

RPI SETUP

Topi

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1. Burn 32 bit buster image using Rpi imager.
2. Create file "ssh" into boot partition.
3. Create file: wpa_supplicant.conf into boot partition.

```
1 country=SE
2 ctrl_interface=DIR=/var/run/wpa_supplicant GROUP=netdev
3 update_config=1
4
5 network={
6 ssid="#Telia-D5B7C8"
7 psk="*G41H*2r#pE-faR4"
8 }
```

4. So the wpa did not work with the telia ssid - needed to change that to nkai wifi and then worked... What the heck... Anyhow, then in `/etc/wpa_supplicant/` go and edit the file `sudo nano wpa_supplicant.conf` and add the other ssids...

5. `sudo pat update && sudo apt upgrade`

6. We try to install <https://github.com/mpromonet/v4l2rtspserver.git>

- `sudo apt install git cmake`
- `git clone https://github.com/mpromonet/v4l2rtspserver.git`
- `cd v4l2rtspserver && sudo cmake . && sudo make && sudo make install`
- Now you can run: `sudo v4l2rtspserver /dev/video0`
- On you local machine: open vlc, media -> open network stream -> `rtsp://<rpi ip>:8554/unicast`
- WORKS! Latency around 2sec.
- `sudo raspistill -v -o test.jpg`

7. Installed database <https://github.com/andymccurdy/redis-py>: `sudo apt get redis, client: pip3 install redis`

8. Redis is a server that is running on RPi. It is running there! Start, by `redis-server`

9. Subscribe from rpi to redis server - by python script.

10. On jetson write things into the database/server.

Enabling servo control using 16ch adafruit controller board.

1. create virtual env. `python3 -m venv venv`
2. activate it: `source venv/bin/activate`
3. `sudo apt-get install python-smbus`
4. `sudo apt-get install i2c-tools`
5. Read the i2c devices: `sudo i2cdetect -y 1`

6. install circuit python servokit: `pip3 install adafruit-circuitpython-servokit`

7. add topiko to i2c group for permissions: `sudo adduser topiko i2c`

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