

Tae Ha (Jeff) Park

✉ tpark94@stanford.edu | 🌐 taehajeffpark.com | 📧 tpark94 | 📺 taehajeffpark | 📍 Tae Ha Park

Education

Stanford University

PH.D. IN AERONAUTICS & ASTRONAUTICS

Stanford, CA

Expected June 2024

- Topic: Robust deep learning in spaceborne computer vision and autonomous navigation.
- Advisor: Dr. Simone D'Amico.

Stanford University

M.S. IN AERONAUTICS & ASTRONAUTICS

Stanford, CA

April 2020

- Conducted research on deep learning, computer vision, spacecraft swarm navigation and optimization.

Harvey Mudd College (HMC)

B.S. IN ENGINEERING

Claremont, CA

May 2017

- Graduated with High Distinction (GPA: 3.81/4.0).

Research

Space Rendezvous Laboratory (SLAB), Stanford University

RESEARCH ASSISTANT. ADVISOR: DR. SIMONE D'AMICO

Stanford, CA

September 2018 - Current

- Developing robust deep learning models and GN&C algorithms for vision-based relative navigation in space to support future mission concepts such as on-orbit servicing and debris removal with the ultimate goal of improving the sustainability of the Earth's orbit.
- Developing and calibrating the robotic Testbed for Rendezvous and Optical Navigation (TRON) facility at SLAB to (1) physically simulate spacecraft proximity operations against a mockup satellite model under high-fidelity space-like illumination settings and (2) generate high-accuracy pose labels.
- Developing the next-generation benchmark datasets (e.g., SPEED+, SHIRT) using TRON to train and validate spaceborne vision-based deep learning and navigation algorithms with emphasis on robustness across domain gap between synthetic training and target spaceborne data.
- Organizing the second international Satellite Pose Estimation Competition (SPEC2021) in collaboration with the European Space Agency. [\[link\]](#)

Dynamics Laboratory, HMC

DE PIETRO FELLOW. ADVISOR: DR. ZIYAD DURON

Claremont, CA

May 2016 - May 2017

- Developed a method to assess the functionality of steel anchors embedded within a concrete dam based on the Performance-Based Testing using spectral analysis, spectrogram, and model verification.
- Analyzed the earthquake response of Monticello dam by constructing and evaluating a lumped element model of dam, reservoir and a spillway.

HMC

STUDENT RESEARCHER. ADVISOR: DR. PHILIP D. CHA

Claremont, CA

May 2016 - May 2017

- Developed a method to accelerate the modal convergence of the eigen-characteristics of uniform and non-uniform rods carrying various lumped attachments.

Internship

Infinite Orbits SAS

COMPUTER VISION AND GUIDANCE, NAVIGATION AND CONTROL (GNC) INTERN

Toulouse, France

June 2022 - August 2022

- Integrated a PyTorch-based neural networks into the MATLAB/Simulink-based closed-loop GNC simulator.
- Constructed a satellite rendezvous simulator and scene renderer based on Unreal Engine 5 (UE5) to train and validate neural networks for monocular pose estimation and tracking.

Publications

Journal Articles

Park, T. H., Märten, M., Jawaaid, M., Wang, Z., Chen, B., Chin., T.-J., Izzo, D., D'Amico, S. "Satellite Pose Estimation Competition 2021: Results and Analyses." Special Issue on AI for Space, Acta Astronautica (2022). [\(Revision under Review\)](#)

Park, T. H. and D'Amico, S. "Robust Multi-Task Learning and Online Refinement for Spacecraft Pose Estimation across Domain Gap." Advances in Space Research (2022). [\(Submitted\)](#)

Park, T. H. and D'Amico, S. "Adaptive Neural Network-based Unscented Kalman Filter for Robust Pose Tracking of Noncooperative Spacecraft." Journal of Guidance, Control, and Dynamics (2022). [\(Submitted\)](#)

Pasqualetto Cassinis, L., **Park, T. H.**, Stacey, N., D'Amico, S., Menicucci, A., Gill, E., Ahrens, I., Sanchez-Gestido, M. "Leveraging Neural Network Uncertainty in Adaptive Unscented Kalman Filter for Spacecraft Pose Estimation." Advances in Space Research (2022). [\(Submitted\)](#)

Kisantal, M., Sharma, S., **Park, T. H.**, Izzo, D., Märtens, M. and D'Amico, S. "Satellite Pose Estimation Challenge: Dataset, Competition Design and Results." *IEEE Transactions on Aerospace and Electronic Systems*, Vol. 56, No. 5, pp. 4083-4098 (2020). DOI: 10.1109/TAES.2020.2989063. [\[link\]](#)

Cha, P. D. and **Park, T. H.** "Improved Modal Convergence Using the Assumed Modes Method for Rods Carrying Various Lumped Elements." *International Journal of Mechanical Engineering Education*, Vol 46, Issue 1, pp. 3-30 (2018). DOI:10.1177/0306419017720424. [\[link\]](#)

Conference Proceedings

Park, T. H. and D'Amico, S. "Adaptive Neural Network-based Unscented Kalman Filter for Spacecraft Pose Tracking at Rendezvous." 2022 AAS/AIAA Astrodynamics Specialist Conference, Charlotte, North Carolina, August 7-11 (2022). [\[arXiv\]](#)

Park, T. H. and D'Amico, S. "Robust Multi-Task Learning and Online Refinement for Spacecraft Pose Estimation across Domain Gap." 11th International Workshop on Satellite Constellations & Formation Flying, Milano, Italy, June 7-10 (2022). [\[arXiv\]](#) [\[code\]](#)

Park, T. H., Märtens, M., Lecuyer, G, Izzo, D. and D'Amico, S. "SPEED+: Next-Generation Dataset for Spacecraft Pose Estimation across Domain Gap." 2022 IEEE Aerospace Conference (AERO), 2022, pp. 1-15, DOI: 10.1109/AERO53065.2022.9843439. [\[link\]](#) [\[code\]](#)

Park, T. H., Bosse, J. and D'Amico, S. "Robotic Testbed for Rendezvous and Optical Navigation: Multi-Source Calibration and Machine Learning Use Cases." 2021 AAS/AIAA Astrodynamics Specialist Conference, Virtual, August 8-12 (2021). [\[pdf\]](#)

Park, T. H. and D'Amico, S. "Generative Model for Spacecraft Image Synthesis using Limited Dataset." 2020 AAS/AIAA Astrodynamics Specialist Conference, South Lake Tahoe, California, August 9 - 13 (2020). [\[pdf\]](#)

Park, T. H., Sharma, S. and D'Amico, S. "Towards Robust Learning-Based Pose Estimation of Noncooperative Spacecraft." 2019 AAS/AIAA Astrodynamics Specialist Conference, Portland, Maine, August 11-15 (2019). **<Best Paper Award>** [\[pdf\]](#)

Datasets

Park, T. H., Märtens, M., Lecuyer, G, Izzo, D. and D'Amico, S. (2021). Next Generation Spacecraft Pose Estimation Dataset (SPEED+). Stanford Digital Repository. Available at <https://purl.stanford.edu/wv398fc4383>. <https://doi.org/10.25740/wv398fc4383>. [\[link\]](#)

Skills

Programming MATLAB/Simulink, Python, C++, \LaTeX
Libraries PyTorch, CVX, OpenCV
Tools Unreal Engine
Languages Korean⁵, English⁴, Japanese³, Chinese², French²

Leadership

2016 - 17 **Secretary**, Tau Beta Pi (TBP) Engineering Honors Society, HMC chapter Claremont, CA
2016 **Clinic Project Leader**, leading a 6-person team on a year-long project sponsored by Hewlett Packard, Inc. Claremont, CA

Teaching

2019, **Teaching Assistant**, AA279A: Space Mechanics Stanford, CA
2021-22
2016 - 17 **Proctor**, E79/80: Engineering Systems Claremont, CA
2016 **Tutor**, E171: Dynamics of Elastic Systems Claremont, CA
2015 - 17 **TBP Tutor**, E72: Engineering Mathematics, E83: Continuum Mechanics, E101: Advanced Systems Engineering Claremont, CA

Honors & Awards

2019 **Best Paper Award**, 2019 AAS/AIAA Astrodynamics Specialist Conference Portland, ME
2015 **Tau Beta Pi Engineering Honors Society**, HMC Claremont, CA
2015 **De Pietro Fellowship in Civil Engineering**, HMC Claremont, CA
2013 **Harvey S. Mudd Merits**, HMC Claremont, CA
2013-17 **Dean's List**, HMC Claremont, CA

⁵ native proficiency ⁴ full professional proficiency ³ professional working proficiency ² limited working proficiency