Tensor Products of Pointed Sets

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008H This chapter contains some material on tensor products of pointed sets.

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008J 1 Bilinear Morphisms of Pointed Sets

008K 1.1 Left Bilinear Morphisms of Pointed Sets

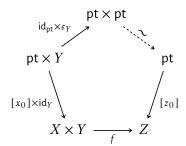
Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets.

OOSL Definition 1.1.1.1. A left bilinear morphism of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0) is a map of sets

$$f: (X \times Y, (x_0, y_0)) \rightarrow (Z, z_0)$$

satisfying the following condition:1,2

(★) Left Unital Bilinearity. The diagram



commutes, i.e. for each $y \in Y$, we have

$$f(x_0, y) = z_0.$$

Definition 1.1.1.2. The **set of left bilinear morphisms of pointed sets from** $(X \times Y, (x_0, y_0))$ **to** (Z, z_0) is the set $\mathsf{Hom}_{\mathsf{Sets}_*}^{\otimes, \mathsf{L}}(X \times Y, Z)$ defined by

$$\operatorname{Hom}_{\operatorname{\mathsf{Sets}}_*}^{\otimes, \mathsf{L}}(X\times Y,Z)\stackrel{\scriptscriptstyle\mathsf{def}}{=} \{f\in\operatorname{\mathsf{Sets}}_*(A\times B,C)\,|\, f \text{ is left bilinear}\}.$$

008N 1.2 Right Bilinear Morphisms of Pointed Sets

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets.

$$f(x_0, y) = z_0$$

 $^{^{1}}$ Slogan: f is left bilinear if it preserves basepoints in its first argument.

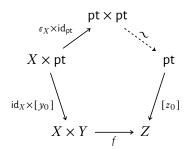
 $^{^{2}}$ Succinctly, f is bilinear if we have

OOSP Definition 1.2.1.1. A right bilinear morphism of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0) is a map of sets

$$f: (X \times Y, (x_0, y_0)) \rightarrow (Z, z_0)$$

satisfying the following condition:3,4

(★) Right Unital Bilinearity. The diagram



commutes, i.e. for each $x \in X$, we have

$$f(x, y_0) = z_0.$$

Definition 1.2.1.2. The **set of right bilinear morphisms of pointed sets from** $(X \times Y, (x_0, y_0))$ **to** (Z, z_0) is the set $\mathsf{Hom}_{\mathsf{Sets}_*}^{\otimes, \mathsf{R}}(X \times Y, Z)$ defined by

$$\mathsf{Hom}_{\mathsf{Sets}_*}^{\otimes,\mathsf{R}}(X\times Y,Z)\stackrel{\mathrm{def}}{=}\{f\in\mathsf{Sets}_*(A\times B,C)\ |\ f\text{ is right bilinear}\}.$$

008R 1.3 Bilinear Morphisms of Pointed Sets

Let (X, x_0) , (Y, y_0) , and (Z, z_0) be pointed sets.

OO8S Definition 1.3.1.1. A bilinear morphism of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0) is a map of sets

$$f: (X \times Y, (x_0, y_0)) \rightarrow (Z, z_0)$$

that is both left bilinear and right bilinear.

$$f(x, y_0) = z_0$$

for each $x \in X$.

for each $y \in Y$.

 $^{^3}$ Slogan: f is right bilinear if it preserves basepoints in its second argument.

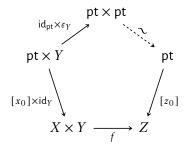
 $^{^4}$ Succinctly, f is bilinear if we have

Remark 1.3.1.2. In detail, a bilinear morphism of pointed sets from $(X \times Y, (x_0, y_0))$ to (Z, z_0) is a map of sets

$$f: (X \times Y, (x_0, y_0)) \rightarrow (Z, z_0)$$

satisfying the following conditions:5,6

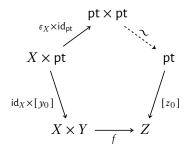
1. Left Unital Bilinearity. The diagram



commutes, i.e. for each $y \in Y$, we have

$$f(x_0, y) = z_0.$$

2. Right Unital Bilinearity. The diagram



commutes, i.e. for each $x \in X$, we have

$$f(x, y_0) = z_0.$$

Definition 1.3.1.3. The **set of bilinear morphisms of pointed sets from** $(X \times Y, (x_0, y_0))$ **to** (Z, z_0) is the set $\mathsf{Hom}_{\mathsf{Sets}_*}^{\otimes}(X \times Y, Z)$ defined by

$$\operatorname{Hom}_{\operatorname{\mathsf{Sets}}_*}^\otimes(X\times Y,Z)\stackrel{\operatorname{\scriptscriptstyle def}}{=}\{f\in\operatorname{\mathsf{Sets}}_*(A\times B,C)\,|\,f\text{ is bilinear}\}.$$

$$f(x_0, y) = z_0,$$

$$f(x, y_0) = z_0$$

⁵Slogan: f is bilinear if it preserves basepoints in each argument.

 $^{^6}$ Succinctly, f is bilinear if we have

2 Tensors and Cotensors of Pointed Sets by Sets

008W 2.1 Tensors of Pointed Sets by Sets

Let (X, x_0) be a pointed set and let A be a set.

- **Definition 2.1.1.1.** The **tensor of** (X, x_0) **by** A is the pointed set $A \odot (X, x_0)$ satisfying the following universal property:
 - (UP) We have a bijection

$$\mathsf{Sets}_*(A \odot X, K) \cong \mathsf{Sets}(A, \mathbf{Sets}_*(X, K)),$$

natural in $(K, k_0) \in Obj(Sets_*)$.

Remark 2.1.1.2. The tensor of (X, x_0) by A satisfies the following universal property:

$$\mathsf{Sets}_*(A \odot X, K) \cong \mathsf{Sets}^{\otimes}_{\mathbb{E}_0}(A \times X, K),$$

where $\mathsf{Sets}^{\otimes}_{\mathbb{E}_0}(A \times X, K)$ is the set defined by

$$\mathsf{Sets}_{\mathbb{B}_0}^{\otimes}(A\times X,K) \stackrel{\mathrm{def}}{=} \bigg\{ f \in \mathsf{Sets}(A\times X,K) \, \left| \, \begin{array}{l} \mathsf{for \ each} \ a \in A, \, \mathsf{we \ have} \\ f(a,x_0) = k_0 \end{array} \right\}.$$

- **Construction 2.1.1.3.** Concretely, the **tensor of** (X, x_0) **by** A is the pointed set $A \odot (X, x_0)$ consisting of
 - · The Underlying Set. The set $A \odot X$ given by

$$A \odot X \cong \bigvee_{a \in A} (X, x_0);$$

· The Basepoint. The point $[x_0]$ of $\bigvee_{a \in A} (X, x_0)$.

0090 2.2 Cotensors of Pointed Sets by Sets

Let (X, x_0) be a pointed set and let A be a set.

- **Definition 2.2.1.1.** The **cotensor of** (X, x_0) **by** A is the pointed set $A \cap (X, x_0)$ satisfying the following universal property:
 - (UP) We have a bijection

$$\mathsf{Sets}_*(K, A \pitchfork X) \cong \mathsf{Sets}(A, \mathbf{Sets}_*(K, X)),$$

natural in $(K, k_0) \in Obj(Sets_*)$.

Remark 2.2.1.2. The cotensor of (X, x_0) by A satisfies the following universal property:

$$\mathsf{Sets}_*(K, A \pitchfork X) \cong \mathsf{Sets}_{\mathbb{E}_0}^{\otimes}(A \times K, X),$$

where $\mathsf{Sets}^\otimes_{\mathbb{E}_0}(A \times K, X)$ is the set defined by

$$\mathsf{Sets}_{\mathbb{E}_0}^{\otimes}(A \times K, X) \stackrel{\mathrm{def}}{=} \bigg\{ f \in \mathsf{Sets}(A \times K, X) \, \bigg| \, \begin{array}{l} \mathsf{for \ each} \ a \in A, \, \mathsf{we \ have} \\ f(a, k_0) = x_0 \end{array} \bigg\}.$$

- **Construction 2.2.1.3.** Concretely, the **cotensor of** (X, x_0) **by** A is the pointed set $A \cap (X, x_0)$ consisting of
 - · The Underlying Set. The set $A \cap X$ given by

$$A \cap X \cong \bigwedge_{a \in A} (X, x_0);$$

· The Basepoint. The point $[(x_0, x_0, x_0, \ldots)]$ of $\bigwedge_{a \in A} (X, x_0)$.

3 The Left Tensor Product of Pointed Sets

0095 3.1 Foundations

Let (X, x_0) and (Y, y_0) be pointed sets.

Definition 3.1.1.1. The **left tensor product of pointed sets** is the functor

$$\triangleleft_{\mathsf{Sets}_*} : \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*$$

defined as the composition

$$\mathsf{Sets}_* \times \mathsf{Sets}_* \xrightarrow{\mathsf{id} \times \bar{\bowtie}} \mathsf{Sets}_* \times \mathsf{Sets} \xrightarrow{\beta_{\mathsf{Sets}_*}^{\mathsf{Cats}_2}} \mathsf{Sets} \times \mathsf{Sets}_* \xrightarrow{\odot} \mathsf{Sets}_*.$$

Remark 3.1.1.2. The left tensor product of pointed sets satisfies the following universal property:⁷

$$\mathsf{Sets}_* \big(X \lhd_{\mathsf{Sets}_*} Y, Z \big) \cong \mathsf{Hom}_{\mathsf{Sets}_*}^{\otimes, \mathsf{L}} (X \times Y, Z).$$

for each $x \in X$ and each $y \in Y$.

⁷Namely, a pointed map $f: X \triangleleft_{\mathsf{Sets}_*} Y \to Z$ is the same as a map $f^\dagger: X \times Y \to Z$ such that

$$f^{\dagger}(x_0, y) = z_0$$

for each $y \in Y$.

Remark 3.1.1.3. In detail, the **left tensor product of** (X, x_0) **and** (Y, y_0) is the pointed set $(X \triangleleft_{\mathsf{Sets}_*} Y, [x_0])$ consisting of⁸

· The Underlying Set. The set $X \triangleleft_{\mathsf{Sets}_*} Y$ defined by

$$X \lhd_{\mathsf{Sets}_*} Y \stackrel{\text{def}}{=} |Y| \odot X$$

$$\cong \bigvee_{y \in Y} (X, x_0);$$

· The Underlying Basepoint. The point $[x_0]$ of $\bigvee_{v \in Y} (X, x_0)$.

Proposition 3.1.1.4. Let (X, x_0) and (Y, y_0) be pointed sets.

1. Functoriality. The assignments $X, Y, (X, Y) \mapsto X \triangleleft_{\mathsf{Sets}_*} Y$ define functors

$$X \triangleleft_{\mathsf{Sets}_*} -: \mathsf{Sets}_* \to \mathsf{Sets}_*,$$
 $- \triangleleft_{\mathsf{Sets}_*} Y : \mathsf{Sets}_* \to \mathsf{Sets}_*,$
 $-_1 \triangleleft_{\mathsf{Sets}_*} -_2 : \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*.$

Proof. Item 1, Functoriality: Omitted.

009B 3.2 The Skew Associator

Definition 3.2.1.1. The **skew associator of the left tensor product of pointed sets** is the natural isomorphism

$$\alpha^{\mathsf{Sets}_*, \triangleleft} \colon \lhd_{\mathsf{Sets}_*} \circ (\lhd_{\mathsf{Sets}_*} \times \mathsf{id}_{\mathsf{Sets}_*}) \stackrel{\cong}{\Longrightarrow} \lhd_{\mathsf{Sets}_*} \circ (\mathsf{id}_{\mathsf{Sets}_*} \times \lhd_{\mathsf{Sets}_*}),$$

whose component

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*,\lhd} \colon \left(X \lhd_{\mathsf{Sets}_*} Y\right) \lhd_{\mathsf{Sets}_*} Z \xrightarrow{\cong} X \lhd_{\mathsf{Sets}_*} \left(Y \lhd_{\mathsf{Sets}_*} Z\right)$$

$$X \times Y \to \underbrace{X \triangleleft_{\mathsf{Sets}_*} Y}_{\cong \bigvee_{y \in Y} (X, x_0)}$$

sending (x, y) to the element $x \in X$ in the yth copy of X in $\bigvee_{y \in Y} (X, x_0)$. Note that we have

$$x_0 \triangleleft_{\mathsf{Sets}_*} y = x_0 \triangleleft_{\mathsf{Sets}_*} y',$$

for each $y, y' \in Y$.

⁸ Further Notation: We write $x \triangleleft_{Sets_*} y$ for the image of (x, y) under the map

at (X, Y, Z) is given by the composition⁹

$$\begin{array}{l} \left(X \lhd_{\mathsf{Sets}_*} Y\right) \lhd_{\mathsf{Sets}_*} Z \stackrel{\mathsf{def}}{=} |Z| \odot \left(X \lhd_{\mathsf{Sets}_*} Y\right) \\ \stackrel{\mathsf{def}}{=} |Z| \odot \left(|Y| \odot X\right) \\ \cong \bigvee_{z \in Z} \left(|Y| \odot X, [x_0]\right) \\ \stackrel{\mathsf{def}}{=} \bigvee_{z \in Z} \left(\bigvee_{y \in Y} (X, x_0)\right) \\ \cong \bigvee_{(z, y) \in \bigvee_{z \in Z} (Y, y_0)} (X, x_0) \\ \stackrel{\mathsf{def}}{=} \bigvee_{(z, y) \in |Z| \odot Y} (X, x_0) \\ \cong ||Z| \odot Y| \odot X \\ \stackrel{\mathsf{def}}{=} |Y \lhd_{\mathsf{Sets}_*} Z| \odot X \\ \stackrel{\mathsf{def}}{=} X \lhd_{\mathsf{Sets}_*} (Y \lhd_{\mathsf{Sets}_*} Z), \end{array}$$

where the isomorphism

$$\bigvee_{z \in Z} \left(\bigvee_{y \in Y} (X, x_0) \right) \cong \bigvee_{(y, z) \in \bigvee_{z \in Z} (Y, y_0)} (X, x_0)$$

is given by $[(z, (y, x))] \mapsto [((z, y), x)].$

009D 3.3 The Skew Left Unitor

Definition 3.3.1.1. The **skew left unitor of the left tensor product of pointed sets** is the natural transformation

whose component

$$\lambda_X^{\mathsf{Sets}_*, \lhd} \colon S^0 \lhd_{\mathsf{Sets}_*} X \to X$$

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*, \lhd} ((x \lhd_{\mathsf{Sets}_*} y) \lhd_{\mathsf{Sets}_*} z) \stackrel{\mathsf{def}}{=} x \lhd_{\mathsf{Sets}_*} (y \lhd_{\mathsf{Sets}_*} z)$$

 $\text{for each } \left(x \vartriangleleft_{\mathsf{Sets}_*} y\right) \vartriangleleft_{\mathsf{Sets}_*} z \in \left(X \vartriangleleft_{\mathsf{Sets}_*} Y\right) \vartriangleleft_{\mathsf{Sets}_*} Z.$

⁹In other words, $\alpha_{X,Y,Z}^{\mathsf{Sets}_*, \triangleleft}$ acts on elements as

at X is given by the composition 10

$$S^0 \triangleleft_{\mathsf{Sets}_*} X \cong |X| \odot S^0$$

$$\cong \bigvee_{x \in X} S^0$$

$$\to X$$

where $\bigvee_{x \in X} S^0 \to X$ is the map given by

$$(x,0) \mapsto x,$$

 $(x,1) \mapsto x.$

009F 3.4 The Skew Right Unitor

Definition 3.4.1.1. The **skew right unitor of the left tensor product of pointed sets** is the natural transformation

$$\rho^{\mathsf{Sets}_*, \lhd} \colon \mathsf{id}_{\mathsf{Sets}_*} \Longrightarrow \lhd_{\mathsf{Sets}_*} \circ \Big(\mathsf{id}_{\mathsf{Sets}_*} \times \mathbb{1}^{\mathsf{Sets}_*}\Big),$$

whose component

$$\rho_X^{\mathsf{Sets}_*, \triangleleft} \colon X \to X \triangleleft_{\mathsf{Sets}_*} S^0$$

at X is given by the composition¹¹

$$\begin{split} X &\to X \vee X \\ &\cong |S^0| \odot X \\ &\cong S^0 \lhd_{\mathsf{Sets}_*} X, \end{split}$$

where $X \to X \vee X$ is the map sending X to the first factor of X in $X \vee X$.

$$\lambda_X^{\mathsf{Sets}_*, \triangleleft} (x \triangleleft_{\mathsf{Sets}_*} 0) \stackrel{\mathsf{def}}{=} x, \\ \lambda_X^{\mathsf{Sets}_*, \triangleleft} (x \triangleleft_{\mathsf{Sets}_*} 1) \stackrel{\mathsf{def}}{=} x,$$

for each $x \in X$.

¹¹ In other words, $\rho_X^{\mathsf{Sets}_*, \triangleleft}$ acts on elements as

$$\rho_X^{\mathsf{Sets}_*, \triangleleft}(x) \stackrel{\mathsf{def}}{=} x \triangleleft_{\mathsf{Sets}_*} 0$$

for each $x \in X$.

 $^{^{10}}$ In other words, $\lambda_X^{\mathsf{Sets}_*, \lhd}$ acts on elements as

009H 3.5 The Left-Skew Monoidal Category Structure on Pointed Sets

Proposition 3.5.1.1. The category Sets* admits a left-skew monoidal category structure consisting of ¹²

· The Skew Monoidal Product. The left tensor product functor

$$\triangleleft_{\mathsf{Sets}_*} \colon \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*,$$

of Proposition 3.1.1.4;

· The Skew Monoidal Unit. The functor

$$\mathbb{1}^{\mathsf{Sets}_*} \colon \mathsf{pt} \to \mathsf{Sets}_*$$

defined by

$$\mathbb{F}_{\mathsf{Sets}_n} \stackrel{\mathsf{def}}{=} S^0$$
;

· The Skew Associators. The natural isomorphism

$$\alpha^{\mathsf{Sets}_*, \lhd} \colon \lhd_{\mathsf{Sets}_*} \circ \bigl(\lhd_{\mathsf{Sets}_*} \times \mathsf{id}_{\mathsf{Sets}_*} \bigr) \stackrel{\cong}{\Longrightarrow} \lhd_{\mathsf{Sets}_*} \circ \bigl(\mathsf{id}_{\mathsf{Sets}_*} \times \lhd_{\mathsf{Sets}_*} \bigr),$$

of Definition 3.2.1.1;

· The Skew Left Unitors. The natural transformation

$$\lambda^{\mathsf{Sets}_*, \lhd} \colon \lhd_{\mathsf{Sets}_*} \circ \left(\varkappa^{\mathsf{Sets}_*} \times \mathsf{id}_{\mathsf{Sets}_*} \right) \Longrightarrow \mathsf{id}_{\mathsf{Sets}_*},$$

of Definition 3.3.1.1;

· The Skew Right Unitors. The natural transformation

$$\rho^{\mathsf{Sets}_*, \triangleleft} \colon \mathsf{id}_{\mathsf{Sets}_*} \Longrightarrow \triangleleft_{\mathsf{Sets}_*} \circ \Big(\mathsf{id}_{\mathsf{Sets}_*} \times \mathbb{1}^{\mathsf{Sets}_*}\Big),$$

of Definition 3.4.1.1.

009K

Proof. Omitted.

4 The Right Tensor Product of Pointed Sets

¹²Note in particular that, differently from general left-skew monoidal categories, the skew associator of

009L 4.1 Foundations

Let (X, x_0) and (Y, y_0) be pointed sets.

Definition 4.1.1.1. The **right tensor product of pointed sets** is the functor

$$\triangleright_{\mathsf{Sets}_*} : \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*$$

defined as the composition

$$\mathsf{Sets}_* \times \mathsf{Sets}_* \xrightarrow{\overline{\bowtie} \times \mathsf{id}} \mathsf{Sets} \times \mathsf{Sets}_* \xrightarrow{\odot} \mathsf{Sets}_*.$$

Remark 4.1.1.2. The right tensor product of pointed sets satisfies the following universal property:¹³

$$\mathsf{Sets}_* \big(X \rhd_{\mathsf{Sets}_*} Y, Z \big) \cong \mathsf{Hom}_{\mathsf{Sets}_*}^{\otimes, \mathsf{R}} (X \times Y, Z).$$

- **Remark 4.1.1.3.** In detail, the **right tensor product of** (X, x_0) **and** (Y, y_0) is the pointed set $(X \triangleright_{\mathsf{Sets}_*} Y, [y_0])$ consisting of ¹⁴
 - · The Underlying Set. The set $X \triangleright_{\mathsf{Sets}_*} Y$ defined by

$$X \rhd_{\mathsf{Sets}_*} Y \stackrel{\text{def}}{=} |X| \odot Y$$

$$\cong \bigvee_{x \in X} (Y, y_0);$$

- · The Underlying Basepoint. The point $[y_0]$ of $\bigvee_{x \in X} (Y, y_0)$.
- **Proposition 4.1.1.4.** Let (X, x_0) and (Y, y_0) be pointed sets.

 $\left(\mathsf{Sets}_*, \lhd_{\mathsf{Sets}_*}, S^0 \right)$ is a natural isomorphism.

¹³Namely, a pointed map $f: X \triangleleft_{\mathsf{Sets}_n} Y \to Z$ is the same as a map $f^{\dagger}: X \times Y \to Z$ such that

$$f^{\dagger}(x, y_0) = z_0$$

for each $y \in Y$.

¹⁴ Further Notation: We write $x \triangleright_{\mathsf{Sets}_*} y$ for the image of (x, y) under the map

$$X\times Y\to \underbrace{X\rhd_{\mathsf{Sets}_*}Y}_{\cong\bigvee_{x\in X}(Y,y_0)}.$$

sending (x, y) to the element $y \in Y$ in the xth copy of Y in $\bigvee_{x \in X} (Y, y_0)$. Note that we have

$$x \rhd_{\mathsf{Sets}_*} y_0 = x' \rhd_{\mathsf{Sets}_*} y_0$$
,

for each $x, x' \in X$.

009R 1. Functoriality. The assignments $X, Y, (X, Y) \mapsto X \triangleright_{\mathsf{Sets}_*} Y$ define functors

$$X \rhd_{\mathsf{Sets}_*} -: \mathsf{Sets}_* \to \mathsf{Sets}_*,$$

 $- \rhd_{\mathsf{Sets}_*} Y : \mathsf{Sets}_* \to \mathsf{Sets}_*,$
 $-_1 \rhd_{\mathsf{Sets}_*} -_2 : \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*.$

Proof. Item 1, Functoriality: Omitted.

009S 4.2 The Skew Associator

Definition 4.2.1.1. The **skew associator of the right tensor product of pointed sets** is the natural isomorphism

$$\alpha^{\mathsf{Sets}_*, \rhd} \colon \rhd_{\mathsf{Sets}_*} \circ (\mathsf{id}_{\mathsf{Sets}_*} \times \rhd_{\mathsf{Sets}_*}) \stackrel{\cong}{\Longrightarrow} \rhd_{\mathsf{Sets}_*} \circ (\rhd_{\mathsf{Sets}_*} \times \mathsf{id}_{\mathsf{Sets}_*}),$$

whose component

$$\alpha_{XYZ}^{\mathsf{Sets}_*, \triangleright} : X \rhd_{\mathsf{Sets}_*} (Y \rhd_{\mathsf{Sets}_*} Z) \xrightarrow{\cong} (X \rhd_{\mathsf{Sets}_*} Y) \rhd_{\mathsf{Sets}_*} Z$$

at (X, Y, Z) is given by the composition¹⁵

$$\begin{split} X \rhd_{\mathsf{Sets}_*} & \left(Y \rhd_{\mathsf{Sets}_*} Z \right) \stackrel{\text{def}}{=} |X| \odot \left(Y \rhd_{\mathsf{Sets}_*} Z \right) \\ \stackrel{\text{def}}{=} |X| \odot \left(|Y| \odot Z \right) \\ & \cong |X| \odot \left(\bigvee_{y \in Y} (Z, z_0) \right) \\ & \cong \bigvee_{x \in X} \left(\bigvee_{y \in Y} (Z, z_0) \right) \\ & \cong \bigvee_{(x,y) \in \bigvee_{x \in X} (Y, y_0)} \left(Z, z_0 \right) \\ & \cong \left| \bigvee_{x \in X} (Y, y_0) \right| \odot Z \\ \stackrel{\text{def}}{=} |X \odot Y| \odot Z \\ \stackrel{\text{def}}{=} |X \rhd_{\mathsf{Sets}_*} Y| \odot Z \\ \stackrel{\text{def}}{=} (X \rhd_{\mathsf{Sets}_*} Y) \rhd_{\mathsf{Sets}_*} Z \end{split}$$

$$\alpha_{X,Y,Z}^{\mathsf{Sets}_*, \vdash} (x \rhd_{\mathsf{Sets}_*} (y \rhd_{\mathsf{Sets}_*} z)) \stackrel{\mathsf{def}}{=} (x \rhd_{\mathsf{Sets}_*} y) \rhd_{\mathsf{Sets}_*} z$$

¹⁵In other words, $\alpha_{X,Y,Z}^{\mathsf{Sets}_*,\triangleright}$ acts on elements as

where the isomorphism

$$\bigvee_{x \in X} \left(\bigvee_{y \in Y} (Z, z_0) \right) \cong \bigvee_{(x,y) \in \bigvee_{x \in X} (Y, y_0)} (Z, z_0)$$

is given by $[(x, (y, z))] \mapsto [((x, y), z)].$

009U 4.3 The Skew Left Unitor

Definition 4.3.1.1. The **skew left unitor of the right tensor product of pointed sets** is the natural transformation

$$\lambda^{\mathsf{Sets}_*, \triangleright} \colon \mathsf{id}_{\mathsf{Sets}_*} \Longrightarrow \rhd_{\mathsf{Sets}_*} \circ \Big({ { \hspace{-.6mm} \not \hspace{-.6mm} \hspace{-.6mm} }}^{\mathsf{Sets}_*} \times \mathsf{id}_{\mathsf{Sets}_*} \Big),$$

whose component

$$\lambda_X^{\mathsf{Sets}_*, \triangleright} \colon X \to S^0 \rhd_{\mathsf{Sets}_*} X$$

at X is given by the composition 16

$$X \to X \lor X$$

$$\cong |S^0| \odot X$$

$$\cong S^0 \rhd_{\mathsf{Sets}_n} X,$$

where $X \to X \vee X$ is the map sending X to the first factor of X in $X \vee X$.

009W 4.4 The Skew Right Unitor

Definition 4.4.1.1. The **skew right unitor of the right tensor product of pointed sets** is the natural transformation

$$\rho^{\mathsf{Sets}_*, \triangleright} : \rhd_{\mathsf{Sets}_*} \circ \left(\mathsf{id}_{\mathsf{Sets}_*} \times \mathbb{1}^{\mathsf{Sets}_*}\right) \Longrightarrow \mathsf{id}_{\mathsf{Sets}_*},$$

 $\begin{array}{c} \text{for each } x \rhd_{\mathsf{Sets}_*} \big(y \rhd_{\mathsf{Sets}_*} z \big) \in X \rhd_{\mathsf{Sets}_*} \big(Y \rhd_{\mathsf{Sets}_*} Z \big). \\ \\ {}^{16} \text{In other words, } \lambda_X^{\mathsf{Sets}_*, \rhd} \text{ acts on elements as} \end{array}$

$$\lambda_X^{\mathsf{Sets}_*, \triangleright}(x) \stackrel{\mathsf{def}}{=} 0 \triangleright_{\mathsf{Sets}_*} x$$

for each $x \in X$.

whose component¹⁷

$$\rho_X^{\mathsf{Sets}_*, \triangleright} : X \rhd_{\mathsf{Sets}_*} S^0 \to X$$

at X is given by the composition

$$\begin{split} X \rhd_{\mathsf{Sets}_*} S^0 &\cong |X| \odot S^0 \\ &\cong \bigvee_{x \in X} S^0 \\ &\to X \end{split}$$

where $\bigvee_{x \in X} S^0 \to X$ is the map given by

$$(x,0)\mapsto x$$
,

$$(x,1) \mapsto x$$
.

009Y 4.5 The Right-Skew Monoidal Category Structure on Pointed Sets

Proposition 4.5.1.1. The category Sets* admits a right-skew monoidal category structure consisting of ¹⁸

· The Skew Monoidal Product. The right tensor product functor

$$\triangleright_{\mathsf{Sets}_*} : \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*,$$

of Item 1;

· The Skew Monoidal Unit. The functor

$$\mathbb{1}^{\mathsf{Sets}_*} \colon \mathsf{pt} \to \mathsf{Sets}_*$$

defined by

$$\mathbb{F}_{\mathsf{Sets}_*} \stackrel{\mathsf{def}}{=} S^0;$$

$$\rho_{X}^{\mathsf{Sets}_*, \triangleright} (x \rhd_{\mathsf{Sets}_*} 0) \stackrel{\text{def}}{=} x,$$

$$\rho_{X}^{\mathsf{Sets}_*, \triangleright} (x \rhd_{\mathsf{Sets}_*} 1) \stackrel{\text{def}}{=} x$$

for each $x \in X$.

¹⁸ Note in particular that, differently from general right-skew monoidal categories, the skew associator of $(Sets_*, \triangleright_{Sets_*}, S^0)$ is a natural isomorphism.

¹⁷In other words, $\rho_X^{\mathsf{Sets}_*, \triangleright}$ acts on elements as

· The Skew Associators. The natural isomorphism

$$\alpha^{\mathsf{Sets}_*, \rhd} \colon \rhd_{\mathsf{Sets}_*} \circ (\rhd_{\mathsf{Sets}_*} \times \mathsf{id}_{\mathsf{Sets}_*}) \stackrel{\cong}{\Longrightarrow} \rhd_{\mathsf{Sets}_*} \circ (\mathsf{id}_{\mathsf{Sets}_*} \times \rhd_{\mathsf{Sets}_*}),$$

of Definition 4.2.1.1;

· The Skew Left Unitors. The natural transformation

$$\lambda^{\mathsf{Sets}_*, \triangleright} \colon \mathsf{id}_{\mathsf{Sets}_*} \Longrightarrow \rhd_{\mathsf{Sets}_*} \circ \Big(\varkappa^{\mathsf{Sets}_*} \times \mathsf{id}_{\mathsf{Sets}_*} \Big),$$

of Definition 3.3.1.1;

· The Skew Right Unitors. The natural transformation

$$\rho^{\mathsf{Sets}_*, \bowtie} : \rhd_{\mathsf{Sets}_*} \circ \left(\mathsf{id}_{\mathsf{Sets}_*} \times \mathbb{1}^{\mathsf{Sets}_*}\right) \Longrightarrow \mathsf{id}_{\mathsf{Sets}_*},$$

of Definition 3.4.1.1.

Proof. Omitted.

90A0 5 Smash Products of Pointed Sets

00A1 5.1 Foundations

Let (X, x_0) and (Y, y_0) be pointed sets.

Definition 5.1.1.1. The **smash product of** (X, x_0) **and** $(Y, y_0)^{19}$ is the pointed set $X \wedge Y^{20}$ such that we have a bijection

$$\mathsf{Sets}_*(X \wedge Y, Z) \cong \mathsf{Hom}_{\mathsf{Sets}_*}^{\otimes}(X \times Y, Z),$$

natural in (X, x_0) , (Y, y_0) , $(Z, z_0) \in Obj(Sets_*)$.

- **Remark 5.1.1.2.** In detail, the **smash product of** (X, x_0) **and** (Y, y_0) is the pair $((X \land Y, [(x_0, y_0)]), \iota)$ consisting of
 - · A pointed set $(X \wedge Y, [(x_0, y_0)])$;
 - · A bilinear morphism of pointed sets $\iota: (X \times Y, (x_0, y_0)) \to X \wedge Y$;

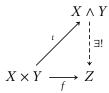
satisfying the following universal property:

¹⁹ Further Terminology: Also called the **tensor product of** \mathbb{F}_1 -modules of (X, x_0) and (Y, y_0) or the **tensor product of** (X, x_0) and (Y, y_0) over \mathbb{F}_1 .

²⁰ Further Notation: Also written $X \otimes_{\mathbb{F}_1} Y$.

- (UP) Given another such pair $((Z, z_0), f)$ consisting of
 - A pointed set (Z, z_0) ;
 - A bilinear morphism of pointed sets $f: (X \times Y, (x_0, y_0)) \to X \wedge Y$;

there exists a unique morphism of pointed sets $X \wedge Y \xrightarrow{\exists !} Z$ making the diagram



commute.

Construction 5.1.1.3. Concretely, the **smash product of** (X, x_0) **and** (Y, y_0) is the pointed set $(X \wedge Y, [(x_0, y_0)])$ consisting of²¹

· The Underlying Set. The set $X \wedge Y$ defined by

where \sim is the equivalence relation of $X \times Y$ obtained by declaring $(x, y) \sim (x', y')$ iff $(x, y), (x', y') \in X \vee Y$, i.e. by declaring

$$(x_0, y) \sim (x_0, y'),$$

 $(x, y_0) \sim (x', y_0)$

for all $x \in X$ and all $y \in Y$;

$$X \times Y \twoheadrightarrow \underbrace{\frac{X \times Y}{X \vee Y}}_{\stackrel{\text{def}}{=} X \wedge Y}$$

Note that we have

$$x \wedge y_0 = x' \wedge y_0,$$

 $x_0 \wedge y = x_0 \wedge y'$

²¹ Further Notation: We write $x \wedge y$ for the image of (x, y) under the quotient map

• The Basepoint. The element $[(x_0, y_0)]$ of $X \wedge Y$ given by the equivalence class of (x_0, y_0) under the equivalence relation \sim on $X \times Y$.

Proof. Clear.

- **Example 5.1.1.4.** Here are some examples of smash products of pointed sets.
 - 1. Smashing With S^0 . For any pointed set X, we have isomorphisms of pointed sets

$$S^0 \wedge X \cong X$$
,
 $X \wedge S^0 \cong X$.

- **Proposition 5.1.1.5.** Let (X, x_0) and (Y, y_0) be pointed sets.
- 00A7 1. Functoriality. The assignments $(X, x_0), (Y, y_0), ((X, x_0), (Y, y_0)) \mapsto X \wedge Y$ define functors

$$X \land -: \mathsf{Sets}_* \to \mathsf{Sets}_*,$$

 $- \land Y : \mathsf{Sets}_* \to \mathsf{Sets}_*,$
 $-_1 \land -_2 : \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*.$

00A8 2. Adjointness. We have adjunctions

$$(X \land - \dashv \mathbf{Sets}_*(X, -)) : \quad \mathsf{Sets}_* \underbrace{\bot}_{X \land -} \mathsf{Sets}_*,$$

$$(- \land Y \dashv \mathbf{Sets}_*(Y, -)) : \quad \mathsf{Sets}_* \underbrace{\bot}_{\bot} \mathsf{Sets}_*,$$

$$\mathsf{Sets}_*(Y, -)$$

witnessed by bijections

$$\begin{split} \mathsf{Sets}_*(X \wedge Y, Z) &\cong \mathsf{Sets}_*(X, \mathbf{Sets}_*(Y, Z)), \\ \mathsf{Sets}_*(X \wedge Y, Z) &\cong \mathsf{Sets}_*(X, \mathbf{Sets}_*(A, Z)), \end{split}$$

natural in (X, x_0) , (Y, y_0) , $(Z, z_0) \in Obj(Sets_*)$, which internalise to isomorphisms of pointed sets

$$\mathsf{Sets}_*(X \land Y, Z) \cong \mathsf{Sets}_*(X, \mathsf{Sets}_*(Y, Z)),$$

 $\mathsf{Sets}_*(X \land Y, Z) \cong \mathsf{Sets}_*(X, \mathsf{Sets}_*(A, Z)),$

again natural in (X, x_0) , (Y, y_0) , $(Z, z_0) \in Obj(Sets_*)$.

OOA9 3. Closed Symmetric Monoidality. The quadruple (Sets_{*}, \wedge , S^0 , **Sets**_{*}) is a closed symmetric monoidal category.

4. Morphisms From the Monoidal Unit. We have a bijection of sets²²

$$\mathsf{Sets}_* \left(S^0, X \right) \cong X,$$

natural in $(X, x_0) \in \mathsf{Obj}(\mathsf{Sets}_*)$, internalising also to an isomorphism of pointed sets

$$\mathbf{Sets}_*\Big(S^0,X\Big)\cong (X,x_0),$$

again natural in $(X, x_0) \in \mathsf{Obj}(\mathsf{Sets}_*)$.

5. Symmetric Strong Monoidality With Respect to Free Pointed Sets. The free pointed set functor of Pointed Sets, Item 1 of Proposition 4.2.1.2 has a symmetric strong monoidal structure

$$\left((-)^+,(-)^{+,\times},(-)^{+,\times}_{\mathbb{F}}\right)\colon (\mathsf{Sets},\times,\mathsf{pt}) \to \left(\mathsf{Sets}_*,\wedge,S^0\right)\!,$$

being equipped with isomorphisms of pointed sets

$$(-)_{X,Y}^{+,\times} \colon X^{+} \wedge Y^{+} \xrightarrow{\cong} (X \times Y)^{+},$$
$$(-)_{\mathbb{F}}^{+,\times} \colon S^{0} \xrightarrow{\cong} \mathsf{pt}^{+},$$

natural in $X, Y \in Obj(Sets)$.

6. Distributivity Over Wedge Sums. We have isomorphisms of pointed sets

$$X \wedge (Y \vee Z) \cong (X \wedge Y) \vee (X \wedge Z),$$

$$(X \vee Y) \wedge Z \cong (X \wedge Z) \vee (Y \wedge Z),$$

natural in $(X, x_0), (Y, y_0), (Z, z_0) \in Obj(Sets_*).$

7. Universal Property I. The symmetric monoidal structure on the category Sets* is uniquely determined by the following requirements:

defined on objects by sending a pointed set to its underlying set is corepresentable by S^0 .

for each $x, x' \in X$ and each $y, y' \in Y$.

²²In other words, the forgetful functor

(a) Two-Sided Preservation of Colimits. The smash product

$$\land \colon \mathsf{Sets}_* \times \mathsf{Sets}_* \to \mathsf{Sets}_*$$

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of Sets* preserves colimits separately in each variable.

- (b) The Unit Object Is S^0 . We have $\mathbb{1}_{\mathsf{Sets}_*} = S^0$.
- 00AE 8. Universal Property II. The symmetric monoidal structure on the category Sets* is the unique symmetric monoidal structure on Sets* such that the free pointed set functor

$$(-)^+$$
: Sets \rightarrow Sets_{*}

admits a symmetric monoidal structure.

- 9. Existence of Monoidal Diagonals. The triple (Sets $_*$, \wedge , S^0) is a monoidal category with diagonals:
 - (a) Monoidal Diagonals. The natural transformation

$$\Delta \colon \mathsf{id}_{\mathsf{Sets}_*} \Longrightarrow \wedge \circ \Delta^{\mathsf{Cats}_2}_{\mathsf{Sets}_*}, \qquad \begin{matrix} \mathsf{id}_{\mathsf{Sets}_*} \\ & & \downarrow \\ \Delta \\ & & \downarrow \\ \Delta \\ \mathsf{Sets}_* \\ \mathsf{Sets}_* \\ \mathsf{Sets}_* \\ \mathsf{Sets}_* \\ \mathsf{Sets}_*, \end{matrix}$$

whose component

$$\Delta_X \colon (X, x_0) \to (X \land X, [(x_0, x_0)])$$

at $(X, x_0) \in \mathsf{Obj}(\mathsf{Sets}_*)$ is given by the composition

$$(X, x_0) \xrightarrow{\Delta_X} (X \times X, (x_0, x_0))$$

$$\longrightarrow (\frac{X \times X}{X \vee X}, [(x_0, x_0)])$$

$$\stackrel{\text{def}}{=} (X \wedge X, [(x_0, x_0)])$$

in Sets*, is a monoidal natural transformation:

i. Naturality. For each morphism $f: X \to Y$ of pointed sets, the diagram

$$X \xrightarrow{f} Y$$

$$\downarrow^{\Delta_X} \downarrow \qquad \downarrow^{\Delta_Y}$$

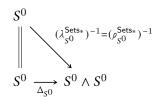
$$X \wedge X \xrightarrow{f \wedge f} Y \wedge Y$$

commutes.

ii. Compatibility With Strong Monoidality Constraints. For each (X, x_0) , $(Y, y_0) \in Obj(Sets_*)$, the diagram

commutes.

iii. Compatibility With Strong Unitality Constraints. The diagram



commutes.

(b) The Diagonal of the Unit. The component

$$\Delta_{S^0}^{\mathsf{Sets}_*} \colon S^0 \xrightarrow{\cong} S^0 \wedge S^0$$

of the diagonal natural transformation of Sets_* at S^0 is an isomorphism.

00AG 10. Comonoids in Sets*. The symmetric monoidal functor

$$((-)^+, (-)^{+,\times}, (-)^{+,\times}_{\mathbb{F}}) : (\mathsf{Sets}, \times, \mathsf{pt}) \to (\mathsf{Sets}_*, \wedge, S^0),$$

of Pointed Sets, Item 4 of Proposition 4.2.1.2 lifts to an equivalence of categories

$$\mathsf{CoMon}\Big(\mathsf{Sets}_*, \wedge, S^0\Big) \stackrel{\mathrm{eq.}}{\cong} \mathsf{CoMon}(\mathsf{Sets}, \times, \mathsf{pt})$$

 $\cong \mathsf{Sets}.$

Proof. Item 1, Functoriality: Omitted.

Item 2, Adjointness: Omitted.

Item 3, Closed Symmetric Monoidality: Omitted.

Item 4, Morphisms From the Monoidal Unit: Omitted.

Item 5, Symmetric Strong Monoidality With Respect to Free Pointed Sets: Omitted.

Item 6, Distributivity Over Wedge Sums: This follows from Item 3, Monoidal Categories, ?? of ??, and the fact that \lor is the coproduct in Sets_{*}.

Item 7, Universal Property I: Omitted.

Item 8, *Universal Property II*: See [GGN15, Theorem 5.1].

Item 9, Existence of Monoidal Diagonals: Omitted.

Item 10, Comonoids in Sets*: See [PS19, Lemma 2.4].

Appendices

A Other Chapters

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- 12. Bicategories
- 13. Internal Adjunctions

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15. The Cycle Category

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16. The Cube Category

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17. The Globe Category

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- 19. Monoids
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Monoids With Zero

- 21. Monoids With Zero
- 22. Constructions With Monoids With Zero

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- 23. Groups
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