

Tensor Products of Pointed Sets

The Clowder Project Authors

May 3, 2024

In this chapter we introduce, construct, and study tensor products of pointed sets. The most well-known among these is the *smash product of pointed sets*

$$\wedge : \mathbf{Sets}_* \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*,$$

introduced in [Section 5.1](#), defined via a universal property as inducing a bijection between the following data:

- Pointed maps $f : X \wedge Y \rightarrow Z$.
- Maps of sets $f : X \times Y \rightarrow Z$ satisfying

$$\begin{aligned} f(x_0, y) &= z_0, \\ f(x, y_0) &= z_0 \end{aligned}$$

for each $x \in X$ and each $y \in Y$.

As it turns out, however, dropping either of the *bilinearity* conditions

$$\begin{aligned} f(x_0, y) &= z_0, \\ f(x, y_0) &= z_0 \end{aligned}$$

while retaining the other leads to two other tensor products of pointed sets,

$$\begin{aligned} \triangleleft : \mathbf{Sets}_* \times \mathbf{Sets}_* &\rightarrow \mathbf{Sets}_*, \\ \triangleright : \mathbf{Sets}_* \times \mathbf{Sets}_* &\rightarrow \mathbf{Sets}_*, \end{aligned}$$

called the *left* and *right tensor products of pointed sets*. In contrast to \wedge , which turns out to endow \mathbf{Sets}_* with a monoidal category structure ([Proposition 5.9.1](#)), these do not admit invertible associators and unitors, but do endow \mathbf{Sets}_* with the structure of a skew monoidal category, however ([Propositions 3.8.1](#) and [4.8.1](#)).

Finally, in addition to the tensor products \triangleleft , \triangleright , and \wedge , we also have a “tensor product” of the form

$$\odot : \mathbf{Sets} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*,$$

called the *tensor* of sets with pointed sets. All in all, these tensor products assemble into a family of functors of the form

$$\begin{aligned} \otimes_{k,\ell} : \mathbf{Mon}_{\mathbb{B}_k}(\mathbf{Sets}) \times \mathbf{Mon}_{\mathbb{B}_\ell}(\mathbf{Sets}) &\rightarrow \mathbf{Mon}_{\mathbb{B}_{k+\ell}}(\mathbf{Sets}), \\ \triangleleft_{i,k} : \mathbf{Mon}_{\mathbb{B}_k}(\mathbf{Sets}) \times \mathbf{Mon}_{\mathbb{B}_k}(\mathbf{Sets}) &\rightarrow \mathbf{Mon}_{\mathbb{B}_k}(\mathbf{Sets}), \\ \triangleright_{i,k} : \mathbf{Mon}_{\mathbb{B}_k}(\mathbf{Sets}) \times \mathbf{Mon}_{\mathbb{B}_k}(\mathbf{Sets}) &\rightarrow \mathbf{Mon}_{\mathbb{B}_k}(\mathbf{Sets}), \end{aligned}$$

where $k, \ell, i \in \mathbb{N}$ with $i \leq k - 1$. Together with the Cartesian product \times of \mathbf{Sets} , the tensor products studied in this chapter form the cases:

- $(k, \ell) = (-1, -1)$ for the Cartesian product of \mathbf{Sets} ;
- $(k, \ell) = (0, -1)$ and $(-1, 0)$ for the tensor of sets with pointed sets of [Definition 2.1.1](#);
- $(i, k) = (-1, 0)$ for the left and right tensor products of pointed sets of [Sections 3](#) and [4](#);
- $(k, \ell) = (-1, -1)$ for the smash product of pointed sets of [Section 5](#).

In this chapter, we will carefully define and study bilinearity for pointed sets, as well as all the tensor products described above. Then, in ??, we will extend these to tensor products involving also monoids and commutative monoids, which will end up covering all cases up to $k, \ell \leq 2$, and hence *all* cases since \mathbb{B}_k -monoids on \mathbf{Sets} are the same as \mathbb{B}_2 -monoids on \mathbf{Sets} when $k \geq 2$.

Contents

1	Bilinear Morphisms of Pointed Sets.....	4
1.1	Left Bilinear Morphisms of Pointed Sets.....	4
1.2	Right Bilinear Morphisms of Pointed Sets.....	5
1.3	Bilinear Morphisms of Pointed Sets.....	6
2	Tensors and Cotensors of Pointed Sets by Sets.....	7
2.1	Tensors of Pointed Sets by Sets.....	7
2.2	Cotensors of Pointed Sets by Sets.....	16

3	The Left Tensor Product of Pointed Sets	25
3.1	Foundations	25
3.2	The Left Internal Hom of Pointed Sets	30
3.3	The Left Skew Unit	32
3.4	The Left Skew Associator	32
3.5	The Left Skew Left Unitor	35
3.6	The Left Skew Right Unitor	39
3.7	The Diagonal	41
3.8	The Left Skew Monoidal Structure on Pointed Sets Associated to \triangleleft	42
3.9	Monoids With Respect to the Left Tensor Product of Pointed Sets	47
4	The Right Tensor Product of Pointed Sets	52
4.1	Foundations	52
4.2	The Right Internal Hom of Pointed Sets	57
4.3	The Right Skew Unit	59
4.4	The Right Skew Associator	60
4.5	The Right Skew Left Unitor	63
4.6	The Right Skew Right Unitor	65
4.7	The Diagonal	68
4.8	The Right Skew Monoidal Structure on Pointed Sets Associated to \triangleright	70
4.9	Monoids With Respect to the Right Tensor Product of Pointed Sets	75
5	The Smash Product of Pointed Sets	80
5.1	Foundations	80
5.2	The Internal Hom of Pointed Sets	91
5.3	The Monoidal Unit	94
5.4	The Associator	94
5.5	The Left Unitor	96
5.6	The Right Unitor	99
5.7	The Symmetry	102
5.8	The Diagonal	105
5.9	The Monoidal Structure on Pointed Sets Associated to \wedge	109
5.10	Universal Properties of the Smash Product of Pointed Sets I	114
5.11	Universal Properties of the Smash Product of Pointed Sets II	114
5.12	Monoids With Respect to the Smash Product of Pointed Sets	114
5.13	Comonoids With Respect to the Smash Product of Pointed Sets	115
6	Miscellany	115
6.1	The Smash Product of a Family of Pointed Sets	115

A Other Chapters 116

1 Bilinear Morphisms of Pointed Sets

1.1 Left Bilinear Morphisms of Pointed Sets

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets.

DEFINITION 1.1.1 ► LEFT BILINEAR MORPHISMS OF POINTED SETS

A **left bilinear morphism of pointed sets** from $(X \times Y, (x_0, y_0))$ to (Z, z_0) is a map of sets

$$f: X \times Y \rightarrow Z$$

satisfying the following condition:^{1,2}

(★) *Left Unital Bilinearity*. The diagram

$$\begin{array}{ccccc}
 & & \text{pt} \times \text{pt} & & \\
 & \nearrow \text{id}_{\text{pt}} \times \epsilon_Y & & \searrow \sim & \\
 \text{pt} \times Y & & & & \text{pt} \\
 \downarrow [x_0] \times \text{id}_Y & & & & \downarrow [z_0] \\
 X \times Y & \xrightarrow{f} & Z & &
 \end{array}$$

commutes, i.e. for each $y \in Y$, we have

$$f(x_0, y) = z_0.$$

¹*Slogan*: The map f is left bilinear if it preserves basepoints in its first argument.

²Succinctly, f is bilinear if we have

$$f(x_0, y) = z_0$$

for each $y \in Y$.

DEFINITION 1.1.2 ► THE SET OF LEFT BILINEAR MORPHISMS OF POINTED SETS

The **set of left bilinear morphisms of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0)** is the set $\text{Hom}_{\text{Sets}_*}^{\otimes, L}(X \times Y, Z)$ defined by

$$\text{Hom}_{\text{Sets}_*}^{\otimes, L}(X \times Y, Z) \stackrel{\text{def}}{=} \{f \in \text{Hom}_{\text{Sets}}(X \times Y, Z) \mid f \text{ is left bilinear}\}.$$

1.2 Right Bilinear Morphisms of Pointed Sets

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets.

DEFINITION 1.2.1 ► RIGHT BILINEAR MORPHISMS OF POINTED SETS

A **right bilinear morphism of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0)** is a map of sets

$$f: X \times Y \rightarrow Z$$

satisfying the following condition:^{1,2}

(★) *Right Unital Bilinearity.* The diagram

$$\begin{array}{ccccc} & & \text{pt} \times \text{pt} & & \\ & \nearrow \epsilon_X \times \text{id}_{\text{pt}} & & \searrow \sim & \\ X \times \text{pt} & & & & \text{pt} \\ & \searrow \text{id}_X \times [y_0] & & \nearrow [z_0] & \\ X \times Y & \xrightarrow{f} & Z & & \end{array}$$

commutes, i.e. for each $x \in X$, we have

$$f(x, y_0) = z_0.$$

¹*Slogan:* The map f is right bilinear if it preserves basepoints in its second argument.

²Succinctly, f is bilinear if we have

$$f(x, y_0) = z_0$$

for each $x \in X$.

DEFINITION 1.2.2 ► THE SET OF RIGHT BILINEAR MORPHISMS OF POINTED SETS

The **set of right bilinear morphisms of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0)** is the set $\text{Hom}_{\text{Sets}_*}^{\otimes, R}(X \times Y, Z)$ defined by

$$\text{Hom}_{\text{Sets}_*}^{\otimes, R}(X \times Y, Z) \stackrel{\text{def}}{=} \{f \in \text{Hom}_{\text{Sets}}(X \times Y, Z) \mid f \text{ is right bilinear}\}.$$

1.3 Bilinear Morphisms of Pointed Sets

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets.

DEFINITION 1.3.1 ► BILINEAR MORPHISMS OF POINTED SETS

A **bilinear morphism of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0)** is a map of sets

$$f: X \times Y \rightarrow Z$$

that is both left bilinear and right bilinear.

REMARK 1.3.2 ► UNWINDING DEFINITION 1.3.1

In detail, a **bilinear morphism of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0)** is a map of sets

$$f: (X \times Y, (x_0, y_0)) \rightarrow (Z, z_0)$$

satisfying the following conditions:^{1,2}

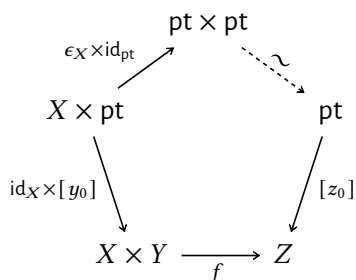
1. *Left Unital Bilinearity.* The diagram

$$\begin{array}{ccccc}
 & & \text{pt} \times \text{pt} & & \\
 & \nearrow \text{id}_{\text{pt}} \times \epsilon_Y & & \searrow \sim & \\
 \text{pt} \times Y & & & & \text{pt} \\
 \downarrow [x_0] \times \text{id}_Y & & & & \downarrow [z_0] \\
 X \times Y & \xrightarrow{f} & Z & &
 \end{array}$$

commutes, i.e. for each $y \in Y$, we have

$$f(x_0, y) = z_0.$$

2. *Right Unital Bilinearity.* The diagram



commutes, i.e. for each $x \in X$, we have

$$f(x, y_0) = z_0.$$

¹*Slogan:* The map f is bilinear if it preserves basepoints in each argument.

²Succinctly, f is bilinear if we have

$$f(x_0, y) = z_0,$$

$$f(x, y_0) = z_0$$

for each $x \in X$ and each $y \in Y$.

DEFINITION 1.3.3 ► THE SET OF BILINEAR MORPHISMS OF POINTED SETS

The **set of bilinear morphisms of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0)** is the set $\text{Hom}_{\text{Sets}_*}^{\otimes}(X \times Y, Z)$ defined by

$$\text{Hom}_{\text{Sets}_*}^{\otimes}(X \times Y, Z) \stackrel{\text{def}}{=} \{f \in \text{Hom}_{\text{Sets}}(X \times Y, Z) \mid f \text{ is bilinear}\}.$$

2 Tensors and Cotensors of Pointed Sets by Sets

2.1 Tensors of Pointed Sets by Sets

Let (X, x_0) be a pointed set and let A be a set.

DEFINITION 2.1.1 ► TENSORS OF POINTED SETS BY SETS

The **tensor of** (X, x_0) **by** A ¹ is the pointed set² $A \odot (X, x_0)$ satisfying the following universal property:

(UP) We have a bijection

$$\text{Sets}_*(A \odot X, K) \cong \text{Sets}(A, \text{Sets}_*(X, K)),$$

natural in $(K, k_0) \in \text{Obj}(\text{Sets}_*)$.

¹Further Terminology: Also called the **copower of** (X, x_0) **by** A .

²Further Notation: Often written $A \odot X$ for simplicity.

REMARK 2.1.2 ► UNWINDING DEFINITION 2.1.1

The universal property in **Definition 2.1.1** is equivalent to the following one:

(UP) We have a bijection

$$\text{Sets}_*(A \odot X, K) \cong \text{Sets}_{\mathbb{E}_0}^{\otimes}(A \times X, K),$$

natural in $(K, k_0) \in \text{Obj}(\text{Sets}_*)$, where $\text{Sets}_{\mathbb{E}_0}^{\otimes}(A \times X, K)$ is the set defined by

$$\text{Sets}_{\mathbb{E}_0}^{\otimes}(A \times X, K) \stackrel{\text{def}}{=} \left\{ f \in \text{Sets}(A \times X, K) \left| \begin{array}{l} \text{for each } a \in A, \text{ we} \\ \text{have } f(a, x_0) = k_0 \end{array} \right. \right\}.$$

PROOF 2.1.3 ► PROOF OF REMARK 2.1.2

We claim we have a bijection

$$\text{Sets}(A, \text{Sets}_*(X, K)) \cong \text{Sets}_{\mathbb{E}_0}^{\otimes}(A \times X, K)$$

natural in $(K, k_0) \in \text{Obj}(\text{Sets}_*)$. Indeed, this bijection is a restriction of the bijection

$$\text{Sets}(A, \text{Sets}(X, K)) \cong \text{Sets}(A \times X, K)$$

of **Constructions With Sets, Item 2 of Proposition 1.3.3**:

- A map

$$\begin{aligned}\xi: A &\longrightarrow \text{Sets}_*(X, K), \\ a &\mapsto (\xi_a: X \rightarrow K),\end{aligned}$$

in $\text{Sets}(A, \text{Sets}_*(X, K))$ gets sent to the map

$$\xi^\dagger: A \times X \rightarrow K$$

defined by

$$\xi^\dagger(a, x) \stackrel{\text{def}}{=} \xi_a(x)$$

for each $(a, x) \in A \times X$, which indeed lies in $\text{Sets}_{\mathbb{E}_0}^\otimes(A \times X, K)$, as we have

$$\begin{aligned}\xi^\dagger(a, x_0) &\stackrel{\text{def}}{=} \xi_a(x_0) \\ &\stackrel{\text{def}}{=} k_0\end{aligned}$$

for each $a \in A$, where we have used that $\xi_a \in \text{Sets}_*(X, K)$ is a morphism of pointed sets.

- Conversely, a map

$$\xi: A \times X \rightarrow K$$

in $\text{Sets}_{\mathbb{E}_0}^\otimes(A \times X, K)$ gets sent to the map

$$\begin{aligned}\xi^\dagger: A &\longrightarrow \text{Sets}_*(X, K), \\ a &\mapsto (\xi_a^\dagger: X \rightarrow K),\end{aligned}$$

where

$$\xi_a^\dagger: X \rightarrow K$$

is the map defined by

$$\xi_a^\dagger(x) \stackrel{\text{def}}{=} \xi(a, x)$$

for each $x \in X$, and indeed lies in $\text{Sets}_*(X, K)$, as we have

$$\begin{aligned}\xi_a^\dagger(x_0) &\stackrel{\text{def}}{=} \xi(a, x_0) \\ &\stackrel{\text{def}}{=} k_0.\end{aligned}$$

This finishes the proof.



CONSTRUCTION 2.1.4 ► CONSTRUCTION OF TENSORS OF POINTED SETS BY SETS

Concretely, the **tensor of** (X, x_0) **by** A is the pointed set $A \odot (X, x_0)$ consisting of:

- *The Underlying Set.* The set $A \odot X$ given by

$$A \odot X \cong \bigvee_{a \in A} (X, x_0),$$

where $\bigvee_{a \in A} (X, x_0)$ is the wedge product of the A -indexed family $((X, x_0))_{a \in A}$ of **Pointed Sets, Definition 3.2.1**.

- *The Basepoint.* The point $[(a, x_0)] = [(a', x_0)]$ of $\bigvee_{a \in A} (X, x_0)$.

PROOF 2.1.5 ► PROOF OF CONSTRUCTION 2.1.4

(Proven below in a bit.)

**NOTATION 2.1.6 ► ELEMENTS OF TENSORS OF POINTED SETS BY SETS**

We write $a \odot x$ for the element $[(a, x)]$ of

$$\begin{aligned} A \odot X &\cong \bigvee_{a \in A} (X, x_0) \\ &\stackrel{\text{def}}{=} \left(\coprod_{i \in I} X_i \right) / \sim. \end{aligned}$$

REMARK 2.1.7 ► BASEPOINTS OF TENSORS OF POINTED SETS BY SETS

Taking the tensor of any element of A with the basepoint x_0 of X leads to the same element in $A \odot X$, i.e. we have

$$a \odot x_0 = a' \odot x_0,$$

for each $a, a' \in A$. This is due to the equivalence relation \sim on

$$\bigvee_{a \in A} (X, x_0) \stackrel{\text{def}}{=} \coprod_{a \in A} X / \sim$$

identifying (a, x_0) with (a', x_0) , so that the equivalence class $a \odot x_0$ is independent from the choice of $a \in A$.

PROOF 2.1.8 ► PROOF OF CONSTRUCTION 2.1.4

We claim we have a bijection

$$\mathbf{Sets}_*(A \odot X, K) \cong \mathbf{Sets}(A, \mathbf{Sets}_*(X, K))$$

natural in $(K, k_0) \in \mathbf{Obj}(\mathbf{Sets}_*)$.

• *Map I.* We define a map

$$\Phi_K : \mathbf{Sets}_*(A \odot X, K) \rightarrow \mathbf{Sets}(A, \mathbf{Sets}_*(X, K))$$

by sending a morphism of pointed sets

$$\xi : (A \odot X, a \odot x_0) \rightarrow (K, k_0)$$

to the map of sets

$$\begin{aligned} \xi^\dagger : A &\rightarrow \mathbf{Sets}_*(X, K), \\ a &\mapsto (\xi_a : X \rightarrow K), \end{aligned}$$

where

$$\xi_a : (X, x_0) \rightarrow (K, k_0)$$

is the morphism of pointed sets defined by

$$\xi_a(x) \stackrel{\text{def}}{=} \xi(a \odot x)$$

for each $x \in X$. Note that we have

$$\begin{aligned} \xi_a(x_0) &\stackrel{\text{def}}{=} \xi(a \odot x_0) \\ &= k_0, \end{aligned}$$

so that ξ_a is indeed a morphism of pointed sets, where we have used that ξ is a morphism of pointed sets.

• *Map II.* We define a map

$$\Psi_K : \mathbf{Sets}(A, \mathbf{Sets}_*(X, K)) \rightarrow \mathbf{Sets}_*(A \odot X, K)$$

given by sending a map

$$\begin{aligned}\xi &: A \longrightarrow \text{Sets}_*(X, K), \\ a &\mapsto (\xi_a: X \rightarrow K),\end{aligned}$$

to the morphism of pointed sets

$$\xi^\dagger: (A \odot X, a \odot x_0) \rightarrow (K, k_0)$$

defined by

$$\xi^\dagger(a \odot x) \stackrel{\text{def}}{=} \xi_a(x)$$

for each $a \odot x \in A \odot X$. Note that ξ^\dagger is indeed a morphism of pointed sets, as we have

$$\begin{aligned}\xi^\dagger(a \odot x_0) &\stackrel{\text{def}}{=} \xi_a(x_0) \\ &= k_0,\end{aligned}$$

where we have used that $\xi(a) \in \text{Sets}_*(X, K)$ is a morphism of pointed sets.

· *Invertibility I.* We claim that

$$\Psi_K \circ \Phi_K = \text{id}_{\text{Sets}_*(A \odot X, K)}.$$

Indeed, given a morphism of pointed sets

$$\xi: (A \odot X, a \odot x_0) \rightarrow (K, k_0),$$

we have

$$\begin{aligned}[\Psi_K \circ \Phi_K](\xi) &= \Psi_K(\Phi_K(\xi)) \\ &= \Psi_K(\llbracket a \mapsto \llbracket x \mapsto \xi(a \odot x) \rrbracket \rrbracket) \\ &= \Psi_K(\llbracket a' \mapsto \llbracket x' \mapsto \xi(a' \odot x') \rrbracket \rrbracket) \\ &= \llbracket a \odot x \mapsto \text{ev}_x(\text{ev}_a(\llbracket a' \mapsto \llbracket x' \mapsto \xi(a' \odot x') \rrbracket \rrbracket)) \rrbracket \\ &= \llbracket a \odot x \mapsto \text{ev}_x(\llbracket x' \mapsto \xi(a \odot x') \rrbracket) \rrbracket \\ &= \llbracket a \odot x \mapsto \xi(a \odot x) \rrbracket \\ &= \xi.\end{aligned}$$

· *Invertibility II.* We claim that

$$\Phi_K \circ \Psi_K = \text{id}_{\text{Sets}(A, \text{Sets}_*(X, K))}.$$

Indeed, given a morphism $\xi: A \rightarrow \text{Sets}_*(X, K)$, we have

$$\begin{aligned} [\Phi_K \circ \Psi_K](\xi) &= \Phi_K(\Psi_K(\xi)) \\ &= \Phi_K(\llbracket a \odot x \mapsto \xi_a(x) \rrbracket) \\ &= \llbracket a \mapsto \llbracket x \mapsto \xi_a(x) \rrbracket \rrbracket \\ &= \llbracket a \mapsto \xi(a) \rrbracket \\ &= \xi. \end{aligned}$$

· *Naturality of Φ .* We need to show that, given a morphism of pointed sets

$$\phi: (K, k_0) \rightarrow (K', k'_0),$$

the diagram

$$\begin{array}{ccc} \text{Sets}_*(A \odot X, K) & \xrightarrow{\Phi_K} & \text{Sets}(A, \text{Sets}_*(X, K)) \\ \phi_* \downarrow & & \downarrow (\phi_*)_* \\ \text{Sets}_*(A \odot X, K') & \xrightarrow{\Phi_{K'}} & \text{Sets}(A, \text{Sets}_*(X, K')) \end{array}$$


commutes. Indeed, given a morphism of pointed sets

$$\xi: (A \odot X, a \odot x_0) \rightarrow (K, k_0),$$

we have

$$\begin{aligned} [\Phi_{K'} \circ \phi_*](\xi) &= \Phi_{K'}(\phi_*(\xi)) \\ &= \Phi_{K'}(\phi \circ \xi) \\ &= (\phi \circ \xi)^\dagger \\ &= \llbracket a \mapsto \phi \circ \xi(a \odot -) \rrbracket \\ &= \llbracket a \mapsto \phi_*(\xi(a \odot -)) \rrbracket \\ &= (\phi_*)_*(\llbracket a \mapsto \xi(a \odot -) \rrbracket) \\ &= (\phi_*)_*(\Phi_K(\xi)) \\ &= [(\phi_*)_* \circ \Phi_K](\xi). \end{aligned}$$

- *Naturality of Ψ* . Since Φ is natural and Φ is a componentwise inverse to Ψ , it follows from [Categories, Item 2](#) of [Proposition 8.6.2](#) that Ψ is also natural.

This finishes the proof. 

PROPOSITION 2.1.9 ► PROPERTIES OF TENSORS OF POINTED SETS BY SETS

Let (X, x_0) be a pointed set and let A be a set.

1. *Functoriality*. The assignments $A, (X, x_0), (A, (X, x_0))$ define functors

$$\begin{aligned} A \odot - &: \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*, \\ - \odot X &: \mathbf{Sets} \rightarrow \mathbf{Sets}_*, \\ -_1 \odot -_2 &: \mathbf{Sets} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*. \end{aligned}$$

In particular, given:

- A map of sets $f: A \rightarrow B$;
- A pointed map $\phi: (X, x_0) \rightarrow (Y, y_0)$;

the induced map

$$f \odot \phi: A \odot X \rightarrow B \odot Y$$

is given by

$$[f \odot \phi](a \odot x) \stackrel{\text{def}}{=} f(a) \odot \phi(x)$$

for each $a \odot x \in A \odot X$.

2. *Adjointness I*. We have an adjunction

$$(- \odot X \dashv \mathbf{Sets}_*(X, -)) : \mathbf{Sets} \begin{array}{c} \xrightarrow{- \odot X} \\ \perp \\ \xleftarrow{\mathbf{Sets}_*(X, -)} \end{array} \mathbf{Sets}_*,$$

witnessed by a bijection

$$\mathbf{Sets}_*(A \odot X, K) \cong \mathbf{Sets}(A, \mathbf{Sets}_*(X, K)),$$

natural in $A \in \mathbf{Obj}(\mathbf{Sets})$ and $X, Y \in \mathbf{Obj}(\mathbf{Sets}_*)$.

3. *Adjointness II.* We have an adjunctions

$$(A \odot - \dashv A \multimap -): \text{Sets}_* \begin{array}{c} \xrightarrow{A \odot -} \\ \perp \\ \xleftarrow{A \multimap -} \end{array} \text{Sets}_*,$$

witnessed by a bijection

$$\text{Hom}_{\text{Sets}_*}(A \odot X, Y) \cong \text{Hom}_{\text{Sets}_*}(X, A \multimap Y),$$

natural in $A \in \text{Obj}(\text{Sets})$ and $X, Y \in \text{Obj}(\text{Sets}_*)$.

4. *As a Weighted Colimit.* We have

$$A \odot X \cong \text{colim}^{[A]}(X),$$

where in the right hand side we write:

- A for the functor $A: \text{pt} \rightarrow \text{Sets}$ picking $A \in \text{Obj}(\text{Sets})$;
- X for the functor $X: \text{pt} \rightarrow \text{Sets}_*$ picking $(X, x_0) \in \text{Obj}(\text{Sets}_*)$.

5. *Iterated Tensors.* We have an isomorphism of pointed sets

$$A \odot (B \odot X) \cong (A \times B) \odot X,$$

natural in $A, B \in \text{Obj}(\text{Sets})$ and $(X, x_0) \in \text{Obj}(\text{Sets}_*)$.

6. *Interaction With Homs.* We have a natural isomorphism

$$\text{Sets}_*(A \odot X, -) \cong A \multimap \text{Sets}_*(X, -).$$

7. *The Tensor Evaluation Map.* For each $X, Y \in \text{Obj}(\text{Sets}_*)$, we have a map

$$\text{ev}_{X,Y}^\odot: \text{Sets}_*(X, Y) \odot X \rightarrow Y,$$

natural in $X, Y \in \text{Obj}(\text{Sets}_*)$, and given by

$$\text{ev}_{X,Y}^\odot(f \odot x) \stackrel{\text{def}}{=} f(x)$$

for each $f \odot x \in \text{Sets}_*(X, Y) \odot X$.

8. *The Tensor Coevaluation Map.* For each $A \in \text{Obj}(\text{Sets})$ and each $X \in \text{Obj}(\text{Sets}_*)$, we have a map

$$\text{coev}_{A,X}^\odot : A \rightarrow \text{Sets}_*(X, A \odot X),$$

natural in $A \in \text{Obj}(\text{Sets})$ and $X \in \text{Obj}(\text{Sets}_*)$, and given by

$$\text{coev}_{A,X}^\odot(a) \stackrel{\text{def}}{=} \llbracket x \mapsto a \odot x \rrbracket$$

for each $a \in A$.

PROOF 2.1.10 ► PROOF OF PROPOSITION 2.1.9

Item 1: Functoriality

This is the special case of ??, ?? of ?? for when $C = \text{Sets}_*$.

Item 2: Adjointness I

This is simply a rephrasing of [Definition 2.1.1](#).

Item 3: : Adjointness II

This is the special case of ??, ?? of ?? for when $C = \text{Sets}_*$.

Item 4: As a Weighted Colimit

This is the special case of ??, ?? of ?? for when $C = \text{Sets}_*$.

Item 5: Iterated Tensors

This is the special case of ??, ?? of ?? for when $C = \text{Sets}_*$.


Item 6: Interaction With Homs

This is the special case of ??, ?? of ?? for when $C = \text{Sets}_*$.

Item 7: The Tensor Evaluation Map

This is the special case of ??, ?? of ?? for when $C = \text{Sets}_*$.

Item 8: The Tensor Coevaluation Map

This is the special case of ??, ?? of ?? for when $C = \text{Sets}_*$. 

2.2 Cotensors of Pointed Sets by Sets

Let (X, x_0) be a pointed set and let A be a set.

DEFINITION 2.2.1 ► COTENSORS OF POINTED SETS BY SETS

The **cotensor of** (X, x_0) **by** A ¹ is the pointed set² $A \pitchfork (X, x_0)$ satisfying the following universal property:

(UP) We have a bijection

$$\text{Sets}_*(K, A \pitchfork X) \cong \text{Sets}(A, \text{Sets}_*(K, X)),$$

natural in $(K, k_0) \in \text{Obj}(\text{Sets}_*)$.

¹*Further Terminology:* Also called the **power of** (X, x_0) **by** A .

²*Further Notation:* Often written $A \pitchfork X$ for simplicity.

REMARK 2.2.2 ► UNWINDING DEFINITION 2.2.1

The universal property of **Definition 2.2.1** is equivalent to the following one:

(UP) We have a bijection

$$\text{Sets}_*(K, A \pitchfork X) \cong \text{Sets}_{\mathbb{E}_0}^{\otimes}(A \times K, X),$$


natural in $(K, k_0) \in \text{Obj}(\text{Sets}_*)$, where $\text{Sets}_{\mathbb{E}_0}^{\otimes}(A \times K, X)$ is the set defined by

$$\text{Sets}_{\mathbb{E}_0}^{\otimes}(A \times K, X) \stackrel{\text{def}}{=} \left\{ f \in \text{Sets}(A \times K, X) \left| \begin{array}{l} \text{for each } a \in A, \text{ we} \\ \text{have } f(a, k_0) = x_0 \end{array} \right. \right\}.$$

PROOF 2.2.3 ► PROOF OF REMARK 2.2.2

This follows from the bijection

$$\text{Sets}(A, \text{Sets}_*(K, X)) \cong \text{Sets}_{\mathbb{E}_0}^{\otimes}(A \times K, X),$$

natural in $(K, k_0) \in \text{Obj}(\text{Sets}_*)$ constructed in the proof of **Remark 2.1.2**. 

CONSTRUCTION 2.2.4 ► CONSTRUCTION OF COTENSORS OF POINTED SETS BY SETS

Concretely, the **cotensor of** (X, x_0) **by** A is the pointed set $A \pitchfork (X, x_0)$ consisting of:

- *The Underlying Set.* The set $A \pitchfork X$ given by

$$A \pitchfork X \cong \bigwedge_{a \in A} (X, x_0),$$

where $\bigwedge_{a \in A} (X, x_0)$ is the smash product of the A -indexed family $((X, x_0))_{a \in A}$ of [Definition 6.1.1](#).

- *The Basepoint.* The point $[(x_0)_{a \in A}] = [(x_0, x_0, x_0, \dots)]$ of $\bigwedge_{a \in A} (X, x_0)$.

PROOF 2.2.5 ► PROOF OF CONSTRUCTION 2.2.4

We claim we have a bijection

$$\mathbf{Sets}_*(K, A \pitchfork X) \cong \mathbf{Sets}(A, \mathbf{Sets}_*(K, X)),$$

natural in $(K, k_0) \in \mathbf{Obj}(\mathbf{Sets}_*)$.

- *Map I.* We define a map

$$\Phi_K: \mathbf{Sets}_*(K, A \pitchfork X) \rightarrow \mathbf{Sets}(A, \mathbf{Sets}_*(K, X)),$$

by sending a morphism of pointed sets

$$\xi: (K, k_0) \rightarrow (A \pitchfork X, [(x_0)_{a \in A}])$$

to the map of sets

$$\begin{aligned} \xi^\dagger: A &\rightarrow \mathbf{Sets}_*(K, X), \\ a &\mapsto (\xi_a: K \rightarrow X), \end{aligned}$$

where

$$\xi_a: (K, k_0) \rightarrow (X, x_0)$$

is the morphism of pointed sets defined by

$$\xi_a(k) = \begin{cases} x_a^k & \text{if } \xi(k) \neq [(x_0)_{a \in A}], \\ x_0 & \text{if } \xi(k) = [(x_0)_{a \in A}] \end{cases}$$

for each $k \in K$, where x_a^k is the a th component of $\xi(k) = [(x_a^k)_{a \in A}]$. Note that:

1. The definition of $\xi_a(k)$ is independent of the choice of equivalence class. Indeed, suppose we have

$$\begin{aligned}\xi(k) &= [(x_a^k)_{a \in A}] \\ &= [(y_a^k)_{a \in A}]\end{aligned}$$

with $x_a^k \neq y_a^k$ for some $a \in A$. Then there exist $a_x, a_y \in A$ such that $x_{a_x}^k = y_{a_y}^k = x_0$. The equivalence relation \sim on $\prod_{a \in A} X$ then forces

$$\begin{aligned}[(x_a^k)_{a \in A}] &= [(x_0)_{a \in A}], \\ [(y_a^k)_{a \in A}] &= [(x_0)_{a \in A}],\end{aligned}$$

however, and $\xi_a(k)$ is defined to be x_0 in this case.

2. The map ξ_a is indeed a morphism of pointed sets, as we have

$$\xi_a(k_0) = x_0$$

since $\xi(k_0) = [(x_0)_{a \in A}]$ as ξ is a morphism of pointed sets and $\xi_a(k_0)$, defined to be the a th component of $[(x_0)_{a \in A}]$, is equal to x_0 .

• *Map II.* We define a map

$$\Psi_K: \text{Sets}(A, \text{Sets}_*(K, X)) \rightarrow \text{Sets}_*(K, A \pitchfork X),$$

given by sending a map

$$\begin{aligned}\xi: A &\rightarrow \text{Sets}_*(K, X), \\ a &\mapsto (\xi_a: K \rightarrow X),\end{aligned}$$

to the morphism of pointed sets

$$\xi^\dagger: (K, k_0) \rightarrow (A \pitchfork X, [(x_0)_{a \in A}])$$

defined by

$$\xi^\dagger(k) \stackrel{\text{def}}{=} [(\xi_a(k))_{a \in A}]$$

for each $k \in K$. Note that ξ^\dagger is indeed a morphism of pointed sets, as we have

$$\begin{aligned}\xi^\dagger(k_0) &\stackrel{\text{def}}{=} [(\xi_a(k_0))_{a \in A}] \\ &= x_0,\end{aligned}$$

where we have used that $\xi_a \in \text{Sets}_*(K, X)$ is a morphism of pointed sets for each $a \in A$.

- *Naturality of Ψ* . We need to show that, given a morphism of pointed sets

$$\phi: (K, k_0) \rightarrow (K', k'_0),$$

the diagram

$$\begin{array}{ccc}\text{Sets}(A, \text{Sets}_*(K', X)) & \xrightarrow{\Psi_{K'}} & \text{Sets}_*(K', A \pitchfork X) \\ (\phi^*)_* \downarrow & & \downarrow \phi^* \\ \text{Sets}(A, \text{Sets}_*(K, X)) & \xrightarrow{\Psi_K} & \text{Sets}_*(K, A \pitchfork X)\end{array}$$

commutes. Indeed, given a map of sets

$$\begin{aligned}\xi: A &\rightarrow \text{Sets}_*(K', X), \\ a &\mapsto (\xi_a: K' \rightarrow X),\end{aligned}$$

we have

$$\begin{aligned}[\Psi_K \circ (\phi^*)_*](\xi) &= \Psi_K((\phi^*)_*(\xi)) \\ &= \Psi_K((\phi^*)_*([a \mapsto \xi_a])) \\ &= \Psi_K([a \mapsto \phi^*(\xi_a)]) \\ &= \Psi_K([a \mapsto [k \mapsto \xi_a(\phi(k))]]) \\ &= [k \mapsto [(\xi_a(\phi(k)))_{a \in A}]] \\ &= \phi^*([k' \mapsto [(\xi_a(k'))_{a \in A}]]) \\ &= \phi^*(\Psi_{K'}(\xi)) \\ &= [\phi^* \circ \Psi_{K'}](\xi).\end{aligned}$$

- *Naturality of Φ* . Since Ψ is natural and Ψ is a componentwise inverse to Φ , it follows from [Categories, Item 2](#) of [Proposition 8.6.2](#) that Φ is also natural.
- *Invertibility I*. We claim that

$$\Psi_K \circ \Phi_K = \text{id}_{\text{Sets}_*(K, A \pitchfork X)}.$$

Indeed, given a morphism of pointed sets

$$\xi: (K, k_0) \rightarrow (A \pitchfork X, [(x_0)_{a \in A}])$$

we have

$$\begin{aligned} [\Psi_K \circ \Phi_K](\xi) &= \Psi_K(\Phi_K(\xi)) \\ &= \Psi_K([a \mapsto \xi_a]) \\ &= \Psi_K([a' \mapsto \xi_{a'}]) \\ &= [k \mapsto [(ev_a([a' \mapsto \xi_{a'}(k)]))_{a \in A}]] \\ &= [k \mapsto [(\xi_a(k))_{a \in A}]]. \end{aligned}$$

Now, we have two cases:

1. If $\xi(k) = [(x_0)_{a \in A}]$, we have

$$\begin{aligned} [\Psi_K \circ \Phi_K](\xi) &= \dots \\ &= [k \mapsto [(\xi_a(k))_{a \in A}]] \\ &= [k \mapsto [(x_0)_{a \in A}]] \\ &= [k \mapsto \xi(k)] \\ &= \xi. \end{aligned}$$

2. If $\xi(k) \neq [(x_0)_{a \in A}]$ and $\xi(k) = [(x_a^k)_{a \in A}]$ instead, we have

$$\begin{aligned} [\Psi_K \circ \Phi_K](\xi) &= \dots \\ &= [k \mapsto [(\xi_a(k))_{a \in A}]] \\ &= [k \mapsto [(x_a^k)_{a \in A}]] \\ &= [k \mapsto \xi(k)] \\ &= \xi. \end{aligned}$$


In both cases, we have $[\Psi_K \circ \Phi_K](\xi) = \xi$, and thus we are done.

· *Invertibility II.* We claim that

$$\Phi_K \circ \Psi_K = \text{id}_{\text{Sets}(A, \text{Sets}_*(K, X))}.$$

Indeed, given a morphism $\xi: A \rightarrow \text{Sets}_*(K, X)$, we have

$$\begin{aligned} [\Phi_K \circ \Psi_K](\xi) &= \Phi_K(\Psi_K(\xi)) \\ &= \Phi_K([k \mapsto [(\xi_a(k))_{a \in A}]]]) \\ &= [a \mapsto [k \mapsto \xi_a(k)]] \\ &= \xi \end{aligned}$$

This finishes the proof. 

PROPOSITION 2.2.6 ► PROPERTIES OF COTENSORS OF POINTED SETS BY SETS

Let (X, x_0) be a pointed set and let A be a set.

1. *Functoriality.* The assignments $A, (X, x_0), (A, (X, x_0))$ define functors

$$\begin{aligned} A \pitchfork - &: \text{Sets}_* \rightarrow \text{Sets}_*, \\ - \pitchfork X &: \text{Sets}^{\text{op}} \rightarrow \text{Sets}_*, \\ -_1 \pitchfork -_2 &: \text{Sets}^{\text{op}} \times \text{Sets}_* \rightarrow \text{Sets}_*. \end{aligned}$$

In particular, given:

- A map of sets $f: A \rightarrow B$;
- A pointed map $\phi: (X, x_0) \rightarrow (Y, y_0)$;

the induced map

$$f \odot \phi: A \pitchfork X \rightarrow B \pitchfork Y$$

is given by

$$[f \odot \phi]([x_a]_{a \in A}) \stackrel{\text{def}}{=} [(\phi(x_{f(a)}))_{a \in A}]$$

for each $[x_a]_{a \in A} \in A \pitchfork X$.

2. *Adjointness I.* We have an adjunction

$$(- \pitchfork X \dashv \text{Sets}_*(-, X)) : \text{Sets}^{\text{op}} \begin{array}{c} \xrightarrow{- \pitchfork X} \\ \perp \\ \xleftarrow{\text{Sets}_*(-, X)} \end{array} \text{Sets}_*,$$

witnessed by a bijection

$$\text{Sets}_*^{\text{op}}(A \pitchfork X, K) \cong \text{Sets}(A, \text{Sets}_*(K, X)),$$

i.e. by a bijection

$$\text{Sets}_*(K, A \pitchfork X) \cong \text{Sets}(A, \text{Sets}_*(K, X)),$$

natural in $A \in \text{Obj}(\text{Sets})$ and $X, Y \in \text{Obj}(\text{Sets}_*)$.

3. *Adjointness II.* We have an adjunctions

$$(A \odot - \dashv A \pitchfork -) : \text{Sets}_* \begin{array}{c} \xrightarrow{A \odot -} \\ \perp \\ \xleftarrow{A \pitchfork -} \end{array} \text{Sets}_*,$$

witnessed by a bijection

$$\text{Hom}_{\text{Sets}_*}(A \odot X, Y) \cong \text{Hom}_{\text{Sets}_*}(X, A \pitchfork Y),$$

natural in $A \in \text{Obj}(\text{Sets})$ and $X, Y \in \text{Obj}(\text{Sets}_*)$.

4. *As a Weighted Limit.* We have

$$A \pitchfork X \cong \lim^{[A]}(X),$$

where in the right hand side we write:

- A for the functor $A : \text{pt} \rightarrow \text{Sets}$ picking $A \in \text{Obj}(\text{Sets})$;
- X for the functor $X : \text{pt} \rightarrow \text{Sets}_*$ picking $(X, x_0) \in \text{Obj}(\text{Sets}_*)$.

5. *Iterated Cotensors.* We have an isomorphism of pointed sets

$$A \pitchfork (B \pitchfork X) \cong (A \times B) \pitchfork X,$$

natural in $A, B \in \text{Obj}(\text{Sets})$ and $(X, x_0) \in \text{Obj}(\text{Sets}_*)$.

6. *Commutativity With Homs.* We have natural isomorphisms

$$\begin{aligned} A \pitchfork \mathbf{Sets}_*(X, -) &\cong \mathbf{Sets}_*(A \odot X, -), \\ A \pitchfork \mathbf{Sets}_*(-, Y) &\cong \mathbf{Sets}_*(-, A \pitchfork Y). \end{aligned}$$

7. *The Cotensor Evaluation Map.* For each $X, Y \in \mathbf{Obj}(\mathbf{Sets}_*)$, we have a map

$$\mathrm{ev}_{X,Y}^{\pitchfork} : X \rightarrow \mathbf{Sets}_*(X, Y) \pitchfork Y,$$

natural in $X, Y \in \mathbf{Obj}(\mathbf{Sets}_*)$, and given by

$$\mathrm{ev}_{X,Y}^{\pitchfork}(x) \stackrel{\mathrm{def}}{=} [(f(x))_{f \in \mathbf{Sets}_*(X,Y)}]$$

for each $x \in X$.

8. *The Cotensor Coevaluation Map.* For each $X \in \mathbf{Obj}(\mathbf{Sets}_*)$ and each $A \in \mathbf{Obj}(\mathbf{Sets})$, we have a map

$$\mathrm{coev}_{A,X}^{\pitchfork} : A \rightarrow \mathbf{Sets}_*(A \pitchfork X, X),$$

natural in $X \in \mathbf{Obj}(\mathbf{Sets}_*)$ and $A \in \mathbf{Obj}(\mathbf{Sets})$, and given by

$$\mathrm{coev}_{A,X}^{\pitchfork}(a) \stackrel{\mathrm{def}}{=} [[(x_b)_{b \in A}] \mapsto x_a]]$$

for each $a \in A$.

PROOF 2.2.7 ► PROOF OF PROPOSITION 2.2.6

Item 1: Functoriality

This is the special case of ??, ?? of ?? for when $C = \mathbf{Sets}_*$.

Item 2: Adjointness I

This is simply a rephrasing of [Definition 2.2.1](#).

Item 3: : Adjointness II

This is the special case of ??, ?? of ?? for when $C = \mathbf{Sets}_*$.

Item 4: As a Weighted Limit

This is the special case of ??, ?? of ?? for when $C = \mathbf{Sets}_*$.

Item 5: Iterated Cotensors

This is the special case of ??, ?? of ?? for when $C = \mathbf{Sets}_*$.

Item 6: Commutativity With Homs

This is the special case of ??, ?? of ?? for when $C = \mathbf{Sets}_*$.

Item 7: The Cotensor Evaluation Map

This is the special case of ??, ?? of ?? for when $C = \mathbf{Sets}_*$.

Item 8: The Cotensor Coevaluation Map

This is the special case of ??, ?? of ?? for when $C = \mathbf{Sets}_*$.



3 The Left Tensor Product of Pointed Sets

3.1 Foundations

Let (X, x_0) and (Y, y_0) be pointed sets.

DEFINITION 3.1.1 ► THE LEFT TENSOR PRODUCT OF POINTED SETS

The **left tensor product of pointed sets** is the functor¹

$$\triangleleft : \mathbf{Sets}_* \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$

defined as the composition

$$\mathbf{Sets}_* \times \mathbf{Sets}_* \xrightarrow{\mathrm{id} \times \omega} \mathbf{Sets}_* \times \mathbf{Sets} \xrightarrow{\beta_{\mathbf{Sets}_*, \mathbf{Sets}}^{\mathbf{Cats}_2}} \mathbf{Sets} \times \mathbf{Sets}_* \xrightarrow{\odot} \mathbf{Sets}_*,$$

where:

- $\omega : \mathbf{Sets}_* \rightarrow \mathbf{Sets}$ is the forgetful functor from pointed sets to sets.
- $\beta_{\mathbf{Sets}_*, \mathbf{Sets}}^{\mathbf{Cats}_2} : \mathbf{Sets}_* \times \mathbf{Sets} \xrightarrow{\cong} \mathbf{Sets} \times \mathbf{Sets}_*$ is the braiding of \mathbf{Cats}_2 , i.e. the functor witnessing the isomorphism

$$\mathbf{Sets}_* \times \mathbf{Sets} \cong \mathbf{Sets} \times \mathbf{Sets}_*.$$

- $\odot : \mathbf{Sets} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$ is the tensor functor of [Item 1 of Proposition 2.1.9](#).

¹Further Notation: Also written $\triangleleft_{\mathbf{Sets}_*}$.

REMARK 3.1.2 ► UNWINDING DEFINITION 3.1.1: UNIVERSAL PROPERTY I

The left tensor product of pointed sets satisfies the following natural bijection:

$$\text{Sets}_*(X \triangleleft Y, Z) \cong \text{Hom}_{\text{Sets}_*}^{\otimes, \mathbb{L}}(X \times Y, Z).$$

That is to say, the following data are in natural bijection:

1. Pointed maps $f: X \triangleleft Y \rightarrow Z$.
2. Maps of sets $f: X \times Y \rightarrow Z$ satisfying $f(x_0, y) = z_0$ for each $y \in Y$.

REMARK 3.1.3 ► UNWINDING DEFINITION 3.1.1: UNIVERSAL PROPERTY II

The left tensor product of pointed sets may be described as follows:

- The left tensor product of (X, x_0) and (Y, y_0) is the pair $((X \triangleleft Y, x_0 \triangleleft y_0), \iota)$ consisting of
 - A pointed set $(X \triangleleft Y, x_0 \triangleleft y_0)$;
 - A left bilinear morphism of pointed sets $\iota: (X \times Y, (x_0, y_0)) \rightarrow X \triangleleft Y$;

satisfying the following universal property:

(UP) Given another such pair $((Z, z_0), f)$ consisting of

- * A pointed set (Z, z_0) ;
- * A left bilinear morphism of pointed sets $f: (X \times Y, (x_0, y_0)) \rightarrow Z$;

there exists a unique morphism of pointed sets $X \triangleleft Y \xrightarrow{\exists!} Z$ making the diagram

$$\begin{array}{ccc} & X \triangleleft Y & \\ \iota \nearrow & & \downarrow \exists! \\ X \times Y & \xrightarrow{f} & Z \end{array}$$

commute.

CONSTRUCTION 3.1.4 ► THE LEFT TENSOR PRODUCT OF POINTED SETS

In detail, the **left tensor product of** (X, x_0) **and** (Y, y_0) is the pointed set $(X \triangleleft Y, [x_0])$ consisting of

- *The Underlying Set.* The set $X \triangleleft Y$ defined by

$$\begin{aligned} X \triangleleft Y &\stackrel{\text{def}}{=} |Y| \odot X \\ &\cong \bigvee_{y \in Y} (X, x_0), \end{aligned}$$

where $|Y|$ denotes the underlying set of (Y, y_0) ;

- *The Underlying Basepoint.* The point $[(y_0, x_0)]$ of $\bigvee_{y \in Y} (X, x_0)$, which is equal to $[(y, x_0)]$ for any $y \in Y$.

NOTATION 3.1.5 ► ELEMENTS OF LEFT TENSOR PRODUCTS OF POINTED SETS

We write¹ $x \triangleleft y$ for the element $[(y, x)]$ of

$$X \triangleleft Y \cong |Y| \odot X.$$

¹Further Notation: Also written $x \triangleleft_{\text{Sets}_*} y$.

REMARK 3.1.6 ► BASEPOINTS OF LEFT TENSOR PRODUCTS OF POINTED SETS

Employing the notation introduced in **Notation 3.1.5**, we have

$$x_0 \triangleleft y_0 = x_0 \triangleleft y$$

for each $y \in Y$, and

$$x_0 \triangleleft y = x_0 \triangleleft y'$$

for each $y, y' \in Y$.

PROPOSITION 3.1.7 ► PROPERTIES OF LEFT TENSOR PRODUCTS OF POINTED SETS

Let (X, x_0) and (Y, y_0) be pointed sets.

1. *Functoriality.* The assignments $X, Y, (X, Y) \mapsto X \triangleleft Y$ define functors

$$\begin{aligned} X \triangleleft - &: \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*, \\ - \triangleleft Y &: \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*, \\ -_1 \triangleleft -_2 &: \mathbf{Sets}_* \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*. \end{aligned}$$

In particular, given pointed maps

$$\begin{aligned} f &: (X, x_0) \rightarrow (A, a_0), \\ g &: (Y, y_0) \rightarrow (B, b_0), \end{aligned}$$

the induced map

$$f \triangleleft g: X \triangleleft Y \rightarrow A \triangleleft B$$

is given by

$$[f \triangleleft g](x \triangleleft y) \stackrel{\text{def}}{=} f(x) \triangleleft g(y)$$

for each $x \triangleleft y \in X \triangleleft Y$.

2. *Adjointness I.* We have an adjunction

$$\left(- \triangleleft Y \dashv [Y, -]_{\mathbf{Sets}_*}^{\triangleleft} \right): \mathbf{Sets}_* \begin{array}{c} \xrightarrow{- \triangleleft Y} \\ \perp \\ \xleftarrow{[Y, -]_{\mathbf{Sets}_*}^{\triangleleft}} \end{array} \mathbf{Sets}_*,$$

witnessed by a bijection of sets

$$\text{Hom}_{\mathbf{Sets}_*}(X \triangleleft Y, Z) \cong \text{Hom}_{\mathbf{Sets}_*}(X, [Y, Z]_{\mathbf{Sets}_*}^{\triangleleft})$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\mathbf{Sets}_*)$, where $[X, Y]_{\mathbf{Sets}_*}^{\triangleleft}$ is the pointed set of [Definition 3.2.1](#).

3. *Adjointness II.* The functor

$$X \triangleleft -: \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$

does not admit a right adjoint.

4. *Adjointness III.* We have a bijection of sets

$$\text{Hom}_{\mathbf{Sets}_*}(X \triangleleft Y, Z) \cong \text{Hom}_{\mathbf{Sets}}(|Y|, \mathbf{Sets}_*(X, Z))$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\mathbf{Sets}_*)$.

PROOF 3.1.8 ► PROOF OF PROPOSITION 3.1.7

Item 1: Functoriality

Clear.

Item 2: Adjointness I

This follows from **Item 3** of **Proposition 2.1.9**.

Item 3: Adjointness II

For $X \triangleleft -$ to admit a right adjoint would require it to preserve colimits by ??, ?? of ??. However, we have

$$\begin{aligned} X \triangleleft \text{pt} &\stackrel{\text{def}}{=} |\text{pt}| \odot X \\ &\cong X \\ &\neq \text{pt}, \end{aligned}$$

and thus we see that $X \triangleleft -$ does not have a right adjoint.

Item 4: Adjointness III

This follows from **Item 2** of **Proposition 2.1.9**. 

REMARK 3.1.9 ► ON THE FAILURE OF $X \triangleleft -$ TO BE A LEFT ADJOINT

Here is some intuition on why $X \triangleleft -$ fails to be a left adjoint. **Item 4** of **Proposition 3.1.7** states that we have a natural bijection

$$\text{Hom}_{\mathbf{Sets}_*}(X \triangleleft Y, Z) \cong \text{Hom}_{\mathbf{Sets}}(|Y|, \mathbf{Sets}_*(X, Z)),$$

so it would be reasonable to wonder whether a natural bijection of the form

$$\text{Hom}_{\mathbf{Sets}_*}(X \triangleleft Y, Z) \cong \text{Hom}_{\mathbf{Sets}_*}(Y, \mathbf{Sets}_*(X, Z)),$$

also holds, which would give $X \triangleleft - \dashv \mathbf{Sets}_*(X, -)$. However, such a bijection would require every map

$$f: X \triangleleft Y \rightarrow Z$$

to satisfy

$$f(x \triangleleft y_0) = z_0$$

for each $x \in X$, whereas we are imposing such a basepoint preservation condition only for elements of the form $x_0 \triangleleft y$. Thus $\mathbf{Sets}_*(X, -)$ can't be a right adjoint for $X \triangleleft -$, and as shown by **Item 3** of **Proposition 3.1.7**, no functor can.¹

¹The functor $\mathbf{Sets}_*(X, -)$ is instead right adjoint to $X \wedge -$, the smash product of pointed sets of Definition 5.1.1. See Item 2 of Proposition 5.1.10.

3.2 The Left Internal Hom of Pointed Sets

Let (X, x_0) and (Y, y_0) be pointed sets.

DEFINITION 3.2.1 ► THE LEFT INTERNAL HOM OF POINTED SETS

The **left internal Hom of pointed sets** is the functor

$$[-, -]_{\mathbf{Sets}_*}^{\triangleleft} : \mathbf{Sets}_*^{\text{op}} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$


defined as the composition

$$\mathbf{Sets}_*^{\text{op}} \times \mathbf{Sets}_* \xrightarrow{\text{忘} \times \text{id}} \mathbf{Sets}^{\text{op}} \times \mathbf{Sets}_* \xrightarrow{\pitchfork} \mathbf{Sets}_*,$$

where:

- $\text{忘} : \mathbf{Sets}_* \rightarrow \mathbf{Sets}$ is the forgetful functor from pointed sets to sets.
- $\pitchfork : \mathbf{Sets}^{\text{op}} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$ is the cotensor functor of Item 1 of Proposition 2.2.6.

PROOF 3.2.2 ► PROOF OF DEFINITION 3.2.1

For a proof that $[-, -]_{\mathbf{Sets}_*}^{\triangleleft}$ is indeed the left internal Hom of \mathbf{Sets}_* with respect to the left tensor product of pointed sets, see Item 2 of Proposition 3.1.7. 

REMARK 3.2.3 ► UNWINDING DEFINITION 3.2.1, I: UNIVERSAL PROPERTY

The left internal Hom of pointed sets satisfies the following universal property:

$$\mathbf{Sets}_*(X \triangleleft Y, Z) \cong \mathbf{Sets}_*(X, [Y, Z]_{\mathbf{Sets}_*}^{\triangleleft})$$

That is to say, the following data are in bijection:

1. Pointed maps $f : X \triangleleft Y \rightarrow Z$.
2. Pointed maps $f : X \rightarrow [Y, Z]_{\mathbf{Sets}_*}^{\triangleleft}$.

REMARK 3.2.4 ► UNWINDING DEFINITION 3.2.1, II: EXPLICIT DESCRIPTION

In detail, the **left internal Hom of** (X, x_0) **and** (Y, y_0) is the pointed set $([X, Y]_{\mathbf{Sets}_*}^{\triangleleft}, [(y_0)_{x \in X}])$ consisting of

- *The Underlying Set.* The set $[X, Y]_{\mathbf{Sets}_*}^{\triangleleft}$ defined by

$$\begin{aligned} [X, Y]_{\mathbf{Sets}_*}^{\triangleleft} &\stackrel{\text{def}}{=} |X| \wr Y \\ &\cong \bigwedge_{x \in X} (Y, y_0), \end{aligned}$$

where $|X|$ denotes the underlying set of (X, x_0) ;

- *The Underlying Basepoint.* The point $[(y_0)_{x \in X}]$ of $\bigwedge_{x \in X} (Y, y_0)$.

PROPOSITION 3.2.5 ► PROPERTIES OF LEFT INTERNAL HOMS OF POINTED SETS

Let (X, x_0) and (Y, y_0) be pointed sets.

1. *Functoriality.* The assignments $X, Y, (X, Y) \mapsto [X, Y]_{\mathbf{Sets}_*}^{\triangleleft}$ define functors

$$\begin{aligned} [X, -]_{\mathbf{Sets}_*}^{\triangleleft} &: \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*, \\ [-, Y]_{\mathbf{Sets}_*}^{\triangleleft} &: \mathbf{Sets}_*^{\text{op}} \rightarrow \mathbf{Sets}_*, \\ [-_1, -_2]_{\mathbf{Sets}_*}^{\triangleleft} &: \mathbf{Sets}_*^{\text{op}} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*. \end{aligned}$$

In particular, given pointed maps

$$\begin{aligned} f &: (X, x_0) \rightarrow (A, a_0), \\ g &: (Y, y_0) \rightarrow (B, b_0), \end{aligned}$$

the induced map

$$[f, g]_{\mathbf{Sets}_*}^{\triangleleft} : [A, Y]_{\mathbf{Sets}_*}^{\triangleleft} \rightarrow [X, B]_{\mathbf{Sets}_*}^{\triangleleft}$$

is given by

$$[f, g]_{\mathbf{Sets}_*}^{\triangleleft}([(y_a)_{a \in A}]) \stackrel{\text{def}}{=} [(g(y_{f(x)}))_{x \in X}]$$

for each $[(y_a)_{a \in A}] \in [A, Y]_{\mathbf{Sets}_*}^{\triangleleft}$.

2. *Adjointness I.* We have an adjunction

$$\left(- \triangleleft Y \dashv [Y, -]_{\mathbf{Sets}_*}^{\triangleleft} \right): \mathbf{Sets}_* \begin{array}{c} \xrightarrow{- \triangleleft Y} \\ \perp \\ \xleftarrow{[Y, -]_{\mathbf{Sets}_*}^{\triangleleft}} \end{array} \mathbf{Sets}_*$$

witnessed by a bijection of sets

$$\mathrm{Hom}_{\mathbf{Sets}_*}(X \triangleleft Y, Z) \cong \mathrm{Hom}_{\mathbf{Sets}_*}(X, [Y, Z]_{\mathbf{Sets}_*}^{\triangleleft})$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \mathrm{Obj}(\mathbf{Sets}_*)$

3. *Adjointness II.* The functor

$$X \triangleleft - : \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$

does not admit a right adjoint.

PROOF 3.2.6 ► PROOF OF PROPOSITION 3.2.5

Item 1: Functoriality

Clear.

Item 2: Adjointness I

This is a repetition of **Item 2** of **Proposition 3.1.7**, and is proved there.

Item 3: Adjointness II

This is a repetition of **Item 3** of **Proposition 3.1.7**, and is proved there. 

3.3 The Left Skew Unit

DEFINITION 3.3.1 ► THE LEFT SKEW UNIT OF \triangleleft

The **left skew unit of the left tensor product of pointed sets** is the functor

$$\mathbb{1}^{\mathbf{Sets}_*, \triangleleft} : \mathbf{pt} \rightarrow \mathbf{Sets}_*$$

defined by

$$\mathbb{1}_{\mathbf{Sets}_*}^{\triangleleft} \stackrel{\mathrm{def}}{=} S^0.$$

3.4 The Left Skew Associator

DEFINITION 3.4.1 ► THE LEFT SKEW ASSOCIATOR OF \triangleleft

The **skew associator of the left tensor product of pointed sets** is the natural transformation

$$\alpha^{\text{Sets}_*, \triangleleft} : \triangleleft \circ (\triangleleft \times \text{id}_{\text{Sets}_*}) \Longrightarrow \triangleleft \circ (\text{id}_{\text{Sets}_*} \times \triangleleft) \circ \alpha^{\text{Cats}}_{\text{Sets}_*, \text{Sets}_*, \text{Sets}_*}$$

as in the diagram

$$\begin{array}{ccc}
 & \text{Sets}_* \times (\text{Sets}_* \times \text{Sets}_*) & \\
 \alpha^{\text{Cats}}_{\text{Sets}_*, \text{Sets}_*, \text{Sets}_*} \nearrow & & \searrow \text{id} \times \triangleleft \\
 (\text{Sets}_* \times \text{Sets}_*) \times \text{Sets}_* & & \text{Sets}_* \times \text{Sets}_* \\
 \triangleleft \times \text{id} \searrow & \alpha^{\text{Sets}_*, \triangleleft} \nearrow & \searrow \triangleleft \\
 \text{Sets}_* \times \text{Sets}_* & \xrightarrow{\triangleleft} & \text{Sets}_*
 \end{array}$$

whose component

$$\alpha^{\text{Sets}_*, \triangleleft}_{X,Y,Z} : (X \triangleleft Y) \triangleleft Z \rightarrow X \triangleleft (Y \triangleleft Z)$$

at $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\text{Sets}_*)$ is given by

$$\begin{aligned}
 (X \triangleleft Y) \triangleleft Z &\stackrel{\text{def}}{=} |Z| \odot (X \triangleleft Y) \\
 &\stackrel{\text{def}}{=} |Z| \odot (|Y| \odot X) \\
 &\cong \bigvee_{z \in Z} |Y| \odot X \\
 &\cong \bigvee_{z \in Z} \left(\bigvee_{y \in Y} X \right) \\
 &\rightarrow \bigvee_{[(z,y)] \in \bigvee_{z \in Z} Y} X \\
 &\cong \bigvee_{[(z,y)] \in |Z| \odot Y} X \\
 &\cong ||Z| \odot Y| \odot X \\
 &\stackrel{\text{def}}{=} |Y \triangleleft Z| \odot X \\
 &\stackrel{\text{def}}{=} X \triangleleft (Y \triangleleft Z),
 \end{aligned}$$

where the map

$$\bigvee_{z \in Z} (\bigvee_{y \in Y} X) \rightarrow \bigvee_{(z,y) \in \bigvee_{z \in Z} Y} X$$

is given by $[(z, [(y, x)])] \mapsto [([(z, y)], x)]$.

PROOF 3.4.2 ► PROOF OF DEFINITION 3.4.1

(Proven below in a bit.)



REMARK 3.4.3 ► UNWINDING DEFINITION 3.4.1

Unwinding the notation for elements, we have

$$\begin{aligned} [(z, [(y, x)])] &\stackrel{\text{def}}{=} [(z, x \triangleleft y)] \\ &\stackrel{\text{def}}{=} (x \triangleleft y) \triangleleft z \end{aligned}$$

and

$$\begin{aligned} [([(z, y)], x)] &\stackrel{\text{def}}{=} [(y \triangleleft z, x)] \\ &\stackrel{\text{def}}{=} x \triangleleft (y \triangleleft z). \end{aligned}$$

So, in other words, $\alpha_{X,Y,Z}^{\text{Sets}, \triangleleft}$ acts on elements via

$$\alpha_{X,Y,Z}^{\text{Sets}, \triangleleft} ((x \triangleleft y) \triangleleft z) \stackrel{\text{def}}{=} x \triangleleft (y \triangleleft z)$$

for each $(x \triangleleft y) \triangleleft z \in (X \triangleleft Y) \triangleleft Z$.

REMARK 3.4.4 ► NON-INVERTIBILITY OF THE SKEW ASSOCIATOR OF \triangleleft

Taking $y = y_0$, we see that the morphism $\alpha_{X,Y,Z}^{\text{Sets}, \triangleleft}$ acts on elements as

$$\alpha_{X,Y,Z}^{\text{Sets}, \triangleleft} ((x \triangleleft y_0) \triangleleft z) \stackrel{\text{def}}{=} x \triangleleft (y_0 \triangleleft z).$$

However, by the definition of \triangleleft , we have $y_0 \triangleleft z = y_0 \triangleleft z'$ for all $z, z' \in Z$, preventing $\alpha_{X,Y,Z}^{\text{Sets}, \triangleleft}$ from being non-invertible.

PROOF 3.4.5 ► PROOF OF DEFINITION 3.4.1

Firstly, note that, given $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\text{Sets}_*)$, the map

$$\alpha_{X,Y,Z}^{\text{Sets}_*, \triangleleft} : (X \triangleleft Y) \triangleleft Z \rightarrow X \triangleleft (Y \triangleleft Z)$$

is indeed a morphism of pointed sets, as we have

$$\alpha_{X,Y,Z}^{\text{Sets}_*, \triangleleft}((x_0 \triangleleft y_0) \triangleleft z_0) = x_0 \triangleleft (y_0 \triangleleft z_0).$$

Next, we claim that $\alpha^{\text{Sets}_*, \triangleleft}$ is a natural transformation. We need to show that, given morphisms of pointed sets


$$\begin{aligned} f &: (X, x_0) \rightarrow (X', x'_0), \\ g &: (Y, y_0) \rightarrow (Y', y'_0), \\ h &: (Z, z_0) \rightarrow (Z', z'_0) \end{aligned}$$

the diagram

$$\begin{array}{ccc} (X \triangleleft Y) \triangleleft Z & \xrightarrow{(f \triangleleft g) \triangleleft h} & (X' \triangleleft Y') \triangleleft Z' \\ \alpha_{X,Y,Z}^{\text{Sets}_*, \triangleleft} \downarrow & & \downarrow \alpha_{X',Y',Z'}^{\text{Sets}_*, \triangleleft} \\ X \triangleleft (Y \triangleleft Z) & \xrightarrow{f \triangleleft (g \triangleleft h)} & X' \triangleleft (Y' \triangleleft Z') \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc} (x \triangleleft y) \triangleleft z & \longmapsto & (f(x) \triangleleft g(y)) \triangleleft h(z) \\ \downarrow & & \downarrow \\ x \triangleleft (y \triangleleft z) & \longmapsto & f(x) \triangleleft (g(y) \triangleleft h(z)) \end{array}$$

and hence indeed commutes, showing $\alpha^{\text{Sets}_*, \triangleleft}$ to be a natural transformation. This finishes the proof. 

3.5 The Left Skew Left Unitor

DEFINITION 3.5.1 ► THE LEFT SKEW LEFT UNITOR OF \triangleleft

The **skew left unitor of the left tensor product of pointed sets** is the natural transformation

$$\lambda^{\text{Sets}_*, \triangleleft} : \triangleleft \circ (\mathbb{1}_{\text{Sets}_*} \times \text{id}_{\text{Sets}_*}) \xRightarrow{\sim} \lambda_{\text{Sets}_*}^{\text{Cats}_2}$$

whose component

$$\lambda_X^{\text{Sets}_*, \triangleleft} : S^0 \triangleleft X \rightarrow X$$

at $(X, x_0) \in \text{Obj}(\text{Sets}_*)$ is given by the composition

$$\begin{aligned} S^0 \triangleleft X &\cong |X| \odot S^0 \\ &\cong \bigvee_{x \in X} S^0 \\ &\rightarrow X, \end{aligned}$$

where $\bigvee_{x \in X} S^0 \rightarrow X$ is the map given by

$$\begin{aligned} [(x, 0)] &\mapsto x_0, \\ [(x, 1)] &\mapsto x. \end{aligned}$$

PROOF 3.5.2 ► PROOF OF DEFINITION 3.5.1

(Proven below in a bit.)



REMARK 3.5.3 ► UNWINDING DEFINITION 3.5.1

In other words, $\lambda_X^{\text{Sets}_*, \triangleleft}$ acts on elements as

$$\begin{aligned}\lambda_X^{\text{Sets}_*, \triangleleft}(0 \triangleleft x) &\stackrel{\text{def}}{=} x_0, \\ \lambda_X^{\text{Sets}_*, \triangleleft}(1 \triangleleft x) &\stackrel{\text{def}}{=} x\end{aligned}$$

for each $1 \triangleleft x \in S^0 \triangleleft X$.

REMARK 3.5.4 ► NON-INVERTIBILITY OF THE SKEW LEFT UNITOR OF \triangleleft

The morphism $\lambda_X^{\text{Sets}_*, \triangleleft}$ is almost invertible, with its would-be-inverse

$$\phi_X: X \rightarrow S^0 \triangleleft X$$

given by

$$\phi_X(x) \stackrel{\text{def}}{=} 1 \triangleleft x$$

for each $x \in X$. Indeed, we have

$$\begin{aligned}[\lambda_X^{\text{Sets}_*, \triangleleft} \circ \phi](x) &= \lambda_X^{\text{Sets}_*, \triangleleft}(\phi(x)) \\ &= \lambda_X^{\text{Sets}_*, \triangleleft}(1 \triangleleft x) \\ &= x \\ &= [\text{id}_X](x)\end{aligned}$$

so that

$$\lambda_X^{\text{Sets}_*, \triangleleft} \circ \phi = \text{id}_X$$

and

$$\begin{aligned}[\phi \circ \lambda_X^{\text{Sets}_*, \triangleleft}](1 \triangleleft x) &= \phi(\lambda_X^{\text{Sets}_*, \triangleleft}(1 \triangleleft x)) \\ &= \phi(x) \\ &= 1 \triangleleft x \\ &= [\text{id}_{S^0 \triangleleft X}](1 \triangleleft x),\end{aligned}$$

but

$$\begin{aligned}[\phi \circ \lambda_X^{\text{Sets}_*, \triangleleft}](0 \triangleleft x) &= \phi(\lambda_X^{\text{Sets}_*, \triangleleft}(0 \triangleleft x)) \\ &= \phi(x_0) \\ &= 1 \triangleleft x_0,\end{aligned}$$

where $0 \triangleleft x \neq 1 \triangleleft x_0$. Thus

$$\phi \circ \lambda_X^{\text{Sets}_*, \triangleleft} \stackrel{?}{=} \text{id}_{S^0 \triangleleft X}$$

holds for all elements in $S^0 \triangleleft X$ except one.

PROOF 3.5.5 ► PROOF OF DEFINITION 3.5.1

Firstly, note that, given $(X, x_0) \in \text{Obj}(\text{Sets}_*)$, the map

$$\lambda_X^{\text{Sets}_*, \triangleleft} : S^0 \triangleleft X \rightarrow X$$

is indeed a morphism of pointed sets, as we have

$$\lambda_X^{\text{Sets}_*, \triangleleft}(0 \triangleleft x_0) = x_0.$$

Next, we claim that $\lambda^{\text{Sets}_*, \triangleleft}$ is a natural transformation. We need to show that, given a morphism of pointed sets

$$f : (X, x_0) \rightarrow (Y, y_0),$$

the diagram


$$\begin{array}{ccc} S^0 \triangleleft X & \xrightarrow{\text{id}_{S^0} \triangleleft f} & S^0 \triangleleft Y \\ \lambda_X^{\text{Sets}_*, \triangleleft} \downarrow & & \downarrow \lambda_Y^{\text{Sets}_*, \triangleleft} \\ X & \xrightarrow{f} & Y \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc} 0 \triangleleft x & & 0 \triangleleft x \mapsto 0 \triangleleft f(x) \\ \downarrow & & \downarrow \\ x_0 \mapsto & f(x_0) & y_0 \end{array}$$

and

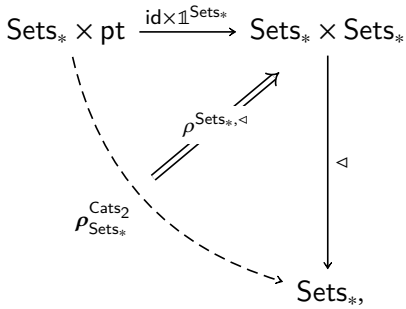
$$\begin{array}{ccc} 1 \triangleleft x \mapsto & 1 \triangleleft f(x) & \\ \downarrow & \downarrow & \\ x \mapsto & f(x) & \end{array}$$

and hence indeed commutes, showing $\lambda^{\text{Sets}_*, \triangleleft}$ to be a natural transformation. This finishes the proof. 

3.6 The Left Skew Right Unitor

DEFINITION 3.6.1 ► THE LEFT SKEW RIGHT UNITOR OF \triangleleft

The **skew right unitor of the left tensor product of pointed sets** is the natural transformation

$$\rho^{\text{Sets}_*, \triangleleft} : \rho_{\text{Sets}_*}^{\text{Cats}_2} \xrightarrow{\sim} \triangleleft \circ (\text{id} \times \mathbb{1}_{\text{Sets}_*}),$$


whose component


$$\rho_X^{\text{Sets}_*, \triangleleft} : X \rightarrow X \triangleleft S^0$$

at $(X, x_0) \in \text{Obj}(\text{Sets}_*)$ is given by the composition

$$\begin{aligned} X &\rightarrow X \vee X \\ &\cong |S^0| \odot X \\ &\cong X \triangleleft S^0, \end{aligned}$$

where $X \rightarrow X \vee X$ is the map sending X to the second factor of X in $X \vee X$.

PROOF 3.6.2 ► PROOF OF DEFINITION 3.6.1

(Proven below in a bit.) 

REMARK 3.6.3 ► UNWINDING DEFINITION 3.6.1

In other words, $\rho_X^{\text{Sets}_*, \triangleleft}$ acts on elements as

$$\rho_X^{\text{Sets}_*, \triangleleft}(x) \stackrel{\text{def}}{=} [(1, x)]$$

i.e. by

$$\rho_X^{\text{Sets}_*, \triangleleft}(x) \stackrel{\text{def}}{=} x \triangleleft 1$$

for each $x \in X$.

REMARK 3.6.4 ► NON-INVERTIBILITY OF THE SKEW RIGHT UNITOR OF \triangleleft

The morphism $\rho_X^{\text{Sets}_*, \triangleleft}$ is non-invertible, as it is non-surjective when viewed as a map of sets, since the elements $x \triangleleft 0$ of $X \triangleleft S^0$ with $x \neq x_0$ are outside the image of $\rho_X^{\text{Sets}_*, \triangleleft}$, which sends x to $x \triangleleft 1$.

PROOF 3.6.5 ► PROOF OF DEFINITION 3.6.1

Firstly, note that, given $(X, x_0) \in \text{Obj}(\text{Sets}_*)$, the map

$$\rho_X^{\text{Sets}_*, \triangleleft} : X \rightarrow X \triangleleft S^0$$

is indeed a morphism of pointed sets as we have

$$\begin{aligned} \rho_X^{\text{Sets}_*, \triangleleft}(x_0) &= x_0 \triangleleft 1 \\ &= x_0 \triangleleft 0. \end{aligned}$$

Next, we claim that $\rho^{\text{Sets}_*, \triangleleft}$ is a natural transformation. We need to show that, given a morphism of pointed sets


$$f : (X, x_0) \rightarrow (Y, y_0),$$

the diagram

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ \rho_X^{\text{Sets}_*, \triangleleft} \downarrow & & \downarrow \rho_Y^{\text{Sets}_*, \triangleleft} \\ X \triangleleft S^0 & \xrightarrow{f \triangleleft \text{id}_{S^0}} & Y \triangleleft S^0 \end{array}$$

commutes. Indeed, this diagram acts on elements as

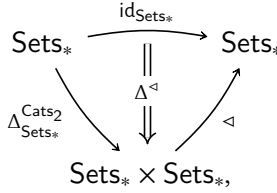
$$\begin{array}{ccc} x & \xrightarrow{\quad} & f(x) \\ \downarrow & & \downarrow \\ x \triangleleft 0 & \xrightarrow{\quad} & f(x) \triangleleft 0 \end{array}$$

and hence indeed commutes, showing $\rho^{\text{Sets}_*, \triangleleft}$ to be a natural transformation. This finishes the proof. 

3.7 The Diagonal

DEFINITION 3.7.1 ► THE DIAGONAL OF \triangleleft

The **diagonal of the left tensor product of pointed sets** is the natural transformation

$$\Delta^{\triangleleft} : \text{id}_{\text{Sets}_*} \Rightarrow \triangleleft \circ \Delta_{\text{Sets}_*}^{\text{Cats}_2},$$


The diagram shows a square with Sets_* at the top-left and top-right corners, and $\text{Sets}_* \times \text{Sets}_*$ at the bottom-left and bottom-right corners. A horizontal arrow $\text{id}_{\text{Sets}_*}$ points from the top-left to the top-right. A curved arrow $\Delta_{\text{Sets}_*}^{\text{Cats}_2}$ points from the top-left to the bottom-left. A curved arrow \triangleleft points from the top-right to the bottom-right. A vertical double arrow Δ^{\triangleleft} points from the top-right to the bottom-right, with a small \triangleleft symbol next to it.

whose component

$$\Delta_X^{\triangleleft} : (X, x_0) \rightarrow (X \triangleleft X, x_0 \triangleleft x_0)$$

at $(X, x_0) \in \text{Obj}(\text{Sets}_*)$ is given by

$$\Delta_X^{\triangleleft}(x) \stackrel{\text{def}}{=} x \triangleleft x$$

for each $x \in X$.

PROOF 3.7.2 ► PROOF OF DEFINITION 3.7.1

Being a Morphism of Pointed Sets

We have

$$\Delta_X^\triangleleft(x_0) \stackrel{\text{def}}{=} x_0 \triangleleft x_0,$$

and thus Δ_X^\triangleleft is a morphism of pointed sets.

Naturality

We need to show that, given a morphism of pointed sets


$$f: (X, x_0) \rightarrow (Y, y_0),$$

the diagram

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ \Delta_X^\triangleleft \downarrow & & \downarrow \Delta_Y^\triangleleft \\ X \triangleleft X & \xrightarrow{f \triangleleft f} & Y \triangleleft Y \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc} x & \longmapsto & f(x) \\ \downarrow & & \downarrow \\ x \triangleleft x & \longmapsto & f(x) \triangleleft f(x) \end{array}$$

and hence indeed commutes, showing Δ^\triangleleft to be natural. 

3.8 The Left Skew Monoidal Structure on Pointed Sets Associated to \triangleleft

PROPOSITION 3.8.1 ► THE LEFT SKEW MONOIDAL STRUCTURE ON POINTED SETS ASSOCIATED TO \triangleleft

The category \mathbf{Sets}_* admits a left-closed left skew monoidal category structure consisting of

- *The Underlying Category.* The category \mathbf{Sets}_* of pointed sets;
- *The Left Skew Monoidal Product.* The left tensor product functor

$$\triangleleft: \mathbf{Sets}_* \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$

of **Definition 3.1.1**;

- *The Left Internal Skew Hom.* The left internal Hom functor

$$[-, -]_{\mathbf{Sets}_*}^{\triangleleft} : \mathbf{Sets}_*^{\text{op}} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$

of **Definition 3.2.1**;

- *The Left Skew Monoidal Unit.* The functor

$$\mathbb{1}^{\mathbf{Sets}_*, \triangleleft} : \text{pt} \rightarrow \mathbf{Sets}_*$$

of **Definition 3.3.1**;

- *The Left Skew Associators.* The natural transformation

$$\alpha^{\mathbf{Sets}_*, \triangleleft} : \triangleleft \circ (\triangleleft \times \text{id}_{\mathbf{Sets}_*}) \Longrightarrow \triangleleft \circ (\text{id}_{\mathbf{Sets}_*} \times \triangleleft) \circ \alpha_{\mathbf{Sets}_*, \mathbf{Sets}_*, \mathbf{Sets}_*}^{\mathbf{Cats}}$$

of **Definition 3.4.1**;

- *The Left Skew Left Unitors.* The natural transformation

$$\lambda^{\mathbf{Sets}_*, \triangleleft} : \triangleleft \circ (\mathbb{1}^{\mathbf{Sets}_*} \times \text{id}_{\mathbf{Sets}_*}) \xrightarrow{\sim} \lambda_{\mathbf{Sets}_*}^{\mathbf{Cats}_2}$$

of **Definition 3.5.1**;

- *The Left Skew Right Unitors.* The natural transformation

$$\rho^{\mathbf{Sets}_*, \triangleleft} : \rho_{\mathbf{Sets}_*}^{\mathbf{Cats}_2} \xrightarrow{\sim} \triangleleft \circ (\text{id} \times \mathbb{1}^{\mathbf{Sets}_*})$$

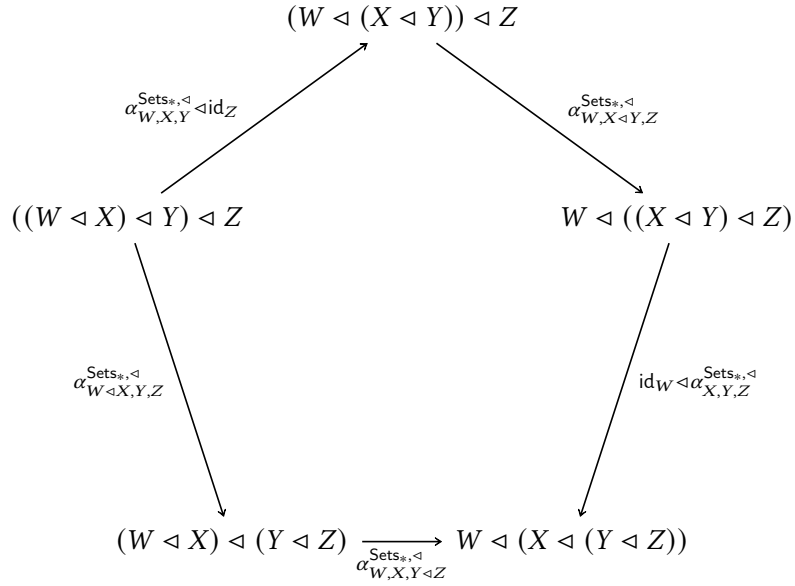
of **Definition 3.6.1**.

PROOF 3.8.2 ► PROOF OF PROPOSITION 3.8.1

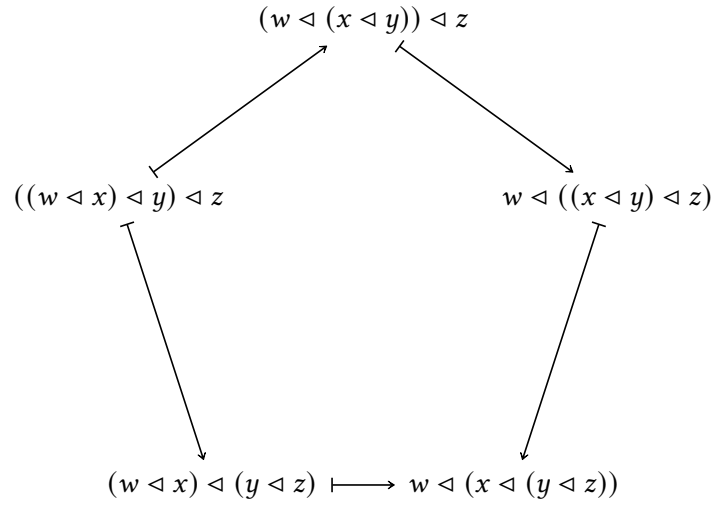
The Pentagon Identity

Let (W, w_0) , (X, x_0) , (Y, y_0) and (Z, z_0) be pointed sets. We have to show that

the diagram



commutes. Indeed, this diagram acts on elements as



and thus we see that the pentagon identity is satisfied.

The Left Skew Left Triangle Identity

Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram

$$\begin{array}{ccc}
 (S^0 \triangleleft X) \triangleleft Y & \xrightarrow{\alpha_{S^0, X, Y}^{\text{Sets}_*, \triangleleft}} & S^0 \triangleleft (X \triangleleft Y) \\
 \searrow \lambda_X^{\text{Sets}_*, \triangleleft} \triangleleft \text{id}_Y & & \downarrow \lambda_{X \triangleleft Y}^{\text{Sets}_*, \triangleleft} \\
 & & X \triangleleft Y
 \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
 (0 \triangleleft x) \triangleleft y & \mapsto & 0 \triangleleft (x \triangleleft y) \\
 \swarrow & & \downarrow \\
 & & x_0 \triangleleft y = x_0 \triangleleft y_0
 \end{array}$$

and

$$\begin{array}{ccc}
 (1 \triangleleft x) \triangleleft y & \mapsto & 1 \triangleleft (x \triangleleft y) \\
 \swarrow & & \downarrow \\
 & & x \triangleleft y
 \end{array}$$

and hence indeed commutes. Thus the left skew triangle identity is satisfied.

The Left Skew Right Triangle Identity

Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram

$$\begin{array}{ccc}
 X \triangleleft Y & & \\
 \downarrow \rho_{X \triangleleft Y}^{\text{Sets}_*, \triangleleft} & \searrow \text{id}_X \triangleleft \rho_Y^{\text{Sets}_*, \triangleleft} & \\
 (X \triangleleft Y) \triangleleft S^0 & \xrightarrow[\alpha_{X, Y, S^0}^{\text{Sets}_*, \triangleleft}]{} & X \triangleleft (Y \triangleleft S^0)
 \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc} x \triangleleft y & & \\ \downarrow & \searrow & \\ (x \triangleleft y) \triangleleft 1 & \mapsto & x \triangleleft (y \triangleleft 1) \end{array}$$

and hence indeed commutes. Thus the right skew triangle identity is satisfied.

The Left Skew Middle Triangle Identity

Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram

$$\begin{array}{ccc} X \triangleleft Y & \xlongequal{\quad} & X \triangleleft Y \\ \downarrow \rho_X^{\text{Sets}_*, \triangleleft} \triangleleft \text{id}_Y & & \uparrow \text{id}_X \triangleleft \lambda_Y^{\text{Sets}_*, \triangleleft} \\ (X \triangleleft S^0) \triangleleft Y & \xrightarrow[\alpha_{X, S^0, Y}^{\text{Sets}_*, \triangleleft}]{} & X \triangleleft (S^0 \triangleleft Y) \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc} x \triangleleft y & \xrightarrow{\quad} & x \triangleleft y \\ \downarrow & & \uparrow \\ (x \triangleleft 1) \triangleleft y & \xrightarrow{\quad} & x \triangleleft (1 \triangleleft y) \end{array}$$

and hence indeed commutes. Thus the right skew triangle identity is satisfied.

The Zig-Zag Identity

We have to show that the diagram

$$\begin{array}{ccc} S^0 & \xrightarrow{\rho_{S^0}^{\text{Sets}_*, \triangleleft}} & S^0 \triangleleft S^0 \\ & \searrow & \downarrow \lambda_{S^0}^{\text{Sets}_*, \triangleleft} \\ & & S^0 \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc} 0 & \xrightarrow{\quad} & 0 \triangleleft 1 \\ & \searrow & \downarrow \\ & & 0 \end{array}$$

and

$$\begin{array}{ccc} 1 & \xrightarrow{\quad} & 1 \triangleleft 1 \\ & \searrow & \downarrow \\ & & 1 \end{array}$$

and hence indeed commutes. Thus the zig-zag identity is satisfied.

Left Skew Monoidal Left-Closedness

This follows from [Item 2](#) of [Proposition 3.1.7](#). 

3.9 Monoids With Respect to the Left Tensor Product of Pointed Sets

PROPOSITION 3.9.1 ► MONOIDS WITH RESPECT TO \triangleleft

The category of monoids on $(\text{Sets}_*, \triangleleft, S^0)$ is isomorphic to the category of “monoids with left zero”¹ and morphisms between them.

¹A monoid with left zero is defined similarly as the monoids with zero of ???. Succinctly, they are monoids (A, μ_A, η_A) with a special element 0_A satisfying

$$0_A a = 0_A$$

for each $a \in A$.

PROOF 3.9.2 ► PROOF OF PROPOSITION 3.9.1

Monoids on $(\text{Sets}_*, \triangleleft, S^0)$

A monoid on $(\text{Sets}_*, \triangleleft, S^0)$ consists of:

- *The Underlying Object.* A pointed set $(A, 0_A)$.

- *The Multiplication Morphism.* A morphism of pointed sets

$$\mu_A: A \triangleleft A \rightarrow A,$$

determining a left bilinear morphism of pointed sets

$$\begin{aligned} A \times A &\longrightarrow A \\ (a, b) &\longmapsto ab. \end{aligned}$$

- *The Unit Morphism.* A morphism of pointed sets

$$\eta_A: S^0 \rightarrow A$$

picking an element 1_A of A .

satisfying the following conditions:

1. *Associativity.* The diagram

$$\begin{array}{ccccc} & & A \triangleleft (A \triangleleft A) & & \\ \alpha_{A,A,A}^{\text{Sets}_{*,\triangleleft}} \nearrow & & & \searrow \text{id}_A \triangleleft \mu_A & \\ (A \triangleleft A) \triangleleft A & & & & A \triangleleft A \\ \mu_A \triangleleft \text{id}_A \searrow & & & \swarrow \mu_A & \\ & A \triangleleft A & \xrightarrow{\mu_A} & A & \end{array}$$

2. *Left Unitality.* The diagram

$$\begin{array}{ccc} S^0 \triangleleft A & \xrightarrow{\eta_A \times \text{id}_A} & A \triangleleft A \\ & \searrow \lambda_A^{\text{Sets}_{*,\triangleleft}} & \downarrow \mu_A \\ & & A \end{array}$$

commutes.

3. *Right Unitality*. The diagram

$$\begin{array}{ccc}
 A & \xrightarrow{\rho_A^{\text{Sets}, \triangleleft}} & A \triangleleft S^0 \\
 \parallel & & \downarrow \text{id}_A \times \eta_A \\
 A & \xleftarrow{\mu_A} & A \triangleleft A
 \end{array}$$

commutes.

Being a left-bilinear morphism of pointed sets, the multiplication map satisfies

$$0_A a = 0_A$$

for each $a \in A$. Now, the associativity, left unitality, and right unitality conditions act on elements as follows:

1. *Associativity*. The associativity condition acts as

$$\begin{array}{ccc}
 & & a \triangleleft (b \triangleleft c) \\
 & \swarrow & \searrow \\
 (a \triangleleft b) \triangleleft c & & (a \triangleleft b) \triangleleft c \\
 \searrow & & \swarrow \\
 ab \triangleleft c & \mapsto & (ab)c \\
 & & \\
 & & a \triangleleft bc \\
 & & \searrow \\
 & & a(bc)
 \end{array}$$

This gives

$$(ab)c = a(bc)$$

for each $a, b, c \in A$.

2. *Left Unitality*. The left unitality condition acts:

(a) On $0 \triangleleft a$ as

$$\begin{array}{ccc}
 0 \triangleleft a & \mapsto & 0_A \triangleleft a \\
 \searrow & & \downarrow \\
 & & 0_A a
 \end{array}$$

(b) On $1 \triangleleft a$ as

$$\begin{array}{ccc} 1 \triangleleft a & & 1 \triangleleft a \mapsto 1_A \triangleleft a \\ & \searrow & \downarrow \\ & a & 1_A a. \end{array}$$

This gives

$$\begin{aligned} 1_A a &= a, \\ 0_A a &= 0_A \end{aligned}$$

for each $a \in A$.

3. *Right Unitality*. The right unitality condition acts as

$$\begin{array}{ccc} a & & a \mapsto a \triangleleft 1 \\ \downarrow & & \downarrow \\ a & & a 1_A \longleftarrow a \triangleleft 1_A \end{array}$$

This gives

$$a 1_A = a$$

for each $a \in A$.

Thus we see that monoids with respect to \triangleleft are exactly monoids with left zero.

Morphisms of Monoids on $(\text{Sets}_*, \triangleleft, S^0)$

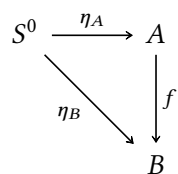
A morphism of monoids on $(\text{Sets}_*, \triangleleft, S^0)$ from $(A, \mu_A, \eta_A, 0_A)$ to $(B, \mu_B, \eta_B, 0_B)$ is a morphism of pointed sets

$$f: (A, 0_A) \rightarrow (B, 0_B)$$

satisfying the following conditions:

$$\begin{array}{ccc} A \triangleleft A & \xrightarrow{f \triangleleft f} & B \triangleleft B \\ \mu_A \downarrow & & \downarrow \mu_B \\ A & \xrightarrow{f} & B \end{array}$$

2. *Compatibility With the Unit Morphisms.* The diagram



These act on elements as

$$\begin{array}{ccc} a \triangleleft b & & a \triangleleft b \mapsto f(a) \triangleleft f(b) \\ \downarrow & & \downarrow \\ ab \mapsto f(ab) & & f(a)f(b) \end{array}$$

$$\begin{array}{ccc} 0 & \xrightarrow{\quad} & 0_A \\ \searrow & & \downarrow \\ & & f(0_A) \end{array}$$
$$\begin{array}{ccc} 1 & \xrightarrow{\quad} & 1_A \\ & \searrow & \downarrow \\ & & f(1_A) \end{array}$$

giving


$$f(ab) = f(a)f(b),$$

$$f(0_A) = 0_B,$$

$$f(1_A) = 1_B,$$

for each $a, b \in A$, which is exactly a morphism of monoids with left zero.

Identities and Composition

Similarly, the identities and composition of $\text{Mon}(\text{Sets}_*, \triangleleft, S^0)$ can be easily seen to agree with those of monoids with left zero, which finishes the proof. 

4 The Right Tensor Product of Pointed Sets

4.1 Foundations

Let (X, x_0) and (Y, y_0) be pointed sets.

DEFINITION 4.1.1 ► THE RIGHT TENSOR PRODUCT OF POINTED SETS

The **right tensor product of pointed sets** is the functor¹

$$\triangleright : \text{Sets}_* \times \text{Sets}_* \rightarrow \text{Sets}_*$$

defined as the composition

$$\text{Sets}_* \times \text{Sets}_* \xrightarrow{\text{忘} \times \text{id}} \text{Sets} \times \text{Sets}_* \xrightarrow{\odot} \text{Sets}_*,$$

where:

- $\text{忘} : \text{Sets}_* \rightarrow \text{Sets}$ is the forgetful functor from pointed sets to sets.
- $\odot : \text{Sets} \times \text{Sets}_* \rightarrow \text{Sets}_*$ is the tensor functor of **Item 1 of Proposition 2.1.9**.

¹*Further Notation:* Also written $\triangleright_{\text{Sets}_*}$.

REMARK 4.1.2 ► UNWINDING DEFINITION 4.1.1: UNIVERSAL PROPERTY I

The right tensor product of pointed sets satisfies the following natural bijection:

$$\text{Sets}_*(X \triangleright Y, Z) \cong \text{Hom}_{\text{Sets}_*}^{\otimes, R}(X \times Y, Z).$$

That is to say, the following data are in natural bijection:

1. Pointed maps $f: X \triangleright Y \rightarrow Z$.
2. Maps of sets $f: X \times Y \rightarrow Z$ satisfying $f(x, y_0) = z_0$ for each $x \in X$.

REMARK 4.1.3 ► UNWINDING DEFINITION 4.1.1: UNIVERSAL PROPERTY II

The right tensor product of pointed sets may be described as follows:

- The right tensor product of (X, x_0) and (Y, y_0) is the pair $((X \triangleright Y, x_0 \triangleright y_0), \iota)$ consisting of
 - A pointed set $(X \triangleright Y, x_0 \triangleright y_0)$;
 - A right bilinear morphism of pointed sets $\iota: (X \times Y, (x_0, y_0)) \rightarrow X \triangleright Y$;

satisfying the following universal property:

(UP) Given another such pair $((Z, z_0), f)$ consisting of

- * A pointed set (Z, z_0) ;
- * A right bilinear morphism of pointed sets $f: (X \times Y, (x_0, y_0)) \rightarrow Z$;

there exists a unique morphism of pointed sets $X \triangleright Y \xrightarrow{\exists!} Z$ making the diagram

$$\begin{array}{ccc} & X \triangleright Y & \\ \iota \nearrow & & \downarrow \exists! \\ X \times Y & \xrightarrow{f} & Z \end{array}$$

commute.

CONSTRUCTION 4.1.4 ► THE RIGHT TENSOR PRODUCT OF POINTED SETS

In detail, the **right tensor product of** (X, x_0) **and** (Y, y_0) is the pointed set $(X \triangleright Y, [y_0])$ consisting of:

- *The Underlying Set.* The set $X \triangleright Y$ defined by

$$\begin{aligned} X \triangleright Y &\stackrel{\text{def}}{=} |X| \odot Y \\ &\cong \bigvee_{x \in X} (Y, y_0), \end{aligned}$$

where $|X|$ denotes the underlying set of (X, x_0) .

- *The Underlying Basepoint.* The point $[(x_0, y_0)]$ of $\bigvee_{x \in X} (Y, y_0)$, which is equal to $[(x, y_0)]$ for any $x \in X$.

NOTATION 4.1.5 ► ELEMENTS OF RIGHT TENSOR PRODUCTS OF POINTED SETS

We write¹ $x \triangleright y$ for the element $[(x, y)]$ of

$$X \triangleright Y \cong |X| \odot Y.$$

¹Further Notation: Also written $x \triangleright_{\text{Sets}_*} y$.

REMARK 4.1.6 ► BASEPOINTS OF RIGHT TENSOR PRODUCTS OF POINTED SETS

Employing the notation introduced in **Notation 4.1.5**, we have

$$x_0 \triangleright y_0 = x \triangleright y_0$$

for each $x \in X$, and

$$x \triangleright y_0 = x' \triangleright y_0$$

for each $x, x' \in X$.

PROPOSITION 4.1.7 ► PROPERTIES OF RIGHT TENSOR PRODUCTS OF POINTED SETS

Let (X, x_0) and (Y, y_0) be pointed sets.

1. *Functoriality.* The assignments $X, Y, (X, Y) \mapsto X \triangleright Y$ define functors

$$\begin{aligned} X \triangleright - &: \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*, \\ - \triangleright Y &: \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*, \\ -_1 \triangleright -_2 &: \mathbf{Sets}_* \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*. \end{aligned}$$

In particular, given pointed maps

$$\begin{aligned} f &: (X, x_0) \rightarrow (A, a_0), \\ g &: (Y, y_0) \rightarrow (B, b_0), \end{aligned}$$

the induced map

$$f \triangleright g: X \triangleright Y \rightarrow A \triangleright B$$

is given by

$$[f \triangleright g](x \triangleright y) \stackrel{\text{def}}{=} f(x) \triangleright g(y)$$

for each $x \triangleright y \in X \triangleright Y$.

2. *Adjointness I.* We have an adjunction

$$\left(X \triangleright - \dashv [X, -]_{\mathbf{Sets}_*}^{\triangleright} \right): \mathbf{Sets}_* \begin{array}{c} \xrightarrow{X \triangleright -} \\ \perp \\ \xleftarrow{[X, -]_{\mathbf{Sets}_*}^{\triangleright}} \end{array} \mathbf{Sets}_*,$$

witnessed by a bijection of sets

$$\text{Hom}_{\mathbf{Sets}_*}(X \triangleright Y, Z) \cong \text{Hom}_{\mathbf{Sets}_*}(Y, [X, Z]_{\mathbf{Sets}_*}^{\triangleright})$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\mathbf{Sets}_*)$, where $[X, Y]_{\mathbf{Sets}_*}^{\triangleright}$ is the pointed set of [Definition 4.2.1](#).

3. *Adjointness II.* The functor

$$- \triangleright Y: \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$

does not admit a right adjoint.

4. *Adjointness III.* We have a bijection of sets

$$\text{Hom}_{\mathbf{Sets}_*}(X \triangleright Y, Z) \cong \text{Hom}_{\mathbf{Sets}}(|X|, \mathbf{Sets}_*(Y, Z))$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\mathbf{Sets}_*)$.

PROOF 4.1.8 ► PROOF OF PROPOSITION 4.1.7

Item 1: Functoriality

Clear.

Item 2: Adjointness I

This follows from Item 3 of Proposition 2.1.9.

Item 3: Adjointness II

For $- \triangleright Y$ to admit a right adjoint would require it to preserve colimits by ??, ?? of ??. However, we have

$$\begin{aligned} \text{pt} \triangleright X &\stackrel{\text{def}}{=} |\text{pt}| \odot X \\ &\cong X \\ &\neq \text{pt}, \end{aligned}$$

and thus we see that $- \triangleright Y$ does not have a right adjoint.

Item 4: Adjointness III

This follows from Item 2 of Proposition 2.1.9. 

REMARK 4.1.9 ► ON THE FAILURE OF $- \triangleright Y$ TO BE A LEFT ADJOINT

Here is some intuition on why $- \triangleright Y$ fails to be a left adjoint. Item 4 of Proposition 3.1.7 states that we have a natural bijection

$$\text{Hom}_{\mathbf{Sets}_*}(X \triangleright Y, Z) \cong \text{Hom}_{\mathbf{Sets}}(|X|, \mathbf{Sets}_*(Y, Z)),$$

so it would be reasonable to wonder whether a natural bijection of the form

$$\text{Hom}_{\mathbf{Sets}_*}(X \triangleright Y, Z) \cong \text{Hom}_{\mathbf{Sets}_*}(X, \mathbf{Sets}_*(Y, Z)),$$

also holds, which would give $- \triangleright Y \dashv \mathbf{Sets}_*(Y, -)$. However, such a bijection would require every map

$$f: X \triangleright Y \rightarrow Z$$

to satisfy

$$f(x_0 \triangleright y) = z_0$$

for each $x \in X$, whereas we are imposing such a basepoint preservation condition only for elements of the form $x \triangleright y_0$. Thus $\mathbf{Sets}_*(Y, -)$ can't be a right adjoint for $- \triangleright Y$, and as shown by Item 3 of Proposition 4.1.7, no functor can.¹

¹The functor $\mathbf{Sets}_*(Y, -)$ is instead right adjoint to $- \wedge Y$, the smash product of pointed sets of Definition 5.1.1. See Item 2 of Proposition 5.1.10.

4.2 The Right Internal Hom of Pointed Sets

Let (X, x_0) and (Y, y_0) be pointed sets.

DEFINITION 4.2.1 ► THE RIGHT INTERNAL HOM OF POINTED SETS

The **right internal Hom of pointed sets** is the functor

$$[-, -]_{\mathbf{Sets}_*}^{\triangleright} : \mathbf{Sets}_*^{\text{op}} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$


defined as the composition

$$\mathbf{Sets}_*^{\text{op}} \times \mathbf{Sets}_* \xrightarrow{\text{忘} \times \text{id}} \mathbf{Sets}^{\text{op}} \times \mathbf{Sets}_* \xrightarrow{\pitchfork} \mathbf{Sets}_*,$$

where:

- $\text{忘} : \mathbf{Sets}_* \rightarrow \mathbf{Sets}$ is the forgetful functor from pointed sets to sets.
- $\pitchfork : \mathbf{Sets}^{\text{op}} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$ is the cotensor functor of Item 1 of Proposition 2.2.6.

PROOF 4.2.2 ► PROOF OF DEFINITION 4.2.1

For a proof that $[-, -]_{\mathbf{Sets}_*}^{\triangleright}$ is indeed the right internal Hom of \mathbf{Sets}_* with respect to the right tensor product of pointed sets, see Item 2 of Proposition 4.1.7. 

REMARK 4.2.3 ► UNWINDING DEFINITION 4.2.1, I: COMPARISON WITH $[-, -]_{\mathbf{Sets}_*}^{\triangleleft}$

We have

$$[-, -]_{\mathbf{Sets}_*}^{\triangleleft} = [-, -]_{\mathbf{Sets}_*}^{\triangleright}.$$

REMARK 4.2.4 ► UNWINDING DEFINITION 4.2.1, II: UNIVERSAL PROPERTY

The right internal Hom of pointed sets satisfies the following universal property:

$$\mathbf{Sets}_*(X \triangleright Y, Z) \cong \mathbf{Sets}_*(Y, [X, Z]_{\mathbf{Sets}_*}^{\triangleright})$$

That is to say, the following data are in bijection:

1. Pointed maps $f: X \triangleright Y \rightarrow Z$.
2. Pointed maps $f: Y \rightarrow [X, Z]_{\mathbf{Sets}_*}^\triangleright$.

REMARK 4.2.5 ► UNWINDING DEFINITION 4.2.1, III: EXPLICIT DESCRIPTION

In detail, the **right internal Hom of** (X, x_0) **and** (Y, y_0) is the pointed set $([X, Y]_{\mathbf{Sets}_*}^\triangleright, [(y_0)_{x \in X}])$ consisting of

- *The Underlying Set.* The set $[X, Y]_{\mathbf{Sets}_*}^\triangleright$ defined by

$$\begin{aligned} [X, Y]_{\mathbf{Sets}_*}^\triangleright &\stackrel{\text{def}}{=} |X| \wr Y \\ &\cong \bigwedge_{x \in X} (Y, y_0), \end{aligned}$$

where $|X|$ denotes the underlying set of (X, x_0) ;

- *The Underlying Basepoint.* The point $[(y_0)_{x \in X}]$ of $\bigwedge_{x \in X} (Y, y_0)$.

PROPOSITION 4.2.6 ► PROPERTIES OF RIGHT INTERNAL HOMS OF POINTED SETS

Let (X, x_0) and (Y, y_0) be pointed sets.

1. *Functoriality.* The assignments $X, Y, (X, Y) \mapsto [X, Y]_{\mathbf{Sets}_*}^\triangleright$ define functors

$$\begin{aligned} [X, -]_{\mathbf{Sets}_*}^\triangleright &: \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*, \\ [-, Y]_{\mathbf{Sets}_*}^\triangleright &: \mathbf{Sets}_*^{\text{op}} \rightarrow \mathbf{Sets}_*, \\ [-_1, -_2]_{\mathbf{Sets}_*}^\triangleright &: \mathbf{Sets}_*^{\text{op}} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*. \end{aligned}$$

In particular, given pointed maps

$$\begin{aligned} f &: (X, x_0) \rightarrow (A, a_0), \\ g &: (Y, y_0) \rightarrow (B, b_0), \end{aligned}$$

the induced map

$$[f, g]_{\mathbf{Sets}_*}^\triangleright : [A, Y]_{\mathbf{Sets}_*}^\triangleright \rightarrow [X, B]_{\mathbf{Sets}_*}^\triangleright$$

is given by

$$[f, g]_{\text{Sets}_*}^\triangleright ([y_a]_{a \in A}) \stackrel{\text{def}}{=} [(g(y_{f(x)}))_{x \in X}]$$

for each $[(y_a)_{a \in A}] \in [A, Y]_{\text{Sets}_*}^\triangleright$.

2. *Adjointness I.* We have an adjunction

$$\left(X \triangleright - \dashv [X, -]_{\text{Sets}_*}^\triangleright \right): \text{Sets}_* \begin{array}{c} \xrightarrow{X \triangleright -} \\ \perp \\ \xleftarrow{[X, -]_{\text{Sets}_*}^\triangleright} \end{array} \text{Sets}_*$$

witnessed by a bijection of sets

$$\text{Hom}_{\text{Sets}_*}(X \triangleright Y, Z) \cong \text{Hom}_{\text{Sets}_*}(Y, [X, Z]_{\text{Sets}_*}^\triangleright)$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\text{Sets}_*)$, where $[X, Y]_{\text{Sets}_*}^\triangleright$ is the pointed set of [Definition 4.2.1](#).

3. *Adjointness II.* The functor

$$- \triangleright Y: \text{Sets}_* \rightarrow \text{Sets}_*$$

does not admit a right adjoint.

PROOF 4.2.7 ► PROOF OF PROPOSITION 4.2.6

Item 1: Functoriality

Clear.

Item 2: Adjointness I

This is a repetition of [Item 2](#) of [Proposition 4.1.7](#), and is proved there.

Item 3: Adjointness II

This is a repetition of [Item 3](#) of [Proposition 4.1.7](#), and is proved there. 

4.3 The Right Skew Unit

DEFINITION 4.3.1 ► THE RIGHT SKEW UNIT OF \triangleright

The **right skew unit of the right tensor product of pointed sets** is the functor

$$\mathbb{1}^{\text{Sets}_*, \triangleright} : \text{pt} \rightarrow \text{Sets}_*$$

defined by

$$\mathbb{1}_{\text{Sets}_*}^{\triangleright} \stackrel{\text{def}}{=} S^0.$$

4.4 The Right Skew Associator**DEFINITION 4.4.1 ► THE RIGHT SKEW ASSOCIATOR OF \triangleright**

The **skew associator of the right tensor product of pointed sets** is the natural transformation

$$\alpha^{\text{Sets}_*, \triangleright} : \triangleright \circ (\text{id}_{\text{Sets}_*} \times \triangleright) \Longrightarrow \triangleright \circ (\triangleright \times \text{id}_{\text{Sets}_*}) \circ \alpha_{\text{Sets}_*, \text{Sets}_*, \text{Sets}_*}^{\text{Cats}, -1}$$

as in the diagram

$$\begin{array}{ccccc}
 & & (\text{Sets}_* \times \text{Sets}_*) \times \text{Sets}_* & & \\
 & \nearrow \alpha_{\text{Sets}_*, \text{Sets}_*, \text{Sets}_*}^{\text{Cats}, -1} & & \searrow \triangleright \times \text{id} & \\
 \text{Sets}_* \times (\text{Sets}_* \times \text{Sets}_*) & & & & \text{Sets}_* \times \text{Sets}_* \\
 \downarrow \text{id} \times \triangleright & \nearrow \alpha^{\text{Sets}_*, \triangleright} & & \searrow \triangleright & \\
 \text{Sets}_* \times \text{Sets}_* & \xrightarrow{\triangleright} & \text{Sets}_* & &
 \end{array}$$

whose component

$$\alpha_{X,Y,Z}^{\text{Sets}_*, \triangleright} : X \triangleright (Y \triangleright Z) \rightarrow (X \triangleright Y) \triangleright Z$$

at $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\text{Sets}_*)$ is given by

$$\begin{aligned}
 X \triangleright (Y \triangleright Z) &\stackrel{\text{def}}{=} |X| \odot (Y \triangleright Z) \\
 &\stackrel{\text{def}}{=} |X| \odot (|Y| \odot Z) \\
 &\cong \bigvee_{x \in X} (|Y| \odot Z) \\
 &\cong \bigvee_{x \in X} \left(\bigvee_{y \in Y} Z \right) \\
 &\rightarrow \bigvee_{[(x,y)] \in \bigvee_{x \in X} Y} Z \\
 &\cong \bigvee_{[(x,y)] \in |X| \odot Y} Z \\
 &\cong ||X| \odot Y| \odot Z \\
 &\stackrel{\text{def}}{=} |X \triangleright Y| \odot Z \\
 &\stackrel{\text{def}}{=} (X \triangleright Y) \triangleright Z,
 \end{aligned}$$

where the map

$$\bigvee_{x \in X} \left(\bigvee_{y \in Y} Z \right) \rightarrow \bigvee_{[(x,y)] \in \bigvee_{x \in X} Y} Z$$

is given by $[(x, [(y, z)])] \mapsto [([(x, y)], z)]$.

PROOF 4.4.2 ► PROOF OF DEFINITION 4.4.1

(Proven below in a bit.)



REMARK 4.4.3 ► UNWINDING DEFINITION 4.4.1

Unwinding the notation for elements, we have

$$\begin{aligned}
 [(x, [(y, z)])] &\stackrel{\text{def}}{=} [(x, y \triangleright z)] \\
 &\stackrel{\text{def}}{=} x \triangleright (y \triangleright z)
 \end{aligned}$$

and

$$\begin{aligned}
 [([(x, y)], z)] &\stackrel{\text{def}}{=} [(x \triangleright y, z)] \\
 &\stackrel{\text{def}}{=} (x \triangleright y) \triangleright z.
 \end{aligned}$$

So, in other words, $\alpha_{X,Y,Z}^{\text{Sets}_*, \triangleright}$ acts on elements via

$$\alpha_{X,Y,Z}^{\text{Sets}_*, \triangleright} (x \triangleright (y \triangleright z)) \stackrel{\text{def}}{=} (x \triangleright y) \triangleright z$$

for each $x \triangleright (y \triangleright z) \in X \triangleright (Y \triangleright Z)$.

REMARK 4.4.4 ► NON-INVERTIBILITY OF THE SKEW ASSOCIATOR OF \triangleright

Taking $y = y_0$, we see that the morphism $\alpha_{X,Y,Z}^{\text{Sets}_*, \triangleright}$ acts on elements as

$$\alpha_{X,Y,Z}^{\text{Sets}_*, \triangleright} (x \triangleright (y_0 \triangleright z)) \stackrel{\text{def}}{=} (x \triangleright y_0) \triangleright z.$$

However, by the definition of \triangleright , we have $x \triangleright y_0 = x' \triangleright y_0$ for all $x, x' \in X$, preventing $\alpha_{X,Y,Z}^{\text{Sets}_*, \triangleright}$ from being non-invertible.

PROOF 4.4.5 ► PROOF OF DEFINITION 4.4.1

Firstly, note that, given $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\text{Sets}_*)$, the map

$$\alpha_{X,Y,Z}^{\text{Sets}_*, \triangleright} : X \triangleright (Y \triangleright Z) \rightarrow (X \triangleright Y) \triangleright Z$$

is indeed a morphism of pointed sets, as we have

$$\alpha_{X,Y,Z}^{\text{Sets}_*, \triangleright} (x_0 \triangleright (y_0 \triangleright z_0)) = (x_0 \triangleright y_0) \triangleright z_0.$$

Next, we claim that $\alpha^{\text{Sets}_*, \triangleright}$ is a natural transformation. We need to show that, given morphisms of pointed sets

$$f: (X, x_0) \rightarrow (X', x'_0),$$

$$g: (Y, y_0) \rightarrow (Y', y'_0),$$


$$h: (Z, z_0) \rightarrow (Z', z'_0)$$

the diagram

$$\begin{array}{ccc} X \triangleright (Y \triangleright Z) & \xrightarrow{f \triangleright (g \triangleright h)} & X' \triangleright (Y' \triangleright Z') \\ \alpha_{X,Y,Z}^{\text{Sets}_*, \triangleright} \downarrow & & \downarrow \alpha_{X',Y',Z'}^{\text{Sets}_*, \triangleright} \\ (X \triangleright Y) \triangleright Z & \xrightarrow{(f \triangleright g) \triangleright h} & (X' \triangleright Y') \triangleright Z' \end{array}$$

commutes. Indeed, this diagram acts on elements as

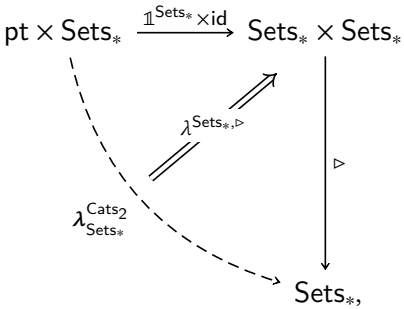
$$\begin{array}{ccc} x \triangleright (y \triangleright z) & \longmapsto & f(x) \triangleright (g(y) \triangleright h(z)) \\ \downarrow & & \downarrow \\ (x \triangleright y) \triangleright z & \longmapsto & (f(x) \triangleright g(y)) \triangleright h(z) \end{array}$$

and hence indeed commutes, showing $\alpha^{\text{Sets}_*, \triangleright}$ to be a natural transformation. This finishes the proof. 

4.5 The Right Skew Left Unitor

DEFINITION 4.5.1 ► THE RIGHT SKEW LEFT UNITOR OF \triangleright

The **skew left unitor of the right tensor product of pointed sets** is the natural transformation

$$\lambda^{\text{Sets}_*, \triangleright} : \lambda_{\text{Sets}_*}^{\text{Cats}_2} \xrightarrow{\sim} \triangleright \circ (\mathbb{1}_{\text{Sets}_*} \times \text{id}_{\text{Sets}_*})$$


whose component

$$\lambda_X^{\text{Sets}_*, \triangleright} : X \rightarrow S^0 \triangleright X$$

at $(X, x_0) \in \text{Obj}(\text{Sets}_*)$ is given by the composition

$$\begin{aligned} X &\rightarrow X \vee X \\ &\cong |S^0| \odot X \\ &\cong S^0 \triangleright X, \end{aligned}$$

where $X \rightarrow X \vee X$ is the map sending X to the second factor of X in $X \vee X$.

PROOF 4.5.2 ► PROOF OF DEFINITION 4.5.1

(Proven below in a bit.)

**REMARK 4.5.3 ► UNWINDING DEFINITION 4.5.1**

In other words, $\lambda_X^{\text{Sets}_*, \triangleright}$ acts on elements as

$$\lambda_X^{\text{Sets}_*, \triangleright}(x) \stackrel{\text{def}}{=} [(1, x)]$$

i.e. by

$$\lambda_X^{\text{Sets}_*, \triangleright}(x) \stackrel{\text{def}}{=} 1 \triangleright x$$

for each $x \in X$.

REMARK 4.5.4 ► NON-INVERTIBILITY OF THE SKEW LEFT UNITOR OF \triangleright

The morphism $\lambda_X^{\text{Sets}_*, \triangleright}$ is non-invertible, as it is non-surjective when viewed as a map of sets, since the elements $0 \triangleright x$ of $S^0 \triangleright X$ with $x \neq x_0$ are outside the image of $\lambda_X^{\text{Sets}_*, \triangleright}$, which sends x to $1 \triangleright x$.

PROOF 4.5.5 ► PROOF OF DEFINITION 4.5.1

Firstly, note that, given $(X, x_0) \in \text{Obj}(\text{Sets}_*)$, the map

$$\lambda_X^{\text{Sets}_*, \triangleright} : X \rightarrow S^0 \triangleright X$$

is indeed a morphism of pointed sets, as we have

$$\begin{aligned} \lambda_X^{\text{Sets}_*, \triangleright}(x_0) &= 1 \triangleright x_0 \\ &= 0 \triangleright x_0. \end{aligned}$$

Next, we claim that $\lambda^{\text{Sets}_*, \triangleright}$ is a natural transformation. We need to show that, given a morphism of pointed sets


$$f : (X, x_0) \rightarrow (Y, y_0),$$

the diagram

$$\begin{array}{ccc}
 X & \xrightarrow{f} & Y \\
 \lambda_X^{\text{Sets}_*, \triangleright} \downarrow & & \downarrow \lambda_Y^{\text{Sets}_*, \triangleright} \\
 S^0 \triangleright X & \xrightarrow{\text{id}_{S^0} \triangleright f} & S^0 \triangleright Y
 \end{array}$$

commutes. Indeed, this diagram acts on elements as

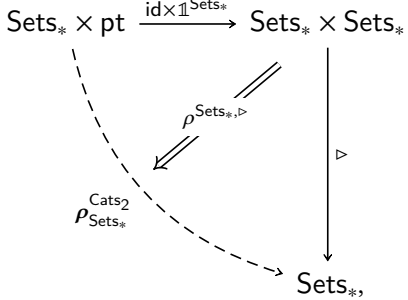
$$\begin{array}{ccc}
 x & \mapsto & f(x) \\
 \downarrow & & \downarrow \\
 1 \triangleright x & \mapsto & 1 \triangleright f(x)
 \end{array}$$

and hence indeed commutes, showing $\lambda^{\text{Sets}_*, \triangleright}$ to be a natural transformation. This finishes the proof. 

4.6 The Right Skew Right Unitor

DEFINITION 4.6.1 ► THE RIGHT SKEW RIGHT UNITOR OF \triangleright

The **skew right unitor of the right tensor product of pointed sets** is the natural transformation

$$\rho^{\text{Sets}_*, \triangleright} : \triangleright \circ (\text{id} \times \mathbb{1}^{\text{Sets}_*}) \xrightarrow{\sim} \rho_{\text{Sets}_*}^{\text{Cats}_2},$$


whose component

$$\rho_X^{\text{Sets}_*, \triangleright} : X \triangleright S^0 \rightarrow X$$

at $(X, x_0) \in \text{Obj}(\text{Sets}_*)$ is given by the composition

$$\begin{aligned} X \triangleright S^0 &\cong |X| \odot S^0 \\ &\cong \bigvee_{x \in X} S^0 \\ &\rightarrow X, \end{aligned}$$

where $\bigvee_{x \in X} S^0 \rightarrow X$ is the map given by

$$\begin{aligned} [(x, 0)] &\mapsto x_0, \\ [(x, 1)] &\mapsto x. \end{aligned}$$

PROOF 4.6.2 ► PROOF OF DEFINITION 4.6.1

(Proven below in a bit.)



REMARK 4.6.3 ► UNWINDING DEFINITION 4.6.1

In other words, $\rho_X^{\text{Sets}_*, \triangleright}$ acts on elements as

$$\begin{aligned} \rho_X^{\text{Sets}_*, \triangleright}(x \triangleright 0) &\stackrel{\text{def}}{=} x_0, \\ \rho_X^{\text{Sets}_*, \triangleright}(x \triangleright 1) &\stackrel{\text{def}}{=} x \end{aligned}$$

for each $x \triangleright 1 \in X \triangleright S^0$.

REMARK 4.6.4 ► NON-INVERTIBILITY OF THE SKEW RIGHT UNITOR OF \triangleright

The morphism $\rho_X^{\text{Sets}_*, \triangleright}$ is almost invertible, with its would-be-inverse

$$\phi_X: X \rightarrow X \triangleright S^0$$

given by

$$\phi_X(x) \stackrel{\text{def}}{=} x \triangleright 1$$

for each $x \in X$. Indeed, we have

$$\begin{aligned} [\rho_X^{\text{Sets}_*, \triangleright} \circ \phi](x) &= \rho_X^{\text{Sets}_*, \triangleright}(\phi(x)) \\ &= \rho_X^{\text{Sets}_*, \triangleright}(x \triangleright 1) \\ &= x \\ &= [\text{id}_X](x) \end{aligned}$$

so that

$$\rho_X^{\text{Sets}_*, \triangleright} \circ \phi = \text{id}_X$$

and

$$\begin{aligned} [\phi \circ \rho_X^{\text{Sets}_*, \triangleright}](x \triangleright 1) &= \phi(\rho_X^{\text{Sets}_*, \triangleright}(x \triangleright 1)) \\ &= \phi(x) \\ &= x \triangleright 1 \\ &= [\text{id}_{X \triangleright S^0}](x \triangleright 1), \end{aligned}$$

but

$$\begin{aligned} [\phi \circ \rho_X^{\text{Sets}_*, \triangleright}](x \triangleright 0) &= \phi(\rho_X^{\text{Sets}_*, \triangleright}(x \triangleright 0)) \\ &= \phi(x_0) \\ &= 1 \triangleright x_0, \end{aligned}$$

where $x \triangleright 0 \neq 1 \triangleright x_0$. Thus

$$\phi \circ \rho_X^{\text{Sets}_*, \triangleright} \stackrel{?}{=} \text{id}_{X \triangleright S^0}$$

holds for all elements in $X \triangleright S^0$ except one.

PROOF 4.6.5 ► PROOF OF DEFINITION 4.6.1

Firstly, note that, given $(X, x_0) \in \text{Obj}(\text{Sets}_*)$, the map

$$\rho_X^{\text{Sets}_*, \triangleright} : X \triangleright S^0 \rightarrow X$$

is indeed a morphism of pointed sets as we have

$$\rho_X^{\text{Sets}_*, \triangleright}(x_0 \triangleright 0) = x_0.$$

Next, we claim that $\rho^{\text{Sets}_*, \triangleright}$ is a natural transformation. We need to show that, given a morphism of pointed sets

$$f: (X, x_0) \rightarrow (Y, y_0),$$

the diagram


$$\begin{array}{ccc} X \triangleright S^0 & \xrightarrow{f \triangleright \text{id}_{S^0}} & Y \triangleright S^0 \\ \rho_X^{\text{Sets}_*, \triangleright} \downarrow & & \downarrow \rho_Y^{\text{Sets}_*, \triangleright} \\ X & \xrightarrow{f} & Y \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc} x \triangleright 0 & & x \triangleright 0 \mapsto f(x) \triangleright 0 \\ \downarrow & & \downarrow \\ x_0 \mapsto f(x_0) & & y_0 \end{array}$$

and

$$\begin{array}{ccc} x \triangleright 1 \mapsto f(x) \triangleright 1 & & \\ \downarrow & & \downarrow \\ x \mapsto f(x) & & \end{array}$$

and hence indeed commutes, showing $\rho^{\text{Sets}_*, \triangleright}$ to be a natural transformation. This finishes the proof. 

4.7 The Diagonal

DEFINITION 4.7.1 ► THE DIAGONAL OF \triangleright

The **diagonal of the right tensor product of pointed sets** is the natural transformation

$$\Delta^{\triangleright} : \text{id}_{\text{Sets}_*} \Rightarrow \triangleright \circ \Delta_{\text{Sets}_*}^{\text{Cats}_2}$$

whose component

$$\Delta_X^{\triangleright} : (X, x_0) \rightarrow (X \triangleright X, x_0 \triangleright x_0)$$

at $(X, x_0) \in \text{Obj}(\text{Sets}_*)$ is given by

$$\Delta_X^{\triangleright}(x) \stackrel{\text{def}}{=} x \triangleright x$$

for each $x \in X$.

PROOF 4.7.2 ► PROOF OF DEFINITION 4.7.1

Being a Morphism of Pointed Sets

We have

$$\Delta_X^{\triangleright}(x_0) \stackrel{\text{def}}{=} x_0 \triangleright x_0,$$

and thus $\Delta_X^{\triangleright}$ is a morphism of pointed sets.

Naturality

We need to show that, given a morphism of pointed sets


$$f : (X, x_0) \rightarrow (Y, y_0),$$

the diagram

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ \Delta_X^\triangleright \downarrow & & \downarrow \Delta_Y^\triangleright \\ X \triangleright X & \xrightarrow{f \triangleright f} & Y \triangleright Y \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc} x & \longmapsto & f(x) \\ \downarrow & & \downarrow \\ x \triangleright x & \longmapsto & f(x) \triangleright f(x) \end{array}$$

and hence indeed commutes, showing Δ^\triangleright to be natural. 

4.8 The Right Skew Monoidal Structure on Pointed Sets Associated to \triangleright

PROPOSITION 4.8.1 \blacktriangleright THE RIGHT SKEW MONOIDAL STRUCTURE ON POINTED SETS ASSOCIATED TO \triangleright

The category \mathbf{Sets}_* admits a right-closed right skew monoidal category structure consisting of

- *The Underlying Category.* The category \mathbf{Sets}_* of pointed sets;
- *The Right Skew Monoidal Product.* The right tensor product functor

$$\triangleright : \mathbf{Sets}_* \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$

of Definition 4.1.1;

- *The Right Internal Skew Hom.* The right internal Hom functor

$$[-, -]_{\mathbf{Sets}_*}^\triangleright : \mathbf{Sets}_*^{\text{op}} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$

of Definition 4.2.1;

- *The Right Skew Monoidal Unit.* The functor

$$\mathbb{1}^{\text{Sets}_*, \triangleright} : \text{pt} \rightarrow \text{Sets}_*$$

of **Definition 4.3.1**;

- *The Right Skew Associators.* The natural transformation

$$\alpha^{\text{Sets}_*, \triangleright} : \triangleright \circ (\text{id}_{\text{Sets}_*} \times \triangleright) \Rightarrow \triangleright \circ (\triangleright \times \text{id}_{\text{Sets}_*}) \circ \alpha_{\text{Sets}_*, \text{Sets}_*, \text{Sets}_*}^{\text{Cats}, -1}$$

of **Definition 4.4.1**;

- *The Right Skew Left Unitors.* The natural transformation

$$\lambda^{\text{Sets}_*, \triangleright} : \lambda_{\text{Sets}_*}^{\text{Cats}_2} \xrightarrow{\sim} \triangleright \circ (\mathbb{1}^{\text{Sets}_*} \times \text{id}_{\text{Sets}_*})$$

of **Definition 4.5.1**;

- *The Right Skew Right Unitors.* The natural transformation

$$\rho^{\text{Sets}_*, \triangleright} : \triangleright \circ (\text{id} \times \mathbb{1}^{\text{Sets}_*}) \xrightarrow{\sim} \rho_{\text{Sets}_*}^{\text{Cats}_2}$$

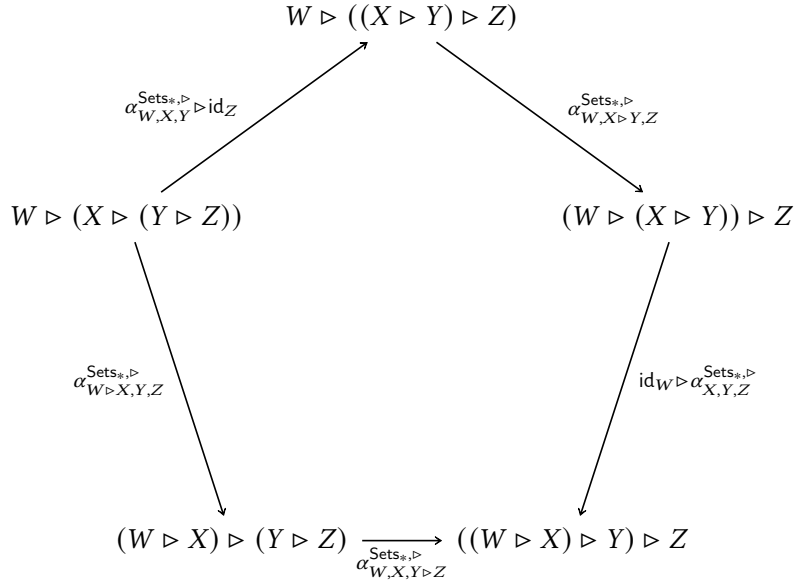
of **Definition 4.6.1**.

PROOF 4.8.2 ► PROOF OF PROPOSITION 4.8.1

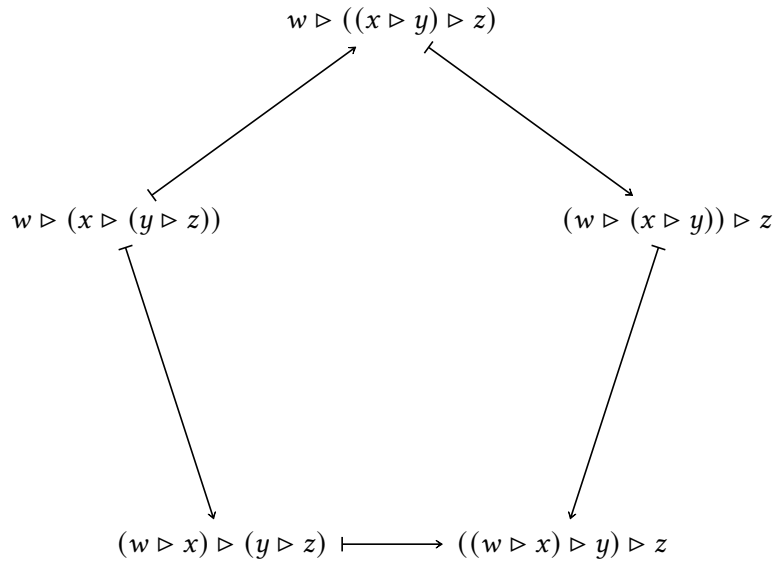
The Pentagon Identity

Let (W, w_0) , (X, x_0) , (Y, y_0) and (Z, z_0) be pointed sets. We have to show that

the diagram



commutes. Indeed, this diagram acts on elements as



and thus we see that the pentagon identity is satisfied.

The Right Skew Left Triangle Identity

Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram

$$\begin{array}{ccc}
 X \triangleright Y & & \\
 \lambda_{X \triangleright Y}^{\text{Sets}_*, \triangleright} \downarrow & \searrow \lambda_X^{\text{Sets}_*, \triangleright} \triangleright \text{id}_Y & \\
 S^0 \triangleright (X \triangleright Y) & \xrightarrow{\alpha_{S^0, X, Y}^{\text{Sets}_*, \triangleright}} & (S^0 \triangleright X) \triangleright Y
 \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
 x \triangleright y & & \\
 \downarrow & \searrow & \\
 1 \triangleright (x \triangleright y) & \mapsto & (1 \triangleright x) \triangleright y
 \end{array}$$

and hence indeed commutes. Thus the left skew triangle identity is satisfied.

The Right Skew Right Triangle Identity

Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram

$$\begin{array}{ccc}
 X \triangleright (Y \triangleright S^0) & \xrightarrow{\text{id}_X \triangleright \rho_Y^{\text{Sets}_*, \triangleright}} & (X \triangleright Y) \triangleright S^0 \\
 & \searrow \alpha_{S^0, X, Y}^{\text{Sets}_*, \triangleright} & \downarrow \rho_{X \triangleright Y}^{\text{Sets}_*, \triangleright} \\
 & & X \triangleright Y
 \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
 x \triangleright (y \triangleright 0) & \mapsto & (x \triangleright y) \triangleright 0 \\
 & \searrow & \downarrow \\
 & & x \triangleright y_0 = x_0 \triangleright y_0
 \end{array}$$

and

$$\begin{array}{ccc}
 x \triangleright (y \triangleright 1) & \mapsto & (x \triangleright y) \triangleright 1 \\
 & \searrow & \downarrow \\
 & & x \triangleright y
 \end{array}$$

and hence indeed commutes. Thus the right skew triangle identity is satisfied.

The Right Skew Middle Triangle Identity

Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram

$$\begin{array}{ccc}
 X \triangleright Y & \xlongequal{\quad} & X \triangleright Y \\
 \text{id}_X \triangleright \lambda_Y^{\text{Sets}_*, \triangleright} \downarrow & & \uparrow \rho_X^{\text{Sets}_*, \triangleright} \triangleright \text{id}_Y \\
 X \triangleright (S^0 \triangleright Y) & \xrightarrow[\alpha_{X, S^0, Y}^{\text{Sets}_*, \triangleright}]{} & (X \triangleright S^0) \triangleright Y
 \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
 x \triangleright y & \xrightarrow{\quad} & x \triangleright y \\
 \downarrow & & \uparrow \\
 x \triangleright (1 \triangleright y) & \xrightarrow{\quad} & (x \triangleright 1) \triangleright y
 \end{array}$$

and hence indeed commutes. Thus the right skew triangle identity is satisfied.

The Zig-Zag Identity

We have to show that the diagram

$$\begin{array}{ccc}
 S^0 & \xrightarrow{\lambda_{S^0}^{\text{Sets}_*, \triangleright}} & S^0 \triangleright S^0 \\
 \searrow & & \downarrow \rho_{S^0}^{\text{Sets}_*, \triangleright} \\
 & & S^0
 \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc} 0 & \xrightarrow{\quad} & 1 \triangleright 0 \\ & \searrow & \downarrow \\ & & 0 \end{array}$$

and

$$\begin{array}{ccc} 1 & \xrightarrow{\quad} & 1 \triangleright 1 \\ & \searrow & \downarrow \\ & & 1 \end{array}$$

and hence indeed commutes. Thus the zig-zag identity is satisfied.

Right Skew Monoidal Right-Closedness

This follows from [Item 2](#) of [Proposition 4.1.7](#).



4.9 Monoids With Respect to the Right Tensor Product of Pointed Sets

PROPOSITION 4.9.1 ► MONOIDS WITH RESPECT TO \triangleright

The category of monoids on $(\text{Sets}_*, \triangleright, S^0)$ is isomorphic to the category of “monoids with right zero”¹ and morphisms between them.

¹A monoid with right zero is defined similarly as the monoids with zero of ???. Succinctly, they are monoids (A, μ_A, η_A) with a special element 0_A satisfying

$$0_A a = 0_A$$

for each $a \in A$.

PROOF 4.9.2 ► PROOF OF PROPOSITION 4.9.1

Monoids on $(\text{Sets}_*, \triangleright, S^0)$

A monoid on $(\text{Sets}_*, \triangleright, S^0)$ consists of:

- *The Underlying Object.* A pointed set $(A, 0_A)$.

- *The Multiplication Morphism.* A morphism of pointed sets

$$\mu_A: A \triangleright A \rightarrow A,$$

determining a right bilinear morphism of pointed sets

$$\begin{aligned} A \times A &\longrightarrow A \\ (a, b) &\longmapsto ab. \end{aligned}$$

- *The Unit Morphism.* A morphism of pointed sets

$$\eta_A: S^0 \rightarrow A$$

picking an element 1_A of A .

satisfying the following conditions:

1. *Associativity.* The diagram

$$\begin{array}{ccccc} & & A \triangleright (A \triangleright A) & & \\ & \nearrow \alpha_{A,A,A}^{\text{Sets}, \triangleright} & & \searrow \text{id}_A \triangleright \mu_A & \\ (A \triangleright A) \triangleright A & & & & A \triangleright A \\ & \searrow \mu_A \triangleright \text{id}_A & & \nearrow \mu_A & \\ & A \triangleright A & \xrightarrow{\mu_A} & A & \end{array}$$

2. *Left Unitality.* The diagram

$$\begin{array}{ccc} A & \xrightarrow{\lambda_A^{\text{Sets}, \triangleright}} & S^0 \triangleright A \\ \parallel & & \downarrow \eta_A \times \text{id}_A \\ A & \xleftarrow{\mu_A} & A \triangleright A \end{array}$$

commutes.

3. *Right Unitality.* The diagram

$$\begin{array}{ccc}
 A \triangleright S^0 & \xrightarrow{\text{id}_A \times \eta_A} & A \triangleright A \\
 \searrow \rho_A^{\text{Sets}_*, \triangleright} & & \downarrow \mu_A \\
 & & A
 \end{array}$$

commutes.

Being a right-bilinear morphism of pointed sets, the multiplication map satisfies

$$0_A a = 0_A$$

for each $a \in A$. Now, the associativity, left unitality, and right unitality conditions act on elements as follows:

1. *Associativity.* The associativity condition acts as

$$\begin{array}{ccc}
 & & a \triangleright (b \triangleright c) \\
 & \swarrow & \searrow \\
 (a \triangleright b) \triangleright c & & (a \triangleright b) \triangleright c \\
 \downarrow & & \downarrow \\
 ab \triangleright c & \xrightarrow{\quad} & (ab)c
 \end{array}
 \qquad
 \begin{array}{ccc}
 & & a \triangleright (b \triangleright c) \\
 & \swarrow & \searrow \\
 (a \triangleright b) \triangleright c & & a \triangleright bc \\
 \downarrow & & \downarrow \\
 & & a(bc)
 \end{array}$$

This gives

$$(ab)c = a(bc)$$

for each $a, b, c \in A$.

2. *Left Unitality.* The left unitality condition acts as

$$\begin{array}{ccc}
 a & \xrightarrow{\quad} & 1 \triangleright a \\
 \downarrow & & \downarrow \\
 a & & 1_A a \longleftarrow 1_A \triangleright a
 \end{array}$$

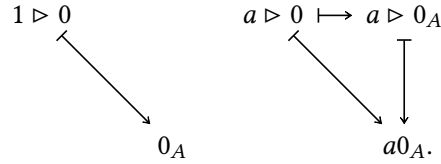
This gives

$$1_A a = a$$

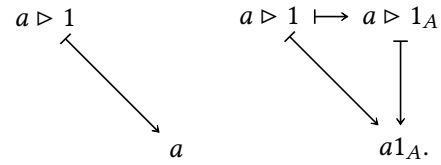
for each $a \in A$.

3. *Right Unitality.* The right unitality condition acts:

(a) On $1 \triangleright 0$ as



(b) On $a \triangleright 1$ as



This gives

$$\begin{aligned}
 a1_A &= a, \\
 a0_A &= 0_A
 \end{aligned}$$

for each $a \in A$.

Thus we see that monoids with respect to \triangleright are exactly monoids with right zero.

Morphisms of Monoids on $(\text{Sets}_*, \triangleright, S^0)$

A morphism of monoids on $(\text{Sets}_*, \triangleright, S^0)$ from $(A, \mu_A, \eta_A, 0_A)$ to $(B, \mu_B, \eta_B, 0_B)$ is a morphism of pointed sets

$$f: (A, 0_A) \rightarrow (B, 0_B)$$

satisfying the following conditions:

1. *Compatibility With the Multiplication Morphisms.* The diagram

$$\begin{array}{ccc}
 A \triangleright A & \xrightarrow{f \triangleright f} & B \triangleright B \\
 \mu_A \downarrow & & \downarrow \mu_B \\
 A & \xrightarrow{f} & B
 \end{array}$$

commutes.

2. *Compatibility With the Unit Morphisms.* The diagram

$$\begin{array}{ccc} S^0 & \xrightarrow{\eta_A} & A \\ & \searrow \eta_B & \downarrow f \\ & & B \end{array}$$

commutes.

These act on elements as

$$\begin{array}{ccc} a \triangleright b & & a \triangleright b \mapsto f(a) \triangleright f(b) \\ \downarrow & & \downarrow \\ ab \mapsto f(ab) & & f(a)f(b) \end{array}$$

and

$$\begin{array}{ccc} 0 & \mapsto & 0_A \\ & \searrow & \downarrow \\ & & f(0_A) \end{array}$$

and

$$\begin{array}{ccc} 1 & \mapsto & 1_A \\ & \searrow & \downarrow \\ & & f(1_A) \end{array}$$

giving


$$f(ab) = f(a)f(b),$$

$$f(0_A) = 0_B,$$

$$f(1_A) = 1_B,$$

for each $a, b \in A$, which is exactly a morphism of monoids with right zero.

Identities and Composition

Similarly, the identities and composition of $\text{Mon}(\text{Sets}_*, \triangleright, S^0)$ can be easily seen to agree with those of monoids with right zero, which finishes the proof. 

5 The Smash Product of Pointed Sets

5.1 Foundations

Let (X, x_0) and (Y, y_0) be pointed sets.

DEFINITION 5.1.1 ► SMASH PRODUCTS OF POINTED SETS

The **smash product** of (X, x_0) and (Y, y_0) ¹ is the pointed set $X \wedge Y$ ² satisfying the bijection

$$\text{Sets}_*(X \wedge Y, Z) \cong \text{Hom}_{\text{Sets}_*}^{\otimes}(X \times Y, Z),$$

naturally in $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\text{Sets}_*)$.

¹*Further Terminology:* In the context of monoids with zero as models for \mathbb{F}_1 -algebras, the smash product $X \wedge Y$ is also called the **tensor product of \mathbb{F}_1 -modules of (X, x_0) and (Y, y_0)** or the **tensor product of (X, x_0) and (Y, y_0) over \mathbb{F}_1** .

²*Further Notation:* In the context of monoids with zero as models for \mathbb{F}_1 -algebras, the smash product $X \wedge Y$ is also denoted $X \otimes_{\mathbb{F}_1} Y$.

REMARK 5.1.2 ► UNWINDING DEFINITION 5.1.1: THE UNIVERSAL PROPERTY I

That is to say, the smash product of pointed sets is defined so as to induce a bijection between the following data:

- Pointed maps $f: X \wedge Y \rightarrow Z$.
- Maps of sets $f: X \times Y \rightarrow Z$ satisfying

$$\begin{aligned} f(x_0, y) &= z_0, \\ f(x, y_0) &= z_0 \end{aligned}$$

for each $x \in X$ and each $y \in Y$.

REMARK 5.1.3 ► UNWINDING DEFINITION 5.1.1: THE UNIVERSAL PROPERTY II

The smash product of pointed sets may be described as follows:

- The smash product of (X, x_0) and (Y, y_0) is the pair $((X \wedge Y, x_0 \wedge y_0), \iota)$ consisting of
 - A pointed set $(X \wedge Y, x_0 \wedge y_0)$;

– A bilinear morphism of pointed sets $\iota: (X \times Y, (x_0, y_0)) \rightarrow X \wedge Y$;

satisfying the following universal property:

(UP) Given another such pair $((Z, z_0), f)$ consisting of

- * A pointed set (Z, z_0) ;
- * A bilinear morphism of pointed sets $f: (X \times Y, (x_0, y_0)) \rightarrow X \wedge Y$;

there exists a unique morphism of pointed sets $X \wedge Y \xrightarrow{\exists!} Z$ making the diagram

$$\begin{array}{ccc} & & X \wedge Y \\ & \nearrow \iota & \downarrow \exists! \\ X \times Y & \xrightarrow{f} & Z \end{array}$$

commute.

CONSTRUCTION 5.1.4 ► SMASH PRODUCTS OF POINTED SETS

Concretely, the **smash product** of (X, x_0) and (Y, y_0) is the pointed set $(X \wedge Y, x_0 \wedge y_0)$ consisting of

- *The Underlying Set.* The set $X \wedge Y$ defined by

$$X \wedge Y \cong (X \times Y) / \sim_R,$$

where \sim_R is the equivalence relation on $X \times Y$ obtained by declaring

$$(x_0, y) \sim_R (x_0, y'),$$

$$(x, y_0) \sim_R (x', y_0)$$

for each $x, x' \in X$ and each $y, y' \in Y$;

- *The Basepoint.* The element $[(x_0, y_0)]$ of $X \wedge Y$ given by the equivalence class of (x_0, y_0) under the equivalence relation \sim on $X \times Y$.

PROOF 5.1.5 ► PROOF OF CONSTRUCTION 5.1.4

By **Equivalence Relations and Apartness Relations**, Item 6 of **Proposition 5.2.3**, we have a natural bijection

$$\mathbf{Sets}_*(X \wedge Y, Z) \cong \mathbf{Hom}_{\mathbf{Sets}}^R(X \times Y, Z).$$

Now, by definition, $\mathbf{Hom}_{\mathbf{Sets}}^R(X \times Y, Z)$ is the set

$$\mathbf{Hom}_{\mathbf{Sets}}^R(X \times Y, Z) \stackrel{\text{def}}{=} \left\{ f \in \mathbf{Hom}_{\mathbf{Sets}}(X \times Y, Z) \left| \begin{array}{l} \text{for each } x, y \in X, \text{ if} \\ (x, y) \sim_R (x', y'), \text{ then} \\ f(x, y) = f(x', y') \end{array} \right. \right\}.$$

However, the condition $(x, y) \sim_R (x', y')$ only holds when:

1. We have $x = x'$ and $y = y'$.
2. The following conditions are satisfied:
 - (a) We have $x = x_0$ or $y = y_0$.
 - (b) We have $x' = x_0$ or $y' = y_0$.

So, given $f \in \mathbf{Hom}_{\mathbf{Sets}}(X \times Y, Z)$ with a corresponding $\bar{f}: X \wedge Y \rightarrow Z$, the latter case above implies

$$\begin{aligned} f(x_0, y) &= f(x, y_0) \\ &= f(x_0, y_0), \end{aligned}$$

and since $\bar{f}: X \wedge Y \rightarrow Z$ is a pointed map, we have

$$\begin{aligned} f(x_0, y_0) &= \bar{f}(x_0, y_0) \\ &= z_0. \end{aligned}$$

Thus the elements f in $\mathbf{Hom}_{\mathbf{Sets}}(X \times Y, Z)$ are precisely those functions $f: X \times Y \rightarrow Z$ satisfying the equalities


$$\begin{aligned} f(x_0, y) &= z_0, \\ f(x, y_0) &= z_0 \end{aligned}$$

for each $x \in X$ and each $y \in Y$, giving an equality

$$\mathrm{Hom}_{\mathrm{Sets}}^R(X \times Y, Z) = \mathrm{Hom}_{\mathrm{Sets}_*}^{\otimes}(X \times Y, Z)$$

of sets, which when composed with our earlier isomorphism

$$\mathrm{Sets}_*(X \wedge Y, Z) \cong \mathrm{Hom}_{\mathrm{Sets}}^R(X \times Y, Z)$$

gives our desired natural bijection, finishing the proof. 

REMARK 5.1.6 ► ON THE CONSTRUCTION OF THE SMASH PRODUCT OF POINTED SETS

It is also somewhat common to write

$$X \wedge Y \stackrel{\mathrm{def}}{=} \frac{X \times Y}{X \vee Y},$$

identifying $X \vee Y$ with the subspace $(\{x_0\} \times Y) \cup (X \times \{y_0\})$ of $X \times Y$, and having the quotient be defined by declaring $(x, y) \sim (x', y')$ iff we have $(x, y), (x', y') \in X \vee Y$.

NOTATION 5.1.7 ► ELEMENTS OF SMASH PRODUCTS OF POINTED SETS

We write $x \wedge y$ for the element $[(x, y)]$ of

$$X \wedge Y \cong X \times Y / \sim.$$

REMARK 5.1.8 ► BASEPOINTS OF SMASH PRODUCTS OF POINTED SETS

Employing the notation introduced in [Notation 5.1.7](#), we have

$$\begin{aligned} x_0 \wedge y_0 &= x \wedge y_0, \\ &= x_0 \wedge y \end{aligned}$$

for each $x \in X$ and each $y \in Y$, and

$$\begin{aligned} x \wedge y_0 &= x' \wedge y_0, \\ x_0 \wedge y &= x_0 \wedge y' \end{aligned}$$

for each $x, x' \in X$ and each $y, y' \in Y$.

EXAMPLE 5.1.9 ► EXAMPLES OF SMASH PRODUCTS OF POINTED SETS

Here are some examples of smash products of pointed sets.

1. *Smashing With pt.* For any pointed set X , we have isomorphisms of pointed sets

$$\begin{aligned} \text{pt} \wedge X &\cong \text{pt}, \\ X \wedge \text{pt} &\cong \text{pt}. \end{aligned}$$

2. *Smashing With S^0 .* For any pointed set X , we have isomorphisms of pointed sets

$$\begin{aligned} S^0 \wedge X &\cong X, \\ X \wedge S^0 &\cong X. \end{aligned}$$

PROPOSITION 5.1.10 ► PROPERTIES OF SMASH PRODUCTS OF POINTED SETS

Let (X, x_0) and (Y, y_0) be pointed sets.

1. *Functoriality.* The assignments $X, Y, (X, Y) \mapsto X \wedge Y$ define functors

$$\begin{aligned} X \wedge - &: \text{Sets}_* \rightarrow \text{Sets}_*, \\ - \wedge Y &: \text{Sets}_* \rightarrow \text{Sets}_*, \\ -_1 \wedge -_2 &: \text{Sets}_* \times \text{Sets}_* \rightarrow \text{Sets}_*. \end{aligned}$$

In particular, given pointed maps

$$\begin{aligned} f &: (X, x_0) \rightarrow (A, a_0), \\ g &: (Y, y_0) \rightarrow (B, b_0), \end{aligned}$$

the induced map

$$f \wedge g: X \wedge Y \rightarrow A \wedge B$$

is given by

$$[f \wedge g](x \wedge y) \stackrel{\text{def}}{=} f(x) \wedge g(y)$$

for each $x \wedge y \in X \wedge Y$.

2. *Adjointness.* We have adjunctions

$$(X \wedge - \dashv \mathbf{Sets}_*(X, -)) : \mathbf{Sets}_* \begin{array}{c} \xrightarrow{X \wedge -} \\ \perp \\ \xleftarrow{\mathbf{Sets}_*(X, -)} \end{array} \mathbf{Sets}_*,$$

$$(- \wedge Y \dashv \mathbf{Sets}_*(Y, -)) : \mathbf{Sets}_* \begin{array}{c} \xrightarrow{- \wedge Y} \\ \perp \\ \xleftarrow{\mathbf{Sets}_*(Y, -)} \end{array} \mathbf{Sets}_*,$$

witnessed by bijections

$$\mathrm{Hom}_{\mathbf{Sets}_*}(X \wedge Y, Z) \cong \mathrm{Hom}_{\mathbf{Sets}_*}(X, \mathbf{Sets}_*(Y, Z)),$$

$$\mathrm{Hom}_{\mathbf{Sets}_*}(X \wedge Y, Z) \cong \mathrm{Hom}_{\mathbf{Sets}_*}(X, \mathbf{Sets}_*(A, Z)),$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \mathrm{Obj}(\mathbf{Sets}_*)$.

3. *Enriched Adjointness.* We have \mathbf{Sets}_* -enriched adjunctions

$$(X \wedge - \dashv \mathbf{Sets}_*(X, -)) : \mathbf{Sets}_* \begin{array}{c} \xrightarrow{X \wedge -} \\ \perp \\ \xleftarrow{\mathbf{Sets}_*(X, -)} \end{array} \mathbf{Sets}_*,$$

$$(- \wedge Y \dashv \mathbf{Sets}_*(Y, -)) : \mathbf{Sets}_* \begin{array}{c} \xrightarrow{- \wedge Y} \\ \perp \\ \xleftarrow{\mathbf{Sets}_*(Y, -)} \end{array} \mathbf{Sets}_*,$$

witnessed by isomorphisms of pointed sets

$$\mathbf{Sets}_*(X \wedge Y, Z) \cong \mathbf{Sets}_*(X, \mathbf{Sets}_*(Y, Z)),$$

$$\mathbf{Sets}_*(X \wedge Y, Z) \cong \mathbf{Sets}_*(X, \mathbf{Sets}_*(A, Z)),$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \mathrm{Obj}(\mathbf{Sets}_*)$.

4. *As a Pushout.* We have an isomorphism

$$X \wedge Y \cong \mathrm{pt} \coprod_{X \vee Y} (X \times Y),$$

$$\begin{array}{ccc} X \wedge Y & \longleftarrow & X \times Y \\ \uparrow \ulcorner & & \uparrow \iota \\ \mathrm{pt} & \longleftarrow & X \vee Y \end{array}$$

natural in $X, Y \in \mathrm{Obj}(\mathbf{Sets}_*)$, where the pushout is taken in \mathbf{Sets} , and the embedding $\iota: X \vee Y \hookrightarrow X \times Y$ is defined following [Remark 5.1.6](#).

5. *Distributivity Over Wedge Sums.* We have isomorphisms of pointed sets

$$X \wedge (Y \vee Z) \cong (X \wedge Y) \vee (X \wedge Z),$$

$$(X \vee Y) \wedge Z \cong (X \wedge Z) \vee (Y \wedge Z),$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\text{Sets}_*)$.

PROOF 5.1.11 ► PROOF OF PROPOSITION 5.1.10

Item 1: Functoriality

The map $f \wedge g$ comes from [Equivalence Relations and Apartness Relations](#), Item 4 of [Proposition 5.2.3](#) via the map

$$f \wedge g: X \times Y \rightarrow A \wedge B$$

sending (x, y) to $f(x) \wedge g(y)$, which we need to show satisfies

$$[f \wedge g](x, y) = [f \wedge g](x', y')$$

for each $(x, y), (x', y') \in X \times Y$ with $(x, y) \sim_R (x', y')$, where \sim_R is the relation constructing $X \wedge Y$ as

$$X \wedge Y \cong (X \times Y) / \sim_R$$

in [Construction 5.1.4](#). The condition defining \sim is that at least one of the following conditions is satisfied:

1. We have $x = x'$ and $y = y'$;
2. Both of the following conditions are satisfied:
 - (a) We have $x = x_0$ or $y = y_0$.
 - (b) We have $x' = x_0$ or $y' = y_0$.

We have five cases:

1. In the first case, we clearly have

$$[f \wedge g](x, y) = [f \wedge g](x', y')$$

since $x = x'$ and $y = y'$.

2. If $x = x_0$ and $x' = x_0$, we have

$$\begin{aligned}
 [f \wedge g](x_0, y) &\stackrel{\text{def}}{=} f(x_0) \wedge g(y) \\
 &= a_0 \wedge g(y) \\
 &= a_0 \wedge g(y') \\
 &= f(x_0) \wedge g(y') \\
 &\stackrel{\text{def}}{=} [f \wedge g](x_0, y').
 \end{aligned}$$

3. If $x = x_0$ and $y' = y_0$, we have

$$\begin{aligned}
 [f \wedge g](x_0, y) &\stackrel{\text{def}}{=} f(x_0) \wedge g(y) \\
 &= a_0 \wedge g(y) \\
 &= a_0 \wedge b_0 \\
 &= f(x') \wedge b_0 \\
 &= f(x') \wedge g(y_0) \\
 &\stackrel{\text{def}}{=} [f \wedge g](x', y_0).
 \end{aligned}$$

4. If $y = y_0$ and $x' = x_0$, we have

$$\begin{aligned}
 [f \wedge g](x, y_0) &\stackrel{\text{def}}{=} f(x) \wedge g(y_0) \\
 &= f(x) \wedge b_0 \\
 &= a_0 \wedge b_0 \\
 &= a_0 \wedge g(y') \\
 &= f(x_0) \wedge g(y') \\
 &\stackrel{\text{def}}{=} [f \wedge g](x_0, y').
 \end{aligned}$$

5. If $y = y_0$ and $y' = y_0$, we have

$$\begin{aligned}
 [f \wedge g](x, y_0) &\stackrel{\text{def}}{=} f(x) \wedge g(y_0) \\
 &= f(x) \wedge b_0 \\
 &= f(x') \wedge b_0 \\
 &= f(x) \wedge g(y_0) \\
 &\stackrel{\text{def}}{=} [f \wedge g](x', y_0).
 \end{aligned}$$

Thus $f \wedge g$ is well-defined. Next, we claim that \wedge preserves identities and composition:

- *Preservation of Identities.* We have

$$\begin{aligned} [\text{id}_X \wedge \text{id}_Y](x \wedge y) &\stackrel{\text{def}}{=} \text{id}_X(x) \wedge \text{id}_Y(y) \\ &= x \wedge y \\ &= [\text{id}_{X \wedge Y}](x \wedge y) \end{aligned}$$

for each $x \wedge y \in X \wedge Y$, and thus

$$\text{id}_X \wedge \text{id}_Y = \text{id}_{X \wedge Y}.$$

- *Preservation of Composition.* Given pointed maps

$$\begin{aligned} f &: (X, x_0) \rightarrow (X', x'_0), \\ h &: (X', x'_0) \rightarrow (X'', x''_0), \\ g &: (Y, y_0) \rightarrow (Y', y'_0), \\ k &: (Y', y'_0) \rightarrow (Y'', y''_0), \end{aligned}$$

we have

$$\begin{aligned} [(h \circ f) \wedge (k \circ g)](x \wedge y) &\stackrel{\text{def}}{=} h(f(x)) \wedge k(g(y)) \\ &\stackrel{\text{def}}{=} [h \wedge k](f(x) \wedge g(y)) \\ &\stackrel{\text{def}}{=} [h \wedge k]([f \wedge g](x \wedge y)) \\ &\stackrel{\text{def}}{=} [(h \wedge k) \circ (f \wedge g)](x \wedge y) \end{aligned}$$

for each $x \wedge y \in X \wedge Y$, and thus

$$(h \circ f) \wedge (k \circ g) = (h \wedge k) \circ (f \wedge g).$$

This finishes the proof.

Item 2: Adjointness

We prove only the adjunction $- \wedge Y \dashv \mathbf{Sets}_*(Y, -)$, witnessed by a natural bijection

$$\text{Hom}_{\mathbf{Sets}_*}(X \wedge Y, Z) \cong \text{Hom}_{\mathbf{Sets}_*}(X, \mathbf{Sets}_*(Y, Z)),$$

as the proof of the adjunction $X \wedge - \dashv \mathbf{Sets}_*(X, -)$ is similar. We claim we have a bijection

$$\mathrm{Hom}_{\mathbf{Sets}_*}^{\otimes}(X \times Y, Z) \cong \mathrm{Hom}_{\mathbf{Sets}_*}(X, \mathbf{Sets}_*(Y, Z))$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \mathrm{Obj}(\mathbf{Sets}_*)$, implying the desired adjunction. Indeed, this bijection is a restriction of the bijection

$$\mathrm{Sets}(X \times Y, Z) \cong \mathrm{Sets}(X, \mathrm{Sets}(Y, Z))$$

of **Constructions With Sets, Item 2 of Proposition 1.3.3**:

- A map

$$\xi: X \times Y \rightarrow Z$$

in $\mathrm{Hom}_{\mathbf{Sets}_*}^{\otimes}(X \times Y, Z)$ gets sent to the pointed map

$$\begin{aligned} \xi^{\dagger}: (X, x_0) &\rightarrow (\mathbf{Sets}_*(Y, Z), \Delta_{z_0}), \\ x &\longmapsto (\xi_x^{\dagger}: Y \rightarrow Z), \end{aligned}$$

where $\xi_x^{\dagger}: Y \rightarrow Z$ is the map defined by

$$\xi_x^{\dagger}(y) \stackrel{\mathrm{def}}{=} \xi(x, y)$$

for each $y \in Y$, where:

- The map ξ^{\dagger} is indeed pointed, as we have

$$\begin{aligned} \xi_{x_0}^{\dagger}(y) &\stackrel{\mathrm{def}}{=} \xi(x_0, y) \\ &\stackrel{\mathrm{def}}{=} z_0 \end{aligned}$$

for each $y \in Y$. Thus $\xi_{x_0}^{\dagger} = \Delta_{z_0}$ and ξ^{\dagger} is pointed.

- The map ξ_x^{\dagger} indeed lies in $\mathbf{Sets}_*(Y, Z)$, as we have

$$\begin{aligned} \xi_x^{\dagger}(y_0) &\stackrel{\mathrm{def}}{=} \xi(x, y_0) \\ &\stackrel{\mathrm{def}}{=} z_0. \end{aligned}$$

· Conversely, a map

$$\begin{aligned}\xi: (X, x_0) &\rightarrow (\mathbf{Sets}_*(Y, Z), \Delta_{z_0}), \\ x &\longmapsto (\xi_x: Y \rightarrow Z),\end{aligned}$$

in $\text{Hom}_{\mathbf{Sets}_*}(X, \mathbf{Sets}_*(Y, Z))$ gets sent to the map

$$\xi^\dagger: X \times Y \rightarrow Z$$

defined by

$$\xi^\dagger(x, y) \stackrel{\text{def}}{=} \xi_x(y)$$

for each $(x, y) \in X \times Y$, which indeed lies in $\text{Hom}_{\mathbf{Sets}_*}^\otimes(X \times Y, Z)$, as:

– *Left Bilinearity.* We have

$$\begin{aligned}\xi^\dagger(x_0, y) &\stackrel{\text{def}}{=} \xi_{x_0}(y) \\ &\stackrel{\text{def}}{=} \Delta_{z_0}(y) \\ &\stackrel{\text{def}}{=} z_0\end{aligned}$$

for each $y \in Y$, since $\xi_{x_0} = \Delta_{z_0}$ as ξ is assumed to be a pointed map.

– *Right Bilinearity.* We have

$$\begin{aligned}\xi^\dagger(x, y_0) &\stackrel{\text{def}}{=} \xi_x(y_0) \\ &\stackrel{\text{def}}{=} z_0\end{aligned}$$

for each $x \in X$, since $\xi_x \in \mathbf{Sets}_*(Y, Z)$ is a morphism of pointed sets.

This finishes the proof.

Item 3: Enriched Adjointness

This follows from [Item 2](#) and [??](#), [??](#) of [??](#).

Item 4: As a Pushout

Following the description of [Constructions With Sets](#), [Remark 2.4.3](#), we have

$$\text{pt} \coprod_{X \vee Y} (X \times Y) \cong (\text{pt} \times (X \times Y)) / \sim,$$

where \sim identifies the element \star in pt with all elements of the form (x_0, y) and (x, y_0) in $X \times Y$. Thus [Equivalence Relations and Apartness Relations, Item 4 of Proposition 5.2.3](#) coupled with [Remark 5.1.8](#) then gives us a well-defined map


$$\text{pt} \amalg_{X \vee Y} (X \times Y) \rightarrow X \wedge Y$$

via $[(\star, (x, y))] \mapsto x \wedge y$, with inverse

$$X \wedge Y \rightarrow \text{pt} \amalg_{X \vee Y} (X \times Y)$$

given by $x \wedge y \mapsto [(\star, (x, y))]$.

Item 5: Distributivity Over Wedge Sums

This follows from [Proposition 5.9.1, ??, ?? of ??](#), and the fact that \vee is the coproduct in Sets_* ([Pointed Sets, Definition 3.3.1](#)). 

5.2 The Internal Hom of Pointed Sets

Let (X, x_0) and (Y, y_0) be pointed sets.

DEFINITION 5.2.1 ► THE INTERNAL HOM OF POINTED SETS

The **internal Hom**¹ of pointed sets from (X, x_0) to (Y, y_0) is the pointed set $\text{Sets}_*((X, x_0), (Y, y_0))$ ² consisting of:

- *The Underlying Set.* The set $\text{Sets}_*((X, x_0), (Y, y_0))$ of morphisms of pointed sets from (X, x_0) to (Y, y_0) .
- *The Basepoint.* The element

$$\Delta_{y_0} : (X, x_0) \rightarrow (Y, y_0)$$

of $\text{Sets}_*((X, x_0), (Y, y_0))$ given by


$$\Delta_{y_0}(x) \stackrel{\text{def}}{=} y_0$$

for each $x \in X$.

¹The pointed set $\text{Sets}_*(X, Y)$ is the internal **Hom** of Sets_* with respect to the smash product of [Tensor Products of Pointed Sets, Definition 5.1.1](#); see [Tensor Products of Pointed Sets, Item 2 of Proposition 5.1.10](#).

²*Further Notation:* Also written $\text{Hom}_{\text{Sets}_*}(X, Y)$.

PROOF 5.2.2 ► PROOF OF DEFINITION 5.2.1

For a proof that \mathbf{Sets}_* is indeed the internal Hom of \mathbf{Sets}_* with respect to the smash product of pointed sets, see [Item 2 of Proposition 5.1.10](#). 

PROPOSITION 5.2.3 ► PROPERTIES OF THE INTERNAL HOM OF POINTED SETS

Let (X, x_0) and (Y, y_0) be pointed sets.

1. *Functoriality.* The assignments $X, Y, (X, Y) \mapsto \mathbf{Sets}_*(X, Y)$ define functors

$$\begin{aligned}\mathbf{Sets}_*(X, -) &: \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*, \\ \mathbf{Sets}_*(-, Y) &: \mathbf{Sets}_*^{\text{op}} \rightarrow \mathbf{Sets}_*, \\ \mathbf{Sets}_*(-_1, -_2) &: \mathbf{Sets}_*^{\text{op}} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*.\end{aligned}$$

In particular, given pointed maps

$$\begin{aligned}f &: (X, x_0) \rightarrow (A, a_0), \\ g &: (Y, y_0) \rightarrow (B, b_0),\end{aligned}$$

the induced map

$$\mathbf{Sets}_*(f, g): \mathbf{Sets}_*(A, Y) \rightarrow \mathbf{Sets}_*(X, B)$$

is given by

$$[\mathbf{Sets}_*(f, g)](\phi) \stackrel{\text{def}}{=} g \circ \phi \circ f$$

for each $\phi \in \mathbf{Sets}_*(A, Y)$.

2. *Adjointness.* We have adjunctions

$$\begin{aligned}(X \wedge - \dashv \mathbf{Sets}_*(X, -)) &: \mathbf{Sets}_* \begin{array}{c} \xrightarrow{X \wedge -} \\ \perp \\ \xleftarrow{\mathbf{Sets}_*(X, -)} \end{array} \mathbf{Sets}_*, \\ (- \wedge Y \dashv \mathbf{Sets}_*(Y, -)) &: \mathbf{Sets}_* \begin{array}{c} \xrightarrow{- \wedge Y} \\ \perp \\ \xleftarrow{\mathbf{Sets}_*(Y, -)} \end{array} \mathbf{Sets}_*,\end{aligned}$$

witnessed by bijections

$$\mathrm{Hom}_{\mathbf{Sets}_*}(X \wedge Y, Z) \cong \mathrm{Hom}_{\mathbf{Sets}_*}(X, \mathbf{Sets}_*(Y, Z)),$$

$$\mathrm{Hom}_{\mathbf{Sets}_*}(X \wedge Y, Z) \cong \mathrm{Hom}_{\mathbf{Sets}_*}(X, \mathbf{Sets}_*(A, Z)),$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \mathrm{Obj}(\mathbf{Sets}_*)$.

3. *Enriched Adjointness*. We have \mathbf{Sets}_* -enriched adjunctions

$$(X \wedge - \dashv \mathbf{Sets}_*(X, -)) : \mathbf{Sets}_* \begin{array}{c} \xrightarrow{X \wedge -} \\ \perp \\ \xleftarrow{\mathbf{Sets}_*(X, -)} \end{array} \mathbf{Sets}_*,$$

$$(- \wedge Y \dashv \mathbf{Sets}_*(Y, -)) : \mathbf{Sets}_* \begin{array}{c} \xrightarrow{- \wedge Y} \\ \perp \\ \xleftarrow{\mathbf{Sets}_*(Y, -)} \end{array} \mathbf{Sets}_*,$$

witnessed by isomorphisms of pointed sets

$$\mathbf{Sets}_*(X \wedge Y, Z) \cong \mathbf{Sets}_*(X, \mathbf{Sets}_*(Y, Z)),$$

$$\mathbf{Sets}_*(X \wedge Y, Z) \cong \mathbf{Sets}_*(X, \mathbf{Sets}_*(A, Z)),$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \mathrm{Obj}(\mathbf{Sets}_*)$.

PROOF 5.2.4 ► PROOF OF PROPOSITION 5.2.3

Item 1: Functoriality

This follows from **Constructions With Sets**, **Item 1** of **Proposition 3.5.2** and from the equalities

$$g \circ \Delta_{y_0} = \Delta_{z_0},$$

$$\Delta_{y_0} \circ f = \Delta_{y_0}$$

for morphisms $f: (K, k_0) \rightarrow (X, x_0)$ and $g: (Y, y_0) \rightarrow (Z, z_0)$, which guarantee pre- and postcomposition by morphisms of pointed sets to also be morphisms of pointed sets.

Item 2: Adjointness

This is a repetition of **Item 2** of **Proposition 5.1.10**, and is proved there.

Item 3: Enriched Adjointness

This is a repetition of **Item 3** of **Proposition 5.1.10**, and is proved there. 

5.3 The Monoidal Unit**DEFINITION 5.3.1 ► THE MONOIDAL UNIT OF \wedge**

The **monoidal unit of the smash product of pointed sets** is the functor

$$\mathbb{1}^{\text{Sets}_*} : \text{pt} \rightarrow \text{Sets}_*$$

defined by

$$\mathbb{1}_{\text{Sets}_*} \stackrel{\text{def}}{=} S^0.$$

5.4 The Associator**DEFINITION 5.4.1 ► THE ASSOCIATOR OF \wedge**

The **associator of the smash product of pointed sets** is the natural isomorphism

$$\alpha^{\text{Sets}_*} : \wedge \circ (\wedge \times \text{id}_{\text{Sets}_*}) \xrightarrow{\sim} \wedge \circ (\text{id}_{\text{Sets}_*} \times \wedge) \circ \alpha^{\text{Cats}_{\text{Sets}_*, \text{Sets}_*, \text{Sets}_*}},$$

as in the diagram

$$\begin{array}{ccccc}
 & & \text{Sets}_* \times (\text{Sets}_* \times \text{Sets}_*) & & \\
 & \nearrow \alpha^{\text{Cats}_{\text{Sets}_*, \text{Sets}_*, \text{Sets}_*}} & & \searrow \text{id} \times \wedge & \\
 (\text{Sets}_* \times \text{Sets}_*) \times \text{Sets}_* & & & & \text{Sets}_* \times \text{Sets}_* \\
 \downarrow \wedge \times \text{id} & \nearrow \alpha^{\text{Sets}_*} & & \downarrow \wedge & \\
 \text{Sets}_* \times \text{Sets}_* & \xrightarrow{\wedge} & \text{Sets}_* & &
 \end{array}$$

whose component

$$\alpha_{X,Y,Z}^{\text{Sets}_*} : (X \wedge Y) \wedge Z \xrightarrow{\cong} X \wedge (Y \wedge Z)$$

at $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\text{Sets}_*)$ is given by

$$\alpha_{X,Y,Z}^{\text{Sets}_*}((x \wedge y) \wedge z) \stackrel{\text{def}}{=} x \wedge (y \wedge z)$$

for each $(x \wedge y) \wedge z \in (X \wedge Y) \wedge Z$.

PROOF 5.4.2 ► PROOF OF DEFINITION 5.4.1

Well-Definedness

Let $[(x, y), z] = [(x', y'), z']$ be an element in $(X \wedge Y) \wedge Z$. Then either:

1. We have $x = x', y = y',$ and $z = z'.$
2. Both of the following conditions are satisfied:
 - (a) We have $x = x_0$ or $y = y_0$ or $z = z_0.$
 - (b) We have $x' = x_0$ or $y' = y_0$ or $z' = z_0.$

In the first case, $\alpha_{X,Y,Z}^{\text{Sets}_*}$ clearly sends both elements to the same element in $X \wedge (Y \wedge Z)$. Meanwhile, in the latter case both elements are equal to the basepoint $(x_0 \wedge y_0) \wedge z_0$ of $(X \wedge Y) \wedge Z$, which gets sent to the basepoint $x_0 \wedge (y_0 \wedge z_0)$ of $X \wedge (Y \wedge Z)$.

Being a Morphism of Pointed Sets

As just mentioned, we have

$$\alpha_{X,Y,Z}^{\text{Sets}_*}((x_0 \wedge y_0) \wedge z_0) \stackrel{\text{def}}{=} x_0 \wedge (y_0 \wedge z_0),$$

and thus $\alpha_{X,Y,Z}^{\text{Sets}_*}$ is a morphism of pointed sets.

Invertibility

Clearly, the inverse of $\alpha_{X,Y,Z}^{\text{Sets}_*}$ is given by the morphism

$$\alpha_{X,Y,Z}^{\text{Sets}_*, -1}: X \wedge (Y \wedge Z) \xrightarrow{\cong} (X \wedge Y) \wedge Z$$

defined by

$$\alpha_{X,Y,Z}^{\text{Sets}_*, -1}(x \wedge (y \wedge z)) \stackrel{\text{def}}{=} (x \wedge y) \wedge z$$

for each $x \wedge (y \wedge z) \in X \wedge (Y \wedge Z)$.

Naturality

We need to show that, given morphisms of pointed sets

$$f: (X, x_0) \rightarrow (X', x'_0),$$

$$g: (Y, y_0) \rightarrow (Y', y'_0),$$

$$h: (Z, z_0) \rightarrow (Z', z'_0)$$

the diagram


$$\begin{array}{ccc} (X \wedge Y) \wedge Z & \xrightarrow{(f \wedge g) \wedge h} & (X' \wedge Y') \wedge Z' \\ \alpha_{X,Y,Z}^{\text{Sets}_*} \downarrow & & \downarrow \alpha_{X',Y',Z'}^{\text{Sets}_*} \\ X \wedge (Y \wedge Z) & \xrightarrow{f \wedge (g \wedge h)} & X' \wedge (Y' \wedge Z') \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc} (x \wedge y) \wedge z & \longmapsto & (f(x) \wedge g(y)) \wedge h(z) \\ \downarrow & & \downarrow \\ x \wedge (y \wedge z) & \longmapsto & f(x) \wedge (g(y) \wedge h(z)) \end{array}$$

and hence indeed commutes, showing α^{Sets_*} to be a natural transformation.

Being a Natural Isomorphism

Since α^{Sets_*} is natural and $\alpha^{\text{Sets}_*, -1}$ is a componentwise inverse to α^{Sets_*} , it follows from **Categories, Item 2** of **Proposition 8.6.2** that $\alpha^{\text{Sets}_*, -1}$ is also natural. Thus α^{Sets_*} is a natural isomorphism. 

5.5 The Left Unitor

DEFINITION 5.5.1 ► THE LEFT UNITOR OF \wedge

The **left unitor of the smash product of pointed sets** is the natural isomorphism

$$\lambda^{\text{Sets}_*} : \wedge \circ (\mathbb{1}^{\text{Sets}_*} \times \text{id}_{\text{Sets}_*}) \xrightarrow{\sim} \lambda_{\text{Sets}_*}^{\text{Cats}_2}$$

whose component

$$\lambda_X^{\text{Sets}_*} : S^0 \wedge X \xrightarrow{\cong} X$$

at $X \in \text{Obj}(\text{Sets}_*)$ is given by

$$0 \wedge x \mapsto x_0,$$

$$1 \wedge x \mapsto x.$$

PROOF 5.5.2 ► PROOF OF DEFINITION 5.5.1

Well-Definedness

Let $[(x, y)] = [(x', y')]$ be an element in $S^0 \wedge X$. Then either:

1. We have $x = x'$ and $y = y'$.
2. Both of the following conditions are satisfied:
 - (a) We have $x = 0$ or $y = x_0$.
 - (b) We have $x' = 0$ or $y' = x_0$.

In the first case, $\lambda_X^{\text{Sets}_*}$ clearly sends both elements to the same element in X . Meanwhile, in the latter case both elements are equal to the basepoint $0 \wedge x_0$ of $S^0 \wedge X$, which gets sent to the basepoint x_0 of X .

Being a Morphism of Pointed Sets

As just mentioned, we have

$$\lambda_X^{\text{Sets}_*}(0 \wedge x_0) \stackrel{\text{def}}{=} x_0,$$

and thus $\lambda_X^{\text{Sets}_*}$ is a morphism of pointed sets.

Invertibility

The inverse of $\lambda_X^{\text{Sets}_*}$ is the morphism

$$\lambda_X^{\text{Sets}_*, -1}: X \xrightarrow{\cong} S^0 \wedge X$$

defined by

$$\lambda_X^{\text{Sets}_*, -1}(x) \stackrel{\text{def}}{=} 1 \wedge x$$

for each $x \in X$. Indeed:

• *Invertibility I.* We have

$$\begin{aligned} [\lambda_X^{\text{Sets}_*, -1} \circ \lambda_X^{\text{Sets}_*}](0 \wedge x) &= \lambda_X^{\text{Sets}_*, -1}(\lambda_X^{\text{Sets}_*}(0 \wedge x)) \\ &= \lambda_X^{\text{Sets}_*, -1}(x_0) \\ &= 1 \wedge x_0 \\ &= 0 \wedge x, \end{aligned}$$

and

$$\begin{aligned} [\lambda_X^{\text{Sets}_*, -1} \circ \lambda_X^{\text{Sets}_*}](1 \wedge x) &= \lambda_X^{\text{Sets}_*, -1}(\lambda_X^{\text{Sets}_*}(1 \wedge x)) \\ &= \lambda_X^{\text{Sets}_*, -1}(x) \\ &= 1 \wedge x \end{aligned}$$

for each $x \in X$, and thus we have

$$\lambda_X^{\text{Sets}_*, -1} \circ \lambda_X^{\text{Sets}_*} = \text{id}_{S^0 \wedge X}.$$

• *Invertibility II.* We have

$$\begin{aligned} [\lambda_X^{\text{Sets}_*} \circ \lambda_X^{\text{Sets}_*, -1}](x) &= \lambda_X^{\text{Sets}_*}(\lambda_X^{\text{Sets}_*, -1}(x)) \\ &= \lambda_X^{\text{Sets}_*, -1}(1 \wedge x) \\ &= x \end{aligned}$$

for each $x \in X$, and thus we have

$$\lambda_X^{\text{Sets}_*} \circ \lambda_X^{\text{Sets}_*, -1} = \text{id}_X.$$

This shows $\lambda_X^{\text{Sets}_*}$ to be invertible.

Naturality

We need to show that, given a morphism of pointed sets

$$f: (X, x_0) \rightarrow (Y, y_0),$$

the diagram

$$\begin{array}{ccc} S^0 \wedge X & \xrightarrow{\text{id}_{S^0} \wedge f} & S^0 \wedge Y \\ \lambda_X^{\text{Sets}_*} \downarrow & & \downarrow \lambda_Y^{\text{Sets}_*} \\ X & \xrightarrow{f} & Y \end{array}$$

commutes. Indeed, this diagram acts on elements as


$$\begin{array}{ccc} 0 \wedge x & & 0 \wedge x \mapsto 0 \wedge f(x) \\ \downarrow & & \downarrow \\ x_0 & \mapsto & f(x_0) \\ & & y_0 \end{array}$$

and

$$\begin{array}{ccc} 1 \wedge x & \mapsto & 1 \wedge f(x) \\ \downarrow & & \downarrow \\ x & \mapsto & f(x) \end{array}$$

and hence indeed commutes, showing λ^{Sets_*} to be a natural transformation.

Being a Natural Isomorphism

Since λ^{Sets_*} is natural and $\lambda^{\text{Sets}_*, -1}$ is a componentwise inverse to λ^{Sets_*} , it follows from [Categories, Item 2](#) of [Proposition 8.6.2](#) that $\lambda^{\text{Sets}_*, -1}$ is also natural. Thus λ^{Sets_*} is a natural isomorphism. 

5.6 The Right Unitor

DEFINITION 5.6.1 ► THE RIGHT UNITOR OF \wedge

The **right unitor of the smash product of pointed sets** is the natural isomorphism

$$\rho^{\text{Sets}_*} : \wedge \circ (\text{id} \times \mathbb{1}^{\text{Sets}_*}) \xrightarrow{\sim} \rho_{\text{Sets}_*}^{\text{Cats}_2},$$

whose component

$$\rho_X^{\text{Sets}_*} : X \wedge S^0 \xrightarrow{\cong} X$$

at $X \in \text{Obj}(\text{Sets}_*)$ is given by

$$x \wedge 0 \mapsto x_0,$$

$$x \wedge 1 \mapsto x.$$

PROOF 5.6.2 ► PROOF OF DEFINITION 5.6.1

Well-Definedness

Let $[(x, y)] = [(x', y')]$ be an element in $X \wedge S^0$. Then either:

1. We have $x = x'$ and $y = y'$.
2. Both of the following conditions are satisfied:
 - (a) We have $x = x_0$ or $y = 0$.
 - (b) We have $x' = x_0$ or $y' = 0$.

In the first case, $\rho_X^{\text{Sets}_*}$ clearly sends both elements to the same element in X . Meanwhile, in the latter case both elements are equal to the basepoint $x_0 \wedge 0$ of $X \wedge S^0$, which gets sent to the basepoint x_0 of X .

Being a Morphism of Pointed Sets

As just mentioned, we have

$$\rho_X^{\text{Sets}_*}(x_0 \wedge 0) \stackrel{\text{def}}{=} x_0,$$

and thus $\rho_X^{\text{Sets}_*}$ is a morphism of pointed sets.

Invertibility

The inverse of $\rho_X^{\text{Sets}_*}$ is the morphism

$$\rho_X^{\text{Sets}_*, -1}: X \xrightarrow{\cong} X \wedge S^0$$

defined by

$$\rho_X^{\text{Sets}_*, -1}(x) \stackrel{\text{def}}{=} x \wedge 1$$

for each $x \in X$. Indeed:

· *Invertibility I.* We have

$$\begin{aligned} [\rho_X^{\text{Sets}_*, -1} \circ \rho_X^{\text{Sets}_*}](x \wedge 0) &= \rho_X^{\text{Sets}_*, -1}(\rho_X^{\text{Sets}_*}(x \wedge 0)) \\ &= \rho_X^{\text{Sets}_*, -1}(x_0) \\ &= x_0 \wedge 1 \\ &= x \wedge 0, \end{aligned}$$

and

$$\begin{aligned} [\rho_X^{\text{Sets}_*, -1} \circ \rho_X^{\text{Sets}_*}](x \wedge 1) &= \rho_X^{\text{Sets}_*, -1}(\rho_X^{\text{Sets}_*}(x \wedge 1)) \\ &= \rho_X^{\text{Sets}_*, -1}(x) \\ &= x \wedge 1 \end{aligned}$$

for each $x \in X$, and thus we have

$$\rho_X^{\text{Sets}_*, -1} \circ \rho_X^{\text{Sets}_*} = \text{id}_{X \wedge S^0}.$$

· *Invertibility II.* We have

$$\begin{aligned} [\rho_X^{\text{Sets}_*} \circ \rho_X^{\text{Sets}_*, -1}](x) &= \rho_X^{\text{Sets}_*}(\rho_X^{\text{Sets}_*, -1}(x)) \\ &= \rho_X^{\text{Sets}_*, -1}(x \wedge 1) \\ &= x \end{aligned}$$

for each $x \in X$, and thus we have

$$\rho_X^{\text{Sets}_*} \circ \rho_X^{\text{Sets}_*, -1} = \text{id}_X.$$

This shows $\rho_X^{\text{Sets}_*}$ to be invertible.

Naturality

We need to show that, given a morphism of pointed sets

$$f: (X, x_0) \rightarrow (Y, y_0),$$

the diagram

$$\begin{array}{ccc} X \wedge S^0 & \xrightarrow{f \wedge \text{id}_{S^0}} & Y \wedge S^0 \\ \rho_X^{\text{Sets}_*} \downarrow & & \downarrow \rho_Y^{\text{Sets}_*} \\ X & \xrightarrow{f} & Y \end{array}$$

commutes. Indeed, this diagram acts on elements as


$$\begin{array}{ccc} x \wedge 0 & & x \wedge 0 \mapsto f(x) \wedge 0 \\ \downarrow & & \downarrow \\ x_0 \mapsto f(x_0) & & y_0 \end{array}$$

and

$$\begin{array}{ccc} x \wedge 1 \mapsto f(x) \wedge 1 & & \\ \downarrow & & \downarrow \\ x \mapsto f(x) & & \end{array}$$

and hence indeed commutes, showing ρ^{Sets_*} to be a natural transformation.

Being a Natural Isomorphism

Since ρ^{Sets_*} is natural and $\rho^{\text{Sets}_*, -1}$ is a componentwise inverse to ρ^{Sets_*} , it follows from [Categories, Item 2](#) of [Proposition 8.6.2](#) that $\rho^{\text{Sets}_*, -1}$ is also natural. Thus ρ^{Sets_*} is a natural isomorphism. 

5.7 The Symmetry

DEFINITION 5.7.1 ► THE SYMMETRY OF \wedge

The **symmetry of the smash product of pointed sets** is the natural isomorphism

$$\sigma^{\text{Sets}_*} : \wedge \xrightarrow{\sim} \wedge \circ \sigma_{\text{Sets}_*, \text{Sets}_*}^{\text{Cats}_2}, \quad \begin{array}{ccc} \text{Sets}_* \times \text{Sets}_* & \xrightarrow{\wedge} & \text{Sets}_* \\ \sigma_{\text{Sets}_*, \text{Sets}_*}^{\text{Cats}_2} \searrow & \Downarrow \sigma^{\text{Sets}_*} & \nearrow \wedge \\ & \text{Sets}_* \times \text{Sets}_* & \end{array}$$

whose component

$$\sigma_{X,Y}^{\text{Sets}_*} : X \wedge Y \xrightarrow{\cong} Y \wedge X$$

at $X, Y \in \text{Obj}(\text{Sets}_*)$ is defined by

$$\sigma_{X,Y}^{\text{Sets}_*}(x \wedge y) \stackrel{\text{def}}{=} y \wedge x$$

for each $x \wedge y \in X \wedge Y$.

PROOF 5.7.2 ► PROOF OF DEFINITION 5.6.1**Well-Definedness**

Let $[(x, y)] = [(x', y')]$ be an element in $X \wedge Y$. Then either:

1. We have $x = x'$ and $y = y'$.
2. Both of the following conditions are satisfied:
 - (a) We have $x = x_0$ or $y = y_0$.
 - (b) We have $x' = x_0$ or $y' = y_0$.

In the first case, $\sigma_X^{\text{Sets}_*}$ clearly sends both elements to the same element in X . Meanwhile, in the latter case both elements are equal to the basepoint $x_0 \wedge y_0$ of $X \wedge Y$, which gets sent to the basepoint $y_0 \wedge x_0$ of $Y \wedge X$.

Being a Morphism of Pointed Sets

As just mentioned, we have

$$\sigma_X^{\text{Sets}_*}(x_0 \wedge y_0) \stackrel{\text{def}}{=} y_0 \wedge x_0,$$

and thus $\sigma_X^{\text{Sets}_*}$ is a morphism of pointed sets.

Invertibility

Clearly, the inverse of $\sigma_{X,Y}^{\text{Sets}_*}$ is given by the morphism

$$\sigma_{X,Y}^{\text{Sets}_*, -1}: Y \wedge X \xrightarrow{\cong} X \wedge Y$$

defined by

$$\sigma_{X,Y}^{\text{Sets}_*, -1}(y \wedge x) \stackrel{\text{def}}{=} x \wedge y$$

for each $y \wedge x \in Y \wedge X$.

Naturality

We need to show that, given morphisms of pointed sets

$$f: (X, x_0) \rightarrow (A, a_0),$$

$$g: (Y, y_0) \rightarrow (B, b_0)$$

the diagram


$$\begin{array}{ccc} X \wedge Y & \xrightarrow{f \wedge g} & A \wedge B \\ \sigma_{X,Y}^{\text{Sets}_*} \downarrow & & \downarrow \sigma_{A,B}^{\text{Sets}_*} \\ Y \wedge X & \xrightarrow{g \wedge f} & B \wedge A \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc} x \wedge y & \longmapsto & f(x) \wedge g(y) \\ \downarrow & & \downarrow \\ y \wedge x & \longmapsto & g(y) \wedge f(x) \end{array}$$

and hence indeed commutes, showing σ^{Sets_*} to be a natural transformation.

Being a Natural Isomorphism

Since σ^{Sets_*} is natural and $\sigma^{\text{Sets}_*, -1}$ is a componentwise inverse to σ^{Sets_*} , it follows from **Categories, Item 2** of **Proposition 8.6.2** that $\sigma^{\text{Sets}_*, -1}$ is also natural. Thus σ^{Sets_*} is a natural isomorphism. 

5.8 The Diagonal

DEFINITION 5.8.1 ► THE DIAGONAL OF \wedge

The **diagonal of the smash product of pointed sets** is the natural transformation

$$\Delta^\wedge : \text{id}_{\text{Sets}_*} \Rightarrow \wedge \circ \Delta_{\text{Sets}_*}^{\text{Cats}_2},$$

whose component

$$\Delta_X^\wedge : (X, x_0) \rightarrow (X \wedge X, x_0 \wedge x_0)$$

at $(X, x_0) \in \text{Obj}(\text{Sets}_*)$ is given by the composition

$$\begin{aligned} (X, x_0) &\xrightarrow{\Delta_X^\wedge} (X \times X, (x_0, x_0)) \\ &\longrightarrow ((X \times X)/\sim, [(x_0, x_0)]) \\ &\stackrel{\text{def}}{=} (X \wedge X, x_0 \wedge x_0) \end{aligned}$$

in Sets_* , and thus by

$$\Delta_X^\wedge(x) \stackrel{\text{def}}{=} x \wedge x$$

for each $x \in X$.

PROOF 5.8.2 ► PROOF OF DEFINITION 5.8.1

Being a Morphism of Pointed Sets

We have

$$\Delta_X^\wedge(x_0) \stackrel{\text{def}}{=} x_0 \wedge x_0,$$

and thus Δ_X^\wedge is a morphism of pointed sets.

Naturality

We need to show that, given a morphism of pointed sets


$$f: (X, x_0) \rightarrow (Y, y_0),$$

the diagram

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ \Delta_X^\wedge \downarrow & & \downarrow \Delta_Y^\wedge \\ X \wedge X & \xrightarrow{f \wedge f} & Y \wedge Y \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc} x & \xrightarrow{\quad} & f(x) \\ \downarrow & & \downarrow \\ x \wedge x & \xrightarrow{\quad} & f(x) \wedge f(x) \end{array}$$

and hence indeed commutes, showing Δ^\wedge to be natural. 

PROPOSITION 5.8.3 ► PROPERTIES OF THE DIAGONAL OF \wedge

Let $(X, x_0) \in \text{Obj}(\text{Sets}_*)$.

1. *Monoidality*. The diagonal

$$\Delta^\wedge: \text{id}_{\text{Sets}_*} \Longrightarrow \wedge \circ \Delta_{\text{Sets}_*}^{\text{Cats}_2},$$

of the smash product of pointed sets is a monoidal natural transformation:

(a) *Compatibility With Strong Monoidality Constraints*. For each $(X, x_0), (Y, y_0) \in \text{Obj}(\text{Sets}_*)$, the diagram

$$\begin{array}{ccc} X \wedge Y & \xrightarrow{\Delta_X^\wedge \wedge \Delta_Y^\wedge} & (X \wedge X) \wedge (Y \wedge Y) \\ & \searrow \Delta_{X \wedge Y}^\wedge & \downarrow \wr \\ & & (X \wedge Y) \wedge (X \wedge Y) \end{array}$$

commutes.

(b) *Compatibility With Strong Unitality Constraints.* The diagrams

$$\begin{array}{ccc}
 S^0 & \xrightarrow{\Delta_{S^0}^\wedge} & S^0 \wedge S^0 \\
 \parallel & & \downarrow \lambda_{S^0}^{\text{Sets}_*} \\
 & & S^0
 \end{array}
 \quad
 \begin{array}{ccc}
 S^0 & \xrightarrow{\Delta_{S^0}^\wedge} & S^0 \wedge S^0 \\
 \parallel & & \downarrow \rho_{S^0}^{\text{Sets}_*} \\
 & & S^0
 \end{array}$$

commute, i.e. we have

$$\begin{aligned}
 \Delta_{S^0}^\wedge &= \lambda_{S^0}^{\text{Sets}_*, -1} \\
 &= \rho_{S^0}^{\text{Sets}_*, -1},
 \end{aligned}$$

where we recall that the equalities

$$\begin{aligned}
 \lambda_{S^0}^{\text{Sets}_*} &= \rho_{S^0}^{\text{Sets}_*}, \\
 \lambda_{S^0}^{\text{Sets}_*, -1} &= \rho_{S^0}^{\text{Sets}_*, -1}
 \end{aligned}$$

are always true in any monoidal category by ??, ?? of ??.

2. *The Diagonal of the Unit.* The component

$$\Delta_{S^0}^\wedge : S^0 \xrightarrow{\cong} S^0 \wedge S^0$$

of Δ^\wedge at S^0 is an isomorphism.

PROOF 5.8.4 ► PROOF OF PROPOSITION 5.8.3

Item 1: Monoidality

We claim that Δ^\wedge is indeed monoidal:

1. *Item 1a: Compatibility With Strong Monoidality Constraints:* We need to show

that the diagram

$$\begin{array}{ccc}
 X \wedge Y & \xrightarrow{\Delta_X^\wedge \wedge \Delta_Y^\wedge} & (X \wedge X) \wedge (Y \wedge Y) \\
 & \searrow \Delta_{X \wedge Y}^\wedge & \downarrow \wr \\
 & & (X \wedge Y) \wedge (X \wedge Y)
 \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
 x \wedge y & \xrightarrow{\quad} & (x \wedge x) \wedge (y \wedge y) \\
 & \searrow & \downarrow \\
 & & (x \wedge y) \wedge (x \wedge y)
 \end{array}$$

and hence indeed commutes.

2. *Item 1b: Compatibility With Strong Unitality Constraints:* As shown in the proof of [Definition 5.5.1](#), the inverse of the left unitor of \mathbf{Sets}_* with respect to to the smash product of pointed sets at $(X, x_0) \in \mathbf{Obj}(\mathbf{Sets}_*)$ is given by

$$\lambda_X^{\mathbf{Sets}_*, -1}(x) \stackrel{\text{def}}{=} 1 \wedge x$$

for each $x \in X$, so when $X = S^0$, we have

$$\lambda_{S^0}^{\mathbf{Sets}_*, -1}(0) \stackrel{\text{def}}{=} 1 \wedge 0,$$

$$\lambda_{S^0}^{\mathbf{Sets}_*, -1}(1) \stackrel{\text{def}}{=} 1 \wedge 1.$$

But since $1 \wedge 0 = 0 \wedge 0$ and


$$\Delta_{S^0}^\wedge(0) \stackrel{\text{def}}{=} 0 \wedge 0,$$

$$\Delta_{S^0}^\wedge(1) \stackrel{\text{def}}{=} 1 \wedge 1,$$

it follows that we indeed have $\Delta_{S^0}^\wedge = \lambda_{S^0}^{\mathbf{Sets}_*, -1}$.

This finishes the proof.

Item 2: The Diagonal of the Unit

This follows from [Item 1](#) and the invertibility of the left/right unitor of \mathbf{Sets}_* with respect to \wedge , proved in the proof of [Definition 5.5.1](#) for the left unitor or the proof of [Definition 5.6.1](#) for the right unitor. 

5.9 The Monoidal Structure on Pointed Sets Associated to \wedge

PROPOSITION 5.9.1 ► THE MONOIDAL STRUCTURE ON POINTED SETS ASSOCIATED TO \wedge

The category \mathbf{Sets}_* admits a closed monoidal category with diagonals structure consisting of

- *The Underlying Category.* The category \mathbf{Sets}_* of pointed sets;
- *The Monoidal Product.* The smash product functor

$$\wedge : \mathbf{Sets}_* \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$

of Item 1 of Proposition 5.1.10;

- *The Internal Hom.* The internal Hom functor

$$\mathbf{Sets}_* : \mathbf{Sets}_*^{\text{op}} \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$

of Item 1 of Proposition 5.2.3;

- *The Monoidal Unit.* The functor

$$\mathbb{1}^{\mathbf{Sets}_*} : \text{pt} \rightarrow \mathbf{Sets}_*$$

of Definition 5.3.1;

- *The Associators.* The natural isomorphism

$$\alpha^{\mathbf{Sets}_*} : \wedge \circ (\wedge \times \text{id}_{\mathbf{Sets}_*}) \xrightarrow{\sim} \wedge \circ (\text{id}_{\mathbf{Sets}_*} \times \wedge) \circ \alpha_{\mathbf{Sets}_*, \mathbf{Sets}_*, \mathbf{Sets}_*}^{\mathbf{Cats}}$$

of Definition 5.4.1;

- *The Left Unitors.* The natural isomorphism

$$\lambda^{\mathbf{Sets}_*} : \wedge \circ (\mathbb{1}^{\mathbf{Sets}_*} \times \text{id}_{\mathbf{Sets}_*}) \xrightarrow{\sim} \lambda_{\mathbf{Sets}_*}^{\mathbf{Cats}_2}$$

of Definition 5.5.1;

- *The Right Unitors.* The natural isomorphism

$$\rho^{\mathbf{Sets}_*} : \wedge \circ (\text{id} \times \mathbb{1}^{\mathbf{Sets}_*}) \xrightarrow{\sim} \rho_{\mathbf{Sets}_*}^{\mathbf{Cats}_2}$$

of Definition 5.6.1;

- *The Symmetry.* The natural isomorphism

$$\sigma^{\text{Sets}_*} : \wedge \xrightarrow{\sim} \wedge \circ \sigma_{\text{Sets}_*, \text{Sets}_*}^{\text{Cats}_2}$$

of Definition 5.7.1;

- *The Diagonals.* The monoidal natural transformation

$$\Delta^{\wedge} : \text{id}_{\text{Sets}_*} \Rightarrow \wedge \circ \Delta_{\text{Sets}_*}^{\text{Cats}_2}$$

of Definition 5.8.1.

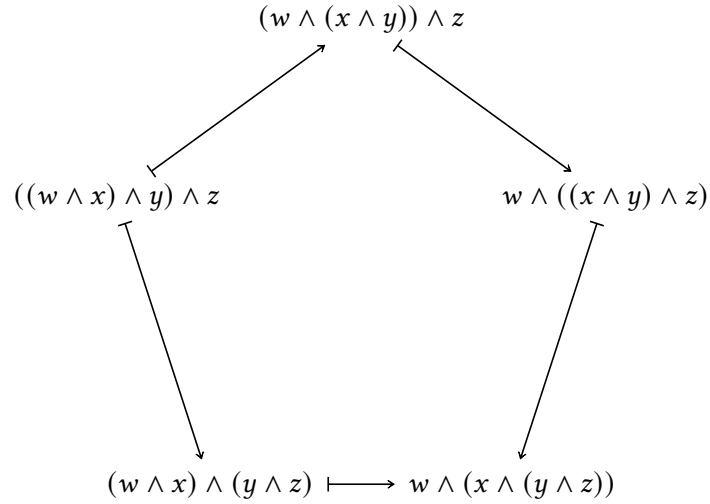
PROOF 5.9.2 ► PROOF OF PROPOSITION 5.9.1

The Pentagon Identity

Let (W, w_0) , (X, x_0) , (Y, y_0) and (Z, z_0) be pointed sets. We have to show that the diagram

$$\begin{array}{ccccc}
 & & (W \wedge (X \wedge Y)) \wedge Z & & \\
 & \nearrow \alpha_{W, X, Y}^{\text{Sets}_*} \wedge \text{id}_Z & & \nwarrow \alpha_{W, X \wedge Y, Z}^{\text{Sets}_*} & \\
 ((W \wedge X) \wedge Y) \wedge Z & & & & W \wedge ((X \wedge Y) \wedge Z) \\
 \searrow \alpha_{W \wedge X, Y, Z}^{\text{Sets}_*} & & & & \swarrow \text{id}_W \wedge \alpha_{X, Y, Z}^{\text{Sets}_*} \\
 (W \wedge X) \wedge (Y \wedge Z) & \xrightarrow{\alpha_{W, X, Y \wedge Z}^{\text{Sets}_*}} & W \wedge (X \wedge (Y \wedge Z)) & &
 \end{array}$$

commutes. Indeed, this diagram acts on elements as



and thus we see that the pentagon identity is satisfied.

The Triangle Identity

Let (X, x_0) and (Y, y_0) be pointed sets. We have to show that the diagram

$$\begin{array}{ccc}
 (X \wedge S^0) \wedge Y & \xrightarrow{\alpha_{X, S^0, Y}^{\text{Sets}_*}} & X \wedge (S^0 \wedge Y) \\
 \searrow \rho_X^{\text{Sets}_*} \wedge \text{id}_Y & & \swarrow \text{id}_X \wedge \lambda_Y^{\text{Sets}_*} \\
 & X \wedge Y &
 \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
 (x \wedge 0) \wedge y & & (x \wedge 0) \wedge y \longmapsto x \wedge (0 \wedge y) \\
 \searrow & & \swarrow \\
 x_0 \wedge y & & x \wedge y_0
 \end{array}$$

and

$$\begin{array}{ccc}
 (x \wedge 1) \wedge y & \xrightarrow{\quad} & x \wedge (1 \wedge y) \\
 & \searrow \quad \swarrow & \\
 & x \wedge y, &
 \end{array}$$

and thus we see that the triangle identity is satisfied.

The Left Hexagon Identity

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets. We have to show that the diagram

$$\begin{array}{ccc}
 & (X \wedge Y) \wedge Z & \\
 \alpha_{X,Y,Z}^{\text{Sets}_*} \swarrow & & \searrow \beta_{X,Y}^{\text{Sets}_*} \wedge \text{id}_Z \\
 X \wedge (Y \wedge Z) & & (Y \wedge X) \wedge Z \\
 \downarrow \beta_{X,Y \wedge Z}^{\text{Sets}_*} & & \downarrow \alpha_{Y,X,Z}^{\text{Sets}_*} \\
 (Y \wedge Z) \wedge X & & Y \wedge (X \wedge Z) \\
 \searrow \alpha_{Y,Z,X}^{\text{Sets}_*} & & \swarrow \text{id}_Y \wedge \beta_{X,Z}^{\text{Sets}_*} \\
 & Y \wedge (Z \wedge X) &
 \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
 & (x \wedge y) \wedge z & \\
 \swarrow & & \searrow \\
 x \wedge (y \wedge z) & & (y \wedge x) \wedge z \\
 \downarrow & & \downarrow \\
 (y \wedge z) \wedge x & & y \wedge (x \wedge z) \\
 \swarrow & & \swarrow \\
 & y \wedge (z \wedge x) &
 \end{array}$$

and thus we see that the left hexagon identity is satisfied.

The Right Hexagon Identity

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets. We have to show that the diagram

$$\begin{array}{ccc}
 & X \wedge (Y \wedge Z) & \\
 (\alpha_{X,Y,Z}^{\text{Sets}_*})^{-1} \swarrow & & \searrow \text{id}_X \wedge \beta_{Y,Z}^{\text{Sets}_*} \\
 (X \wedge Y) \wedge Z & & X \wedge (Z \wedge Y) \\
 \downarrow \beta_{X \wedge Y, Z}^{\text{Sets}_*} & & \downarrow (\alpha_{X,Z,Y}^{\text{Sets}_*})^{-1} \\
 Z \wedge (X \wedge Y) & & (X \wedge Z) \wedge Y \\
 \swarrow (\alpha_{Z,X,Y}^{\text{Sets}_*})^{-1} & & \searrow \beta_{X,Z}^{\text{Sets}_*} \wedge \text{id}_Y \\
 & (Z \wedge X) \wedge Y &
 \end{array}$$

commutes. Indeed, this diagram acts on elements as

$$\begin{array}{ccc}
 & x \wedge (y \wedge z) & \\
 \swarrow & & \searrow \\
 (x \wedge y) \wedge z & & x \wedge (z \wedge y) \\
 \downarrow & & \downarrow \\
 z \wedge (x \wedge y) & & (x \wedge z) \wedge y \\
 \swarrow & & \searrow \\
 & (z \wedge x) \wedge y &
 \end{array}$$

and thus we see that the right hexagon identity is satisfied.

Monoidal Closedness

This follows from [Item 2](#) of [Proposition 5.1.10](#).

Existence of Monoidal Diagonals

This follows from [Items 1](#) and [2](#) of [Proposition 5.8.3](#).



5.10 Universal Properties of the Smash Product of Pointed Sets I

THEOREM 5.10.1 ► UNIVERSAL PROPERTIES OF THE SMASH PRODUCT OF POINTED SETS I

The symmetric monoidal structure on the category \mathbf{Sets}_* is uniquely determined by the following requirements:

1. *Two-Sided Preservation of Colimits.* The smash product

$$\wedge : \mathbf{Sets}_* \times \mathbf{Sets}_* \rightarrow \mathbf{Sets}_*$$

of \mathbf{Sets}_* preserves colimits separately in each variable.

2. *The Unit Object Is S^0 .* We have $\mathbb{1}_{\mathbf{Sets}_*} = S^0$.

PROOF 5.10.2 ► PROOF OF THEOREM 5.10.1

Omitted.



5.11 Universal Properties of the Smash Product of Pointed Sets II

THEOREM 5.11.1 ► UNIVERSAL PROPERTIES OF THE SMASH PRODUCT OF POINTED SETS II

The symmetric monoidal structure on the category \mathbf{Sets}_* is the unique symmetric monoidal structure on \mathbf{Sets}_* such that the free pointed set functor

$$(-)^+ : \mathbf{Sets} \rightarrow \mathbf{Sets}_*$$

admits a symmetric monoidal structure.

PROOF 5.11.2 ► PROOF OF THEOREM 5.11.1

See [GGN15, Theorem 5.1].



5.12 Monoids With Respect to the Smash Product of Pointed Sets

PROPOSITION 5.12.1 ► MONOIDS WITH RESPECT TO \wedge

The category of monoids on $(\text{Sets}_*, \wedge, S^0)$ is isomorphic to the category of monoids with zero and morphisms between them.

PROOF 5.12.2 ► PROOF OF PROPOSITION 5.12.1

See ??, in particular ??, ??, ??, and ??.

**5.13 Comonoids With Respect to the Smash Product of Pointed Sets****PROPOSITION 5.13.1 ► COMONIDS WITH RESPECT TO \wedge**

The symmetric monoidal functor

$$((-)^+, (-)^{+, \times}, (-)_{\perp}^{+, \times}): (\text{Sets}, \times, \text{pt}) \rightarrow (\text{Sets}_*, \wedge, S^0),$$

of [Pointed Sets](#), [Item 4](#) of [Proposition 4.1.2](#) lifts to an equivalence of categories

$$\begin{aligned} \text{CoMon}(\text{Sets}_*, \wedge, S^0) &\stackrel{\text{eq.}}{\cong} \text{CoMon}(\text{Sets}, \times, \text{pt}) \\ &\cong \text{Sets}. \end{aligned}$$

PROOF 5.13.2 ► PROOF OF PROPOSITION 5.13.1

See [\[PS19, Lemma 2.4\]](#).

**6 Miscellany****6.1 The Smash Product of a Family of Pointed Sets**

Let $\{(X_i, x_0^i)\}_{i \in I}$ be a family of pointed sets.

DEFINITION 6.1.1 ► THE SMASH PRODUCT OF A FAMILY OF POINTED SETS

The **smash product of the family** $\{(X_i, x_0^i)\}_{i \in I}$ is the pointed set $\bigwedge_{i \in I} X_i$ consisting of:

· *The Underlying Set.* The set $\bigwedge_{i \in I} X_i$ defined by

$$\bigwedge_{i \in I} X_i \stackrel{\text{def}}{=} (\prod_{i \in I} X_i) / \sim,$$

where \sim is the equivalence relation on $\prod_{i \in I} X_i$ obtained by declaring

$$(x_i)_{i \in I} \sim (y_i)_{i \in I}$$

if there exist $i_0 \in I$ such that $x_{i_0} = x_0$ and $y_{i_0} = y_0$, for each $(x_i)_{i \in I}, (y_i)_{i \in I} \in \prod_{i \in I} X_i$.

· *The Basepoint.* The element $[(x_0)_{i \in I}]$ of $\bigwedge_{i \in I} X_i$.

Appendices

A Other Chapters

Sets

1. [Sets](#)
2. [Constructions With Sets](#)
3. [Pointed Sets](#)
4. [Tensor Products of Pointed Sets](#)

6. [Constructions With Relations](#)

7. [Equivalence Relations and Apartness Relations](#)

Category Theory

8. [Categories](#)

Relations

5. [Relations](#)

Bicategories

9. [Types of Morphisms in Bicategories](#)

References

- [GGN15] David Gepner, Moritz Groth, and Thomas Nikolaus. “Universality of Multiplicative Infinite Loop Space Machines”. In: *Algebr. Geom. Topol.* 15.6 (2015), pp. 3107–3153. ISSN: 1472-2747. DOI: [10.2140/agt.2015.15.3107](https://doi.org/10.2140/agt.2015.15.3107). URL: <https://doi.org/10.2140/agt.2015.15.3107> (cit. on p. 114).

- [PS19] Maximilien Péroux and Brooke Shipley. “Coalgebras in Symmetric Monoidal Categories of Spectra”. In: *Homology Homotopy Appl.* 21.1 (2019), pp. 1–18. ISSN: 1532-0073. DOI: [10.4310/HHA.2019.v21.n1.a1](https://doi.org/10.4310/HHA.2019.v21.n1.a1). URL: <https://doi.org/10.4310/HHA.2019.v21.n1.a1> (cit. on p. 115).