```
#from google.colab import drive
#drive.mount('/content/drive')
      Mounted at /content/drive
%cd /content/drive/MyDrive/youtube_tutorial
#!unzip test.csv.zip
#!unzip train.csv.zip
      /content/drive/MyDrive/youtube_tutorial
     Archive: test.csv.zip
       inflating: test.csv
     Archive: train.csv.zip
       inflating: train.csv
  import torch
  from torch import nn
  import pandas as pd
  from torch import optim
  from torch.utils.data import DataLoader, Dataset
  from torchvision import transforms
  from \quad sklearn.\,model\_selection \quad import \quad train\_test\_split
  import matplotlib.pyplot as plt
  import numpy as np
  import \quad random \quad
  import timeit
  from \ tqdm \ import \ tqdm
RANDOM_SEED=42
BATCH_SIZE=512
EPOCHS=40
#Classification from learnable token
LEARNING_RATE=1e-4
NUM CLASS=10
PATCH_SIZE=4 # One size of a length of square size (4*4), like a respective field in CNN
IMAGE_SIZE=28 #Image is 28*28
IN_CHANNELS=1
NUM_HEADS=8
DROPOUT=0.001
HIDDEN_DIM=768
ADAM_WEIGHT_DECAY=0
ADAM BETAS=(0.9, 0.999)
ACTIVATION="gelu"
NUM_ENCODERS=4 #Stack 4 different encoder
EMBED_DIM=(PATCH_SIZE**2)*IN_CHANNELS #16
NUM_PATCHES=(IMAGE_SIZE//PATCH_SIZE)**2 #49
random.seed(RANDOM_SEED)
np. random. seed (RANDOM SEED)
torch.manual_seed(RANDOM_SEED)
torch.\,cuda.\,manual\_seed\,(\texttt{RANDOM\_SEED})
torch.cuda.manual_seed_al1(RANDOM_SEED)
torch.\ backends.\ cudnn.\ deterministic = True
torch.backends.cudnn.benchmark=False
```

device = "cuda" if torch.cuda.is\_available() else "cpu"

```
class PatchEmbedding(nn.Module):
       def __init__(self, embed_dim, patch_size, num_patches, dropout, in_channels):
               super(). init ()
               #Init x=(512, 1, 28, 28)
               self.patcher = nn.Sequential(
                       nn. Conv2d (
                               in_channels=in_channels, #1
                               out channels=embed dim, #16
                               kernel size=patch size, #4
                               stride=patch_size, #4
                       ).
                       #As stride=4, the shape become (512,16,7,7)
                       nn. Flatten(2))
                       # Keep the first 2 dimension of the data, then concat all of them after it
                       #(512, 16, 7*7)
                self.cls_token = nn.Parameter(torch.randn(size=(1, in_channels, embed_dim)), requires_grad=True) #Classification token, learnable
               #CLS stands for Classification token, torch randn creates a tensor filled with random number (normal distribution with mea
               #indicate it is a part of gradient descent
               #size (1 (Indicate it is a single classification tasks), in_channels (Indicate the image is grayscale), embed_dim stands
                self.position_embeddings = nn.Parameter(torch.randn(size=(1, num_patches+1, embed_dim)), requires_grad=True)
               #size=(1(Indicate it is a single classification tasks, number of total patches+1, number of input embedding ))
               self.dropout = nn.Dropout(p=dropout)
        def forward(self, x):
               {\tt cls\_token} \ = \ {\tt self.cls\_token.expand} \, ({\tt x.shape[0]}, \ -1, \ -1) \ \# {\tt Classification} \ \ {\tt token} \,
               x = self.patcher(x).permute(0, 2, 1)
               #x (512, 49, 16)
               x = \text{torch.cat}([cls\_token, x], dim=1)
               x = self.position\_embeddings + x
               x = self.dropout(x)
               return x
model = PatchEmbedding(EMBED_DIM, PATCH_SIZE, NUM_PATCHES, DROPOUT, IN_CHANNELS).to(device)
x = torch.randn(512, 1, 28, 28).to(device) #(Batch size, number of Channel, Image dimension x, Image dimension y)
print (model(x).shape)
     torch, Size ([512, 50, 16])
class ViT(nn.Module):
    def __init__(self, num_patches, img_size, num_classes, patch_size, embed_dim, num_encoders, num_heads, hidden_dim, dropout, activation, ir
        super().__init__()
        self.\ embeddings\_block=PatchEmbedding\ (embed\_dim, \quad patch\_size, \quad num\_patches, \quad dropout, \quad in\_channels)
        encoder_layer=nn.TransformerEncoderLayer(d_model=embed_dim, nhead=num_heads, dropout=dropout, activation=activation, batch_first=True, norm_f
        {\tt self.encoder\_block=nn.TransformerEncoder(encoder\_layer, num\_layers=num\_encoders)}
        self.mlp_head=nn.Sequential(
               nn.LayerNorm(normalized_shape=embed_dim),
               nn.Linear(in_features=embed_dim, out_features=num_classes)
    def forward(self, x):
        x=self.embeddings_block(x)
        x=self.encoder block(x)
        x=self.mlp\_head(x[:,0,:])
        return x
model=ViT(NUM_PATCHES, IMAGE_SIZE, NUM_CLASS, PATCH_SIZE, EMBED_DIM, NUM_ENCODERS, NUM_HEADS, HIDDEN_DIM, DROPOUT, ACTIVATION, IN_CHANNELS).to(6
#x=torch.randn(512, 1, 28, 28).to(device)
#print (model (x). shape)
     torch. Size([512, 10])
     /usr/local/lib/python3.10/dist-packages/torch/nn/modules/transformer.py:282: UserWarning: enable_nested_tensor is True, but self.use_nested_tensor is
       warnings.warn(f"enable_nested_tensor is True, but self.use_nested_tensor is False because {why_not_sparsity_fast_path}")
```

```
train_df=pd.read_csv("train.csv")
test_df=pd.read_csv('test.csv')
submission_df=pd.read_csv('sample_submission.csv')
```

## 按兩下 (或按 Enter 鍵) 即可編輯

train\_df.head()

	label	pixel0	pixel1	pixel2	pixel3	pixel4	pixel5	pixel6	pixel7	pixel8	• • •	рi
0	1	0	0	0	0	0	0	0	0	0		
1	0	0	0	0	0	0	0	0	0	0		
2	1	0	0	0	0	0	0	0	0	0		
3	4	0	0	0	0	0	0	0	0	0		
4	0	0	0	0	0	0	0	0	0	0		
5 rows × 785 columns									<b>&gt;</b>			

test\_df.head()

	pixel0	pixel1	pixel2	pixel3	pixel4	pixel5	pixel6	pixel7	pixel8	pixel9	• • •	p
0	0	0	0	0	0	0	0	0	0	0		
1	0	0	0	0	0	0	0	0	0	0		
2	0	0	0	0	0	0	0	0	0	0		
3	0	0	0	0	0	0	0	0	0	0		
4	0	0	0	0	0	0	0	0	0	0		
5 rows × 784 columns									•	<b>&gt;</b>		

submission\_df.head()

	ImageId	Label	
0	1	0	ıl.
1	2	0	
2	3	0	
3	4	0	
4	5	0	

Next steps: View recommended plots

 $train\_df, \quad val\_df = train\_test\_split(train\_df, \quad test\_size=0.1, \quad random\_state=RANDOM\_SEED, \quad shuffle=True)$ 

```
class MNISTTrainDataset(Dataset):
       def __init__(self, images, labels, indicies):
               self.images = images
               self.labels = labels
               self.indicies = indicies
               self, transform = transforms. Compose (
                       transforms. ToPILImage(),
                       transforms. RandomRotation (15),
                       transforms. ToTensor(),
                       transforms. Normalize ([0.5], [0.5])
               ])
        def __len__(self):
               return len(self.images)
        def __getitem__(self, idx):
               image = self.images[idx].reshape((28, 28)).astype(np.uint8)
               label = self.labels[idx]
               index = self.indicies[idx]
               image = self.transform(image)
               return {"image": image, "label": label, "index": index}
class MNISTValDataset(Dataset):
       def __init__(self, images, labels, indicies):
               self.images = images
               self.labels = labels
               self.indicies = indicies
               self.transform = transforms.Compose([
                       transforms. ToTensor(),
                       transforms. Normalize ([0.5], [0.5])
               ])
        def __len__(self):
               return len(self.images)
        def __getitem__(self, idx):
               image = self.images[idx].reshape((28, 28)).astype(np.uint8)
               label = self.labels[idx]
               index = self.indicies[idx]
               image = self.transform(image)
               return {"image": image, "label": label, "index": index}
{\tt class \ MNISTSubmitDataset(Dataset):}
        def __init__(self, images, indicies):
               self.images = images
               self.indicies = indicies
               self.transform = transforms.Compose([
                       transforms. ToTensor(),
                       transforms. Normalize([0.5], [0.5])
               ])
        def len (self):
              return len(self.images)
        def __getitem__(self, idx):
               image = self.images[idx].reshape((28, 28)).astype(np.uint8)
               index = self.indicies[idx]
               image = self.transform(image)
               return {"image": image, "index": index}
plt.figure()
f, axarr = plt.subplots(1, 3)
train_dataset = MNISTTrainDataset(train_df.iloc[:, 1:].values.astype(np.uint8), train_df.iloc[:, 0].values, train_df.index.values)
print(len(train_dataset))
print(train_dataset[0])
axarr[0].imshow(train_dataset[0]["image"].squeeze(), cmap="gray")
axarr[0].set_title("Train Image")
print("-"*30)
val_dataset = MNISTValDataset(val_df.iloc[:, 1:].values.astype(np.uint8), val_df.iloc[:, 0].values, val_df.index.values)
print(len(val_dataset))
print(val_dataset[0])
axarr[1].imshow(val dataset[0]["image"].squeeze(). cmap="grav")
```

```
axarr[1].set_title("Val Image")
print("-"*30)

test_dataset = MNISTSubmitDataset(test_df.values.astype(np.uint8), test_df.index.values)
print(len(test_dataset))
print(test_dataset[0])
axarr[2].imshow(test_dataset[0]["image"].squeeze(), cmap="gray")
axarr[2].set_title("Test Image")
print("-"**30)

plt.show()
```

```
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