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## Algorithm 1

```
Initialized variables:
  X: empty m-columns feature matrix
  y: empty target vector
  w^* = w_0: random weights for the regressor
  \gamma \in [0,1] discount rate
  \Delta = 0: number of actions
Other variables:
  f(): regressor function
  m: number of features
  p_t(x^*): stochastic process, function of the last existing chosen state
  X': m-columns simulated states matrix
  x_t(p_t) \in \mathbb{R}^{\mathrm{m}}: current state vector
  \Omega_t(x_t): set of possible actions
  \epsilon: randomness rate
  s(x^*) \in \mathbb{R}: signal value potentially triggered by the modified state
WHILE the learning process is on:
  record x_t
  X' := : \text{ empty } m\text{-columns matrix}
  FOR x' in \Omega_t(x_t):
     append x' to X'
  With probability 1 - \epsilon
     x^* := \operatorname{arg\,max}_{x' \in X'} f(w^*, X')
  With probability \epsilon
     x^* := \text{random sample } x' \in X'
  append x^* to X
  IF s(x^*) != 0:
     FOR \delta in 1:\Delta:
        value = d(\gamma, \Delta, \delta, s(x^*))
        append value to y
     w^* := \arg\min_{w} (l(f(w, X), y))
     \Delta := 0
  ELSE:
     \Delta += 1
```