

## Hamiltonian dynamics on Poisson manifolds

- Generalities on Poisson structures

- Hamiltonian systems

- A first approach to the numerical analysis on Poisson manifolds

## Symplectic groupoids

- Basic notions on groupoids

- Basics on symplectic groupoids

- Lagrangian bisections

- Birealisations

- Hamilton-Jacobi equation

## Hamiltonian Poisson integrators

- Butcher series

- Explicit construction through birealisations

- Numerical tests around a singularity: a Lotka-Volterra system

- Numerical tests of symmetry preservation: the rigid body

## Perspectives

- Poisson integrators in solid mechanics (with L. Le Marrec and V. Carlier)

- Deformation theory of symplectic groupoids and plasma physics

# Rooted trees

## Definition

Let  $T$  be the set of non-planar trees defined as follows. A non-planar Butcher tree is a rooted tree defined recursively by

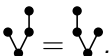
$$\bullet \in T, \quad (\tau_n, \dots, \tau_1)_\bullet \in T, \quad \tau_1, \dots, \tau_n \in T,$$

where the root is graphically represented at the bottom.

$(\tau_n, \dots, \tau_1)_\bullet$  denotes the tree with the root  $\bullet$  and the  $n$  trees  $\tau_n, \dots, \tau_1$  plugged to the root.

## Remark

*By non-planar, we mean that the order of the branches does not*

*matter: for instance, .*

# Grafting

The grafting of trees  $\curvearrowright$  is defined as a product on  $T$  returning the sum of all possibilities (counted with multiplicity) of grafting the root of one tree on the nodes of another tree.

## Example

$$\begin{array}{c} \bullet \\ | \\ \bullet \end{array} \curvearrowright \begin{array}{c} \bullet \\ | \\ \bullet \end{array} = \begin{array}{c} \bullet \\ / \backslash \\ \bullet \quad \bullet \end{array} + \begin{array}{c} \bullet \\ | \\ \bullet \\ | \\ \bullet \end{array}, \quad \bullet \curvearrowright \begin{array}{c} \bullet \\ / \backslash \\ \bullet \quad \bullet \end{array} = \begin{array}{c} \bullet \\ / \backslash \\ \bullet \quad \bullet \end{array} + 2 \begin{array}{c} \bullet \\ | \\ \bullet \\ / \backslash \\ \bullet \quad \bullet \end{array}, \quad \begin{array}{c} \bullet \\ / \backslash \\ \bullet \quad \bullet \end{array} \curvearrowright \bullet = \begin{array}{c} \bullet \\ / \backslash \\ \bullet \quad \bullet \end{array}.$$

By extending  $\curvearrowright$  linearly on  $\mathcal{T} = \text{Span}_{\mathbb{R}}(T)$ , this defines the pre-Lie algebra  $(\mathcal{T}, \curvearrowright)$  of Butcher trees.

## Remark

A natural grading on  $\mathcal{T}$  is given by the number of nodes:  $|\begin{array}{c} \bullet \\ / \backslash \\ \bullet \quad \bullet \end{array}| = 3$ .

$$\forall \tau_1, \tau_2 \in T, \quad |\tau_1 \curvearrowright \tau_2| = |\tau_1| + |\tau_2|.$$

# The elementary differential map

$\mathfrak{p} : \mathbb{G} \rightarrow M$  the cotangent projection  
 $0 : M \rightarrow \mathbb{G}$  the zero section of  $\mathbb{G}$  . Let  $H \in \mathcal{C}^\infty(M)$ .

## Definition (Elementary differential map)

The elementary differential map  $\mathbb{F}^H : \mathcal{T} \rightarrow \mathcal{C}^\infty(M)$  associated to  $H$  is defined by

$$\mathbb{F}^H(\bullet) = H \quad \text{and}$$

$$\mathbb{F}^H((\tau_n, \dots, \tau_1)\bullet) = 0^* \{ \{ \dots \{ \alpha^* H, \mathfrak{p}^* \mathbb{F}^H(\tau_1) \}_\omega, \dots \}_\omega, \mathfrak{p}^* \mathbb{F}^H(\tau_n) \}_\omega.$$

## Example

$$\mathbb{F}^H(\mathfrak{!}) = 0^* \{ \alpha^* H, \mathfrak{p}^* H \}_\omega.$$

## Idea

*Compute the terms of the Taylor series of the Hamilton-Jacobi equation by grafting trees and apply  $\mathbb{F}^H$ .*

# Butcher series

## Definition (Butcher series)

The B-series associated to  $H \in \mathcal{C}^\infty(M)$  is the following formal series indexed by a coefficient map  $a \in \mathcal{T}^*$ :

$$B^H: \begin{array}{ll} \mathcal{T}^* & \rightarrow \mathcal{C}^\infty(M)[[t]] \\ a & \mapsto \sum_{\tau \in \mathcal{T}} \frac{a(\tau)}{\sigma(\tau)} \mathbb{F}^{tH}(\tau) \end{array}$$

where  $\sigma(\tau)$  is the number of graph automorphisms of  $\tau$ , also called the symmetry coefficient.<sup>2</sup>

## Remark

For any  $\tau \in \mathcal{T}$ ,  $\mathbb{F}^{tH}(\tau) \in \mathcal{C}^\infty(M)[t]$ . Actually,  $\deg(\mathbb{F}^{tH}(\tau)) = |\tau|$ .

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<sup>2</sup>See Geometric Numerical Integration, Hairer et al., 2006, sec. III.1, for an explicit formula of the symmetry coefficient.

# Formal solution of HJ equation

## Lemma

For any  $(S_t)_{t \in I} \in \mathcal{C}^\infty(M \times I)$  and any  $(f_t)_{t \in I} \in \mathcal{C}^\infty(T^*M \times I)$ ,

$$\frac{\partial}{\partial t} ((dS_t)^* f_t) = (dS_t)^* \left( \{f_t, \mathfrak{p}^* \frac{\partial S_t}{\partial t}\}_\omega + \frac{\partial f_t}{\partial t} \right). \quad (4)$$

## Theorem (Busnot Laurent, O.C., 2025)

Let  $(S_t)_{t \in I} \in \mathcal{C}^\infty(M \times I)$  be the solution of the Hamilton-Jacobi equation (2), then its Taylor expansion is given by

$$B^H(e) \in \mathcal{C}^\infty(M)[[t]], \quad (5)$$

where  $e \in \mathcal{T}^*$  is given by

$$e(\bullet) = 1, \quad e(\tau) = \frac{1}{|\tau|} e(\tau_1) \dots e(\tau_n), \quad \tau = (\tau_n, \dots, \tau_1)_\bullet.$$

# Explicit construction through birealisations

Let  $\pi$  a Poisson structure on  $\mathbb{R}^d$ . Assume that a birealisation  $(\alpha, \beta)$  is constructed for  $\pi$ . Let  $H \in \mathcal{C}^\infty(\mathbb{R}^n)$ ,  $k \in \mathbb{N}$  and  $\Delta t > 0$  a time-step.

1. Solve the Hamilton-Jacobi equation up to order  $k$  using Butcher series of Equation (5). Obtain  $S_{\Delta t}^k \in \mathcal{C}^\infty(M)$ .
2. Let  $x_n \in \mathbb{R}^d$ . Solve the nonlinear equation

$$\alpha(\bar{x}_n, \nabla_{\bar{x}_n} S_{\Delta t}^k) = x_n$$

by a fixed point method, e.g., Newton descent.

3. One step of the obtained Hamiltonian Poisson integrator of order  $k$  and time-step  $\Delta t$  is then given by

$$x_{n+1} = \beta(\bar{x}_n, \nabla_{\bar{x}_n} S_{\Delta t}^k).$$

## Expected numerical behaviour

- ▶ **stay on a leaf** because the numerical methods are induced by bisections
- ▶ **stability near a singularity** because these bisections are Lagrangian
- ▶ **oscillate around first integrals** as symplectic numerical methods do



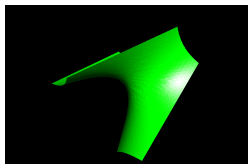
# Poisson structure and foliation of a cluster Poisson structure on $\mathbb{R}^3$

- ▶ **the Poisson bracket**

$$\{f, g\}(x) = (\nabla_x f)^T \cdot \begin{pmatrix} 0 & x_1 x_2 & x_1 x_3 \\ -x_1 x_2 & 0 & x_2 x_3 \\ -x_1 x_3 & -x_2 x_3 & 0 \end{pmatrix} \cdot \nabla_x g$$

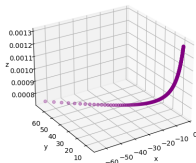
- ▶ **a bi-realisation**  $\left\{ \begin{array}{l} \alpha: (x, p) \mapsto \begin{pmatrix} e^{\frac{1}{2}(x_2 p_2 + x_3 p_3)} x_1 \\ e^{\frac{1}{2}(-x_1 p_1 + x_3 p_3)} x_2 \\ e^{-\frac{1}{2}(x_1 p_1 + x_2 p_2)} x_3 \end{pmatrix} \\ \beta: (x, p) \mapsto \alpha(x, -p) \end{array} \right. ,$

- ▶ **a symplectic leaf**



# A Hamiltonian vector field with an exploding trajectory

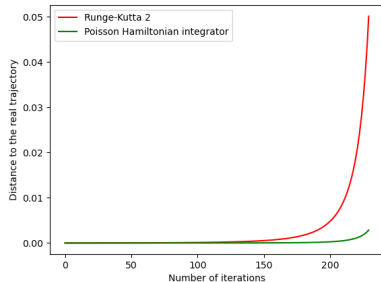
$$H(x) = \sum_{i=1}^3 x_i \Rightarrow \begin{cases} \dot{x}_1 = x_1(x_2 + x_3) \\ \dot{x}_2 = x_2(-x_1 + x_3) \\ \dot{x}_3 = -x_3(x_1 + x_2) \end{cases}$$



Exploding for  $\begin{pmatrix} x_1(0) \\ x_2(0) \\ x_3(0) \end{pmatrix} = \begin{pmatrix} -3 \\ 5 \\ 10^{-3} \end{pmatrix}$   
(Vanhaecke et al. 2016)

$$\begin{cases} \lim_{t \rightarrow \infty} x_1(t) = -\infty \\ \lim_{t \rightarrow \infty} x_2(t) = \infty \\ \lim_{t \rightarrow \infty} x_3(t) = 0 \end{cases} .$$

# Numerical simulation: comparison of numerical errors



Error with respect to the analytical solution

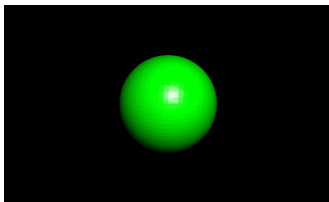
with initial point  $\begin{pmatrix} -3 \\ 5 \\ 10^{-3} \end{pmatrix}$  and  $\Delta t = 10^{-3}$ .

# Poisson structure and foliation of $\mathfrak{so}(3)^*$

- ▶ the Poisson bracket

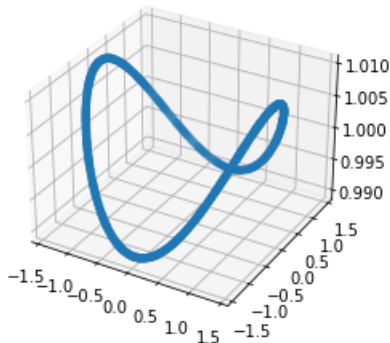
$$\{f, g\}(x) = (\nabla_x f)^T \cdot \begin{pmatrix} 0 & -x_3 & x_2 \\ x_3 & 0 & -x_1 \\ -x_2 & x_1 & 0 \end{pmatrix} \cdot \nabla_x g$$

- ▶ a bi-realisation  $\mathbb{R}^3 \simeq \mathfrak{so}(3) \begin{cases} \alpha: (x, p) \mapsto (I + \frac{p}{2}) \cdot x \cdot (I - \frac{p}{2}) \\ \beta: (x, p) \mapsto \alpha(x, -p) \end{cases}$
- ▶ a symplectic leaf



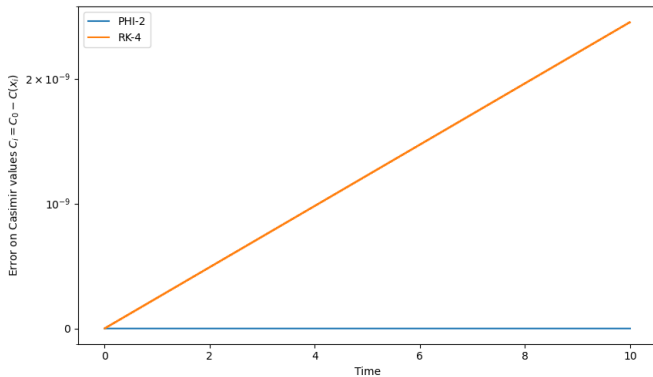
# The Hamiltonian vector field of angular velocity of a rigid body in $\mathbb{R}^3$

$$\begin{aligned} H(x) &= \frac{1}{2} \left( i_1(x_2^2 + x_3^2) \right. \\ &\quad \left. + i_2(x_1^2 + x_3^2) \right. \\ &\quad \left. + i_3(x_1^2 + x_2^2) \right) \\ \Rightarrow \dot{x} &= -x \wedge Ix \end{aligned}$$



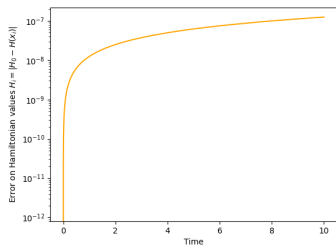
$$x(0) = (1, 1, 0)$$

# Preservation of Casimir levels

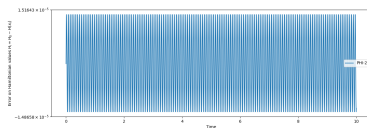


Error on Casimir values for PHI-2 and RK-4

# Controlled oscillations around Hamiltonian levels



Errors on Hamiltonian values for  
RK-4



Errors on Hamiltonian values for  
HPI-2

## Exercises

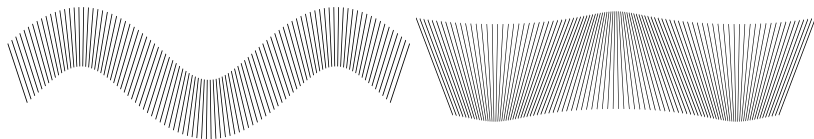
1. Use the lemma of Equation (4) to compute the terms of order 1 and 2 of the solution of the Hamilton-Jacobi equation (2).
2. Verify that the Butcher series of the equation (5) solves the Hamilton-Jacobi equation at order 2.



## Bibliography for the third lecture

- ▶ *Numerical Methods in Poisson Geometry and Applications to Mechanics*, O. C., C. Laurent-Gengoux, V. Salnikov, Mathematics and Mechanics of Solids, 2024
- ▶ *Butcher series for Hamiltonian Poisson integrators through symplectic groupoids*, A. Busnot Laurent, O. C., arXiv, 2025

# Poisson integrators for the Timoshenko model (w. L. Le Marrec, V. Carlier)



Two beam configurations

fig: Le Marrec

## Hamiltonian structure of Timoshenko model<sup>3</sup>

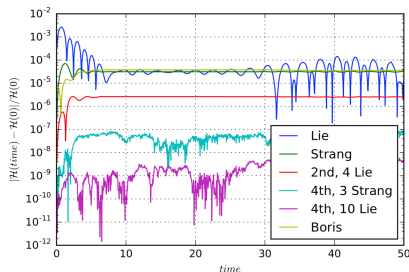
- ▶ compute a birealisation
- ▶ construct Hamiltonian Poisson integrators
- ▶ expect these numerical methods to track periodic orbits efficiently, detect instabilities...

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<sup>3</sup>*Timoshenko beam under finite and dynamic transformations: Lagrangian coordinates and Hamiltonian structures*, O.C. & Le Marrec, 2025

# Construction of birealisations by perturbative techniques

- ▶ Construct birealisations by studying deformation theory of symplectic groupoids  
→ several ongoing discussions with D. Calaque, A. Busnot Laurent, V. Dotsenko
- ▶ Poisson integrators in plasma physics with É. Sonnendrucker



Landau damping: energy error<sup>4</sup>

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<sup>4</sup>GEMPIC, Sonnendrucker et al., 2017