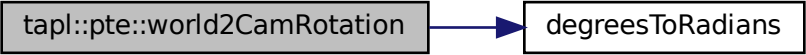


tapl::pte::world2CamRotation



```
graph LR; A[tapl::pte::world2CamRotation] --> B[degreesToRadians]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray fill and a black border, containing the text 'tapl::pte::world2CamRotation'. The right box has a white fill and a black border, containing the text 'degreesToRadians'. A dark blue arrow points from the right side of the left box to the left side of the right box.

degreesToRadians