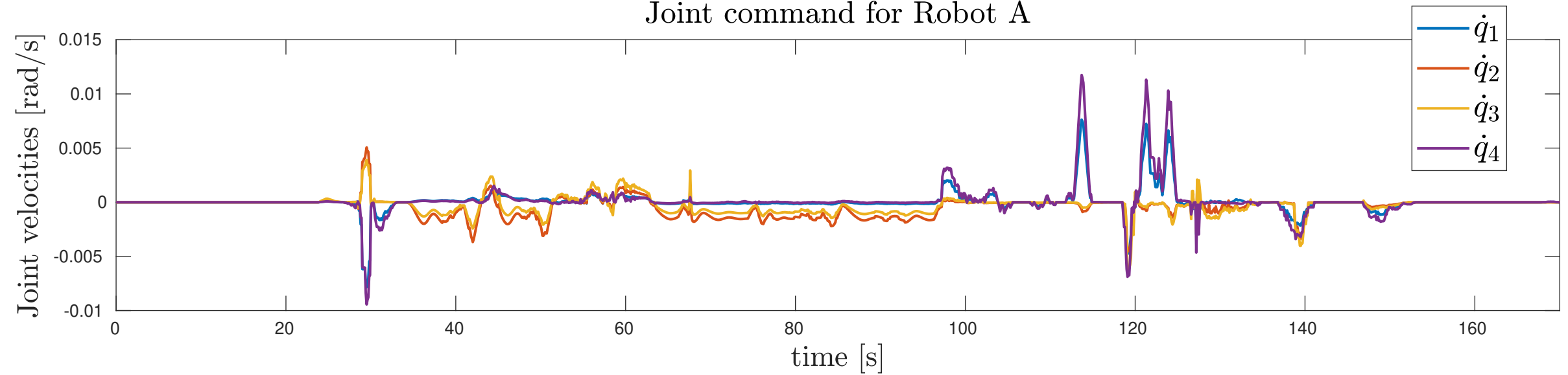
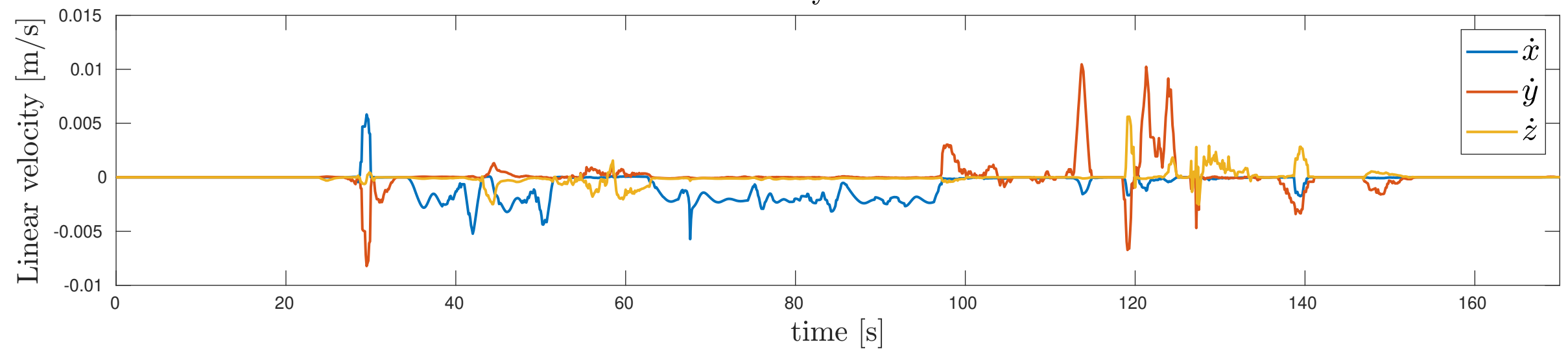


Joint command for Robot A



Vehicle linear velocity command for Robot A



Vehicle angular velocity command for Robot A

