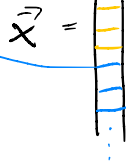
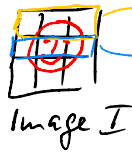


Input \vec{x}

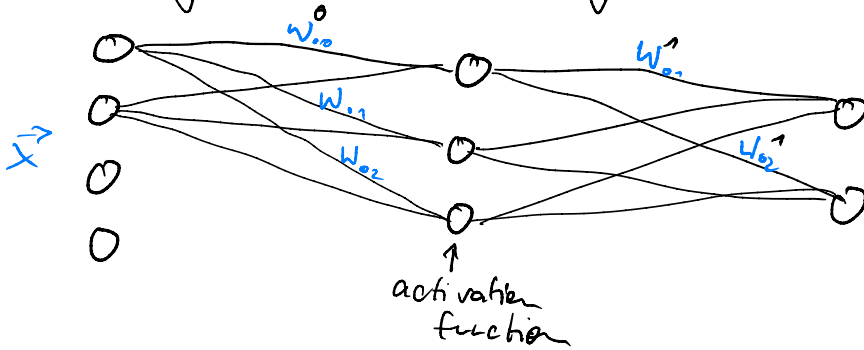


Classifier $\{\text{face, car}\}$
 $y = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \dots$

Input Layer

Hidden Layer

Output layer



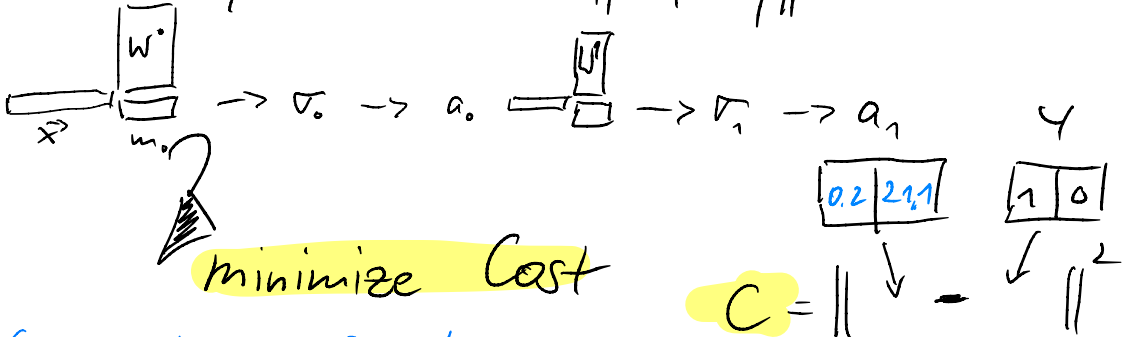
$$\vec{x} \cdot W_0 = m_0$$

$$\vec{a}_0 \cdot W_1 = m_1$$

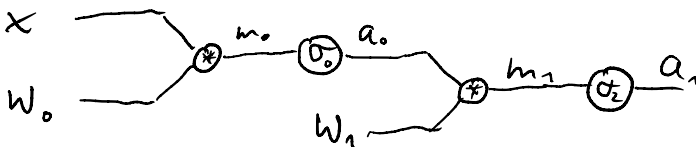
$$\sigma_0(m_0) = a_0$$

$$\sigma_1(m_1) = a_1$$

Loss / Cost $C = \|a_1 - y\|^2$

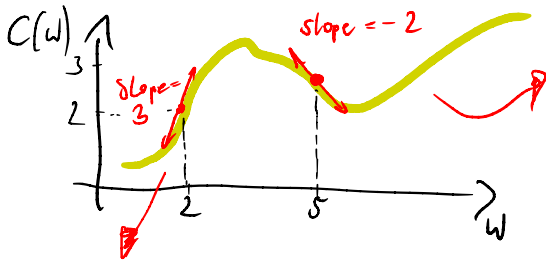


Computational graph



$C(w)$ → Find direction of change

$$\frac{\partial C(w)}{\partial w} \Rightarrow \text{slope}$$



$\frac{\partial C(w)}{\partial w}$ is negative
when $C(w)$ is
decreasing

$\frac{\partial C(w)}{\partial w}$ is positive when
 $C(w)$ is increasing

Goal: Minimize $C(w)$

Learning
rate
↓

if we set $w = w - \alpha \cdot \text{slope}$
at points above $C(w)$ will decrease

$$1.85 = w_{\text{new}} = 2 - \alpha \cdot 3 \quad \alpha = 0.05$$

$$5.1 = w_{\text{new}} = 5 - \alpha \cdot (-2)$$

$$\vec{x} \cdot \vec{w}_0 = m_0$$

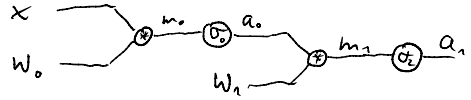
$$\vec{a}_0 \cdot \vec{w}_1 = m_1$$

$$\sigma_0(m_0) = a_0$$

$$\sigma_1(m_1) = a_1$$

$$C = \|a_1 - y\|^2$$

Computational graph



Chain Rule $\frac{\partial C(W)}{\partial W}$

partial derivative w_0 :

$$\boxed{\frac{\partial C}{\partial w_0}} = \frac{\partial C}{\partial a_1} \cdot \frac{\partial a_1}{\partial m_1} \cdot \frac{\partial m_1}{\partial a_0} \cdot \frac{\partial a_0}{\partial m_0} \cdot \frac{\partial m_0}{\partial w_0}$$

partial derivative w_1 :

$$\boxed{\frac{\partial C}{\partial w_1}} = \frac{\partial C}{\partial a_1} \cdot \frac{\partial a_1}{\partial m_1} \cdot \frac{\partial m_1}{\partial w_1}$$

$$\frac{\partial C}{\partial a_1} = 2(a_1 - y) \quad \frac{\partial a_1}{\partial m_1} = \sigma'_1(m_1) \quad \frac{\partial m_1}{\partial a_0} = w_1$$

$$\frac{\partial a_0}{\partial m_0} = \sigma'_0(m_0) \quad \frac{\partial m_0}{\partial w_0} = x$$

$$\frac{\partial m_1}{\partial w_1} = \overline{a_0} \rightarrow \text{is computed in forward pass} \rightarrow \text{should be cached}$$