

Covariance

Let \mathcal{H} be a real Hilbert space and let \mathbb{P} be a probability measure on \mathcal{H} . The covariance of any two bounded linear functionals ϕ, ψ is given by

$$\begin{aligned} \text{Cov}_{\mathbb{P}}(\phi, \psi) &= \mathbb{E}_{\mathbb{P}}[(\phi - \mathbb{E}_{\mathbb{P}}[\phi])(\psi - \mathbb{E}_{\mathbb{P}}[\psi])] \\ &= \int_{h \in \mathcal{H}} \left(\phi(h) - \int_{h' \in \mathcal{H}} \phi(h') d\mathbb{P}(h') \right) \left(\psi(h) - \int_{h' \in \mathcal{H}} \psi(h') d\mathbb{P}(h') \right) d\mathbb{P}(h). \end{aligned} \quad (1)$$

Riesz representation theorem

For every bounded linear functional φ , there exists a unique vector $T\varphi$ such that $\varphi(h) = \langle h, T\varphi \rangle_{\mathcal{H}}$. Hence,

$$\begin{aligned} \text{Cov}_{\mathbb{P}}(\phi, \psi) &= \int_{h \in \mathcal{H}} \left(\langle h, T\phi \rangle_{\mathcal{H}} - \int_{h' \in \mathcal{H}} \langle h', T\phi \rangle_{\mathcal{H}} d\mathbb{P}(h') \right) \left(\langle h, T\psi \rangle_{\mathcal{H}} - \int_{h' \in \mathcal{H}} \langle h', T\psi \rangle_{\mathcal{H}} d\mathbb{P}(h') \right) d\mathbb{P}(h) \\ &= \int_{h \in \mathcal{H}} \left\langle h - \int_{h' \in \mathcal{H}} h' d\mathbb{P}(h'), T\phi \right\rangle_{\mathcal{H}} \left\langle h - \int_{h' \in \mathcal{H}} h' d\mathbb{P}(h'), T\psi \right\rangle_{\mathcal{H}} d\mathbb{P}(h) \\ &= \int_{h \in \mathcal{H}} \langle h - \mu, T\phi \rangle_{\mathcal{H}} \langle h - \mu, T\psi \rangle_{\mathcal{H}} d\mathbb{P}(h) \end{aligned} \quad (2)$$

where μ is the expected $h \in \mathcal{H}$ with respect to \mathbb{P} and is given by $\mu = \int_{h \in \mathcal{H}} h d\mathbb{P}(h)$.

Direct sum decomposition

Let h_1, \dots, h_n be a sample drawn from \mathbb{P} . Since $S = \text{span}\{h_1, \dots, h_n\}$ is a closed subspace of \mathcal{H} , by the Hilbert projection theorem, $\mathcal{H} = S \oplus S^{\perp}$ where S^{\perp} is the orthogonal complement of S . Thus,

$$T\phi = \sum_{i=1}^n \alpha_i h_i + u \quad \text{and} \quad T\psi = \sum_{i=1}^n \beta_i h_i + v \quad (3)$$

for some $\alpha_i, \beta_i \in \mathbb{R}$ and $u, v \in S^{\perp}$.

Empirical covariance

Substituting (3) into (2) and letting $\hat{\mathbb{P}}$ denote the empirical distribution of the sample,

$$\begin{aligned} \text{Cov}_{\hat{\mathbb{P}}}(\phi, \psi) &= \frac{1}{n} \sum_{i=1}^n \left\langle h_i - \bar{h}, \sum_{j=1}^n \alpha_j h_j + u \right\rangle_{\mathcal{H}} \left\langle h_i - \bar{h}, \sum_{j=1}^n \beta_j h_j + v \right\rangle_{\mathcal{H}} \\ &= \frac{1}{n} \sum_{i=1}^n \left(\sum_{j=1}^n \langle h_i - \bar{h}, h_j \rangle_{\mathcal{H}} \alpha_j \right) \left(\sum_{j=1}^n \langle h_i - \bar{h}, h_j \rangle_{\mathcal{H}} \beta_j \right) \\ &= \frac{1}{n} (CG\alpha)^T CG\beta \\ &= \frac{1}{n} \alpha^T GCG\beta \end{aligned} \quad (4)$$

where \bar{h} is the sample mean, $C = I - \frac{1}{n}11^T$ is the symmetric and idempotent (i.e., $C^2 = C$) centering matrix, G is the symmetric matrix with entries $G_{i,j} = \langle h_i, h_j \rangle_{\mathcal{H}}$, and α and β are the n -dimensional vectors with components α_j and β_j , respectively.

Maximum variance functional

Consider the problem of finding a maximum variance functional with unit norm with respect to $\hat{\mathbb{P}}$. From (3) and (4), such a functional has the form $\phi^*(h) = \langle h, \sum_{i=1}^n \alpha_i^* h_i \rangle_{\mathcal{H}}$ where $\alpha^* = (\alpha_1^*, \dots, \alpha_n^*)^T$ is a solution to the optimization problem

$$\begin{aligned} \max_{\alpha \in \mathbb{R}^n} \quad & \frac{1}{n} \alpha^T G C G \alpha \\ \text{s.t.} \quad & \alpha^T G \alpha = 1 \end{aligned} \quad (5)$$

The constraint in (5) follows from the fact that $\|\phi\|_{\mathcal{H}^*} = \|T\phi\|_{\mathcal{H}}$ where \mathcal{H}^* denotes the space of bounded linear functionals on \mathcal{H} .

Centering the data

If we first centre the h_i to obtain the sample h'_1, \dots, h'_n where $h'_i = h_i - \bar{h}$, then the matrix G becomes $G' = C G C$ and (5) becomes

$$\begin{aligned} \max_{\alpha \in \mathbb{R}^n} \quad & \frac{1}{n} \alpha^T (G')^2 \alpha \\ \text{s.t.} \quad & \alpha^T G' \alpha = 1. \end{aligned} \quad (6)$$

Lagrange multipliers

A solution α^* to (6) satisfies the equation $(G')^2 \alpha^* = \gamma G' \alpha^*$ for some constant γ . Hence, if G' is positive definite, then α^* is an eigenvector of G' with corresponding eigenvalue γ . Since G' is symmetric (and assumed positive definite), there exists an orthonormal basis e_1, \dots, e_n of eigenvectors of G' with corresponding eigenvalues $\lambda_1 \geq \dots \geq \lambda_n > 0$, respectively. It follows that $\alpha^* = \frac{e_1}{\sqrt{\lambda_1}}$ is an optimal solution and, hence,

$$\phi^*(h) = \left\langle h, \sum_{i=1}^n \alpha_i^* h'_i \right\rangle_{\mathcal{H}} = \left\langle h, \sum_{i=1}^n \frac{e_1^{(i)}}{\sqrt{\lambda_1}} h'_i \right\rangle_{\mathcal{H}} = \frac{1}{\sqrt{\lambda_1}} \sum_{i=1}^n e_1^{(i)} \langle h, h'_i \rangle_{\mathcal{H}} \quad (7)$$

where $e_1^{(i)}$ denotes the i^{th} component of e_1 .

Maximum variance uncorrelated functionals

It is straightforward to generalize to a sequence of optimization problems where the i^{th} problem is given by

$$\begin{aligned} \max_{\alpha \in \mathbb{R}^n} \quad & \frac{1}{n} \alpha^T (G')^2 \alpha \\ \text{s.t.} \quad & \alpha^T G' \alpha = 1 \\ & \frac{1}{n} \alpha^T (G')^2 \alpha_j^* = 0, \quad j = 1, \dots, i-1 \end{aligned} \quad (8)$$

and where $i = 1$ corresponds to (6). The corresponding sequence of solutions $\alpha_i^* = \frac{e_i}{\sqrt{\lambda_i}}$ correspond to unit norm maximum variance uncorrelated functionals.

Algorithm

1. Construct the matrix G .
2. Centre G to obtain the matrix $G' = C G C$.
3. Compute the spectral decomposition of G' to obtain the matrix of eigenvectors Γ and the matrix of eigenvalues Λ .

4. (a) To obtain k -dimensional representations of the h_i , return the first k columns of $G'\Gamma\Lambda^{-\frac{1}{2}}$.
- (b) To obtain a k -dimensional representation of a new data point h , return the first k components of $\Lambda^{-\frac{1}{2}}\Gamma^T u$ where the i^{th} component of u is $\langle h - \bar{h}, h'_i \rangle_{\mathcal{H}}$.

Examples

1. PCA: Let $\mathcal{H} = \mathbb{R}^d$ and let \mathbb{P} be a probability measure on \mathcal{H} . It follows that G has entries $G_{i,j} = x_i^T x_j$ where x_1, \dots, x_n is a sample drawn from \mathbb{P} .
2. Kernel PCA: Let \mathcal{H} be a reproducing kernel Hilbert space with reproducing kernel $k : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ and let \mathbb{P} be a probability measure on \mathcal{H} given by

$$\mathbb{P}(E) = \mathbb{Q}(\{x \in \mathbb{R}^d \mid \Phi(x) \in E\}), \quad E \subset \mathcal{H}$$

where \mathbb{Q} is a probability measure on \mathbb{R}^d and $\Phi : \mathbb{R}^d \rightarrow \mathcal{H}$ is the canonical feature map $\Phi(x) = k_x$. It follows that G has entries $G_{i,j} = \langle \Phi(x_i), \Phi(x_j) \rangle_{\mathcal{H}} = k(x_i, x_j)$ where x_1, \dots, x_n is a sample drawn from \mathbb{Q} .