

Experimental setup

WRF configurations

Torgeir Blæsterdalen

Department of Industrial Engineering, UiT-The Arctic University of Norway

March 20, 2018

Lecture topics

- ① Dynamical solvers
- ② Map projections
- ③ Namelist.wps (example)
- ④ Numerics: Numerics: diffusion, damping and advection
- ⑤ Physics parametrization schemes
- ⑥ Namelist.input (example)
- ⑦ Super-short on supercomputing
- ⑧ Interactive jobs and jobscripts

1. Dynamic solvers I

The WRF Software Framework (WSF) is a infrastructure that contains the WRF dynamical solver, physical packages and their interface to the solver. The two available solvers are the Advances Research WRF (ARW) and the Nonhydrostatic Mesoscale Model (NMM). The dynamic solver is the key component of the modeling system. The ARW solver is primarily developed at the National Center of Atmospheric Research (NCAR), and the NMM is primarily developed at the National Centers for Environmental Prediction (NCEP).

Some remarks on the comparisons between the cores

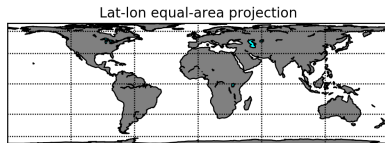
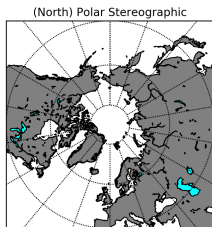
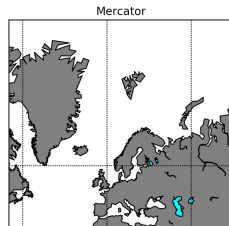
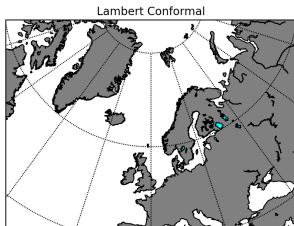
- Bernardet et al. aimed at determining the inter-core differences between the ARW and the NMM cores. They concluded that with their setup, there were no statistically significant difference between the cores.
- The physics packages are largely shared by both ARW and NMM, but there are some schemes that are only compatible with either the ARW or the NMM solver.

1. Dynamic solvers II

- ARW allows two-way nesting and a flexible ratio of the domains, meaning that the ratio between the domains can be chosen freely [Skamarock et al., 2008].

2. Map projections

The ARW solver supports four map projections



According to the ARW user's guide [Wang et al., 2013] the projections are well suited for:

Polar stereographic	High latitudes. Isotropic.
Lambert conformal	Conformal and isotropic, meaning that shapes are preserved, but not areas. Suited for mid-latitudes
Mercator	A cylindrical projection. Suited for low latitudes.
Longitude-latitude	Required for global WRF simulations. Area preserved, but not shapes.

3. Namelist.wps (example) I

Full description on http://www2.mmm.ucar.edu/wrf/users/docs/user_guide_V3/users_guide_chap3.htm#_Description_of_the_1

```
&share
wrf_core = 'ARW',
max_dom = 3,
start_date =
    '2014-01-01_00:00:00','2014-01-01_00:00:00','2014-01-01_00:00:00'
end_date =
    '2014-01-31_00:00:00','2014-01-31_00:00:00','2014-01-31_00:00:00'
interval_seconds = 21600
io_form_geogrid = 2,
/
&geogrid
parent_id      = 1, 1, 2,
parent_grid_ratio = 1, 3, 3,
i_parent_start  = 1, 25, 30,
```

3. Namelist.wps (example) II

```
j_parent_start = 1, 25, 30,  
e_we          = 100, 151, 301,  
e_sn          = 100, 151, 301,  
geog_data_res = '2m', '30s', '30s',  
dx = 18000,  
dy = 18000,  
map_proj = 'polar',  
ref_lat  = 69.1867,  
ref_lon  = 20.6804,  
truelat1 = 69.0,  
stand_lon = 20.0,  
geog_data_path = '/home/WRF/WPS_GEOG/'  
/  
&ungrib  
out_format = 'WPS',  
prefix = 'Rieppi_Jan',  
/
```


3. Namelist.wps (example) III

```
&metgrid  
fg_name = 'Rieppi_Jan'  
io_form_metgrid = 2,  
/
```

4. Numerics: diffusion, damping and advection

- Time-integration scheme option
 - ▶ Leapfrog
 - ▶ 2nd order Runge-Kutta
 - ▶ 3rd order Runge-Kutta
- Advection schemes: 2nd-6th order
- Turbulence and mixing option
- Eddy coefficient option
- Vertical damping

And many more. For the full list of diffusion, damping and advection options, go to https://esrl.noaa.gov/gsd/wrfportal/namelist_input_options.html

[//esrl.noaa.gov/gsd/wrfportal/namelist_input_options.html](https://esrl.noaa.gov/gsd/wrfportal/namelist_input_options.html)

5. Physics parameterization schemes I

- **Microphysics:** Handles water vapour, ice-phases, cloud and precipitation processes. Mixed-phase schemes should be used at grid sizes less than 10 km, especially in terrains where there are much convection or icing. Mixed-phase are computational expensive and should not be used for coarse simulation domains.
- **Cumulus parameterization:** Handles sub-grid-scale effects of convective and/or shallow clouds. These schemes are only valid for grid sizes larger than 10 km because of the spatial resolution needed to release latent heat from the fluid columns at the WRF grids.
- **Radiation:** Atmospheric heating from direct and diffuse radiation from the Sun and ground. In the WRF model, there are two types of radiation: shortwave and longwave. The only source of shortwave radiation is the Sun, including absorption, reflection and scattering of the molecules in the atmosphere. Longwave radiation includes thermal and infrared radiation emitted or absorbed by the gasses in the atmosphere or the ground.

5. Physics parameterization schemes II

- **Surface layer (SL):** Calculates friction velocity at the model surface. Calculates for example surface heat, surface stress and moisture fluxes.
- **Land-surface model (LSM):** Uses the calculations from the SL scheme, radiation from the radiation scheme and precipitation from the Microphysics scheme and merges these schemes along with the land's state variables, land-surface properties and calculates moisture fluxes over land and sea ice. This model handles lower boundary conditions for the vertical transport of for example thermal and moisture fluxes at the surface to the Planetary boundary layer. Vegetation, root and canopy effects are handled in the LSM model, as well as surface snow and ice conditions, soil moisture profile.

5. Physics parameterization schemes III

- **Planetary boundary layer (PBL):** The lowest part of the atmosphere is known as the planetary boundary layer (PBL) or the atmospheric boundary layer. The PBL is extending from the ground surface to the so-called "free atmosphere" where the wind is at *geostrophic balance*. The PBL schemes were developed for improved modelling the fluxes of heat, moisture and momentum in the atmosphere [Deppe et al., 2013] and the accurate representation of meteorological condition at typical wind turbine heights depends on the correct parameterization scheme for the PBL. Balzarini et al. [2014] argues that PBL parameters are one of the most uncertain parameters in model estimates.

The PBL schemes handles the vertical sub-grid-scale fluxes due to eddy transports in the atmospheric column. The surface fluxes are provided by the SL and LSM schemes. There are two types of available PBL parameterization schemes, namely first order closure schemes and turbulent kinetic energy closure schemes.

6. Namelist.input (example) I

More thorough description at https://esrl.noaa.gov/gsd/wrfportal/namelist_input_options.html

[//esrl.noaa.gov/gsd/wrfportal/namelist_input_options.html](https://esrl.noaa.gov/gsd/wrfportal/namelist_input_options.html)

```
&time_control
run_days           = 01,
run_hours          = 00,
run_minutes        = 0,
run_seconds        = 0,
start_year         = 2014, 2014, 2014,
start_month        = 01, 01, 01,
start_day          = 02, 02, 02,
start_hour         = 00, 00, 00,
start_minute       = 00, 00, 00,
start_second       = 00, 00, 00,
end_year           = 2014, 2014, 2014,
end_month          = 01, 01, 01,
end_day            = 03, 03, 03,
end_hour           = 00, 00, 00,
```

6. Namelist.input (example) II

```
end_minute           = 00,  00,  00,  
end_second           = 00,  00,  00,  
interval_seconds     = 21600  
input_from_file      = .true.,.true.,.true.,  
history_interval     = 10, 10,  10,  
frames_per_outfile   = 200000, 200000, 200000,  
restart              = .false.,  
restart_interval     = 500000,  
io_form_history      = 2  
io_form_restart      = 2  
io_form_input        = 2  
io_form_boundary     = 2  
debug_level         = 0  
  
/  
  
&domains  
time_step            = 90,  
time_step_fract_num  = 0,
```

6. Namelist.input (example) III

```
time_step_fract_den      = 1,  
max_dom                  = 3,  
e_we                     = 100,   151,   301,  
e_sn                     = 100,   151,   301,  
e_vert                   = 51,    51,    51,  
p_top_requested          = 1000,  
num_metgrid_levels       = 38,  
num_metgrid_soil_levels  = 4,  
dx                       = 18000, 6000, 2000,  
dy                       = 18000, 6000, 2000,  
grid_id                  = 1,     2,     3,  
parent_id                = 0,     1,     2,  
i_parent_start           = 1,     25,    30,  
j_parent_start           = 1,     25,    30,  
parent_grid_ratio        = 1,     3,     3,  
parent_time_step_ratio   = 1,     3,     3,  
feedback                 = 1,  
smooth_option            = 0
```


6. Namelist.input (example) IV

```
eta_levels = 1.0000, 0.9980, 0.9955, 0.9925, 0.9890, 0.9850,  
0.9805, 0.9755, 0.9700, 0.9640, 0.9575, 0.9505,  
0.9430, 0.9350, 0.9265, 0.9170, 0.9060, 0.8930,  
0.8775, 0.8590, 0.8363, 0.8104, 0.7803, 0.7456,  
0.7059, 0.6615, 0.6126, 0.5594, 0.5041, 0.4479,  
0.3919, 0.3384, 0.2897, 0.2474, 0.2107, 0.1792,  
0.1523, 0.1293, 0.1093, 0.0917, 0.0763, 0.0629,  
0.0513, 0.0413, 0.0328, 0.0255, 0.0194, 0.0144,  
0.0104, 0.0071, 0.0000,  
/  

```

&physics

mp_physics = 4, 4, 4,

ra_lw_physics = 5, 5, 5,

ra_sw_physics = 5, 5, 5,

radt = 9, 3, 1,

sf_sfclay_physics = 2, 2, 2,

sf_surface_physics = 2, 2, 2,

6. Namelist.input (example) V

```
bl_pbl_physics      = 2,      2,      2,  
bldt                = 0,      0,      0,  
cu_physics          = 2,      0,      0,  
cudt                = 5,      5,      5,  
isfflx              = 1,  
ifsnow              = 1,  
icloud              = 1,  
surface_input_source = 1,  
num_soil_layers     = 4,  
sf_urban_physics    = 2,      2,      2,  
/
```

7. Super-short on supercomputing I

Supercomputers are build up of individual computers referred to as *nodes* or *cores*. Super computers can be viewed as a large cluster of servers and storage interconnected by a network. The computers are typically run on the Linux operative system.

Supercomputers are fast because the nodes are working together on big problems that requires parallelization. Each node has one or more processors.

Each Stallo-user has two main directories/disks

- `home/<username>` : Maximum capacity of 200 GB. Files in this directory is backed up regularly. Good location for storing scripts, figures, etc.
- `global/work/<username>` Not backed up and the HPC team are allowed to remove files in this directory. This is where one should run simulations and store big files.

7. Super-short on supercomputing II

Login and computational nodes

- Login node: For small tasks like manage directories and submitting jobs. Never run calculations on the login node, this will reduce the speed for all users on the login node.
- Computational nodes

For more info about Stallo, visit the HPC documentation web page

<https://hpc-uit.readthedocs.io/en/latest/stallo/stallo.html>

8. Interactive jobs and jobscripts I

Calculations on Stallo is done by submitting jobs through a batch system that executes the job applications based on the available resources, like computational and time frame. Stallo's batch system is SLURM (Simple Linux Utility for Resource Management).

To submit a job and get access to the computational nodes one need to submit a job application. This is done either by submitting a jobscript, or by using a computational node.

For interactive jobs or small tasks, it is often useful to use a computational node. The syntax for logging into a computational node is:

```
srunk --nodes=1 --ntasks-per-node=1 --time=00:10:00 --pty bash -i
```

8. Interactive jobs and jobscripts II

The command prompt appears as the job has done queing and are being allocated the requested resources.

When logged in on a computational node one can see the node id, typically blasterdalen@c12-16

A jobscript is a shell script containing information of the resources required to run the job and a estimation of how long the job will last.

When submitting the jobscript (also for applying to a computational node) the job is queued until the resources are allocated.

```
sbatch jobscript.sh
```

Check job status by entering

```
squeue -u <user_name>
```

If the user needs to delete the job, this can be done by

8. Interactive jobs and jobscripts III

```
scancel <job_id>
```

References I

- A Balzarini, F Angelini, L Ferrero, M Moscatelli, MG Perrone, G Pirovano, GM Riva, G Sangiorgi, AM Toppetti, GP Gobbi, et al. Sensitivity analysis of pbl schemes by comparing wrf model and experimental data. *Geoscientific Model Development Discussions*, 7(5):6133–6171, 2014.
- L Bernardet, J Wolf, L Nance, A Loughe, B Weatherhead, E Gilleland, and B Brown. Comparison between wrf-arw and wrf-nmm objective forecast verification scores.
- Adam J Deppe, William A Gallus Jr, and Eugene S Takle. A wrf ensemble for improved wind speed forecasts at turbine height. *Weather and Forecasting*, 28(1):212–228, 2013.
- William C Skamarock, Joseph B Klemp, Jimmy Dudhia, David O Gill, Dale M Barker, Wei Wang, and Jordan G Powers. A description of the advanced research wrf version 3. Technical report, DTIC Document, June 2008.

References II

Wei Wang, Cindy Bruyère, Michael Duda, Jimmy Dudhia, Dave Gill, Michael Kavulich, Kelly Keene, Hui-Chuan Lin, John Michalakes, Syed Rizvi, and Xin Zhang. Arw version 3 modeling system user's guide. Technical report, Mesoscale and Microscale Meteorology Division, April 2013.