

tapl::pte::world2CamRotation



```
graph LR; A[tapl::pte::world2CamRotation] --> B[degreesToRadians]
```

A diagram showing a mapping from the identifier `tapl::pte::world2CamRotation` to the function `degreesToRadians`. The identifier is enclosed in a gray rectangular box with a black border, and the function name is enclosed in a white rectangular box with a black border. A dark blue arrow points from the right side of the gray box to the left side of the white box.

degreesToRadians