

# Project 1, Transformations

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## 1

**Matrices defined:**  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ ,  $B = \begin{bmatrix} 0 & 2 & -1 \\ 1 & 1 & 10 \end{bmatrix}$ ,  $V = \begin{bmatrix} 1 & 4 & 0 \end{bmatrix}$

When `show(A)`, `show(B)`, `show(V)` was input into the python terminal, the output from SageMath was  $\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ ,  $\begin{bmatrix} 0 & 2 & -1 \\ 1 & 1 & 10 \end{bmatrix}$ ,  $\begin{bmatrix} 1 & 4 & 0 \end{bmatrix}$  respectively. The matrices were repeated back to me as I originally entered them

$$\text{For } QQ \rightarrow RR \Rightarrow \begin{bmatrix} 1.0000000000000000 & 3.0000000000000000 \\ 2.0000000000000000 & 4.0000000000000000 \end{bmatrix}$$

$$\text{For } QQ \rightarrow RDF \Rightarrow \begin{bmatrix} 1.0 & 2.0 \\ 3.0 & 4.0 \end{bmatrix}$$

*RR* and *RDF* seem to be data types for the matrices. *RR* appears to be an arbitrary precision floating point, outputting the maximum number of decimal places allowed. It won't be as precise as *QQ*, which is symbolic math, nor will it be as fast as *RDF*, which seems to be reduced decimal form, but it will get you a precise decimal answer when you're looking for one.

$$\text{RREF}(B) = \begin{bmatrix} 1 & 0 & \frac{21}{2} \\ 0 & 1 & -\frac{1}{2} \end{bmatrix}$$

The command `I4 = identity matrix(n)` creates an identity matrix of the degree of the input `n`.

$$\text{For the original command: } \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \text{ For input = 2: } \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \text{ For input = 5: } \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

## 2

**New matrices defined:**  $C = \begin{bmatrix} 3 & 7 \\ 1 & 6 \end{bmatrix}$

**a:** In SageMath, to add:  $A+C$  results in  $\begin{bmatrix} 4 & 9 \\ 4 & 10 \end{bmatrix}$ , to subtract  $A-C$  results in  $\begin{bmatrix} -2 & -5 \\ 2 & -2 \end{bmatrix}$

Lastly, to multiply:  $A*C$  results in  $\begin{bmatrix} 5 & 19 \\ 13 & 45 \end{bmatrix}$ , bonus:  $\det(A*C)$  results in -22

**b:**

$$B^T = \begin{bmatrix} 0 & 1 \\ 2 & 1 \\ -1 & 10 \end{bmatrix} \text{ shows that } \forall x \in B \{x_{ij} \rightarrow x_{ji}\}$$

$A*C==C*A$  returned **false**, meaning  $AC \neq CA$

$(A*C).transpose()==A.transpose()*C.transpose()$  returned **false**, meaning  $(AC)^T \neq A^T C^T$

$(A+C).transpose()==A.transpose()+C.transpose()$  returned **true**, meaning  $(A+C)^T = A^T + C^T$

$(c*A).transpose()==c*A.transpose()$  returned **true** for  $c = 6$  and  $c = 10$ , meaning  $(cA)^T = c * A^T$

The left number of columns in the left matrix must equal the number of rows in the right matrix. If  $m$  is the number of columns in  $A$  and  $p$  is the number of rows in  $B$ , then  $m = p$  must be true. The output of matrix multiplication is going to be of dimension  $n \times q$

## 3

**a:** The output from the code is 4 graphs, each one containing 2 vectors. The blue arrows represent  $P1, P2, P3, P4$  and the purple arrows represent  $Q1, Q2, Q3, Q4$ . See the output tikzpictures [here](#)

**b:** Reflects across the  $y$  axis (or  $x_2$  axis). Vector  $(2, -4)$  becomes  $(-2, -4)$

**c:** Reflects across  $y = x$ ,  $(3, 7)$  becomes  $(7, 3)$  and  $(1, 0)$  becomes  $(0, 1)$

**d:** Reflects across  $y = -x$ ,  $(3, 7)$  becomes  $(-7, -3)$  and  $(1, 0)$  becomes  $(0, -1)$

**e:** Maintains  $x$  value, sets  $y$  value to 0.  $(3, 7)$  becomes  $(3, 0)$  and  $(0, 1)$  becomes  $(0, 0)$

**f:** Pretty much using the reciprocal of the columns of  $M$ , the matrix  $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$  resolves the reflection across the  $x_1$  axis, where  $(3, 7)$  becomes  $(-3, 7)$

**g:** The transformation  $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$  rotates the vector it is multiplied by by angle  $\theta$  counterclockwise.  $(3, 7)$  becomes approx.  $(-2.828, 7.071)$ , creating a  $45^\circ$  dihedral angle

## 4

### 4.1 Derivation

If  $\begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = a + b$ , then  $x_1a + x_2b = a + b$ , meaning  $x_1 = 1$ ,  $x_2 = 1$

If  $\begin{bmatrix} x_3 & x_4 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = a - b$ , then  $x_3a + x_4b = a - b$ , meaning  $x_3 = 1$ ,  $x_4 = -1$

Combining these together, we get transformation matrix  $A = T = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$

### 4.2 Check/Proof

Checking  $\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$  with the Identity Matrix  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ . The expected answer is  $\begin{bmatrix} 1+0 \\ 0-1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

$$\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \cdot 1 + 1 \cdot 0 \\ 1 \cdot 0 + -1 \cdot 1 \end{bmatrix} = \begin{bmatrix} 1+0 \\ 0-1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

We can observe the answer matches the expected, showing the transformation matrix  $A$  is the correct transformation. The answer was checked with SageMath

## 5 Determining the Transformation Matrix J

$$\begin{bmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \\ x_{31} & x_{32} \\ x_{41} & x_{42} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2x_1 - 5x_2 \\ 0 \\ x_1 + 4x_2 \\ x_2 \end{bmatrix}$$

### 5.1 Determining individual rows

Row 1:  $x_1x_{11} + x_2x_{12} = 2x_1 - 5x_2 \Rightarrow x_{11} = 2$  and  $x_{12} = -5$

Row 2:  $x_1x_{21} + x_2x_{22} = 0 \Rightarrow x_{21} = 0$  and  $x_{22} = -0$

Row 3:  $x_1x_{31} + x_2x_{32} = x_1 + 4x_2 \Rightarrow x_{31} = 1$  and  $x_{32} = 4$

Row 4:  $x_1x_{41} + x_2x_{42} = x_2 \Rightarrow x_{41} = 0$  and  $x_{42} = 1$

### 5.2 Combining the results

Combining the results back into the original matrix form:  $J = \begin{bmatrix} 2 & -5 \\ 0 & 0 \\ 1 & 4 \\ 0 & 1 \end{bmatrix}$

## 6 Extras

### 6.1 Section 3 tikzpictures

