

Tae Ha "Jeff" Park

PH.D. CANDIDATE, DEPARTMENT OF AERONAUTICS & ASTRONAUTICS, STANFORD UNIVERSITY

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Education

Stanford University

PH.D. IN AERONAUTICS & ASTRONAUTICS

Stanford, CA

Apr. 2018 - Current

- Topic: Robust deep learning in spaceborne computer vision and autonomous navigation
- Advisor: Dr. Simone D'Amico.

Stanford University

M.S. IN AERONAUTICS & ASTRONAUTICS

Stanford, CA

Sep. 2017 - Apr. 2020

- Conducted research on deep learning, computer vision, spacecraft swarm navigation and optimization

Harvey Mudd College (HMC)

B.S. IN ENGINEERING

Claremont, CA

Aug. 2013 - May 2017

- Graduated with High Distinction (GPA: 3.81/4.0)
- Member of the Tau Beta Pi Engineering Honors Society
- De Pietro fellow in Civil Engineering

Experience

Infinite Orbits SAS

COMPUTER VISION AND GUIDANCE, NAVIGATION AND CONTROL (GNC) INTERN

Toulouse, France

Jun. 2022 - Aug. 2022

- Integrated a PyTorch-based neural networks into the MATLAB/Simulink-based closed-loop GNC simulator
- Constructed a satellite rendezvous simulator and scene renderer based on Unreal Engine 5 and C++ to train and validate convolutional neural networks for monocular pose estimation and tracking of known noncooperative spacecraft

Space Rendezvous Laboratory (SLAB), Stanford University

RESEARCH ASSISTANT | ADVISOR: DR. SIMONE D'AMICO

Stanford, CA

Jan. 2019 - Current

- Developed robust deep learning models and GNC algorithms for vision-based relative navigation in space to support future mission concepts such as on-orbit servicing and debris removal with the ultimate goal of improving the sustainability of the Earth's orbit
- Developed and calibrated the Testbed for Rendezvous and Optical Navigation (TRON) facility at SLAB that is capable of physically simulating spacecraft proximity operations with a mockup satellite model under high-fidelity spaceborne illumination settings and estimating high-accuracy pose labels 📺 📺
- Developed the next-generation open-source benchmark datasets (e.g., SPEED+, SHIRT) using TRON to train and validate spaceborne vision-based deep learning and navigation algorithms with emphasis on robustness across domain gap between synthetic training and target spaceborne data
- Organized the second international Satellite Pose Estimation Competition (SPEC2021) in collaboration with the European Space Agency 📄

Dynamics Laboratory, HMC

DE PIETRO FELLOW | ADVISOR: DR. ZIYAD DURON

Claremont, CA

May 2016 - May 2017

- Developed a method to assess the functionality of steel anchors embedded within a concrete dam based on the Performance-Based Testing using spectral analysis, spectrogram, and model verification
- Analyzed the earthquake response of Monticello dam by constructing and evaluating a lumped element model of dam, reservoir and a spillway

HMC

STUDENT RESEARCHER | ADVISOR: DR. PHILIP D. CHA

Claremont, CA

May 2016 - May 2017


- Developed a method to accelerate the modal convergence of the eigen-characteristics of uniform and non-uniform rods carrying various lumped attachments



Publications


Preprints


Park, T. H. and D'Amico, S. "Online Supervised Training of Spaceborne Vision during Proximity Operations using Adaptive Kalman Filtering." *arXiv preprint arxiv:2309.11645* (2023).


Peer-Reviewed Journal Articles


Park, T. H. and D'Amico, S. "Adaptive Neural-Network-Based Unscented Kalman Filter for Robust Pose Tracking of Noncooperative Spacecraft." *Journal of Guidance, Control, and Dynamics* (2023).  DOI: 10.2514/1.G007387.

Park, T. H. and D'Amico, S. "Robust Multi-Task Learning and Online Refinement for Spacecraft Pose Estimation across Domain Gap." *Advances in Space Research* (2023).   DOI: 10.1016/j.asr.2023.03.036.


Pasqualetto Cassinis, L., **Park, T. H.**, Stacey, N., D'Amico, S., Menicucci, A., Gill, E., Ahrns, I. and Sanchez-Gestido, M. "Leveraging Neural Network Uncertainty in Adaptive Unscented Kalman Filter for Spacecraft Pose Estimation." *Advances in Space Research* (2023).  DOI: 10.1016/j.asr.2023.02.021.


Park, T. H., Märtens, M., Jawaid, M., Wang, Z., Chen, B., Chin., T.-J., Izzo, D. and D'Amico, S. "Satellite Pose Estimation Competition 2021: Results and Analyses." *Acta Astronautica* (2023).  DOI: 10.1016/j.actaastro.2023.01.002.



Kisantal, M., Sharma, S., **Park, T. H.**, Izzo, D., Märtens, M. and D'Amico, S. "Satellite Pose Estimation Challenge: Dataset, Competition Design and Results." *IEEE Transactions on Aerospace and Electronic Systems* (2020).  DOI: 10.1109/TAES.2020.2989063.


Cha, P. D. and **Park, T. H.** "Improved Modal Convergence Using the Assumed Modes Method for Rods Carrying Various Lumped Elements." *International Journal of Mechanical Engineering Education* (2018).  DOI: 10.1177/0306419017720424.


Conference Proceedings & Presentations


Park, T. H. and D'Amico, S. "Adaptive Neural Network-based Unscented Kalman Filter for Spacecraft Pose Tracking at Rendezvous." 2022 AAS/AIAA Astrodynamics Specialist Conference, Charlotte, North Carolina, August 7-11 (2022). 

Park, T. H. and D'Amico, S. "Robust Multi-Task Learning and Online Refinement for Spacecraft Pose Estimation across Domain Gap." 11th International Workshop on Satellite Constellations & Formation Flying, Milano, Italy, June 7-10 (2022). 


Park, T. H., Märtens, M., Lecuyer, G, Izzo, D. and D'Amico, S. "SPEED+: Next-Generation Dataset for Spacecraft Pose Estimation across Domain Gap." 2022 IEEE Aerospace Conference (2022).   DOI: 10.1109/AERO53065.2022.9843439.

Park, T. H., Bosse, J. and D'Amico, S. "Robotic Testbed for Rendezvous and Optical Navigation: Multi-Source Calibration and Machine Learning Use Cases." 2021 AAS/AIAA Astrodynamics Specialist Conference, Virtual, August 8 - 12 (2021). 

Park, T. H. and D'Amico, S. "Generative Model for Spacecraft Image Synthesis using Limited Dataset." 2020 AAS/AIAA Astrodynamics Specialist Conference, South Lake Tahoe, California, August 9 - 13 (2020). 

Park, T. H., Sharma, S. and D'Amico, S. "Towards Robust Learning-Based Pose Estimation of Noncooperative Spacecraft." 2019 AAS/AIAA Astrodynamics Specialist Conference, Portland, Maine, August 11 - 15 (2019).  **<Best Paper Award>**

Datasets

Park, T. H. and D'Amico, S. "SHIRT: Satellite Hardware-In-the-loop Rendezvous Trajectories Dataset." *Stanford Digital Repository* (2022). Available at <https://purl.stanford.edu/zq716br5462>. 

Park, T. H., Märtens, M., Lecuyer, G, Izzo, D. and D'Amico, S. "Next Generation Spacecraft Pose Estimation Dataset (SPEED+)." *Stanford Digital Repository* (2021). Available at <https://purl.stanford.edu/wv398fc4383>.

Sharma, S., **Park, T. H.** and D'Amico, S. "Spacecraft Pose Estimation Dataset (SPEED)." *Stanford Digital Repository* (2019). Available at <https://purl.stanford.edu/dz692fn7184>.

Skills

Programming	MATLAB/Simulink, Python, C/C++, \LaTeX
Libraries	PyTorch, ONNXRuntime, Cython, OpenCV, CVX
Tools	OpenGL, Unreal Engine
Languages	Korean (native), English (fluent), Japanese (proficient), Chinese (elementary), French (elementary)

Leadership

'16 - '17	Secretary , Tau Beta Pi (TBP) Engineering Honors Society, HMC chapter	Claremont, CA
'16	Clinic Project Leader , leading a 6-person team on a year-long project sponsored by Hewlett Packard, Inc.	Claremont, CA

Teaching

'19, '21, '22	Teaching Assistant , AA279A: Space Mechanics	Stanford, CA
'16 - '17	Proctor , E79/80: Engineering Systems	Claremont, CA
'15 - '17	TBP Tutor , E72: Engineering Mathematics, E83: Continuum Mechanics, E101: Advanced Systems Engineering, E171: Dynamics of Elastic Systems	Claremont, CA

Honors & Awards

'19	Best Paper Award , 2019 AAS/AIAA Astrodynamics Specialist Conference	Portland, ME
'15	Tau Beta Pi Engineering Honors Society , HMC	Claremont, CA
'15	De Pietro Fellowship in Civil Engineering , HMC	Claremont, CA
'13	Harvey S. Mudd Merits , HMC	Claremont, CA
'13-'17	Dean's List , HMC	Claremont, CA