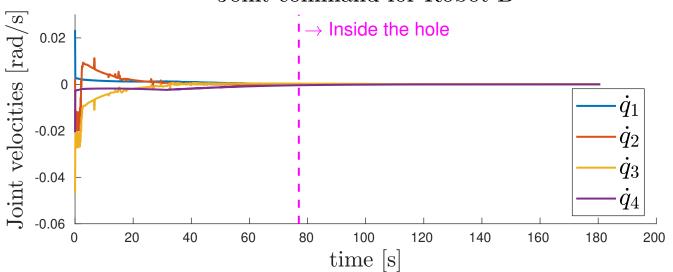
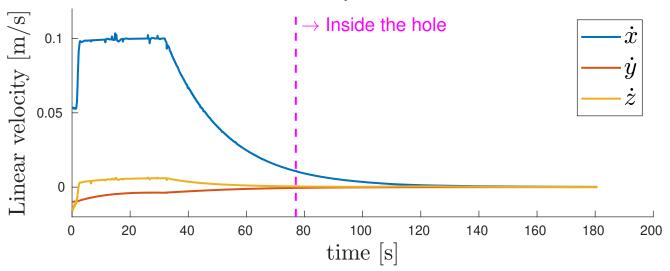
## Joint command for Robot B



## Vehicle linear velocity command for Robot B



## Vehicle angular velocity command for Robot B

