Pointed Sets

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This chapter contains some foundational material on pointed sets.

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1 Pointed Sets

1.1 Foundations

Definition 1.1.1.1. A **pointed set**¹ is equivalently

- An \mathbb{E}_0 -monoid in $(N_{\bullet}(\mathsf{Sets}), \mathrm{pt})$;
- A pointed object in (Sets, pt).

Remark 1.1.1.2. In detail, a **pointed set** is a pair (X, x_0) consisting of

- The Underlying Set. A set X, called the underlying set of (X, x_0) ;
- The Basepoint. A morphism

$$[x_0] \colon \mathrm{pt} \to X$$

in Sets, determining an element $x_0 \in X$, called the **basepoint of** X.

Example 1.1.1.3. The 0-sphere² is the pointed set $(S^0,0)^3$ consisting of

• The Underlying Set. The set S^0 defined by

$$S^0 \stackrel{\text{def}}{=} \{0, 1\};$$

• The Basepoint. The element 0 of S^0 .

Example 1.1.1.4. The **trivial pointed set** is the pointed set (pt, \star) consisting of

- The Underlying Set. The punctual set pt $\stackrel{\text{def}}{=} \{ \star \};$
- The Basepoint. The element \star of pt.

Example 1.1.1.5. The underlying pointed set of a semimodule (M, α_M) is the pointed set $(M, 0_M)$.

Example 1.1.1.6. The underlying pointed set of a module (M, α_M) is the pointed set $(M, 0_M)$.

¹ Further Terminology: Also called an \mathbb{F}_1 -module.

²Further Terminology: Also called the underlying pointed set of the field with one element.

³ Further Notation: Also denoted (\mathbb{F}_1 , 0).

1.2 Morphisms of Pointed Sets

Definition 1.2.1.1. A morphism of pointed sets⁴ is equivalently

- A morphism of \mathbb{E}_0 -monoids in $(N_{\bullet}(\mathsf{Sets}), \mathsf{pt})$.
- A morphism of pointed objects in (Sets, pt).

Remark 1.2.1.2. In detail, a morphism of pointed sets $f:(X,x_0) \to (Y,y_0)$ is a morphism of sets $f:X\to Y$ such that the diagram

$$\begin{array}{c|c}
pt \\
[x_0] & [y_0] \\
X & \xrightarrow{f} Y
\end{array}$$

commutes, i.e. such that

$$f(x_0) = y_0.$$

1.3 The Category of Pointed Sets

Definition 1.3.1.1. The **category of pointed sets** is the category Sets_* defined equivalently as

- The homotopy category of the ∞ -category $\mathsf{Mon}_{\mathbb{E}_0}(N_{\bullet}(\mathsf{Sets}), \mathsf{pt})$ of Monoids in Monoidal ∞ -Categories, $\ref{eq:total_point}$;
- The category Sets_{*} of Categories, ??.

Remark 1.3.1.2. In detail, the category of pointed sets is the category Sets_* where

- Objects. The objects of Sets* are pointed sets;
- Morphisms. The morphisms of Sets* are morphisms of pointed sets;
- Identities. For each $(X, x_0) \in \text{Obj}(\mathsf{Sets}_*)$, the unit map

$$\mathbb{F}^{\mathsf{Sets}_*}_{(X,x_0)} \colon \mathrm{pt} \to \mathsf{Sets}_*((X,x_0),(X,x_0))$$

of Sets_{*} at (X, x_0) is defined by⁵

$$id_{(X,x_0)}^{\mathsf{Sets}_*} \stackrel{\text{def}}{=} id_X;$$

⁴ Further Terminology: Also called a **pointed function** or a **morphism of** \mathbb{F}_1 **-modules**.

⁵Note that id_X is indeed a morphism of pointed sets, as we have $id_X(x_0) = x_0$.

• Composition. For each $(X, x_0), (Y, y_0), (Z, z_0) \in \text{Obj}(\mathsf{Sets}_*)$, the composition map

$$\circ^{\mathsf{Sets}_*}_{(X,x_0),(Y,y_0),(Z,z_0)} \colon \mathsf{Sets}_*((Y,y_0),(Z,z_0)) \times \mathsf{Sets}_*((X,x_0),(Y,y_0)) \to \mathsf{Sets}_*((X,x_0),(Z,z_0))$$

of Sets_* at $((X, x_0), (Y, y_0), (Z, z_0))$ is defined by

$$g \circ^{\mathsf{Sets}_*}_{(X,x_0),(Y,y_0),(Z,z_0)} f \stackrel{\text{def}}{=} g \circ f.$$

1.4 Elementary Properties of Pointed Sets

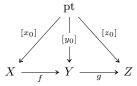
Proposition 1.4.1.1. Let (X, x_0) be a pointed set.

- 1. Completeness. The category Sets_{*} of pointed sets and morphisms between them is complete, having in particular products (Definition 2.1.1.1), pullbacks (Definition 2.3.1.1), and equalisers (Definition 2.2.1.1).
- 2. Cocompleteness. The category Sets_{*} of pointed sets and morphisms between them is cocomplete, having in particular coproducts (Definition 3.1.1.1), pushouts (Definition 3.2.1.1), and coequalisers (Definition 3.3.1.1).
- 3. Failure To Be Cartesian Closed. The category Sets* is not Cartesian closed.
- 4. Relation to Partial Functions. We have an equivalence of categories⁷

$$\mathsf{Sets}_* \stackrel{\mathrm{eq.}}{\cong} \mathsf{Sets}^{\mathrm{part.}}$$

$$g(f(x_0)) = g(y_0)$$
$$= z_0,$$

or



in terms of diagrams.

7 Warning: This is not an isomorphism of categories, only an equivalence.

 $^{^6}$ Note that the composition of two morphisms of pointed sets is indeed a morphism of pointed sets, as we have

between the category of pointed sets and pointed functions between them and the category of sets and partial functions between them.

Proof. Item 1, Completeness: Omitted.

Item 2, Cocompleteness: Omitted.

Item 3, Failure To Be Cartesian Closed: See [MSE2855868].

Item 4, Relation to Partial Functions: Omitted.

2 Limits of Pointed Sets

2.1 Products

Let (X, x_0) and (Y, y_0) be pointed sets.

Definition 2.1.1.1. The **product of** (X, x_0) **and** (Y, y_0) is the pointed set $(X \times Y, (x_0, y_0))$.

2.2 Equalisers

Let $f, g: (X, x_0) \rightrightarrows (Y, y_0)$ be morphisms of pointed sets.

Definition 2.2.1.1. The equaliser of (f, g) is the pointed set $(\text{Eq}_*(f, g), x_0)$ consisting of

• The Underlying Set. The set $Eq_*(f,g)$ defined by

$$\text{Eq}_*(f,g) \stackrel{\text{def}}{=} \{ x \in X \mid f(x) = y_0 = g(x) \};$$

• The Basepoint. The element x_0 of Eq_{*}(f,g).

2.3 Pullbacks

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets and let $f: (X, x_0) \to (Z, z_0)$ and $g: (Y, y_0) \to (Z, z_0)$ be morphisms of pointed sets.

Definition 2.3.1.1. The pullback of (X, x_0) and (Y, y_0) over (Z, z_0) along (f, g) is the pointed set $((X, x_0) \times_{(z, z_0)} (Y, y_0), p_0)$ consisting of

• The Underlying Set. The set $(X, x_0) \times_{(z,z_0)} (Y, y_0)$ defined by

$$(X, x_0) \times_{(z, z_0)} (Y, y_0) \stackrel{\text{def}}{=} \{(x, y) \in X \times Y \mid f(x) = z_0 = g(y)\};$$

• The Basepoint. The element (x_0, y_0) of $(X, x_0) \times_{(z, z_0)} (Y, y_0)$.

3 Colimits of Pointed Sets

3.1 Coproducts

Let (X, x_0) and (Y, y_0) be pointed sets.

Definition 3.1.1.1. The **coproduct of** (X, x_0) **and** (Y, y_0) is their wedge sum $(X \vee Y, p_0)$ of Definition 4.3.1.1.

3.2 Pushouts

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets and let $f: (Z, z_0) \to (X, x_0)$ and $g: (Z, z_0) \to (Y, y_0)$ be morphisms of pointed sets.

Definition 3.2.1.1. The pushout of (X, x_0) and (Y, y_0) over (Z, z_0) along (f, g) is the pointed set $(X \coprod_{f,Z,g} Y, p_0)$, where $p_0 = [x_0] = [y_0]$.

3.3 Coequalisers

Let $f, g: (X, x_0) \rightrightarrows (Y, y_0)$ be morphisms of pointed sets.

Definition 3.3.1.1. The **coequaliser of** (f, g) is the pointed set $(CoEq(f, g), x_0)$.

4 Constructions With Pointed Sets

4.1 Internal Homs

Let (X, x_0) and (Y, y_0) be pointed sets.

Definition 4.1.1.1. The pointed set of morphisms of pointed sets from (X, x_0) to (Y, y_0) is the pointed set $Sets_*(X, Y)$ consisting of

- The Underlying Set. The set $\mathbf{Sets}_*((X, x_0), (Y, y_0))$ of morphisms of pointed sets from (X, x_0) to (Y, y_0) ;
- The Basepoint. The element

$$\Delta_{y_0} \colon (X, x_0) \to (Y, y_0)$$

of $Sets_*((X, x_0), (Y, y_0)).$

4.2 Free Pointed Sets

Let X be a set.

Definition 4.2.1.1. The free pointed set on X is the pointed set X^+ consisting of

• The Underlying Set. The set X^+ defined by

$$X^+ \stackrel{\text{def}}{=} X \prod \text{pt};$$

• The Basepoint. The element \star of X^+ .

Proposition 4.2.1.2. Let X be a set.

1. Functoriality. The assignment $X \mapsto X^+$ defines a functor

$$(-)^+ \colon \mathsf{Sets} \to \mathsf{Sets}_*,$$

where

• Action on Objects. For each $X \in \text{Obj}(\mathsf{Sets})$, we have

$$[(-)^+](X) \stackrel{\text{def}}{=} X_+,$$

where X_{+} is the pointed set of Definition 4.2.1.1;

• Action on Morphisms. For each morphism $f \colon X \to Y$ of Sets, the image

$$f_+\colon X_+\to Y_+$$

of f by $(-)^+$ is the map of pointed sets defined by

$$f^+(x) \stackrel{\text{def}}{=} \begin{cases} f(x) & \text{if } x \in X, \\ \star & \text{if } x = \star. \end{cases}$$

2. Adjointness. We have an adjunction

$$((-)^+ \dashv \overline{\bowtie}): \operatorname{Sets}_{\underbrace{\bot}}^{(-)^+} \operatorname{Sets}_*,$$

witnessed by a bijection of sets

$$\mathsf{Sets}_*((X_+,\star),(Y,y_0)) \cong \mathsf{Sets}(X,Y),$$

natural in $X \in \text{Obj}(\mathsf{Sets})$ and $(Y, y_0) \in \text{Obj}(\mathsf{Sets}_*)$.

3. Symmetric Strong Monoidality With Respect to Wedge Sums. The free pointed set functor of Item 1 has a symmetric strong monoidal structure

$$\left((-)^+,(-)^{+,\coprod},(-)_{\not\Vdash}^{+,\coprod}\right)\colon(\mathsf{Sets},\coprod,\emptyset)\to(\mathsf{Sets}_*,\vee,\mathrm{pt}),$$

being equipped with isomorphisms of pointed sets

$$(-)_{X,Y}^{+,\coprod} \colon X^{+} \vee Y^{+} \xrightarrow{\cong} (X \coprod Y)^{+},$$
$$(-)_{\mathbb{F}}^{+,\coprod} \colon \operatorname{pt} \xrightarrow{\cong} \emptyset^{+},$$

natural in $X, Y \in \text{Obj}(\mathsf{Sets})$.

4. Symmetric Strong Monoidality With Respect to Smash Products. The free pointed set functor of Item 1 has a symmetric strong monoidal structure

$$\left((-)^+, (-)^{+,\times}, (-)^{+,\times}_{\not \vdash} \right) \colon (\mathsf{Sets}, \times, \mathsf{pt}) \to \left(\mathsf{Sets}_*, \wedge, S^0 \right),$$

being equipped with isomorphisms of pointed sets

$$(-)_{X,Y}^{+,\times} \colon X^+ \wedge Y^+ \xrightarrow{\cong} (X \times Y)^+,$$
$$(-)_{\mathbb{P}}^{+,\times} \colon S^0 \xrightarrow{\cong} \mathrm{pt}^+,$$

natural in $X, Y \in \text{Obj}(\mathsf{Sets})$.

Proof. Item 1, Functoriality: Clear.

Item 2, Adjointness: Clear.

Item 3, Symmetric Strong Monoidality With Respect to Wedge Sums: Omitted.

Item 4, Symmetric Strong Monoidality With Respect to Smash Products: Omitted. \Box

4.3 Wedge Sums of Pointed Sets

Let (X, x_0) and (Y, y_0) be pointed sets.

Definition 4.3.1.1. The wedge sum of X and Y is the pointed set $(X \vee Y, p_0)$ consisting of

• The Underlying Set. The set $X \vee Y$ defined by⁸

$$(X \lor Y, p_0) \stackrel{\text{def}}{=} (X, x_0) \coprod (Y, y_0) \qquad X \lor Y \longleftarrow Y$$

$$\cong (X \coprod_{\text{pt}} Y, p_0) \qquad \uparrow \qquad \uparrow \qquad \downarrow_{[y_0]}$$

$$\cong (X \coprod Y/\sim, p_0), \qquad X \longleftarrow_{[x_0]} \text{pt},$$

where \sim is the equivalence relation on $X \coprod Y$ given by $x_0 \sim y_0$;

• The Basepoint. The element p_0 of $X \vee Y$ defined by

$$p_0 \stackrel{\text{def}}{=} [x_0]$$
$$= [y_0].$$

Proposition 4.3.1.2. Let (X, x_0) and (Y, y_0) be pointed sets.

1. Functoriality. The assignments $(X, x_0), (Y, y_0), ((X, x_0), (Y, y_0)) \mapsto (X \vee Y, p_0)$ define functors

$$X \lor -: \mathsf{Sets}_* \to \mathsf{Sets}_*,$$

 $- \lor Y : \mathsf{Sets}_* \to \mathsf{Sets}_*,$
 $-_1 \lor -_2 : \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*.$

2. Associativity. We have an isomorphism of pointed sets

$$(X\vee Y)\vee Z\cong X\vee (Y\vee Z),$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in \mathsf{Sets}_*$.

3. Unitality. We have isomorphisms of pointed sets

$$\operatorname{pt} \vee X \cong X,$$

 $X \vee \operatorname{pt} \cong X,$

natural in $(X, x_0) \in \mathsf{Sets}_*$.

4. Commutativity. We have an isomorphism of pointed sets

$$X \vee Y \cong Y \vee X$$

natural in $(X, x_0), (Y, y_0) \in \mathsf{Sets}_*$.

⁸Here $(X, x_0) \coprod (Y, y_0)$ is the coproduct of (X, x_0) and (Y, y_0) in Sets_{*}.

- 5. Symmetric Monoidality. The triple ($\mathsf{Sets}_*, \vee, \mathsf{pt}$) is a symmetric monoidal category.
- 6. Symmetric Strong Monoidality With Respect to Free Pointed Sets. The free pointed set functor of Item 1 of Proposition 4.2.1.2 has a symmetric strong monoidal structure

$$\left((-)^+,(-)^{+,\coprod},(-)_{\hspace{-0.1cm}\not\hspace{0.1cm}\hspace{0.1cm}}^{+,\coprod}\right)\colon(\mathsf{Sets},\coprod,\emptyset)\to(\mathsf{Sets}_*,\vee,\mathrm{pt}),$$

being equipped with isomorphisms of pointed sets

$$(-)_{X,Y}^{+,\coprod} \colon X^{+} \vee Y^{+} \xrightarrow{\cong} (X \coprod Y)^{+},$$
$$(-)_{\mathbb{K}}^{+,\coprod} \colon \operatorname{pt} \xrightarrow{\cong} \emptyset^{+},$$

natural in $X, Y \in \text{Obj}(\mathsf{Sets})$.

7. The Fold Map. We have a natural transformation

$$\nabla\colon \vee\circ\Delta^{\mathsf{Cats}}_{\mathsf{Sets}_*}\Longrightarrow \mathrm{id}_{\mathsf{Sets}_*}, \qquad \stackrel{\Delta^{\mathsf{Cats}}_{\mathsf{Sets}_*}}{\underbrace{\Delta^{\mathsf{Cats}}_{\mathsf{Sets}_*}}} \bigvee_{\overset{\nabla}{\mathsf{V}}} \mathsf{Sets}_*,$$

called the **fold map**, whose component

$$\nabla_X : X \vee X \to X$$

at X is given by the composition

$$X \xrightarrow{\Delta_X} X \times X$$

$$\longrightarrow X \times X/\sim$$

$$\stackrel{\text{def}}{=} X \vee X.$$

Proof. Item 1, Functoriality: Omitted.

Item 2, Associativity: Omitted.

Item 3, Unitality: Omitted.

Item 4, Commutativity: Omitted.

Item 5, Symmetric Monoidality: Omitted.

Item 6, Symmetric Strong Monoidality With Respect to Free Pointed Sets: Omitted.

Item 7, The Fold Map: Omitted.

Appendices

Cubical Stuff

16. The Cube Category

A Other Chapters

A Other Chapters	
Set Theory	Globular Stuff
1. Sets	17. The Globe Category
2. Constructions With Sets	Cellular Stuff
3. Pointed Sets	18. The Cell Category
4. Tensor Products of Pointed Sets	Monoids
5. Indexed and Fibred Sets	19. Monoids
6. Relations	20. Constructions With Monoids
7. Spans	Monoids With Zero
8. Posets	21. Monoids With Zero
Category Theory	22. Constructions With Monoids With Zero
9. Categories	Groups
10. Constructions With Categories	23. Groups
11. Kan Extensions	24. Constructions With Groups
Bicategories	Hyper Algebra
12. Bicategories	25. Hypermonoids
13. Internal Adjunctions	26. Hypergroups
Internal Category Theory	27. Hypersemirings and Hyperrings
14. Internal Categories	28. Quantales
Cyclic Stuff	Near-Rings
15. The Cycle Category	29. Near-Semirings

30. Near-Rings

Real Analysis

- 31. Real Analysis in One Variable
- 32. Real Analysis in Several Variables

Measure Theory

- 33. Measurable Spaces
- 34. Measures and Integration

Probability Theory

34. Probability Theory

Stochastic Analysis

- 35. Stochastic Processes, Martingales, and Brownian Motion
- 36. Itô Calculus
- 37. Stochastic Differential Equations

Differential Geometry

38. Topological and Smooth Manifolds

Schemes

39. Schemes