Homework 3 - Convolutional Neural Network

This is the example code of homework 3 of the machine learning course by Prof. Hung-yi Lee.

In this homework, you are required to build a convolutional neural network for image classification, possibly with some advanced training tips.

There are three levels here:

Easy: Build a simple convolutional neural network as the baseline. (2 pts)

Medium: Design a better architecture or adopt different data augmentations to improve the performance. (2 pts)

Hard: Utilize provided unlabeled data to obtain better results. (2 pts)

```
from google.colab import drive
drive.mount("/content/drive")

    Mounted at /content/drive

%cd /content/drive/MyDrive/NTU_colab/hw3
    /content/drive/MyDrive/NTU_colab/hw3

import gc
import torch
gc.collect()
torch.cuda.empty cache()
```

```
gpu_info = !nvidia-smi
gpu_info = '\n'.join(gpu_info)
if gpu_info.find('failed') >= 0:
    print('Not connected to a GPU')
else:
    print(gpu_info)
,,,,
import urllib.request

url = 'https://download.pytorch.org/models/resnet34-333f7ec4.pth'
urllib.request.urlretrieve(url, 'resnet34-333f7ec4.pth')
,,,,
```

Sat Feb 17 07:22:04 2024

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'\nimport urllib.request\n\nurl = 'https://download.pytorch.org/models/resnet34-333f7ec4.pth'\nurllib.request.urlretri eve(url, 'resnet34-333f7ec4.pth')\n'

About the Dataset

The dataset used here is food-11, a collection of food images in 11 classes.

For the requirement in the homework, TAs slightly modified the data. Please DO NOT access the original fully-labeled training data or testing labels.

Also, the modified dataset is for this course only, and any further distribution or commercial use is forbidden.

```
#
!gdown --id 'lawF7pZ9Dz7X1jn1 QAiKN- v56veCEKy' --output food-11.zip
!unzip -q food-11.zip
# Download the dataset
# You may choose where to download the data.
# Google Drive
gdown --id 'lawF7pZ9Dz7X1jn1 QAiKN- v56veCEKy' --output food-11.zip
# Dropbox
# !wget https://www.dropbox.com/s/m9q6273j13djal1/food-11.zip -0 food-11.zip
# MEGA
# !sudo apt install megatools
# !megadl "https://mega.nz/#!zt1TTIhK!ZuMbg5ZjGWzWX1I6nEUbfjMZgCmAgeqJlwDkqdIryfg"
# Unzip the dataset.
# This may take some time.
!unzip -q food-11.zip
     /usr/local/lib/python3.10/dist-packages/gdown/cli.py:138: FutureWarning: Option `--id` was deprecated in version 4.3.1
       warnings.warn(
     Downloading...
     From (original): https://drive.google.com/uc?id=1awF7pZ9Dz7X1jn1 OAiKN- v56veCEKy
     From (redirected): https://drive.google.com/uc?id=1awF7pZ9Dz7X1jn1 QAiKN- v56veCEKy&confirm=t&uuid=957c51c9-3e84-4179-
     To: /content/drive/MyDrive/NTU colab/hw3/food-11.zip
     100% 963M/963M [00:05<00:00, 178MB/s]
     '\n# Download the dataset\n# You may choose where to download the data.\n\n# Google Drive\ngdown --id \'1awF7pZ9Dz7X1j
     n1 QAiKN- v56veCEKy\' --output food-11.zip\n\n# Dropbox\n# !wget https://www.dropbox.com/s/m9q6273jl3djall/food-11.zip
     -O food-11.zip\n\n# MEGA\n# !sudo apt install megatools\n# !megadl "https://mega.nz/#!zt1TTIhK!ZuMbg5ZjGWzWX1I6nEUbfjM
     ZgCmAgeqJlwDkqdIrvfg"\n\n# Unzip the dataset.\n# This may take some time.\n!unzip -q food-11.zip\n'
```

Import Packages

1. 清單項目

2. 清單項目

First, we need to import packages that will be used later.

In this homework, we highly rely on **torchvision**, a library of PyTorch.

```
# Import necessary packages.
import numpy as np
import torch
import torch.nn as nn
import torchvision
import torchvision.transforms as transforms
from PIL import Image
# "ConcatDataset" and "Subset" are possibly useful when doing semi-supervised learning.
from torch.utils.data import ConcatDataset, DataLoader, Subset, Dataset
from torchvision.datasets import DatasetFolder

# This is for the progress bar.
#from tqdm.auto import tqdm #may have some bug
from tqdm import tqdm
```

Change Dir to google drive

```
from google.colab import drive
drive.mount('/content/drive')

import os
os.chdir('/content/drive/My Drive/Colab Notebooks/hw3_data') #切換該目錄
os.listdir() #確認目錄內容
"""
```

'\nfrom google.colab import drive\ndrive.mount('/content/drive')\n\nimport os\nos.chdir('/content/drive/My Drive/Colab Notebooks/hw3_data') #切換該目錄\nos.listdir() #確認目錄內容\n'

Torchvision provides lots of useful utilities for image preprocessing, data wrapping as well as data augmentation.

Here, since our data are stored in folders by class labels, we can directly apply **torchvision.datasets.DatasetFolder** for wrapping data without much effort.

Please refer to <u>PyTorch official website</u> for details about different transforms.

```
# It is important to do data augmentation in training.
# However, not every augmentation is useful.
# Please think about what kind of augmentation is helpful for food recognition.
train_tfm = transforms.Compose([
       # Resize the image into a fixed shape (height = width = 128)
       transforms. Resize ((128, 128)),
       # You may add some transforms here.
       # ToTensor() should be the last one of the transforms.
       transforms. ToTensor(),
       #transforms. Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
])
train tfm2 = transforms.Compose([
       # Resize the image into a fixed shape (height = width = 128)
       transforms. Resize ((128, 128)),
       # ToTensor() should be the last one of the transforms.
       transforms. RandomHorizontalFlip (p=1.0),
       transforms. ToTensor(),
       #transforms. Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
])
train tfm3 = transforms.Compose([
       # Resize the image into a fixed shape (height = width = 128)
       transforms. Resize ((128, 128)),
       # ToTensor() should be the last one of the transforms.
       transforms. RandomRotation ((30, 180)),
       transforms. ToTensor(),
       #transforms. Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
7)
train tfm4 = transforms.Compose(
       transforms. Resize ((128, 128)),
       transforms. RandomPerspective (p=1.0),
       transforms. ToTensor(),
       #transforms. Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
])
train tfm5 = transforms.Compose([
       # Resize the image into a fixed shape (height = width = 128)
       transforms. Resize ((128, 128)),
       transforms. RandomHorizontalFlip(p=1.0),
       transforms. ToTensor(),
```

```
#transforms. Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
])
train_tfm6 = transforms.Compose([
       # Resize the image into a fixed shape (height = width = 128)
       transforms. Resize((128, 128)),
       transforms.ColorJitter(brightness=(0, 5), contrast=(
       0, 5), saturation=(0, 5), hue=(-0.1, 0.1)),
       transforms. ToTensor(),
       #transforms. Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
])
# We don't need augmentations in testing and validation.
# All we need here is to resize the PIL image and transform it into Tensor.
test tfm = transforms.Compose([
       transforms. Resize((128, 128)),
       transforms. ToTensor(),
       #transforms. Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
])
```

```
# Batch size for training, validation, and testing.
# A greater batch size usually gives a more stable gradient.
# But the GPU memory is limited, so please adjust it carefully.
batch size = 128
# Construct datasets.
# The argument "loader" tells how torchvision reads the data.
train_set1 = DatasetFolder("food-11/training/labeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train_tfm)
train set2 = DatasetFolder("food-11/training/labeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train tfm2)
train set3 = DatasetFolder("food-11/training/labeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train tfm3)
train_set4 = DatasetFolder("food-11/training/labeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train tfm4)
train set5 = DatasetFolder("food-11/training/labeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train tfm5)
train set6 = DatasetFolder ("food-11/training/labeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train tfm6)
train set = ConcatDataset([train set1, train set2, train set3, train set4, train set5, train set6])
valid set = DatasetFolder("food-11/validation", loader=lambda x: Image.open(x), extensions="jpg", transform=test tfm)
#unlabeled set = DatasetFolder("food-11/training/unlabeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train tfm)
unlabeled set1 = DatasetFolder("food-11/training/unlabeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train tfm)
unlabeled set2 = DatasetFolder("food-11/training/unlabeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train tfm2)
unlabeled set3 = DatasetFolder("food-11/training/unlabeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train tfm3)
unlabeled_set4 = DatasetFolder("food-11/training/unlabeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train_tfm4)
unlabeled set5 = DatasetFolder("food-11/training/unlabeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train tfm5)
unlabeled set6 = DatasetFolder("food-11/training/unlabeled", loader=lambda x: Image.open(x), extensions="jpg", transform=train tfm6)
unlabeled set = ConcatDataset([unlabeled set1, unlabeled set2, unlabeled set3, unlabeled set4, unlabeled set5, unlabeled set6])
test set = DatasetFolder("food-11/testing", loader=lambda x: Image.open(x), extensions="jpg", transform=test tfm)
  Construct data loaders.
# pin memory = false, data will be swapped to driver if necessary
# default num workers = 8
train loader = DataLoader(train set, batch size=batch size, shuffle=True, num workers=16, pin memory=True)
valid loader = DataLoader(valid set, batch size=batch size, shuffle=True, num workers=16, pin memory=True)
test loader = DataLoader(test set, batch size=batch size, shuffle=False)
```

/usr/local/lib/python3.10/dist-packages/torch/utils/data/dataloader.py:557: UserWarning: This DataLoader will create 16 worker processes in tot warnings.warn(create warning msg(

Model

The basic model here is simply a stack of convolutional layers followed by some fully-connected layers.

Since there are three channels for a color image (RGB), the input channels of the network must be three. In each convolutional layer, typically the channels of inputs grow, while the height and width shrink (or remain unchanged, according to some hyperparameters like stride and padding).

Before fed into fully-connected layers, the feature map must be flattened into a single one-dimensional vector (for each image). These features are then transformed by the fully-connected layers, and finally, we obtain the "logits" for each class.

WARNING -- You Must Know

You are free to modify the model architecture here for further improvement. However, if you want to use some well-known architectures such as ResNet50, please make sure **NOT** to load the pre-trained weights. Using such pre-trained models is considered cheating and therefore you will be punished. Similarly, it is your responsibility to make sure no pre-trained weights are used if you use **torch.hub** to load any modules.

For example, if you use ResNet-18 as your model:

model = torchvision.models.resnet18(pretrained=**False**) \rightarrow This is fine.

model = torchvision.models.resnet18(pretrained=**True**) \rightarrow This is **NOT** allowed.

```
class Classifier (nn. Module):
       def init (self):
               super(Classifier, self).__init__()
               # The arguments for commonly used modules:
               # torch.nn.Conv2d(in channels, out channels, kernel size, stride, padding)
               # out channels = feature filter num, by adding 3 RGB input channel result within 1 filter
               # torch.nn.MaxPool2d(kernel_size, stride, padding)
               # after 2x2 kernel maxpool, result will be intput witdth/2 * height/2
               # input image size: [3, 128, 128]
                    original
               self.cnn layers = nn.Sequential(
                      nn. Conv2d(3, 64, 3, 1, 1),
                      nn.BatchNorm2d(64),
                      nn. ReLU(),
                      nn. MaxPool2d(2, 2, 0),
                      nn. Conv2d (64, 128, 3, 1, 1),
                      nn.BatchNorm2d(128),
                      nn. ReLU(),
                      nn. MaxPool2d(2, 2, 0),
                      nn. Conv2d (128, 256, 3, 1, 1),
                      nn. BatchNorm2d(256),
                      nn. ReLU(),
                      nn. MaxPool2d(4, 4, 0),
               self.fc layers = nn.Sequential(
                      nn. Linear (256 * 8 * 8, 256),
                      nn. ReLU(),
                      nn. Linear (256, 256),
                      nn. ReLU(),
                      nn. BatchNorm1d(256),
                      nn. Dropout (p=0.5),
                      nn. Linear (256, 11)
               """
               # add 2 Conv layers
               self.cnn layers = nn.Sequential(
                      nn. Conv2d (3, 64, 3, 1),
                      nn. BatchNorm2d(64),
                      nn. ReLU(),
```

```
nn. MaxPool2d(2, 2, 0),
               nn. Conv2d (64, 128, 3, 1),
               nn.BatchNorm2d(128),
               nn. ReLU(),
               nn. MaxPool2d(2, 2, 0),
               nn. Conv2d (128, 256, 3, 1),
               nn. BatchNorm2d(256),
               nn. ReLU(),
               nn. MaxPool2d(2, 2, 0),
               nn. Conv2d (256, 512, 3, 1),
               nn.BatchNorm2d(512),
               nn. ReLU(),
               nn. MaxPool2d(2, 2, 0),
               nn. Conv2d (512, 1024, 3, 1),
               nn.BatchNorm2d(1024),
               nn. ReLU(),
               nn. MaxPoo12d(2, 2, 0)
       self.fc_layers = nn.Sequential(
               nn. Linear (4096, 1024),
               nn. ReLU(),
               nn.BatchNorm1d(1024),
               nn. Dropout (0.6),
               nn. Linear (1024, 256),
               nn.ReLU(),
               nn. BatchNorm1d(256),
               nn. Dropout (0.4),
               nn. Linear (256, 11)
       )
def forward(self, x):
       # input (x): [batch size, 3, 128, 128]
       # output: [batch_size, 11]
       # Extract features by convolutional layers.
       x = self.cnn_layers(x)
       # The extracted feature map must be flatten before going to fully-connected layers.
```

```
x = x.flatten(1)
# The features are transformed by fully-connected layers to obtain the final logits.
x = self.fc\_layers(x)
return x
```

Training

You can finish supervised learning by simply running the provided code without any modification.

The function "get_pseudo_labels" is used for semi-supervised learning. It is expected to get better performance if you use unlabeled data for semi-supervised learning. However, you have to implement the function on your own and need to adjust several hyperparameters manually.

For more details about semi-supervised learning, please refer to Prof. Lee's slides.

Again, please notice that utilizing external data (or pre-trained model) for training is prohibited.

```
class PseudoDataset (Dataset):
       def __init__(self, x, y):
               self.x = x
               self.y = y
       def len_(self):
              return len(self.y)
       def getitem (self, id):
               return self.x[id][0], self.y[id]
def get pseudo labels (dataset, model, threshold=0.9):
       # This functions generates pseudo-labels of a dataset using given model.
       # It returns an instance of DatasetFolder containing images whose prediction confidences exceed a given threshold.
       # You are NOT allowed to use any models trained on external data for pseudo-labeling.
       # from https://github.com/lam9trash/Hung Yi Lee ML 2021/blob/main/hw/hw3/hw3 code.ipynb
       device = "cuda" if torch.cuda.is available() else "cpu"
       # Construct a data loader.
       data loader = DataLoader(dataset, batch size=batch size, shuffle=False)
       # Make sure the model is in eval mode.
       model.eval()
       # Define softmax function.
       softmax = nn. Softmax (dim=-1)
       i dx = \begin{bmatrix} \end{bmatrix}
       labels = []
       # Iterate over the dataset by batches.
       for i, batch in enumerate (data loader):
               img, = batch
               with torch. no grad():
                      logits = model(img. to(device))
               probs = softmax(logits)
               for j, x in enumerate (probs):
                      if torch. max(x) > threshold:
                              idx.append(i * batch size + j)
                              labels. append (int (torch. argmax (x)))
```

model.train()

```
print ("\nNew pseudo label data: {:5d}\n".format(len(idx)))
       dataset = PseudoDataset (Subset (dataset, idx), labels)
       return dataset
   # "cuda" only when GPUs are available.
    device = "cuda" if torch.cuda.is available() else "cpu"
    # Initialize a model, and put it on the device specified.
    #model = Classifier().to(device)
    #resnet18
    model = torchvision. models. resnet18 (pretrained=False). to (device)
   model weight path = "./resnet18 pre.pth"
    model. load state dict(torch. load(model weight path), strict=False)
    #resnet34
    import torchvision. models as models
# Load the pre-trained ResNet-34 model
    model = models.resnet34(pretrained=False).to(device)
    #model = torchvision.models.resnet34(pretrained=False).to(device)
   model weight path = "./resnet34-333f7ec4.pth"
    model.load state dict(torch.load(model weight path), strict=False)
   num ftrs = model.fc.in features
    model.fc = nn.Linear(num ftrs, 11).to(device)
    model.device = device
    # fix para in model layers
    #for param in model.parameters():
            param.requires grad = True
    model.device = device
    # For the classification task, we use cross-entropy as the measurement of performance.
    criterion = nn. CrossEntropyLoss()
    # Initialize optimizer, you may fine-tune some hyperparameters such as learning rate on your own.
    optimizer = torch.optim.Adam(model.parameters(), 1r=0.0003, weight decay=1e-5)
```

1 0 1

```
# The number of training epochs.
n \text{ epochs} = 20
# Whether to do semi-supervised learning.
do semi = True
best acc = 0.0
train loss record = []
valid loss record = []
train acc record = []
valid acc record = []
for epoch in range (n epochs):
       # ----- TODO -----
       # In each epoch, relabel the unlabeled dataset for semi-supervised learning.
       # Then you can combine the labeled dataset and pseudo-labeled dataset for the training.
       if do semi and best acc > 0.75:
              # Obtain pseudo-labels for unlabeled data using trained model.
              pseudo set = get pseudo labels (unlabeled set, model)
              # Construct a new dataset and a data loader for training.
              # This is used in semi-supervised learning only.
              concat dataset = ConcatDataset([train set, pseudo set])
              train loader = DataLoader(concat dataset, batch size=batch size, shuffle=True, num workers=16, pin memory=True, drop last=
       # ----- Training -----
       # Make sure the model is in train mode before training.
       model. train()
       # These are used to record information in training.
       train loss = []
       train accs = []
       # Iterate the training set by batches.
       for batch in tqdm(train loader):
              # A batch consists of image data and corresponding labels.
              imgs, labels = batch
              # Forward the data. (Make sure data and model are on the same device.)
              logits = model(imgs.to(device))
              # Calculate the cross-entropy loss.
```

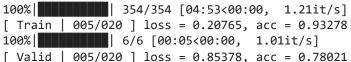
```
# We don't need to apply softmax before computing cross-entropy as it is done automatically.
       loss = criterion(logits, labels.to(device))
       # Gradients stored in the parameters in the previous step should be cleared out first.
       optimizer.zero grad()
       # Compute the gradients for parameters.
       loss. backward()
       # Clip the gradient norms for stable training.
       # 避免梯度爆炸or消失,將梯度限制在某個範圍
       grad norm = nn.utils.clip grad norm (model.parameters(), max norm=10)
       # Update the parameters with computed gradients.
       optimizer.step()
       # Compute the accuracy for current batch.
       acc = (logits.argmax(dim=-1) == labels.to(device)).float().mean()
       # Record the loss and accuracy.
       train loss.append(loss.item())
       train accs. append (acc)
# The average loss and accuracy of the training set is the average of the recorded values.
train loss = sum(train loss) / len(train loss)
train acc = sum(train accs) / len(train accs)
# Print the information.
print(f'') Train | {epoch + 1:03d}/{n epochs:03d} | loss = {train loss:.5f}, acc = {train acc:.5f}'')
# ----- Validation -----
# Make sure the model is in eval mode so that some modules like dropout are disabled and work normally.
model, eval()
# These are used to record information in validation.
valid loss = []
valid accs = []
# Iterate the validation set by batches.
for batch in tqdm(valid loader):
       # A batch consists of image data and corresponding labels.
```

imme labole = batch

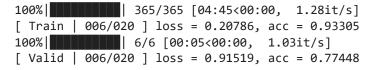
```
# We don't need gradient in validation.
       # Using torch.no grad() accelerates the forward process.
       with torch. no grad():
           logits = model(imgs.to(device))
       # We can still compute the loss (but not the gradient).
       loss = criterion(logits, labels.to(device))
       # Compute the accuracy for current batch.
       acc = (logits.argmax(dim=-1) == labels.to(device)).float().mean()
       # Record the loss and accuracy.
       valid loss.append(loss.item())
       valid accs. append (acc)
# The average loss and accuracy for entire validation set is the average of the recorded values.
valid loss = sum(valid loss) / len(valid loss)
valid acc = sum(valid accs) / len(valid accs)
# Print the information.
print(f''[Valid | {epoch + 1:03d}/{n epochs:03d}] loss = {valid loss:.5f}, acc = {valid acc:.5f}'')
if valid acc > best acc:
   best acc = valid acc
   torch. save (model. state dict(), './model.ckpt')
   print('saving model with acc {:.5f}'.format(best acc))
#record for visualization
train loss record. append (train loss)
valid loss record. append (valid loss)
train acc record. append (train acc)
valid acc record. append (valid acc)
```

imgs, labels - batch

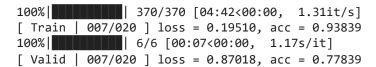
```
100% 297/297 [04:11<00:00, 1.18it/s]
[ Train | 002/020 ] loss = 0.36731, acc = 0.88336
100%| 6/6 [00:08<00:00, 1.40s/it]
[ Valid | 002/020 ] loss = 0.74181, acc = 0.79036
saving model with acc 0.79036
New pseudo label data: 23815
100% 330/330 [04:38<00:00, 1.19it/s]
[ Train \mid 003/020 ] loss = 0.26241, acc = 0.91551
100% | 6/6 [00:07<00:00, 1.26s/it]
[ Valid | 003/020 ] loss = 0.85470, acc = 0.80781
saving model with acc 0.80781
New pseudo label data: 26423
100% | 350/350 [04:40<00:00, 1.25it/s]
[ Train | 004/020 ] loss = 0.25360, acc = 0.91955
100% | 6/6 [00:07<00:00, 1.20s/it]
[ Valid | 004/020 ] loss = 0.68226, acc = 0.81667
saving model with acc 0.81667
New pseudo label data: 26920
100% | 354/354 [04:53<00:00, 1.21it/s]
```



New pseudo label data: 28241



New pseudo label data: 28943



New pseudo label data: 29055

322/371 [04:13<00:38, 1.27it/s]

→ Testing

For inference, we need to make sure the model is in eval mode, and the order of the dataset should not be shuffled ("shuffle=False" in test_loader).

Last but not least, don't forget to save the predictions into a single CSV file. The format of CSV file should follow the rules mentioned in the