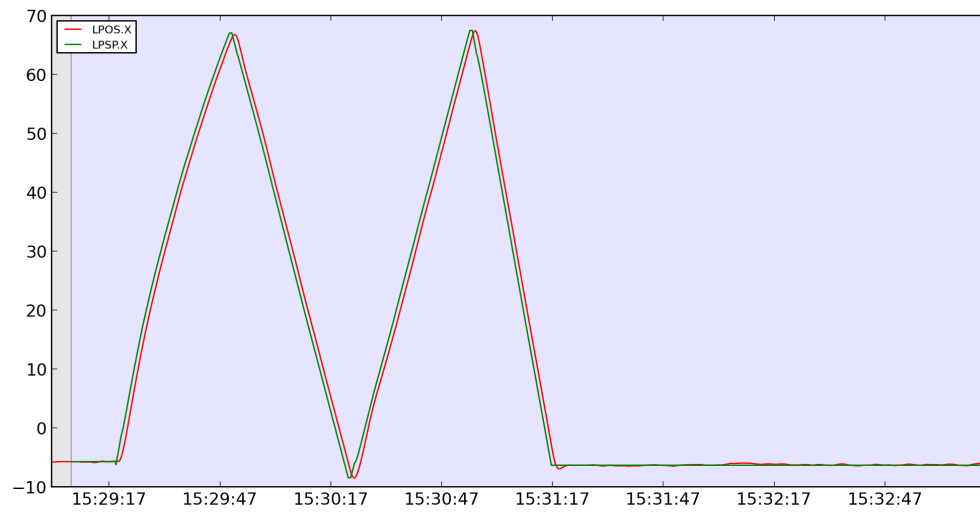
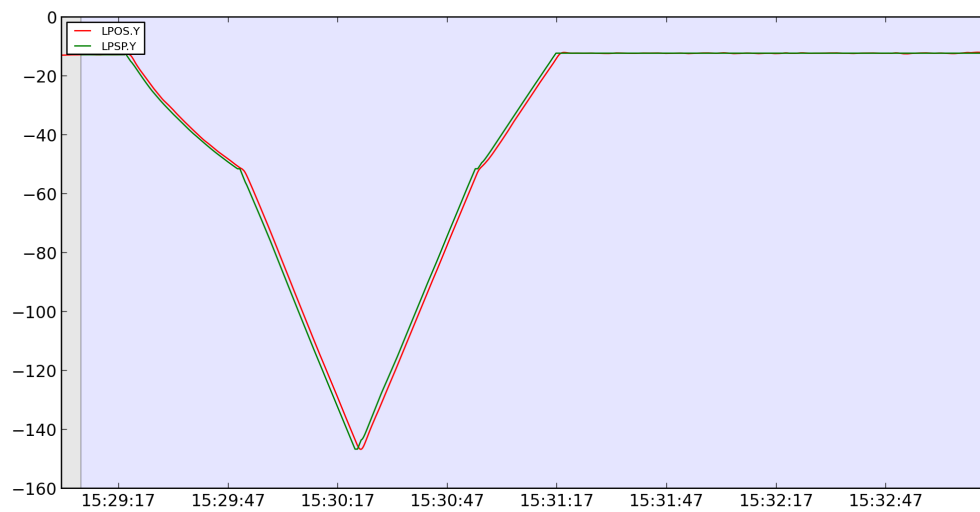
**Roll Angular Rate** [[link](#) | [top](#)]**Yaw / Heading Angle** [[link](#) | [top](#)]

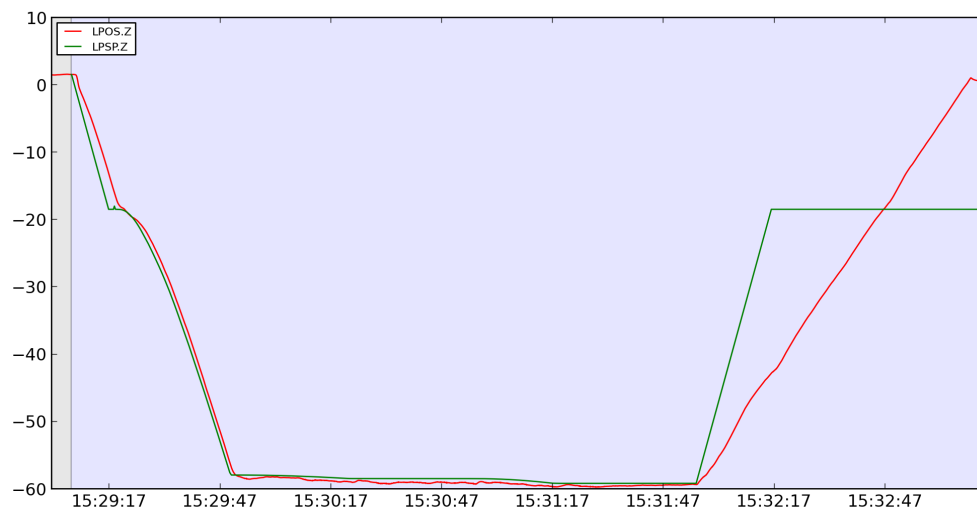
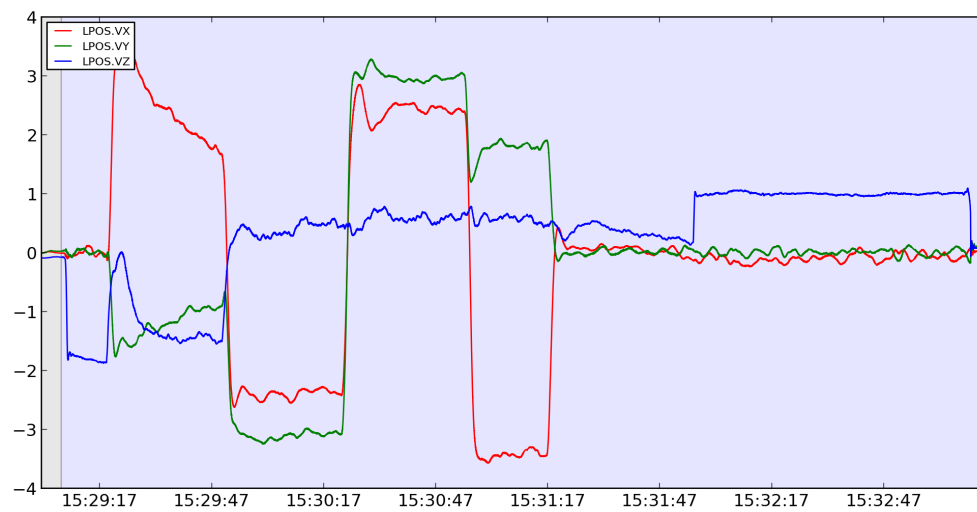


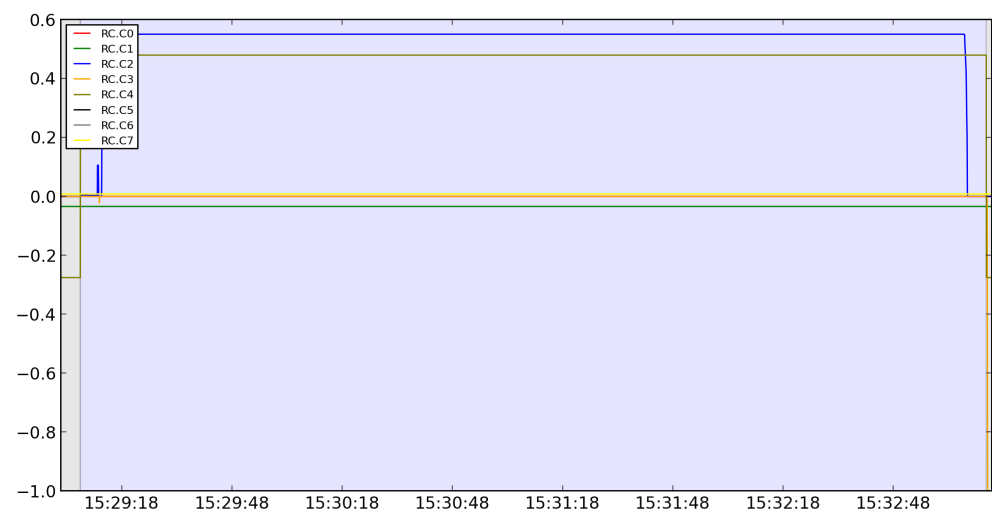
Yaw Angular Rate [\[link\]](#) [\[top\]](#)



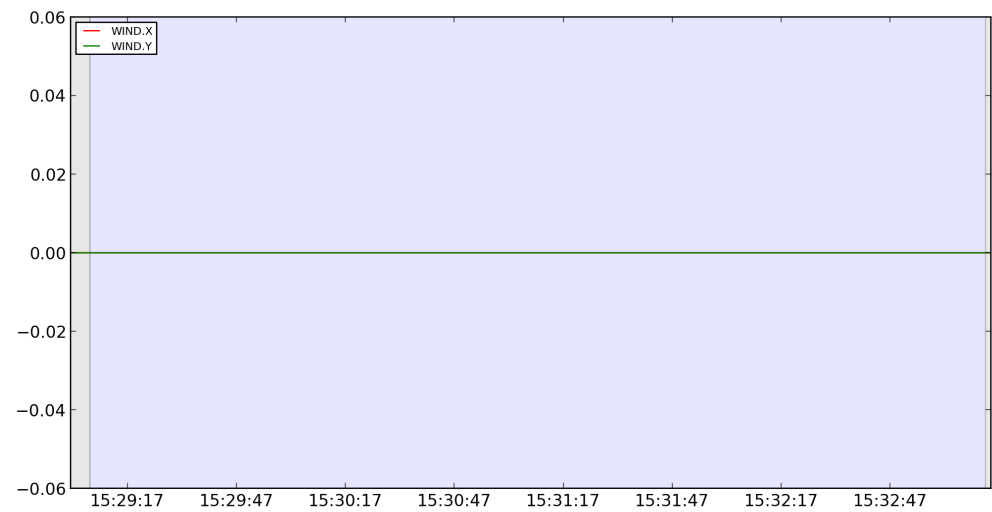
Local Position (X) [\[link\]](#) [\[top\]](#)

**Local Position (Y)** [\[link\]](#) [\[top\]](#)**Local Position (Z)** [\[link\]](#) [\[top\]](#)

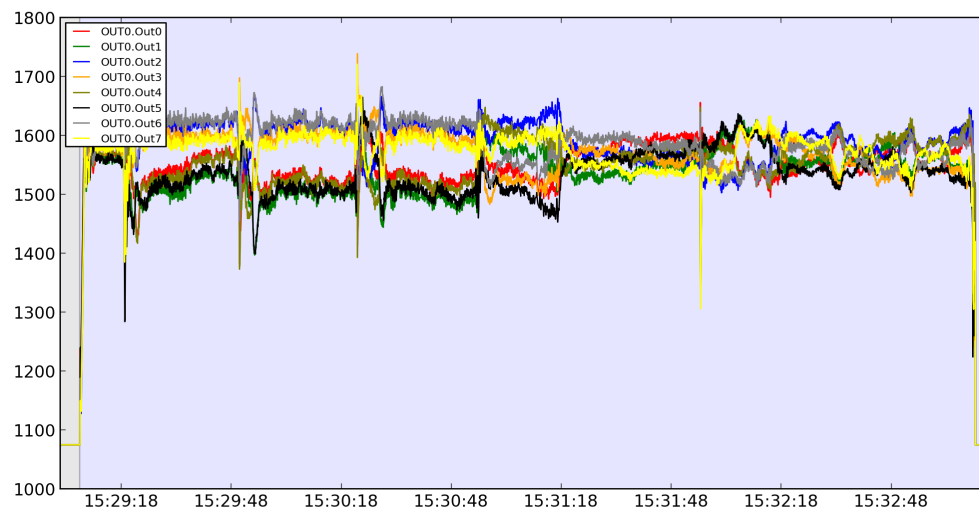
**Velocity** [\[link\]](#) [\[top\]](#)**Raw Radio Control Inputs** [\[link\]](#) [\[top\]](#)



Wind [\[link\]](#) [\[top\]](#)

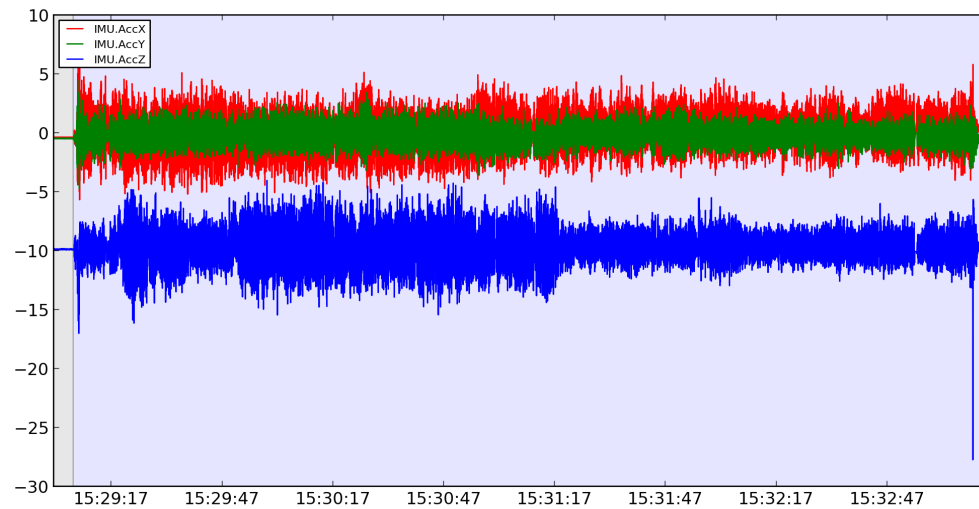


Actuators [\[link\]](#) [\[top\]](#)

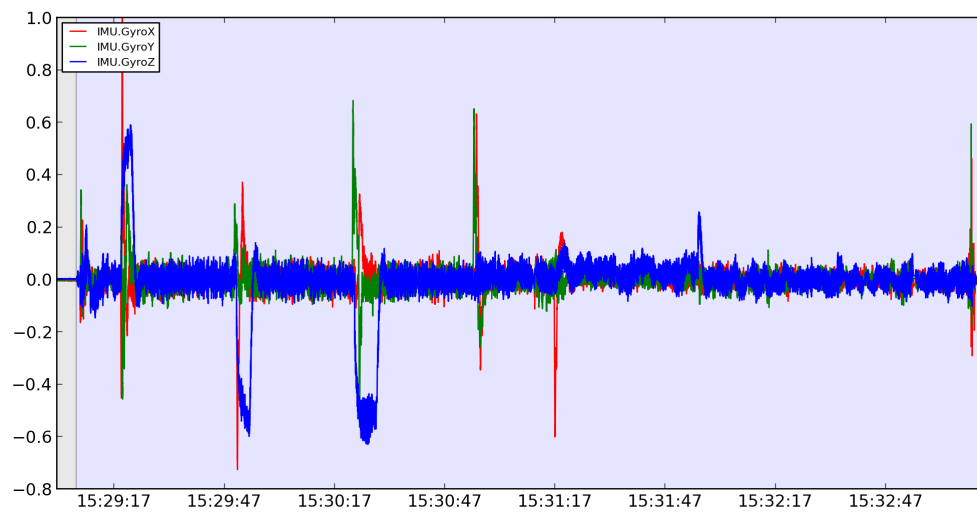
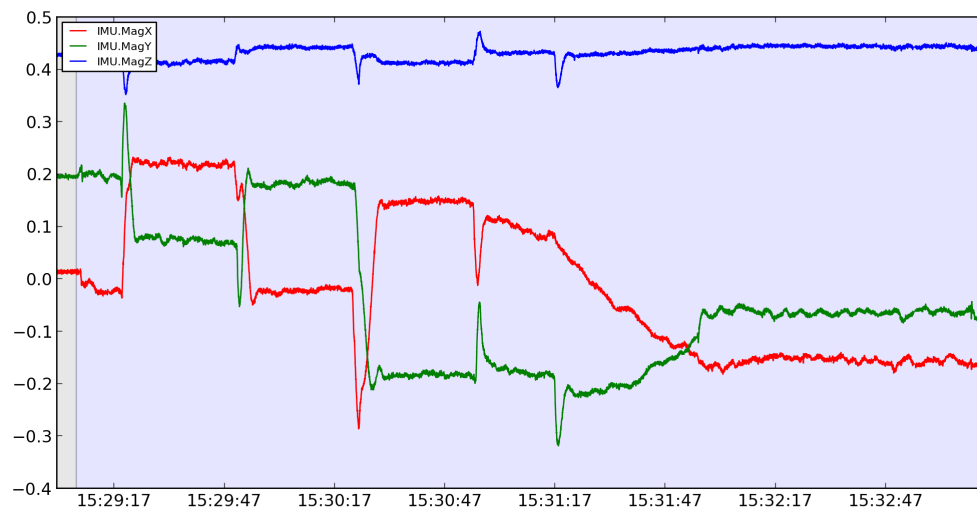


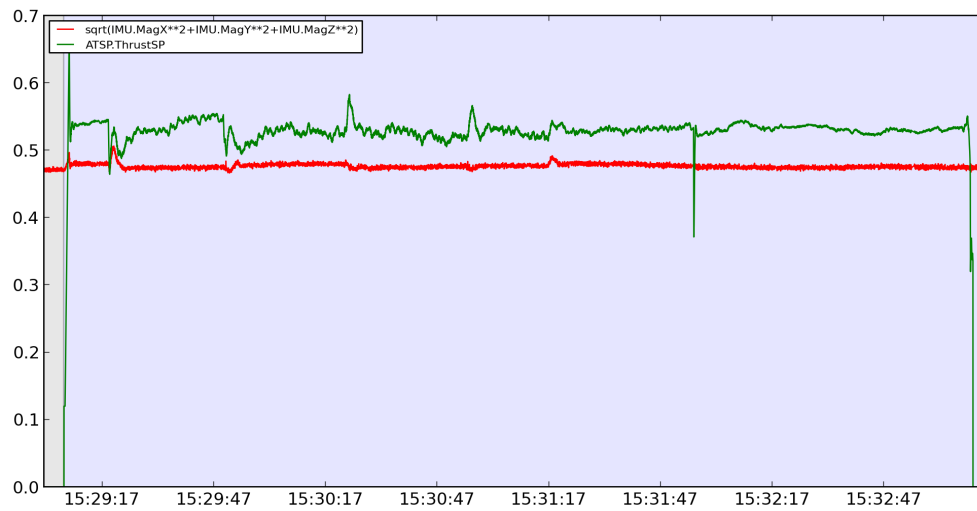
Actuators AUX [\[link\]](#) [\[top\]](#)

Raw Acceleration [\[link\]](#) [\[top\]](#)



Raw Angular Speed [\[link\]](#) [\[top\]](#)

**Magnetic Field Strength** [\[link | top\]](#)**GPS Uncertainty** [\[link | top\]](#)**GPS Noise and Jamming** [\[link | top\]](#)**Thrust and Magnetic Field** [\[link | top\]](#)

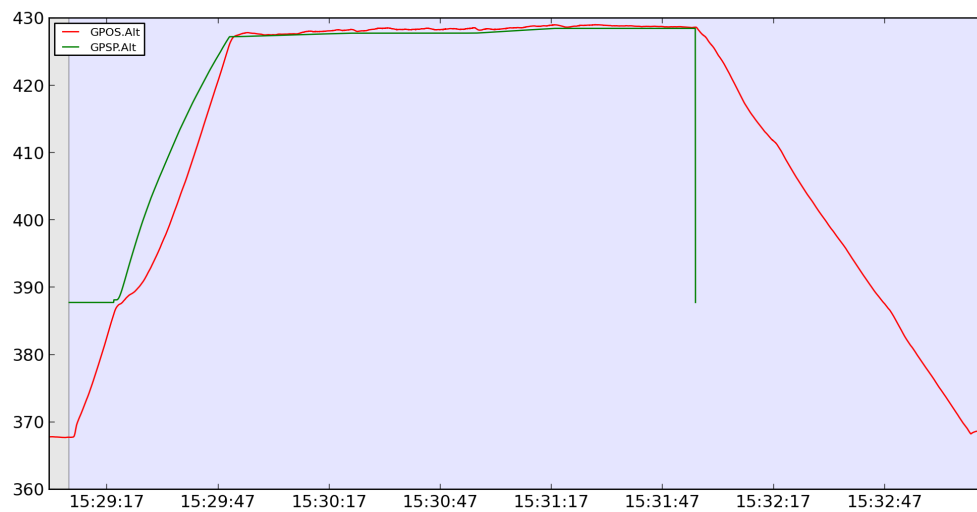


Distance Sensor [\[link\]](#) [\[top\]](#)

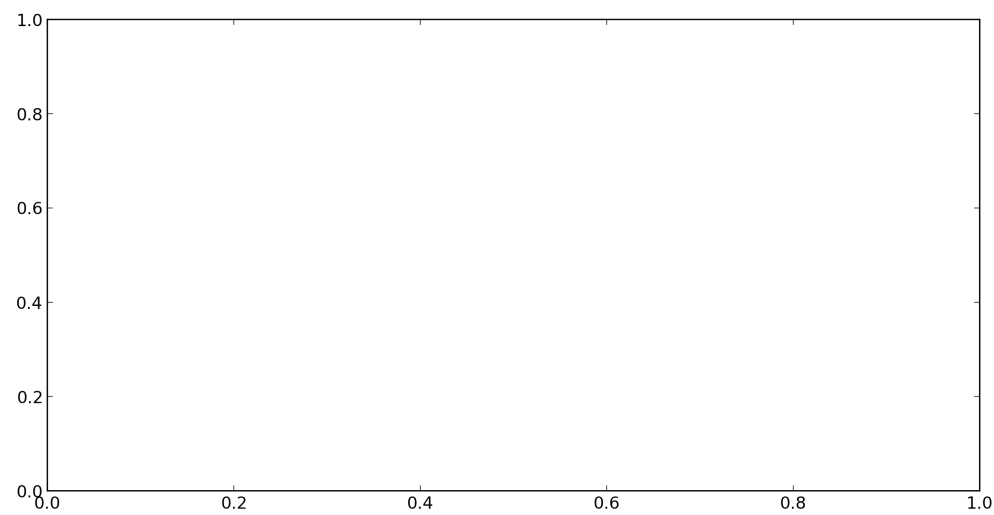
Laser Landing [\[link\]](#) [\[top\]](#)

Power [\[link\]](#) [\[top\]](#)

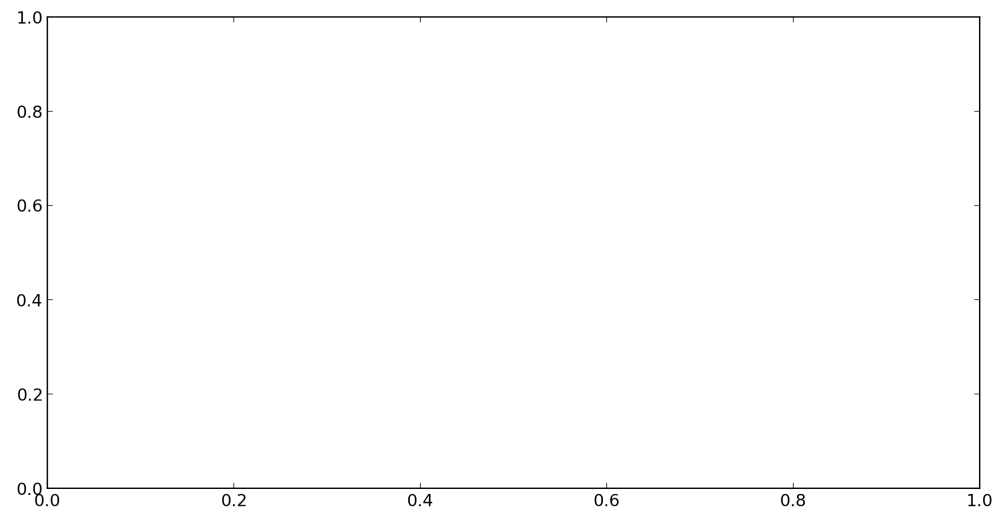
TECS Outer Loop [\[link\]](#) [\[top\]](#)



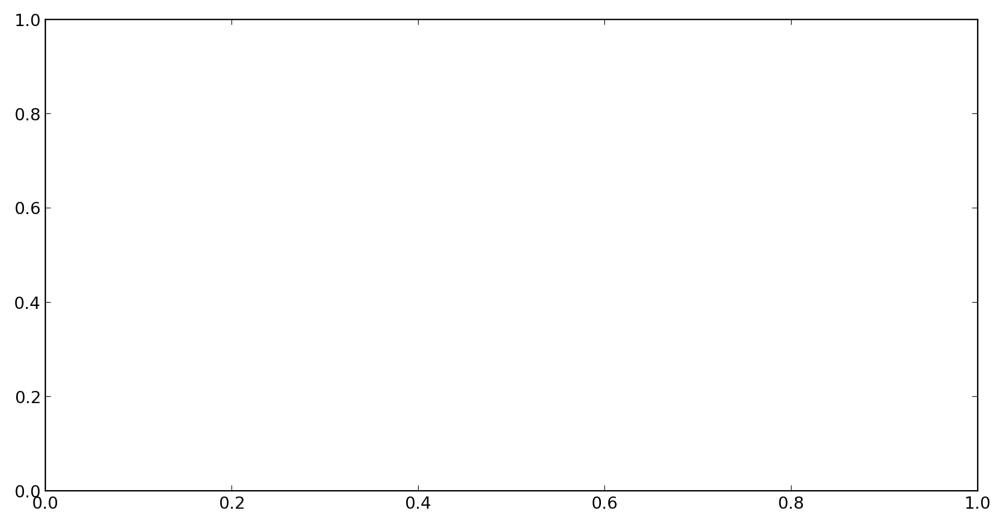
TECS Inner Loop [\[link\]](#) [\[top\]](#)



TECS Airspeed [\[link\]](#) [\[top\]](#)



TECS Airspeed Derivative [\[link\]](#) [\[top\]](#)



TECS Actuators [\[link\]](#) [\[top\]](#)

TECS F [\[link\]](#) [\[top\]](#)

Filter Watchdog [\[link\]](#) [\[top\]](#)

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