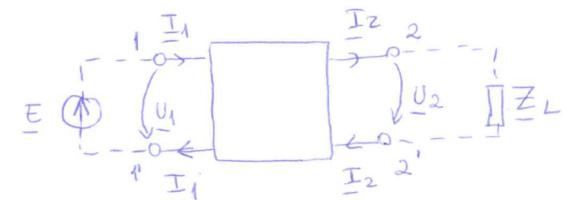
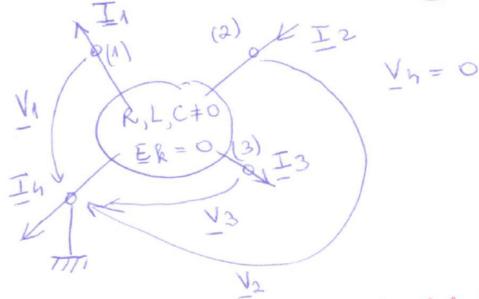


Curs 10

5. TWO-PORT NETWORKS (CUADRIPOLI)



5.1. Equations (Ecuatiile cuadrupolarilor)

a) Fundamental parameters (Ecuatiile fundamentale ale cuadrupolarilor)

$$\begin{cases} \underline{U}_1 = \underline{A} \cdot \underline{U}_2 + \underline{B} \cdot \underline{I}_2 \\ \underline{I}_1 = \underline{C} \cdot \underline{U}_2 + \underline{D} \cdot \underline{I}_2 \end{cases} \rightarrow \underline{A} = \left(\frac{\underline{U}_1}{\underline{U}_2} \right)_{\underline{I}_2=0} = \frac{1}{\left(\frac{\underline{U}_2}{\underline{U}_1} \right)_{\underline{I}_2=0}} ; \underline{B} = \frac{1}{\left(\frac{\underline{I}_2}{\underline{U}_2} \right)_{\underline{U}_2=0}} ; \underline{C} = \frac{1}{\left(\frac{\underline{U}_2}{\underline{I}_1} \right)_{\underline{U}_2=0}} ; \underline{D} = \frac{1}{\left(\frac{\underline{I}_1}{\underline{I}_2} \right)_{\underline{U}_2=0}}$$

A two-port network is said to be reciprocal if the ratio of the excitation to the response is invariant to an interchange of the position of the excitation and response in the network (Un cuadrupol este reciproc dacă raportul dintre excitare și răspunsul la aceasta rămâne constant la repositionarea excitării și răspunsului în cuadrupol).

$$\begin{array}{c} \underline{U}_1 \xrightarrow[\underline{U}_2=0]{} \boxed{\quad} \xrightarrow[\underline{U}_2=0]{} \underline{I}_1 \\ \underline{I}_1 \end{array} \quad \begin{array}{c} \boxed{\quad} \xrightarrow[\underline{U}_1=0]{} \underline{U}_2 \xrightarrow[\underline{U}_1=0]{} \underline{I}_2 \\ \underline{I}_2 \end{array} \Rightarrow \boxed{\underline{A} \cdot \underline{D} - \underline{B} \cdot \underline{C} = 1}$$

Reciprocity condition
Condiția de reciprocitate

b) Impedance parameters (Ecuatiile cuadrupolarilor în parametrii impedanță)

$$\begin{cases} \underline{U}_1 = \underline{Z}_{11} \cdot \underline{I}_1 + \underline{Z}_{12} \cdot \underline{I}_2 \\ \underline{U}_2 = \underline{Z}_{21} \cdot \underline{I}_1 + \underline{Z}_{22} \cdot \underline{I}_2 \end{cases}$$

$$\underline{Z}_{11} = \left(\frac{\underline{U}_1}{\underline{I}_1} \right)_{\underline{I}_2=0} = \frac{\underline{A}}{\underline{C}} ; \quad \underline{Z}_{21} = \left(\frac{\underline{U}_2}{\underline{I}_1} \right)_{\underline{I}_2=0} = \frac{1}{\underline{C}} ; \quad \underline{Z}_{22} = \left(\frac{\underline{U}_2}{\underline{I}_2} \right)_{\underline{I}_1=0} = - \frac{\underline{D}}{\underline{C}}$$

$$\underline{Z}_{12} = \left(\frac{\underline{U}_1}{\underline{I}_2} \right)_{\underline{I}_1=0} = - \frac{\underline{A} \cdot \underline{D} - \underline{B} \cdot \underline{C}}{\underline{C}}$$

$$\begin{cases} \underline{U}_1 = \underline{A} \cdot \underline{U}_2 + \underline{B} \cdot \underline{I}_2 ; \underline{I}_2 = \frac{\underline{U}_1}{\underline{I}_2} = \underline{A} \cdot \left(- \frac{\underline{D}}{\underline{C}} \right) + \underline{B} \\ 0 = \underline{C} \cdot \underline{U}_2 + \underline{D} \cdot \underline{I}_2 \Rightarrow \underline{U}_2 = - \frac{\underline{D}}{\underline{C}} \end{cases}$$

c) Admittance parameters (Ecuatiile quadripolilor în parametri admisită)

$$\begin{cases} \underline{I}_1 = \underline{Y}_{11} \cdot \underline{U}_1 + \underline{Y}_{12} \cdot \underline{U}_2 \\ \underline{I}_2 = \underline{Y}_{21} \cdot \underline{U}_1 + \underline{Y}_{22} \cdot \underline{U}_2 \end{cases} \Rightarrow \underline{Y}_{11} = \left(\frac{\underline{I}_1}{\underline{U}_1} \right)_{\underline{U}_2=0} = \frac{\underline{D}}{\underline{B}} ; \underline{Y}_{21} = \left(\frac{\underline{I}_2}{\underline{U}_1} \right)_{\underline{U}_2=0} = \frac{1}{\underline{B}}$$

$$\underline{Y}_{22} = \left(\frac{\underline{I}_2}{\underline{U}_2} \right)_{\underline{U}_1=0} = -\frac{\underline{A}}{\underline{B}} ; \underline{Y}_{12} = \left(\frac{\underline{I}_1}{\underline{U}_2} \right)_{\underline{U}_1=0} = -\frac{\underline{A}\underline{D} - \underline{B}\underline{C}}{\underline{B}}$$

$$\begin{cases} 0 = \underline{A} \cdot \underline{U}_2 + \underline{B} \cdot \underline{I}_2 \Rightarrow \frac{\underline{I}_2}{\underline{U}_2} = -\frac{\underline{A}}{\underline{B}} \\ \underline{I}_1 = \underline{C} \cdot \underline{U}_2 + \underline{D} \cdot \underline{I}_2 \mid \underline{U}_2 \Rightarrow \frac{\underline{I}_1}{\underline{U}_2} = \underline{C} - \underline{D} \cdot \frac{\underline{A}}{\underline{B}} \end{cases}$$

Reciprocity condition (condiția de reciprocitate):

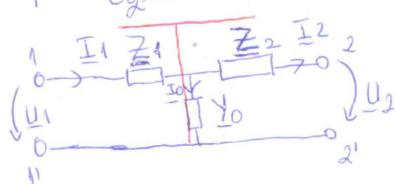
$$\underline{A} \cdot \underline{D} - \underline{B} \cdot \underline{C} = 1 \quad \text{or} \quad \underline{Z}_{12} = -\underline{Z}_{21} \quad \text{or} \quad \underline{Y}_{12} = -\underline{Y}_{21}$$

Symmetry: A two-port network is said to be symmetrical if the input and output ports can be interchanged without altering the port voltages and currents (Un quadripol este simetric dacă bornele de intrare și poziții interzamănează cu cele de ieșire fără ca tensiunile și curentul circuitului să se modifice).

$$\underline{A} = \underline{D} \quad \text{or} \quad \underline{Z}_{11} = -\underline{Z}_{22} \quad \text{or} \quad \underline{Y}_{11} = -\underline{Y}_{12}$$

5.2 Equivalent two-port networks

a) "T" Equivalent "T" schematic (Schema echivalentă în "T")



$$\begin{cases} \underline{U}_1 = \underline{A} \cdot \underline{U}_2 + \underline{B} \cdot \underline{I}_2 \\ \underline{I}_1 = \underline{C} \cdot \underline{U}_2 + \underline{D} \cdot \underline{I}_2 \end{cases}$$

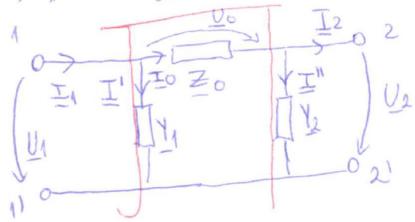
$$\underline{I}_1 = \underline{I}_0 + \underline{I}_2 = \underline{Y}_0 (\underline{Z}_2 \cdot \underline{I}_2 + \underline{U}_2) + \underline{I}_2 = \underline{\frac{Y_0}{C}} \cdot \underline{U}_2 + \underline{\frac{(1 + \underline{Z}_2 \cdot \underline{Y}_0)}{D}} \cdot \underline{I}_2$$

$$\underline{U}_1 = \underline{Z}_1 \cdot \underline{I}_1 + \underline{Z}_2 \cdot \underline{I}_2 + \underline{U}_2 = \underline{Z}_1 \cdot [\underline{Y}_0 \cdot \underline{U}_2 + (1 + \underline{Z}_2 \cdot \underline{Y}_0) \cdot \underline{I}_2] + \underline{Z}_2 \cdot \underline{I}_2 + \underline{U}_2$$

$$\underline{U}_1 = \underline{A} \cdot \underline{U}_2 + \underline{B} \cdot \underline{I}_2$$

$$\Rightarrow \begin{cases} \underline{A} = 1 + \underline{Z}_1 \cdot \underline{Y}_0 \\ \underline{B} = \underline{Z}_1 + \underline{Z}_2 + \underline{Z}_1 \underline{Z}_2 \underline{Y}_0 \\ \underline{C} = \underline{Y}_0 \\ \underline{D} = 1 + \underline{Z}_2 \cdot \underline{Y}_0 \end{cases} \quad \begin{cases} \underline{Y}_0 = \underline{C} \\ \underline{Z}_1 = \underline{A} - 1 \\ \underline{Z}_2 = \underline{D} - 1 \end{cases}$$

b), $\bar{J}I$ " Equivalent $\bar{J}I$ " schematic (Schema echivalentă în $\bar{J}I$ ")



$$\begin{aligned} \underline{U}_1 &= \underline{U}_0 + \underline{U}_2 = \underline{Z}_0 \cdot \underline{I}_0 + \underline{U}_2 = \underline{Z}_0 (\underline{I}_2 + \underline{Y}_2 \underline{U}_2) + \underline{U}_2 \\ \underline{U}_1 &= (\underline{1} + \underline{Z}_0 \cdot \underline{Y}_2) \cdot \underline{U}_2 + \underline{Z}_0 \cdot \underline{I}_2 \end{aligned}$$

A B

$$\underline{I}_1 = \underline{I}^1 + \underline{I}_0 = \underline{U}_1 \cdot \underline{Y}_1 + \underline{I}_2 + \underline{Y}_2 \cdot \underline{U}_2 = \underline{Y}_1 [(\underline{1} + \underline{Z}_0 \cdot \underline{Y}_2) \underline{U}_2 + \underline{Z}_0 \cdot \underline{I}_2] + \underline{I}_2 + \underline{Y}_2 \underline{U}_2$$

$$\underline{I}_1 = \underbrace{(\underline{Y}_1 + \underline{Y}_2 + \underline{Y}_1 \underline{Y}_2 \underline{Z}_0)}_C \cdot \underline{U}_2 + \underbrace{(\underline{1} + \underline{Y}_1 \underline{Z}_0)}_D \cdot \underline{I}_2$$

$$\begin{cases} \underline{A} = \underline{1} + \underline{Z}_0 \cdot \underline{Y}_2 \\ \underline{B} = \underline{Z}_0 \\ \underline{C} = \underline{Y}_1 + \underline{Y}_2 + \underline{Y}_1 \underline{Y}_2 \underline{Z}_0 \\ \underline{D} = \underline{1} + \underline{Z}_0 \cdot \underline{Y}_1 \end{cases} \Rightarrow \begin{cases} \underline{Y}_1 = \frac{\underline{D}-1}{\underline{B}} \\ \underline{Y}_2 = \frac{\underline{A}-1}{\underline{B}} \\ \underline{Z}_0 = \underline{B} \end{cases}$$

5.3 Finding the A, B, C, D parameters (Determinarea parametrilor A, B, C, D)

$$\begin{cases} \underline{U}_1 = \underline{A} \cdot \underline{U}_2 + \underline{B} \cdot \underline{I}_2 \\ \underline{I}_1 = \underline{C} \cdot \underline{U}_2 + \underline{D} \cdot \underline{I}_2 \end{cases} \quad \begin{array}{c} \xrightarrow{\underline{U}_1} \\ \xleftarrow{\underline{I}_1} \end{array} \quad \begin{array}{c} \xrightarrow{\underline{I}_1} \\ \xleftarrow{\underline{U}_2} \end{array} \quad \underline{Z}_L \Rightarrow \begin{cases} \underline{U}_1 = \underline{U}_{10} + \underline{U}_{1\infty} \\ \underline{I}_1 = \underline{I}_{10} + \underline{I}_{1\infty} \end{cases}$$

$$\text{If } \underline{Z}_L \rightarrow \infty \Rightarrow \underline{I}_2 = 0 \text{ (OPEN CIRCUIT)} \quad \text{If } \underline{Z}_L \rightarrow 0 \Rightarrow \underline{U}_2 = 0 \text{ (SHORT CIRCUIT)}$$

$$\begin{cases} \underline{U}_{10} = \underline{A} \cdot \underline{U}_2 \\ \underline{I}_{10} = \underline{C} \cdot \underline{U}_2 \end{cases} \Rightarrow \underline{Z}_{10} = \frac{\underline{U}_{10}}{\underline{I}_{10}} = \frac{\underline{A}}{\underline{C}}$$

$$\begin{cases} \underline{U}_{1\infty} = \underline{B} \cdot \underline{I}_2 \\ \underline{I}_{1\infty} = \underline{D} \cdot \underline{I}_2 \end{cases} \Rightarrow \underline{Z}_{1\infty} = \frac{\underline{U}_{1\infty}}{\underline{I}_{1\infty}} = \frac{\underline{B}}{\underline{D}}$$

$$\begin{cases} \underline{U}_2 = \underline{D} \cdot \underline{U}_1 + \underline{B} \cdot \underline{I}_1 \\ \underline{I}_2 = \underline{C} \cdot \underline{U}_1 + \underline{A} \cdot \underline{I}_1 \end{cases} \quad \begin{array}{c} \xrightarrow{\underline{U}_2} \\ \xleftarrow{\underline{I}_2} \end{array} \quad \begin{array}{c} \xleftarrow{\underline{I}_1} \\ \xrightarrow{\underline{U}_2} \end{array} \quad \begin{cases} \underline{U}_2 = \underline{U}_{20} + \underline{U}_{2\infty} \\ \underline{I}_2 = \underline{I}_{20} + \underline{I}_{2\infty} \end{cases}$$

$$\text{If } \underline{Z}_L \rightarrow \infty \Rightarrow \underline{I}_1 = 0$$

$$\text{If } \underline{Z}_L \rightarrow 0 \Rightarrow \underline{U}_1 = 0$$

$$\begin{cases} \underline{U}_{20} = \underline{D} \cdot \underline{U}_1 \\ \underline{I}_{20} = \underline{C} \cdot \underline{U}_1 \end{cases} \Rightarrow \underline{Z}_{20} = \frac{\underline{U}_{20}}{\underline{I}_{20}} = \frac{\underline{D}}{\underline{C}}$$

$$\begin{cases} \underline{U}_{2\infty} = \underline{B} \cdot \underline{I}_1 \\ \underline{I}_{2\infty} = \underline{A} \cdot \underline{I}_1 \end{cases} \Rightarrow \underline{Z}_{2\infty} = \frac{\underline{U}_{2\infty}}{\underline{I}_{2\infty}} = \frac{\underline{B}}{\underline{A}}$$

$$\Rightarrow \begin{array}{|c|c|} \hline \underline{Z}_{10} = \frac{\underline{A}}{\underline{C}} & \underline{Z}_{1\infty} = \frac{\underline{B}}{\underline{D}} \\ \hline \underline{Z}_{20} = \frac{\underline{D}}{\underline{C}} & \underline{Z}_{2\infty} = \frac{\underline{B}}{\underline{A}} \\ \hline \end{array}$$

$$\Rightarrow \underline{Z}_{10} \cdot \underline{Z}_{2\infty} = \underline{Z}_{1\infty} \cdot \underline{Z}_{20} = \frac{\underline{B}}{\underline{C}}$$

$$\underline{Z}_{10} = \underline{Z}_{10} \cdot e^{j\varphi_{10}} = \frac{\underline{U}_{10}}{\underline{I}_{10}} \cdot e^{j\varphi_{10}}$$

$$P_{10} = \underline{U}_{10} \cdot \underline{I}_{10} \cdot \cos \varphi_{10} \Rightarrow \cos \varphi_{10} = \frac{P_{10}}{\underline{U}_{10} \cdot \underline{I}_{10}} \Rightarrow \varphi_{10}$$

$$\Rightarrow \underline{A} = \underline{C} \cdot \underline{Z}_{10}$$

$$\underline{B} = \underline{C} \cdot \underline{Z}_{10} \cdot \underline{Z}_{20c} = \underline{C} \cdot \underline{Z}_{20} \cdot \underline{Z}_{10c}$$

$$\underline{D} = \underline{C} \cdot \underline{Z}_{20}$$

From $\underline{A}\underline{D} - \underline{B}\underline{C} = 1 \Rightarrow \underline{C}^2 \cdot \underline{Z}_{10} \cdot \underline{Z}_{20} - \underline{C}^2 \underline{Z}_{10} \cdot \underline{Z}_{20c} = 1$

or
(nau) $\underline{C}^2 \cdot \underline{Z}_{10} \cdot \underline{Z}_{20} - \underline{C}^2 \cdot \underline{Z}_{20} \cdot \underline{Z}_{10c} = 1$

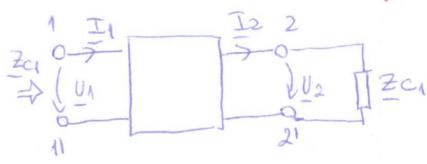
$$\Rightarrow \underline{C} = \pm \frac{1}{\sqrt{\underline{Z}_{20}(\underline{Z}_{10} - \underline{Z}_{10c})}} = \pm \frac{1}{\sqrt{\underline{Z}_{10}(\underline{Z}_{20} - \underline{Z}_{20c})}}$$

5.4 Iterative impedances (Impedanțe caracteristice)

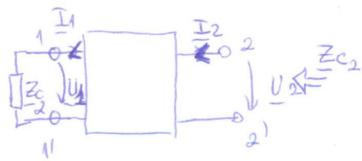
If a value of the output impedance \underline{Z}_c exists, for which the input impedance to a two-port is also \underline{Z}_c , then this impedance is known as iterative impedance:

$$\boxed{\underline{Z}_c = \frac{\underline{U}_1}{\underline{I}_1} = \frac{\underline{U}_2}{\underline{I}_2}}$$

Dacă există o valoare \underline{Z}_c a impedanței de ieșire a unui quadripol pentru care impedanța de intrare e tot \underline{Z}_c , aceasta se numește impedanță caracteristică.



$$\left\{ \begin{array}{l} \underline{U}_1 = \underline{A} \cdot \underline{U}_2 + \underline{B} \cdot \underline{I}_2 \\ \underline{I}_1 = \underline{C} \cdot \underline{U}_2 + \underline{D} \cdot \underline{I}_2 \end{array} \right. \Rightarrow \underline{Z}_{c1} = \frac{\underline{U}_1}{\underline{I}_1} = \frac{\underline{A} \cdot \underline{U}_2 + \underline{B} \cdot \underline{I}_2}{\underline{C} \cdot \underline{U}_2 + \underline{D} \cdot \underline{I}_2} = \underline{Z}_c$$



$$\left\{ \begin{array}{l} \underline{Z}_{c1} = \frac{\underline{A} \cdot \underline{Z}_{c1} + \underline{B}}{\underline{C} \cdot \underline{Z}_{c1} + \underline{D}} \\ \underline{Z}_{c2} = \frac{1}{2\underline{C}} \left[(\underline{D} - \underline{A}) \pm \sqrt{(\underline{D} - \underline{A})^2 + 4 \underline{B} \underline{C}} \right] \end{array} \right.$$

If the two-port is symmetrical (dacă quadripolul este simetric)

$$\underline{A} = \underline{D} \Rightarrow \boxed{\underline{Z}_{c1} = \underline{Z}_{c2} = \pm \sqrt{\frac{\underline{B}}{\underline{C}}} = \underline{Z}_c}$$

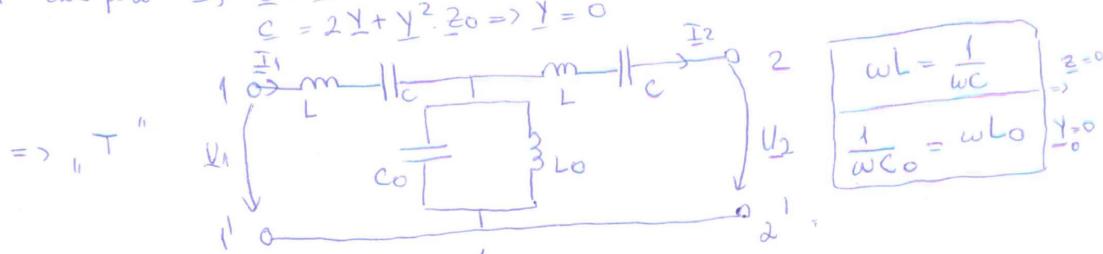
If $\underline{B} = \underline{C} = 0$ (particular case - caz particular) $\Rightarrow \underline{Z}_1 = \underline{Z}_2 = \underline{Z}; \underline{Y}_1 = \underline{Y}_2 = \underline{Y}$

$$\text{"T"-quadripol} \Rightarrow \underline{B} = \underline{Z}_1 + \underline{Z}_2 + \underline{Z}_1 \underline{Z}_2 \cdot \underline{Y}_0 = 2\underline{Z} + \underline{Z}^2 \cdot \underline{Y}_0 \Rightarrow \underline{Z} = 0$$

$$\underline{C} = \underline{Y}_0 = 0$$

$$\text{"II"-two port} \Rightarrow \underline{B} = \underline{Z}_0 = 0$$

$$\underline{C} = 2\underline{Y} + \underline{Y}^2 \cdot \underline{Z}_0 \Rightarrow \underline{Y} = 0$$



5.5. The propagation constant (constanta de propagare)

Can be computed for two-ports that are : $\begin{cases} \text{Symmetrical } A = D \\ \text{Reciprocal } AD - BC = 1 \\ \text{Load impedance} = \text{Termination impedance} = Z_C = \frac{U_2}{I_2} \\ \text{Impedance de sarcină} = \text{imped. caracteristică} \end{cases}$

$$\left\{ \begin{array}{l} U_1 = A \cdot U_2 + B \cdot I_2 = U_2 \left(A + B \cdot \frac{I_2}{U_2} \right) = U_2 \left(A + B \cdot \frac{1}{Z_C} \right) = U_2 \left(A + \sqrt{B \cdot C} \right) \\ I_1 = C \cdot U_2 + D \cdot I_2 = I_2 \left(C \cdot \frac{U_2}{I_2} + D \right) = I_2 \left(C \cdot Z_C + D \right) = I_2 \left(A + \sqrt{B \cdot C} \right) \end{array} \right.$$

$$\Rightarrow \underline{\gamma} = \ln \frac{U_1}{U_2} = \ln \frac{I_1}{I_2} = \ln (A + \sqrt{B \cdot C}) - \text{propagation constant}$$

$\underline{\gamma} = \alpha + j \cdot \beta$ phase constant (constanta de fază)
 $\rightarrow \alpha$ damping constant (constanta de atenuare)

$$e^{\underline{\gamma}} = \frac{U_1}{U_2} ; \quad \underline{\gamma} = \ln \left(\frac{U_1}{U_2} \cdot e^{j\beta} \right) = \underbrace{\ln \frac{U_1}{U_2}}_{\alpha} + j \cdot \beta \quad \begin{cases} \alpha = \ln \frac{U_1}{U_2} \\ \beta = \gamma_{U_1} - \gamma_{U_2} \end{cases}$$

$\frac{U_1}{U_2} = e^{\underline{\gamma}}$ $\Rightarrow \begin{cases} \alpha > 0 \Rightarrow U_2 < U_1 - \text{signal damped (semnal atenuat)} \\ \alpha = 0 \Rightarrow U_2 = U_1 - \text{the signal passes unchanged (semnal nemodificat)} \\ \alpha < 0 \Rightarrow U_2 > U_1 - \text{voltage amplification (semnal amplificat)} \end{cases}$

$$\left. \begin{array}{l} A \cdot D - B \cdot C = 1 \\ A = D \end{array} \right\} \Rightarrow A^2 - B \cdot C = 1 \Rightarrow \underbrace{(A - \sqrt{B \cdot C})}_{e^{-\underline{\gamma}}} \underbrace{(A + \sqrt{B \cdot C})}_{e^{\underline{\gamma}}} = 1$$

$$\Rightarrow \begin{cases} A + \sqrt{B \cdot C} = e^{\underline{\gamma}} \\ A - \sqrt{B \cdot C} = e^{-\underline{\gamma}} \end{cases} \Rightarrow \begin{cases} A = D = \frac{e^{\underline{\gamma}} + e^{-\underline{\gamma}}}{2} = \text{ch } \underline{\gamma} \\ \sqrt{B \cdot C} = \frac{e^{\underline{\gamma}} - e^{-\underline{\gamma}}}{2} = \text{sh } \underline{\gamma} \end{cases} \Rightarrow \begin{cases} A = D = \text{ch } \underline{\gamma} \\ B = Z_C \text{ sh } \underline{\gamma} \\ C = \frac{1}{Z_C} \text{ sh } \underline{\gamma} \end{cases}$$

$$\Rightarrow \text{Ec. fundamentală} \quad \begin{cases} U_1 = \text{ch } \underline{\gamma} \cdot U_2 + Z_C \cdot \text{sh } \underline{\gamma} \cdot I_2 \\ I_1 = \frac{1}{Z_C} \cdot \text{sh } \underline{\gamma} \cdot U_2 + \text{ch } \underline{\gamma} \cdot I_2 \end{cases}$$

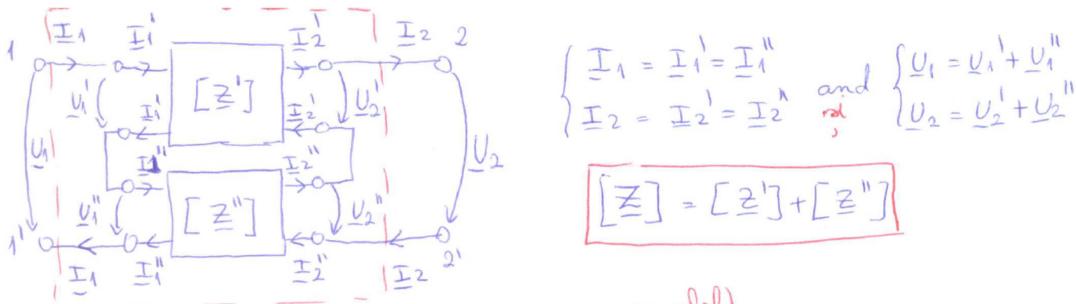
$$\text{For } \begin{cases} I_2 = 0 \text{ (open circuit)} \rightarrow Z_{10} = \frac{U_{10}}{I_{10}} = \frac{Z_C}{\text{th } \underline{\gamma}} \\ U_2 = 0 \text{ (short circuit)} \rightarrow Z_{1sc} = \frac{U_{1sc}}{I_{1sc}} = Z_C \cdot \text{th } \underline{\gamma} \end{cases} \Rightarrow \begin{cases} Z_C = \sqrt{Z_{10} \cdot Z_{1sc}} \\ \text{th } \underline{\gamma} = \sqrt{\frac{Z_{1sc}}{Z_{10}}} \end{cases}$$

5.6. Interconnection of two-port networks (Conexiunile quadripolilor)

5.6. Interconnection of two-port networks (conexiunea seriei)

[A] Series connection (conexiunea seriei)

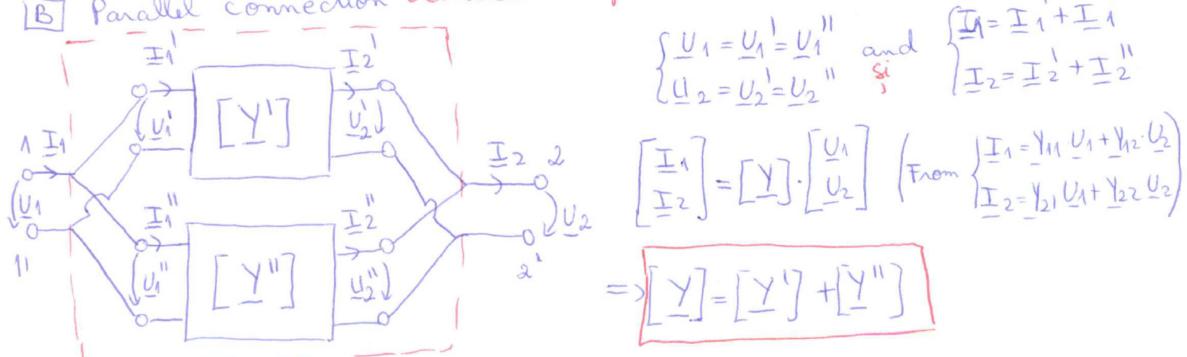
$$\begin{bmatrix} U_1 \\ U_2 \end{bmatrix} = [\underline{Z}] \cdot \begin{bmatrix} I_1 \\ I_2 \end{bmatrix} \quad (\text{From } \begin{cases} U_1 = Z_{11} \cdot I_1 + Z_{12} \cdot I_2 \\ U_2 = Z_{21} \cdot I_1 + Z_{22} \cdot I_2 \end{cases}) ; \quad [\underline{Z}] = [Z'] + [Z''] \quad \text{Serie!}$$



$$\begin{cases} \underline{I}_1 = \underline{I}_1' = \underline{I}_1'' \\ \underline{I}_2 = \underline{I}_2' = \underline{I}_2'' \end{cases} \text{ and } \begin{cases} \underline{U}_1 = \underline{U}_1' + \underline{U}_1'' \\ \underline{U}_2 = \underline{U}_2' + \underline{U}_2'' \end{cases}$$

$$[\underline{Z}] = [\underline{Z}'] + [\underline{Z}'']$$

(B) Parallel connection (conexiunea paralel)

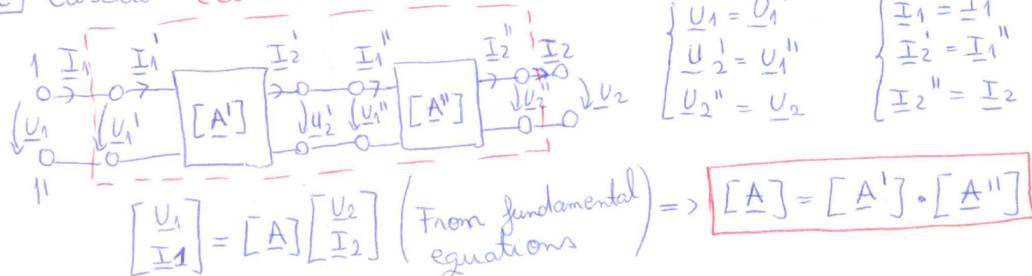


$$\begin{cases} \underline{U}_1 = \underline{U}_1' = \underline{U}_1'' \\ \underline{U}_2 = \underline{U}_2' = \underline{U}_2'' \end{cases} \text{ and } \begin{cases} \underline{I}_1 = \underline{I}_1' + \underline{I}_1'' \\ \underline{I}_2 = \underline{I}_2' + \underline{I}_2'' \end{cases}$$

$$[\underline{Y}] = [\underline{Y}'] \cdot \begin{bmatrix} \underline{U}_1 \\ \underline{U}_2 \end{bmatrix} \quad \text{From } \begin{cases} \underline{I}_1 = Y_{11} \underline{U}_1 + Y_{12} \underline{U}_2 \\ \underline{I}_2 = Y_{21} \underline{U}_1 + Y_{22} \underline{U}_2 \end{cases}$$

$$[\underline{Y}] = [\underline{Y}'] + [\underline{Y}'']$$

(C) Cascade (conexiunea în cascadă)

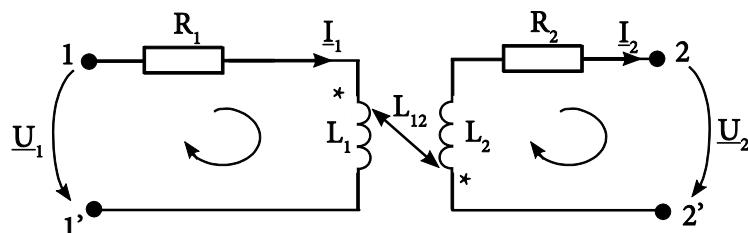


$$\begin{cases} \underline{U}_1 = \underline{U}_1' \\ \underline{U}_2' = \underline{U}_1'' \\ \underline{U}_2'' = \underline{U}_2 \end{cases} \quad \begin{cases} \underline{I}_1 = \underline{I}_1' \\ \underline{I}_2 = \underline{I}_1'' \\ \underline{I}_2'' = \underline{I}_2 \end{cases}$$

$$[\underline{A}] = [\underline{A}'] \cdot \begin{bmatrix} \underline{U}_2 \\ \underline{I}_2 \end{bmatrix} \quad \text{From fundamental equations} \Rightarrow [\underline{A}] = [\underline{A}'] \cdot [\underline{A}'']$$

Exemplu:

1. Pentru cuadripolul din figură, să se determine parametrii impedanță, $[\underline{Z}]$, și constantele fundamentale $\underline{A}, \underline{B}, \underline{C}, \underline{D}$.



Soluție:

Aplicând teorema a doua a lui Kirchhoff pentru cele două ochiuri de circuit rezultă sistemul:

$$\begin{cases} \underline{U}_1 = I_1 \cdot (R_1 + j\omega L_1) + I_2 \cdot j\omega L_{12} \\ -\underline{U}_2 = I_2 \cdot (R_2 + j\omega L_2) + I_1 \cdot j\omega L_{12} / \cdot (-1) \end{cases} \Rightarrow \begin{cases} \underline{U}_1 = I_1 \cdot (R_1 + j\omega L_1) + I_2 \cdot j\omega L_{12} \\ \underline{U}_2 = -I_2 \cdot (R_2 + j\omega L_2) - I_1 \cdot j\omega L_{12} \end{cases}$$

Tinând cont de parametrii impedanță, ecuațiile cuadripolului se rescriu:

$$\begin{cases} \underline{U}_1 = \underline{Z}_{11} \cdot I_1 + \underline{Z}_{12} \cdot I_2 \\ \underline{U}_2 = \underline{Z}_{21} \cdot I_1 + \underline{Z}_{22} \cdot I_2 \end{cases}$$

$$\Rightarrow \underline{Z}_{11} = R_1 + j\omega L_1; \quad \underline{Z}_{12} = j\omega L_{12}; \quad \underline{Z}_{21} = -j\omega L_{12}; \quad \underline{Z}_{22} = -(R_2 + j\omega L_2);$$

Se observă faptul că este îndeplinită condiția de reciprocitate pentru acest cuadripol: ($\underline{Z}_{12} = -\underline{Z}_{21}$)

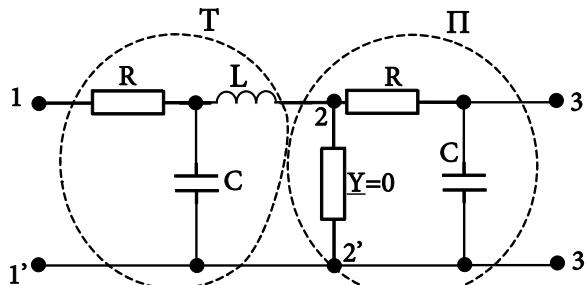
Expresiile lui A, B, C, D în funcție de parametrii impedanță se determină cu formulele:

$$\underline{A} = \frac{\underline{Z}_{11}}{\underline{Z}_{21}}; \quad \underline{B} = \frac{\underline{Z}_{12}^2 - \underline{Z}_{11} \cdot \underline{Z}_{21}}{\underline{Z}_{21}}; \quad \underline{C} = \frac{1}{\underline{Z}_{21}}; \quad \underline{D} = -\frac{\underline{Z}_{22}}{\underline{Z}_{21}}$$

Astfel se obțin:

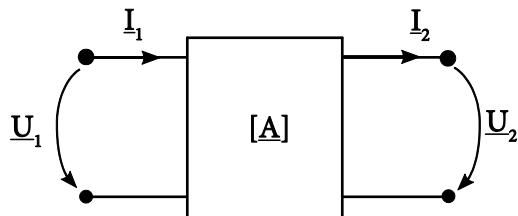
$$\underline{A} = -\frac{R_1 + j\omega L_1}{j\omega L_{12}}; \quad \underline{B} = -(R_1 + j\omega L_1 - j\omega L_{12}); \quad \underline{C} = -\frac{1}{j\omega L_{12}}; \quad \underline{D} = \frac{R_2 + j\omega L_2}{j\omega L_{12}}$$

2. Se cere schema echivalentă în π pentru cuadripolul din figură dacă $\omega^2 LC = 1$ ($\omega L = \frac{1}{\omega C}$).



Soluție

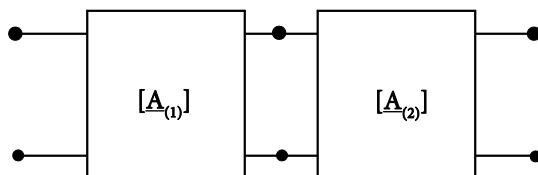
Orice cuadripol poate fi reprezentat ca în figura de mai jos:



Acesta este caracterizat de constantele sale fundamentale (grupate în matricea $[A]$), determinate conform relației:

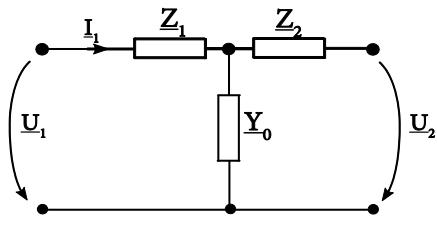
$$\begin{bmatrix} \underline{U}_1 \\ \underline{I}_1 \end{bmatrix} = \underbrace{\begin{bmatrix} A & B \\ C & D \end{bmatrix}}_{[A]} \cdot \begin{bmatrix} \underline{U}_2 \\ \underline{I}_2 \end{bmatrix}$$

Problema noastră poate fi deci privită ca o conexiune în lanț între doi cuadripoli, caracterizați de matricile $[A_{(1)}]$ și $[A_{(2)}]$:



Cuadripolul echivalent va putea fi determinat, în final, din relația: $\underline{A} = \begin{bmatrix} \underline{A}_{(1)} \\ \underline{A}_{(2)} \end{bmatrix}$

Primul cuadripol (în „T”):



Elementele schemei echivalente în „T” sunt:

$$\underline{Z}_1 = \frac{\underline{A}-1}{\underline{C}}, \quad \underline{Z}_2 = \frac{\underline{D}-1}{\underline{C}}, \quad \underline{Y}_0 = \underline{C};$$

$$\text{unde: } \underline{Z}_1 = R, \quad \underline{Z}_2 = j\omega L, \quad \underline{Y}_0 = j\omega C.$$

Ca urmare, constantele fundamentale ale acestui cuadripol se determină din relațiile:

$$\begin{cases} \underline{A} = 1 + \underline{Z}_1 \cdot \underline{Y}_0 \\ \underline{B} = \underline{Z}_1 + \underline{Z}_2 + \underline{Z}_1 \cdot \underline{Z}_2 \cdot \underline{Y}_0 \\ \underline{C} = \underline{Y}_0 \\ \underline{D} = 1 + \underline{Z}_2 \cdot \underline{Y}_0 \end{cases} \quad \text{obținându-se:}$$

$$\underline{A}_1 = 1 + \underline{Z}_1 \cdot \underline{Y}_0 = 1 + R \cdot j\omega C$$

$$\underline{B}_1 = \underline{Z}_1 + \underline{Z}_2 + \underline{Z}_1 \cdot \underline{Z}_2 \cdot \underline{Y}_0 = R + j\omega L + j\omega L \cdot R \cdot j\omega C = R + j\omega L + j^2 \cdot R = j\omega L \quad \text{Deoarece este}$$

$$\underline{C}_1 = \underline{Y}_0 = j\omega C$$

$$\underline{D}_1 = 1 + \underline{Z}_2 \cdot \underline{Y}_0 = 1 + j\omega L \cdot j\omega C = 0.$$

Îndeplinită condiția $\underline{AD} - \underline{BC} = 0 - j^2 = 1$, cuadripolul este reciproc. Dar fiindcă $\underline{A} \neq \underline{D}$, cuadripolul nu este simetric!

Matricea constanțelor fundamentale pentru acest cuadripol este:

$$\begin{bmatrix} \underline{A}_{(1)} \\ \underline{C}_1 \end{bmatrix} = \begin{bmatrix} \underline{A}_1 & \underline{B}_1 \\ \underline{C}_1 & \underline{D}_1 \end{bmatrix} = \begin{bmatrix} 1 + R \cdot j\omega C & j\omega L \\ j\omega C & 0 \end{bmatrix}.$$

Pentru cuadripolul al doilea, elementele schemei echivalente în „π” sunt:

$$\underline{Y}_1 = \frac{\underline{D}-1}{\underline{B}}, \quad \underline{Y}_2 = \frac{\underline{A}-1}{\underline{B}}, \quad \underline{Z}_0 = \underline{B}, \quad \text{unde: } \underline{Z}_0 = R, \quad \underline{Y}_1 = j\omega C, \quad \underline{Y}_2 = 0.$$

Drept urmare, constantele fundamentale se determină cu relațiile:

$$\begin{cases} \underline{A} = 1 + \underline{Z}_0 \cdot \underline{Y}_2 \\ \underline{B} = \underline{Z}_0 \\ \underline{C} = \underline{Y}_1 + \underline{Y}_2 + \underline{Y}_1 \cdot \underline{Y}_2 \cdot \underline{Z}_0 \\ \underline{D} = 1 + \underline{Z}_0 \cdot \underline{Y}_1 \end{cases} \quad \text{obținându-se:} \quad \begin{cases} \underline{A}_2 = 1 + R \cdot j\omega C \\ \underline{B}_2 = R \\ \underline{C}_2 = j\omega C \\ \underline{D}_2 = 1 \end{cases}.$$

Matricea constanțelor fundamentale pentru acest cuadripol este:

$$\begin{bmatrix} \underline{A}_{(2)} \\ \underline{C}_2 \end{bmatrix} = \begin{bmatrix} \underline{A}_2 & \underline{B}_2 \\ \underline{C}_2 & \underline{D}_2 \end{bmatrix} = \begin{bmatrix} 1 + R \cdot j\omega C & R \\ j\omega C & 1 \end{bmatrix}$$

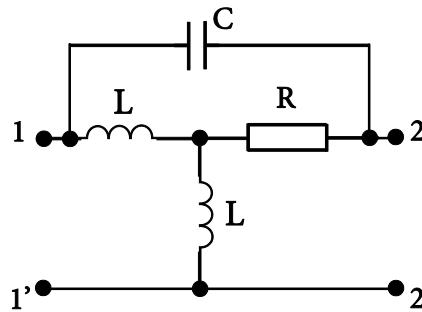
Revenind acum la cuadripolul echivalent, matricea constanțelor fundamentale ale acestuia este:

$$\begin{aligned} \begin{bmatrix} \underline{A}_{(\text{ech})} \\ \underline{C}_{\text{ech}} \end{bmatrix} &= \begin{bmatrix} \underline{A}_{(1)} \\ \underline{C}_1 \end{bmatrix} \cdot \begin{bmatrix} \underline{A}_{(2)} \\ \underline{C}_2 \end{bmatrix} = \begin{bmatrix} 1 + R \cdot j\omega C & j\omega L \\ j\omega C & 0 \end{bmatrix} \cdot \begin{bmatrix} 1 + R \cdot j\omega C & R \\ j\omega C & 1 \end{bmatrix} = \\ &= \begin{bmatrix} (1 + R \cdot j\omega C)^2 + j^2 \omega^2 LC & R(1 + R \cdot j\omega C) + j\omega L \\ j\omega C(1 + R \cdot j\omega C) & R \cdot j\omega C \end{bmatrix} = \\ &= \begin{bmatrix} R \cdot \omega C(2j - R \cdot \omega C) = \underline{A}_{\text{ech}} & R + R^2 \cdot j\omega C + \frac{j}{\omega C} = \underline{B}_{\text{ech}} \\ j\omega C - \omega^2 C^2 R = \underline{C}_{\text{ech}} & R \cdot j\omega C = \underline{D}_{\text{ech}} \end{bmatrix} \end{aligned}$$

Parametrii schemei echivalente în „ π ” se determină în final cu formulele:

$$\underline{Y}_1^{\text{ech}} = \frac{\underline{D}_{\text{ech}} - 1}{\underline{B}_{\text{ech}}} \quad \underline{Y}_2^{\text{ech}} = \frac{\underline{A}_{\text{ech}} - 1}{\underline{B}_{\text{ech}}} \quad \underline{Z}_0^{\text{ech}} = \underline{B}_{\text{ech}}$$

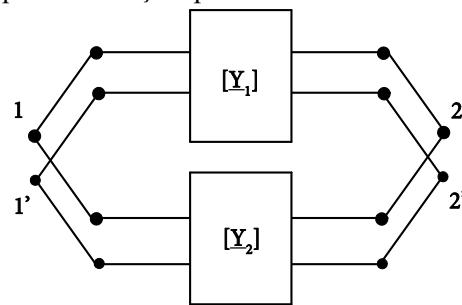
3. Se dă cuadripolul:



Să se determine elementele schemei echivalente în „T” știind că $\omega L = \frac{1}{\omega C} = R$.

Soluție:

Privim cuadripolul ca doi cuadripoli conectați în paralel:

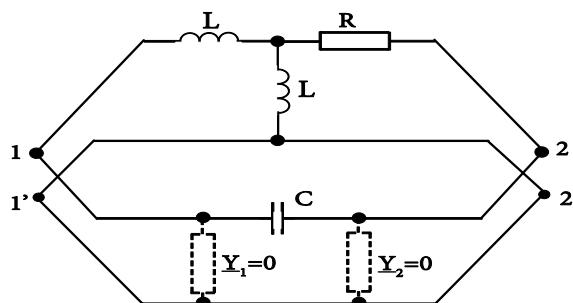


Fiecare dintre acești doi cuadripoli este caracterizat de ecuația matricială: $\begin{bmatrix} \underline{I}_1 \\ \underline{I}_2 \end{bmatrix} = \begin{bmatrix} \underline{Y}_{11} & \underline{Y}_{12} \\ \underline{Y}_{21} & \underline{Y}_{22} \end{bmatrix} \cdot \begin{bmatrix} \underline{U}_1 \\ \underline{U}_2 \end{bmatrix}$;

unde: $\underline{Y}_{11} = \frac{\underline{D}}{\underline{B}}$; $\underline{Y}_{12} = -\frac{\underline{A} \cdot \underline{D} - \underline{B} \cdot \underline{C}}{\underline{B}}$; $\underline{Y}_{21} = \frac{1}{\underline{B}}$; $\underline{Y}_{22} = -\frac{\underline{A}}{\underline{B}}$.

Condiția de reciprocitate pentru acești cuadripoli este: $\underline{Y}_{21} = -\underline{Y}_{12}$.

Primul cuadripol (în „T”):



Elementele schemei echivalente în „T” se identifică sub forma:

$$\underline{Z}_1 = j\omega L, \underline{Z}_2 = R, \underline{Y}_0 = \frac{1}{j\omega L};$$

iar constantele fundamentale sunt:

$$\begin{cases} \underline{A}_1 = 1 + \underline{Z}_1 \cdot \underline{Y}_0 = 1 + j\omega L \cdot \frac{1}{j\omega L} = 2; \\ \underline{B}_1 = \underline{Z}_1 + \underline{Z}_2 + \underline{Z}_1 \cdot \underline{Z}_2 \cdot \underline{Y}_0 = j\omega L + 2R = R(2+j); \\ \underline{C}_1 = \underline{Y}_0 = \frac{1}{j\omega L} = \frac{1}{jR}; \\ \underline{D}_1 = 1 + \underline{Z}_2 \cdot \underline{Y}_0 = 1 + R \cdot \frac{1}{j\omega L} = 1 - j. \end{cases}$$

Matricea admitanță: $\begin{bmatrix} \underline{Y}_{(1)} \end{bmatrix} = \begin{bmatrix} \underline{Y}_{11} & \underline{Y}_{12} \\ \underline{Y}_{21} & \underline{Y}_{22} \end{bmatrix}$ se determină imediat cu relațiile:

$$\underline{Y}_{11} = \frac{\underline{D}_1}{\underline{B}_1} = \frac{1-j}{R(2+j)}, \quad \underline{Y}_{12} = -\frac{2(1-j) - \frac{2+j}{j}}{R(2+j)} = -\frac{2-2j+2j-1}{R(2+j)} = -\frac{1}{R(2+j)};$$

$$\underline{Y}_{21} = \frac{1}{\underline{B}_1} = \frac{1}{R(2+j)}; \quad \underline{Y}_{22} = -\frac{\underline{A}_1}{\underline{B}_1} = -\frac{2}{R(2+j)}.$$

$$\text{Deci: } \begin{bmatrix} \underline{Y}_{(1)} \end{bmatrix} = \begin{bmatrix} \frac{1-j}{R(2+j)} & -\frac{1}{R(2+j)} \\ \frac{1}{R(2+j)} & -\frac{2}{R(2+j)} \end{bmatrix}.$$

Elementele schemei echivalente în „π” pentru al doilea cuadripol se identifică sub forma:

$$\underline{Y}_1 = 0, \underline{Y}_2 = 0; \underline{Z}_0 = \frac{1}{j\omega C}; \text{ iar constantele fundamentale sunt:}$$

$$\begin{cases} \underline{A}_2 = 1 + \underline{Z}_0 \cdot \underline{Y}_2 = 1 \\ \underline{B}_2 = \underline{Z}_0 = \frac{1}{j\omega C} = -jR \\ \underline{C}_2 = \underline{Y}_1 + \underline{Y}_2 + \underline{Y}_1 \cdot \underline{Y}_2 \cdot \underline{Z}_0 = 0 \\ \underline{D}_2 = 1 + \underline{Z}_0 \cdot \underline{Y}_1 = 1 \end{cases}$$

$$\text{Matricea admitanță se calculează direct și este: } \begin{bmatrix} \underline{Y}_{(2)} \end{bmatrix} = \begin{bmatrix} \frac{j}{R} & -\frac{j}{R} \\ \frac{j}{R} & -\frac{j}{R} \end{bmatrix}$$

Se observă că sunt îndeplinite condițiile:

$$\underline{Y}_{12} = -\underline{Y}_{21} \text{ (reciprocitate) și}$$

$$\underline{Y}_{22} = -\underline{Y}_{11} \text{ (simetrie).}$$

Cei doi cuadripoli fiind conectați în paralel, matricea admitanță a cuadripolului echivalent se obține cu relația:

$$[\underline{Y}] = \begin{bmatrix} \underline{Y}_{(1)} \\ \underline{Y}_{(2)} \end{bmatrix} = \begin{bmatrix} \frac{(1-j)+j(2+j)}{R(2+j)} & \frac{-1-j(2+j)}{R(2+j)} \\ \frac{1+j(2+j)}{R(2+j)} & \frac{-2-j(2+j)}{R(2+j)} \end{bmatrix} = \begin{bmatrix} \frac{j}{R(2+j)} & \frac{-2j}{R(2+j)} \\ \frac{2j}{R(2+j)} & \frac{-2j-1}{R(2+j)} \end{bmatrix}.$$

$$\text{Deci: } \underline{Y}_{11}^{\text{tot}} = \frac{j}{R(2+j)}; \quad \underline{Y}_{12}^{\text{tot}} = \frac{-2j}{R(2+j)}; \quad \underline{Y}_{21}^{\text{tot}} = \frac{2j}{R(2+j)}; \quad \underline{Y}_{22}^{\text{tot}} = \frac{-2j-1}{R(2+j)}.$$

De asemenea, constantele fundamentale ale cuadripolului echivalent sunt:

$$\underline{A}^{\text{tot}} = -\frac{\underline{Y}_{22}^{\text{tot}}}{\underline{Y}_{21}^{\text{tot}}} = \frac{2j+1}{R(2+j)} \cdot \frac{R(2+j)}{2j} = \frac{2j+1}{2j} = 1 + \frac{1}{2j} = 1 - j\frac{1}{2};$$

$$\underline{B}^{\text{tot}} = \frac{1}{\underline{Y}_{21}^{\text{tot}}} = \frac{R(2+j)}{2j} = \frac{R}{j} + \frac{1}{2} = \frac{1}{2} - jR;$$

$$\underline{C}^{\text{tot}} = \frac{-\underline{Y}_{11}^{\text{tot}} \cdot \underline{Y}_{22}^{\text{tot}} + \underline{Y}_{12}^{\text{tot}} \cdot \underline{Y}_{21}^{\text{tot}}}{\underline{Y}_{21}^{\text{tot}}} = \frac{\frac{(2j+1)j}{(R(2+j))^2} - \frac{(2j)^2}{(R(2+j))^2}}{\frac{2j}{R(2+j)}} =$$

$$= \frac{2j^2 + j - 4j^2}{(R(2+j))^2} \cdot \frac{R(2+j)}{2j} = \frac{2+j}{R(2+j)} \cdot \frac{1}{2j} = -j \cdot \frac{1}{2R};$$

$$\underline{D}^{\text{tot}} = \frac{\underline{Y}_{11}^{\text{tot}}}{\underline{Y}_{21}^{\text{tot}}} = \frac{j}{R(2+j)} \cdot \frac{R(2+j)}{2j} = \frac{1}{2}.$$

În final, găsim elementele cuadripolului echivalent în „T” ($\underline{Z}_1, \underline{Z}_2, \underline{Y}_0$):

$$\underline{Y}_0 = \underline{C}^{\text{tot}} = -j \frac{1}{2R}; \quad \underline{Z}_1 = \frac{\underline{A}^{\text{tot}} - 1}{\underline{Y}_0} = \frac{1 - j \frac{1}{2} - 1}{-j \frac{1}{2R}} = \frac{1}{2} \cdot 2R = R;$$

$$\underline{Z}_2 = \frac{\underline{D}^{\text{tot}} - 1}{\underline{Y}_0} = \frac{\frac{1}{2} - 1}{-j \frac{1}{2R}} = -jR.$$

Observație:

Aceeași schemă poate fi considerată ca fiind echivalentă cu doi cuadripoli conectați în serie, având structura din figura de mai jos. Problema poate fi astfel rezolvată utilizând parametrii impedanță în locul parametrilor admitanță, utilizati în schema paralel.

