

tapl::cve::computeEssential
Matrix

tapl::cve::computeRelativePose

tapl::CameraFrame::
getIntrinsicMatrix

```
graph LR; A[tapl::cve::computeEssentialMatrix] --> C[tapl::CameraFrame::getIntrinsicMatrix]; B[tapl::cve::computeRelativePose] --> C;
```

The diagram illustrates a dependency or relationship between three code elements. On the left, there are two white rectangular boxes. The top box contains the text 'tapl::cve::computeEssentialMatrix' and the bottom box contains 'tapl::cve::computeRelativePose'. On the right, there is a gray rectangular box containing the text 'tapl::CameraFrame::getIntrinsicMatrix'. Two blue arrows originate from the right side of the two white boxes and point towards the left side of the gray box, indicating that both functions on the left depend on or utilize the 'getIntrinsicMatrix' method.