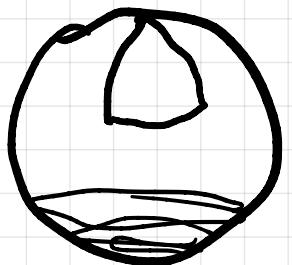


Visual and Scientific Computing

WS 2019/20



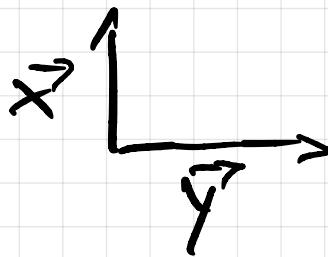
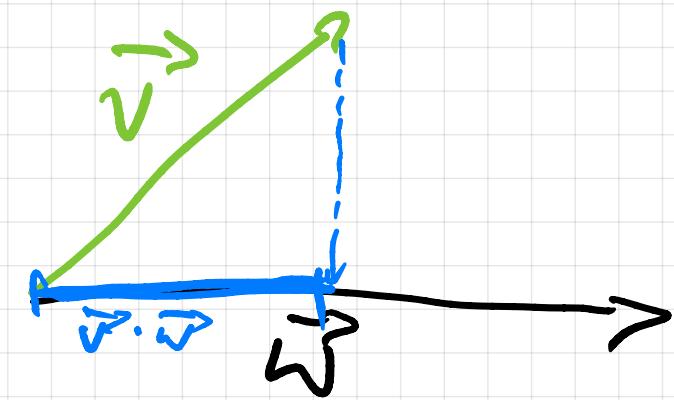
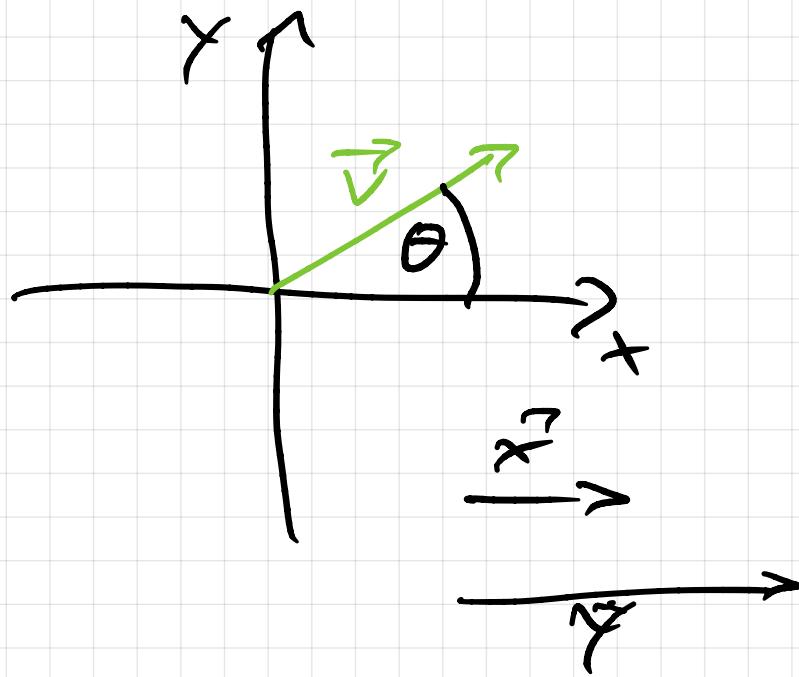


$$A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{bmatrix}$$

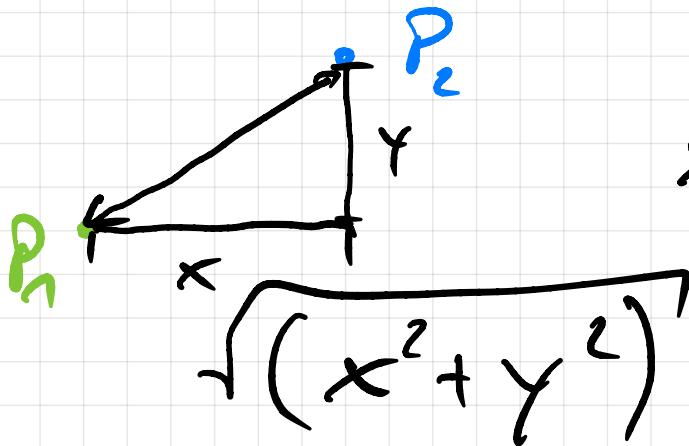
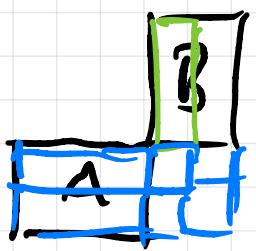
$$B = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 1 & 3 \end{bmatrix}$$

$$\boxed{A} * \boxed{B}$$

$$\begin{array}{|c|c|}\hline A & C \\ \hline B & \\ \hline \end{array}$$



$$x \cdot y = 0$$



$x+y \Rightarrow L_1$ -Norm

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- Rot, Sca, Shear, Mirror

Lil. Trans.

- Trans

Schr (Bsp.):

$$\begin{aligned} 6a + 12b &= 30 \\ 3a + 3b &= 9 \end{aligned}$$

$$\begin{aligned} A &= \begin{bmatrix} 6 & 12 \\ 3 & 3 \end{bmatrix} & Ax &= b \\ b &= \begin{bmatrix} 30 \\ 9 \end{bmatrix} \end{aligned}$$

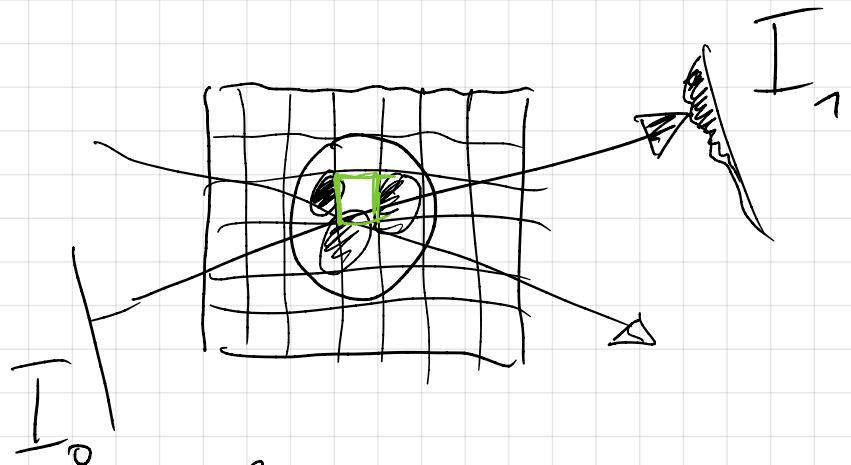
$$f(x) = x^2$$

$$f'(x) = 2x$$

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

Problem \rightarrow math. Formulierung \rightarrow Lösung

Lin GS



$$I_0 \xrightarrow{l=1} I_1$$

$$I_1 = I_0 \cdot c$$

$$c \in [0, 1]$$

Weg
des Strahl
durch
e Elast

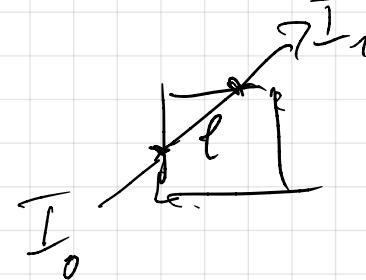
$$I_0 \xrightarrow{l=2} I_1$$

$$I_1 = I_0 \cdot c^2$$

$$I_1 = I_0 \cdot c$$

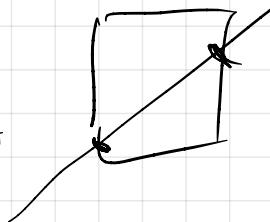
$$I_0 \xrightarrow{l=3} I_1$$

$$I_1 = I_0 \cdot c^{\frac{3}{2}}$$



I_0	C_{00}	C_{01}	C_{02}	C_{03}
I_1	C_{00}	C_{01}	C_{02}	C_{03}
	C_{10}	C_{11}	C_{12}	C_{13}
	\dots	\dots	\dots	\dots

$$I_1 = I_0 \cdot C_{00} \cdot C_{01} \cdot C_{02} \cdot C_{03} \cdots$$



$$Ax = b$$

$$A \vec{x} = \vec{b}$$

$$a_{00}x_1 + a_{01}x_2 + \dots = b_0$$

$$\vdots \quad \vdots \quad \vdots = \vdots$$

$$a_{m0}x_1 + a_{m1}x_2 + \dots = b_m$$

$$\log I_1 = \underbrace{\log I_0}_{b_0} + \underbrace{l_{00} \cdot \log C_{00} + l_{01} \cdot \log C_{01} + l_{02} \cdot \log C_{02} + \dots}_{\vec{b}}$$

$$x_{ij} = \log C_{ij} \rightarrow \text{Unbekannt}$$

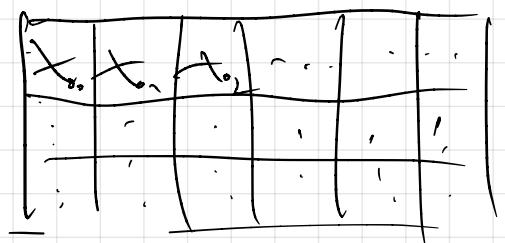
$$l_{00} \dots l_{mm} \rightarrow A$$

$$L \vec{x} = \vec{b}$$

$$b_0 = l_{00}^0 \cdot x_{00} + l_{01}^0 \cdot x_{01} + l_{02}^0 \cdot x_{02} \dots$$

$$b_m = l_{00}^m \cdot x_{00} + l_{01}^m \cdot x_{01} + l_{02}^m \cdot x_{02} \dots$$

$$L \vec{x} = \vec{b}$$



$$\vec{x} = [x_{00}, x_{01}, \dots, x_{0m}, x_{10}, x_{11}, \dots, x_{1m}]$$

$$[L] [x] = [b]$$

Raster
unbekannt

Sondere Vektor \vec{x}

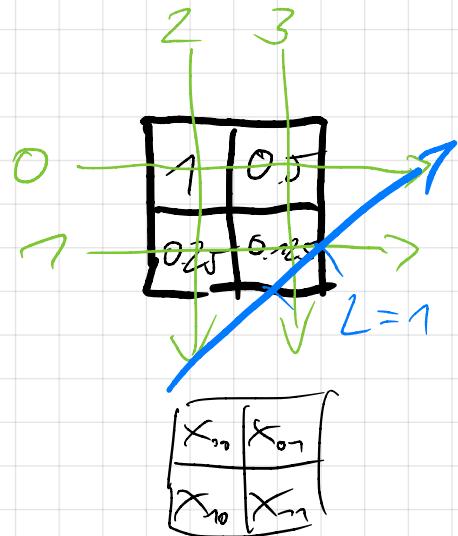
$$\begin{matrix} L_{00} & L_{n \times m} \\ \vdots & \end{matrix}$$

überbestimmtes LGS

$$\begin{array}{c} x \\ | \\ L_{00} \quad L_{01} \\ | \quad | \\ L \end{array} \quad l_{00}x_{00} + l_{01}x_{01} \dots$$

$$= \begin{bmatrix} b \\ 0 \end{bmatrix}$$

Bsp:



$$I_0 = 1 \quad L = 1$$

$$1 \cdot 0.5 = \frac{1}{2}$$

$$\frac{1}{4} \cdot \frac{1}{8} = \frac{1}{32}$$

$$1 \cdot \frac{1}{4} = \frac{1}{4}$$

$$-\frac{1}{2} \cdot \frac{1}{8} = -\frac{1}{16}$$

$$\frac{1}{8}$$

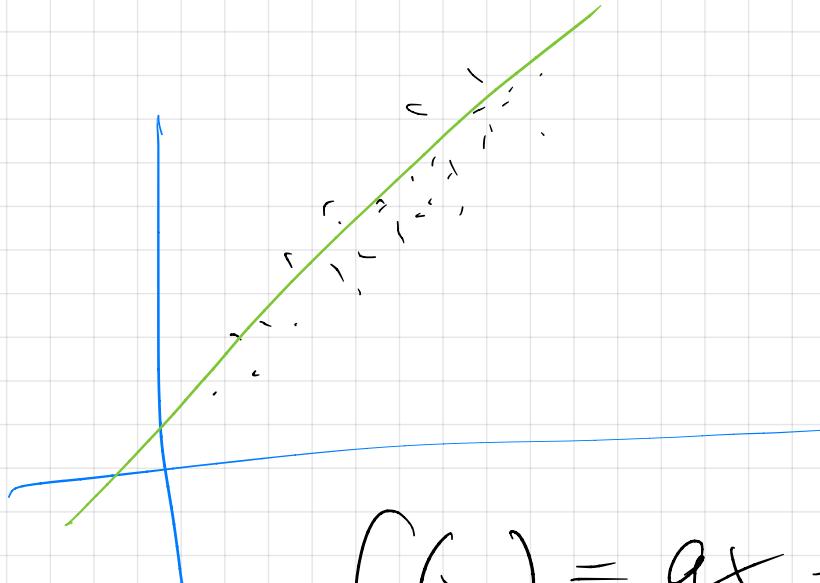
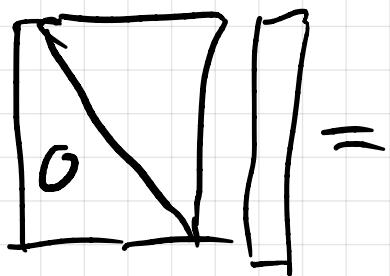
$$I_1 \rightarrow b$$

Log our Basis 2

$$\begin{aligned} b_0 &= -1 \\ b_1 &= -5 \\ b_2 &= -2 \\ b_3 &= -4 \\ b_4 &= -3 \\ L &= \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \\ &\quad \text{0 0 0 1} \end{aligned}$$

$$\begin{bmatrix} l_{0,0}^0 & l_{0,1}^0 & l_{0,2}^0 & l_{0,3}^0 \\ l_{1,0}^0 & l_{1,1}^0 & l_{1,2}^0 & l_{1,3}^0 \\ l_{2,0}^0 & l_{2,1}^0 & l_{2,2}^0 & l_{2,3}^0 \\ l_{3,0}^0 & l_{3,1}^0 & l_{3,2}^0 & l_{3,3}^0 \end{bmatrix} \begin{bmatrix} x_{0,0} \\ x_{0,1} \\ x_{1,0} \\ x_{1,1} \end{bmatrix} = \begin{bmatrix} b^0 \\ b^1 \\ b^2 \\ b^3 \end{bmatrix}$$

$$Ax = b$$



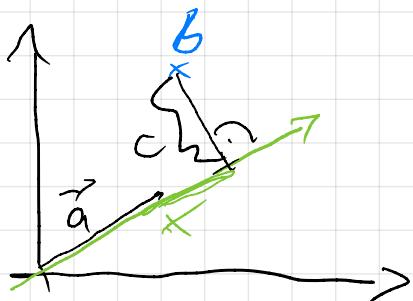
$$f(x) = ax + b$$



$$Ax = b$$

$m =$
Anzahl
der Reze

$$\begin{bmatrix} x \end{bmatrix}_{n^6} = \begin{bmatrix} b \end{bmatrix}_m$$



$$\vec{q} \cdot x \approx \vec{b}$$

$$a \cdot x \neq b$$

$$c = \vec{a}x - \vec{b}$$

$$\vec{a}^T(\vec{a}x - \vec{b}) = 0$$

$$\Leftrightarrow \vec{a}^T \vec{a}x = \vec{a}^T \vec{b}$$

$$x \in \mathbb{R}^n$$

$$A = \left[\vec{a}_0, \vec{a}_1, \dots, \vec{a}_n \right]$$

$$\vec{a} \in \mathbb{R}^d$$

$$n < d$$

$$\begin{bmatrix} A \\ \vdots \end{bmatrix} \begin{bmatrix} x \\ \vdots \\ b \end{bmatrix} = \begin{bmatrix} \vdots \end{bmatrix}$$

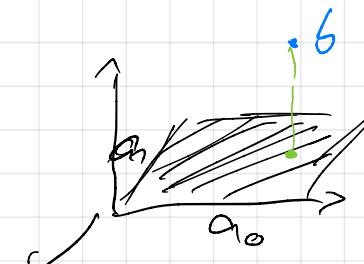
$$Ax - b \approx 0$$

$$\vec{a}_0 \vec{x}_0 + \vec{a}_1 \vec{x}_1 + \dots + \vec{a}_n \vec{x}_n - \vec{b} \approx 0$$

$$\vec{a}_0^T (Ax - b) = 0$$

$$\vec{a}_1^T (Ax - b) = 0$$

\vdots



$$A^T(Ax - b) = 0$$

$$A^T A x = A^T b \quad \rightarrow \text{Normalengleichung}$$

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|^2$$

$$\sum_i^n r_i^2 = \|Ax_i - b\|^2$$

$$\sum_i^m r_i^2 = \|Ax_i - b\|^2$$

$$\hookrightarrow r^T r = F$$

$$(b^T A)^T = \\ A^T b$$

$$\frac{\partial F}{\partial x_i}$$

$$\begin{aligned} r^T r &= (Ax - b)^T (Ax - b) \\ &= (x^T A^T - b^T)(Ax - b) \\ &= \underbrace{x^T A^T A x - x^T A^T b - b^T A x + b^T b}_{ASRauf}$$

$$\frac{\partial F}{\partial x} = 2A^T A x - A^T b - b^T A = \cancel{2A^T A x} - \cancel{2A^T b}$$

$$\frac{\partial F}{\partial x} = \boxed{A^T A x - A^T b = 0}$$

$$\begin{bmatrix} A^T \\ A^T A \end{bmatrix}$$

$$\begin{bmatrix} A^T & | & A^T b \end{bmatrix}$$

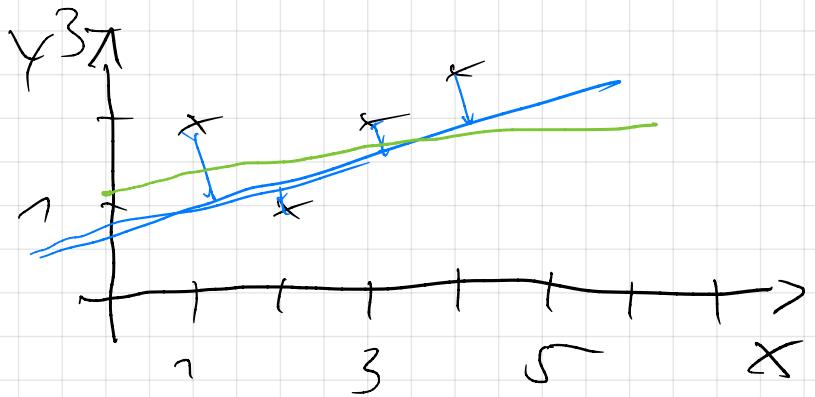
Cholesky } \rightarrow Workhorse for $A^T A x = A^T b$

$$\overbrace{A^T A}^T$$

$$T = L L^T$$

$$\begin{bmatrix} L & 0 \\ 0 & L^T \end{bmatrix}$$

$$\begin{bmatrix} L \\ I \end{bmatrix}$$



$$\begin{pmatrix} 1, 2 \\ 2, 1 \\ 3, 2 \\ 4, 2.5 \end{pmatrix}$$

$$f(x) = a_0 x + a_1$$

$$Ax = b$$

$$\begin{bmatrix} 1 & 1 \\ 2 & 1 \\ 3 & 1 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 2 \\ 2.5 \end{bmatrix}$$

$$\begin{cases} 2 = a_0 \cdot 1 + a_1 \cdot 1 \\ 1 = a_0 \cdot 2 + a_1 \cdot 1 \\ 2 = a_0 \cdot 3 + a_1 \cdot 1 \\ 2.5 = a_0 \cdot 4 + a_1 \cdot 1 \end{cases}$$

b

$$x = \begin{bmatrix} a_0 \\ a_1 \end{bmatrix}$$

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|^2$$

