# NGUYEN DONG HAI PHUONG

# Robotics Researcher - PhD Fellow

# **Personal Information**

Date of Birth: May, 17<sup>th</sup> 1987

Place of Birth: Da Nang city, Vietnam

Gender: Male
Nationality: Vietnamese

Address: Via Morego 30, Genova 16163, Italy

Mobile: +39 348 758 3270 (Italy)

+84 982435660 (Vietnam)

Email: <a href="mailto:phuong.nguyen@iit.it">phuong.nguyen@iit.it</a>

Website: <a href="https://towardthesea.github.io">https://towardthesea.github.io</a>

# **Research Interests**

Spatial perception and sensorimotor competences development in humanoid robotics.

Machine Learning application on Robots.

Control and Motion Planning.

Embedded Systems.

	cat	4 0	

Jan 2016 –	PhD Fellow in Bioengineering and	iCub Facility, Istituto Italiano di Tecnologia,
present	Robotics	Genova, Italy
Sep 2014 – Jul	Master 2 of Advanced Robotics	Università degli Studi di Genova, Genova, Italy
2015		http://goo.gl/c0qI5L
Sep 2013 – Jul	Master 1 of Advanced Robotics	Ecole Centrale de Nantes, Nantes, France
2014		http://goo.gl/BuJEup
		http://goo.gl/uX50yE
Sep 2005-Jul	Bachelor of Electrical Engineering	Da Nang University of Technology, Da Nang,
2010		Vietnam.

# **Academic Projects**

2016 – present	SECURE European project ( <u>http://secure-robots.eu</u> )
2016	WYSIWY European project ( <a href="http://wysiwyd.ufp.edu">http://wysiwyd.ufp.edu</a> )
2015	Real-time Path Generation and Control with obstacles avoidance of Multicopters -
	Toward Autonomous Aerial Vehicles for Search and Rescue
2014	Monitoring and controlling Baxter robot with Oculus Drift.
2014	Developing ROS (Robot Operating System) stack and localization ability for Khepera
	III mobile robot (K-team).

## **Professional Experience**

Jan 2016 - present	Robotics Researcher at iCub Facility, Istituto Italiano di Tecnologia, Italy.
Sep 2015 - Dec 2015	Collaborative Researcher at DIBRIS, Università degli Studi di Genova, Italy.
Feb 2015 - Sep 2015	Research student at Laboratorium lab, DIST, Università degli Studi di Genova, Italy.
Nov 2010 - Jan 2016	Lecturer at Faculty of Electrical Engineering, Da Nang University of Science and
	Technology, Vietnam.
Nov - Dec 2009	Intern at Van Thanh Medical Instruments Company, Da Nang, Vietnam.
Jul - Aug 2009	Intern at Pleikrong Hydropower Plant, Kontum city, Vietnam.

K	Schol	lars	hips	&	Aw	arc	ls
---	-------	------	------	---	----	-----	----

2016 – present	Marie Curie Early Stage Researcher Fellowship	<b>European Commission</b>
2013 - 2015	Eramus Mundus Scholarship	EMARO program
2010	Good Grade Graduation of Course 2005-2010	Da Nang University of
	Award	Technology, Vietnam
2009	Shinco Technos Scholarship for Excellent Students	Shinko Technos Co. Ltd
	of Da Nang University of Technology	
2008	Odon Vallet Scholarship for Excellent Students	Rencontres Du Vietnam
2007	Odon Vallet Scholarship for Excellent Students	Rencontres Du Vietnam

#### **Publications**

- 1. P. D. Nguyen, M. Hoffmann, U. Pattacini, and G. Metta, "A fast heuristic Cartesian space motion planning algorithm for many-DoF robotic manipulators in dynamic environments," presented at the Humanoid Robots (Humanoids), 2016 IEEE-RAS 16th International Conference on, 2016, pp. 884–891.
- 2. P. D. Nguyen, C. T. Recchiuto, and A. Sgorbissa, "Real-Time Path Generation and Obstacle Avoidance for Multirotors: A Novel Approach," Journal of Intelligent & Robotic Systems, pp. 1–23, 2017.
- 3. P. D. Nguyen, C. T. Recchiuto, and A. Sgorbissa, "Real-time path generation for multicopters in environments with obstacles," presented at the Intelligent Robots and Systems (IROS), 2016 IEEE/RSJ International Conference on, 2016, pp. 1582–1588.

### **Technical Skills**

Programming language:

• C/C++, Assembly: skilled user

o ROS C++ (Robot Operating System), OpenCV C++, YARP.

Python: good user.

Visual Basic: good user.

• Ladder, STL: good user (S7 Family of Siemens)

Simulation:

Matlab & Simulink: proficient user

 Power Electronic and Electric Machines, Automatic Control System, Robot Manipulator, Mobile Robot, System Identification and Digital Signal Processing.

Robots:

- Mobile robots: Khepera III (K-team), Firefly (Asctec), Mindstorms (LEGO)
- Manufacturing robots: Puma, Baxter (Rethink Robotics)
- Humanoid robots: iCub (IIT), Reem-C (Pal Robotics)

MPU/MCU:

- Microchip PIC16, PIC18 & dsPIC, Cypress PSoC: expert user.
- Intel 8086 MPU Family: good user.
- Atmel 8051 MCU Family: good user.
- TI Fixed- Point Digital Signal Processor Family, Stellaris Family: basic user.

# **Language Skills**

Vietnamese: mother-tongue

English: IELTS 6.5 (June 2012)

French: Beginner Italian: Beginner

#### **Extra-Curricular Activities**

Mar 2007

Liaison Officer in EWEC Meeting 2007 held in Da Nang city, Vietnam.

Oct 2006 Liaison Officer in APEC Tourism Ministerial Meeting held in Hoi An city, Quang Nam

province, Vietnam.

Sep 2006 Staff Volunteer in 16<sup>th</sup> APEC SOM III held in Da Nang city, Vietnam.

#### References

1. Professor Giorgio Metta (PhD supervisor)

iCub Facility, Istituto Italiano di Tecnologia, Genova, Italy

Email: giorgio.metta@iit.it

2. Ugo Pattacini, PhD (PhD supervisor)

iCub Facility, Istituto Italiano di Tecnologia, Genova, Italy

Email: ugo.pattacini@iit.it

3. Professor Antonio Sgorbissa (Master thesis supervisor),

Laboratorium lab, DIST, Università degli Studi di Genova, Genova, Italy

Email: antonio.sgorbissa@unige.it

4. Professor Wisama Khalil,

Robotics group, IRCCyN, Ecole Centrale de Nantes, Nantes, France

Email: wisama.khalil@irccyn.ec-nantes.fr

5. Professor Garcia Gaetan,

Robotics group, IRCCyN, Ecole Centrale de Nantes, Nantes, France

Email: gaetan.garcia@ec-nantes.fr

6. Dr. Nguyen Anh Duy,

Vice Rector, Da Nang College of Technology, University of Da Nang, Da Nang city, Vietnam

Email: naduy2000@gmail.com; naduy@dct.udn.vn