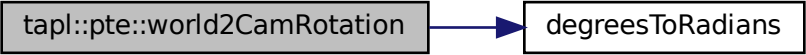


tapl::pte::world2CamRotation



```
graph LR; A[tapl::pte::world2CamRotation] --> B[degreesToRadians]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'tapl::pte::world2CamRotation'. The right box is white and contains the text 'degreesToRadians'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

degreesToRadians