

NVIDIA JETPACK 3.3

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User Documentation



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JetPack

NVIDIA JetPack SDK is the most comprehensive solution for building AI applications. Use the JetPack installer to flash your Jetson Developer Kit with the latest OS image, to install developer tools for both the host PC and Developer Kit, and to install the libraries and APIs, samples, and documentation needed to jumpstart your development environment.

What's Included in JetPack?

OS Image

A sample file system derived from Ubuntu for <u>Jetson</u>.

Libraries

- CUDA Toolkit for Host PC (Ubuntu with cross-development support)
- CUDA Toolkit for Jetson

CUDA Toolkit provides a comprehensive development environment for C and C++ developers building. GPU-accelerated applications. The toolkit includes a compiler for NVIDIA GPUs, math libraries, and tools for debugging and optimizing the performance of your applications.

- OpenCV
- VisionWorks

VisionWorks is a software development package for Computer Vision (CV) and image processing. It Includes VPI (Vision Programming Interface), a set of optimized CV primitives for use by CUDA developers. The NVX library enables direct access to VPI, and the OVX library enables indirect access to VPI via OpenVX framework.

cuDNN

CUDA Deep Neural Network library provides high-performance primitives for deep learning frameworks. It includes support for convolutions, activation functions and tensor transformations.

TensorRT

TensorRT is a high performance deep learning inference runtime for image classification, segmentation, and object detection neural networks. It speeds up deep learning inference as well as reducing the runtime memory footprint for convolutional and deconv neural networks.

MultiMedia API

The Jetson Multimedia API package provides low level APIs for flexible application development.

Camera application API: libargus offers a low-level frame-synchronous API for camera applications, with per frame camera parameter control, multiple (including

synchronized) camera support, and EGL stream outputs. RAW output CSI cameras needing ISP can be used with either libargus or GStreamer plugin. In either case, the V4L2 media-controller sensor driver API is used.

Sensor driver API: V4L2 API enables video decode, encode, format conversion and scaling functionality. V4L2 for encode opens up many features like bit rate control, quality presets, low latency encode, temporal tradeoff, motion vector maps, and more.

Developer Tools

NVIDIA System Profiler

A multi-core CPU PC sampling profiler that provides an interactive view of captured profiling data, helping improve overall application performance.

Tegra Graphics Debugger

A console-grade tool that allows developers to debug and profile OpenGL ES 2.0, OpenGL ES 3.1, and OpenGL 4.3-4.6 applications, enabling developers to get the most out of the Jetson platform.

Samples

- NVIDIA GameWorks OpenGL samples
- Multimedia API samples
- CUDA samples
- VisionWorks

Documentation

- Tegra Linux Driver Package Documentation
- JetPack Documentation

Release Notes

JetPack 3.3

What's New

• To increase security and data integrity, all server communications will now use the HTTPS protocol.

Known Issues

- Please use the default download and install directories provided by JetPack. Changing the directories may cause an installation error.
- The installation of VisionWorks results in Ubuntu distro OpenCV 2.4.9 packages to be installed, in addition to OpenCV 3.3.1. This does not affect the usage of OpenCV 3.3.1.

Download and Install JetPack

This document is intended to help you get familiar with installing JetPack, using the tools, and running sample code.

System Requirements

Host Platform:

Ubuntu Linux x64 v16.04

Note that a valid Internet connection and at least 10GB of disk space is needed for the complete installation of JetPack.

Target Platform:

- One of the following developer kits:
 - Jetson TX2
 - Jetson TX2i
 - Jetson TX1
- Additional target requirements:
 - USB Micro-B cable connecting Jetson to your Linux host for flashing.
 - (Not included in the developer kit) To connect USB peripherals such as keyboard, mouse, and [optional] USB/Ethernet adapter (for network connection), a USB hub could be connected to the USB port on the Jetson system.
 - An HDMI cable plugged into the HDMI port on Jetson Developer Kit, which is connected to an external HDMI display.
 - An Ethernet cable plugged into the on-board Ethernet port, which is connected to either a secondary network card on your Linux host or the same network router providing internet access for the Linux host.

Download the Latest JetPack Version

The latest version of JetPack is available in the NVIDIA Embedded Developer Zone at:

https://developer.nvidia.com/jetson-development-pack

All available JetPack downloads can be found at:

https://developer.nvidia.com/jetpack-archive

Downloading JetPack

- On the host machine running Ubuntu, create a new directory to store installation packages.
- Download JetPack-\${VERSION}.run into the new directory on the host Ubuntu machine.

Avoid running or installing JetPack in a path that contains a "." Paths that contain a "." are known to cause installation issues.

Installing JetPack

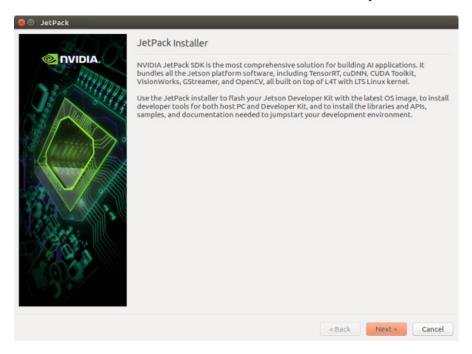
JetPack runs on the host Ubuntu x86_64 machine and sets up your development environment and Jetson Development Kit target via remote access. Please refer to the <u>System Requirements</u> section for supported hardware configurations.

The following instructions assume you have downloaded the latest JetPack version, JetPack-\${VERSION}.run, where \${VERSION} refers to the version string for the installer you have.

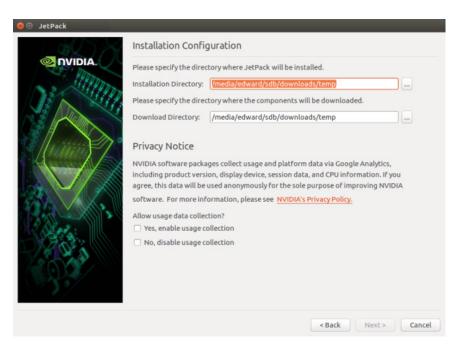
1. Add exec permission for the JetPack-\${VERSION}.run

chmod +x JetPack-\${VERSION}.run

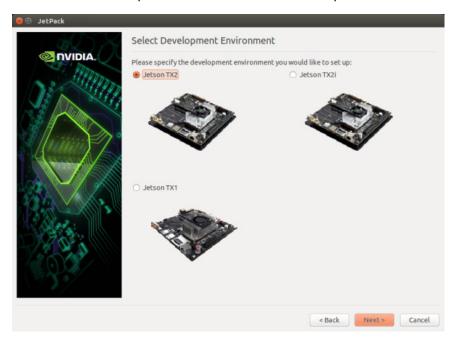
2. Run JetPack-\${VERSION}.run in terminal on your host Ubuntu machine.



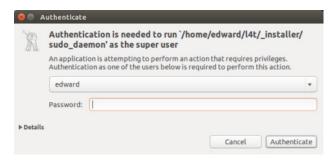
3. Next, the JetPack installer will indicate the installation directory. In the Privacy Notice section, select whether or not to enable data collection.



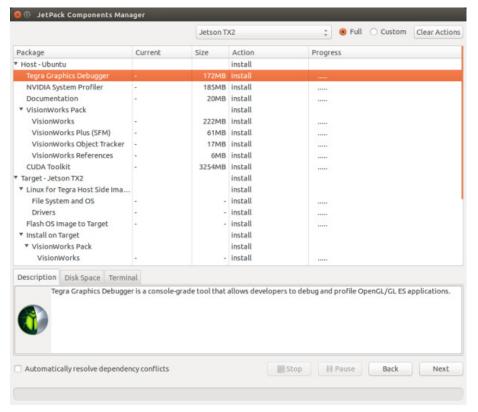
4. Select the development environment to setup.



5. The JetPack installer will pop up a window to ask for permission to use during the installation process; you will need to enter your sudo password here.

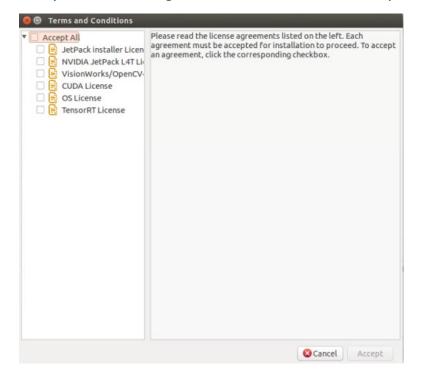


6. The Component Manager opens, which allows you to customize which components to install. Select the Jetson Developer Kit you would like to develop for to customize the installation components for each device.

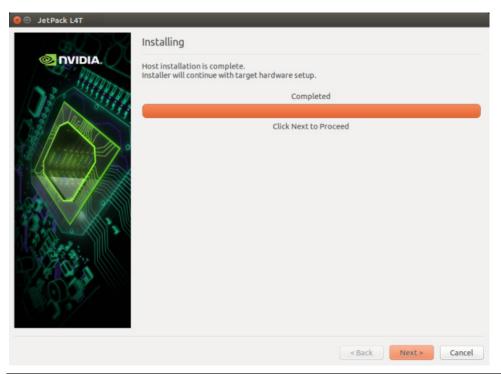


NOTE: To run a standalone Ubuntu install, deselect Jetson target specific entries.

7. Accept the license agreement for the selected components.

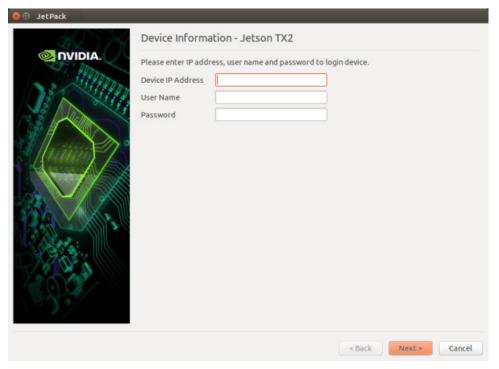


8. The Component Manager will proceed with the installation. Once the host installation steps are completed, click the Next button to continue with the installation of target components.



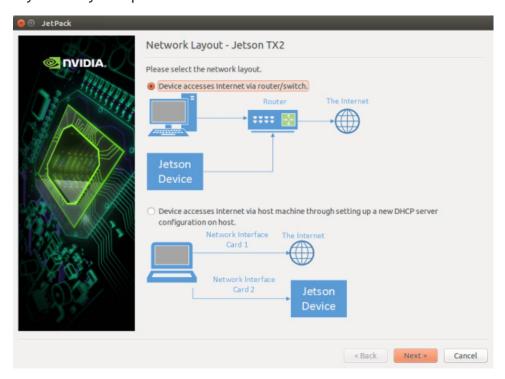
NOTE: JetPack will now proceed with setting up the Jetson Developer Kit target, if the corresponding components were selected (i.e., flashing the OS and pushing components to the Jetson Developer Kit target).

9. If you de-selected **Flash OS** in the <u>Component Manager</u>, you will need to enter the IP address, user name, and password to set up an ssh connection to the target device.

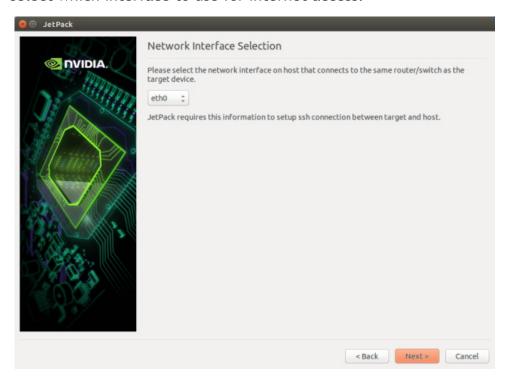


After you enter the required information and click **Next**, JetPack will begin installing components on the target device.

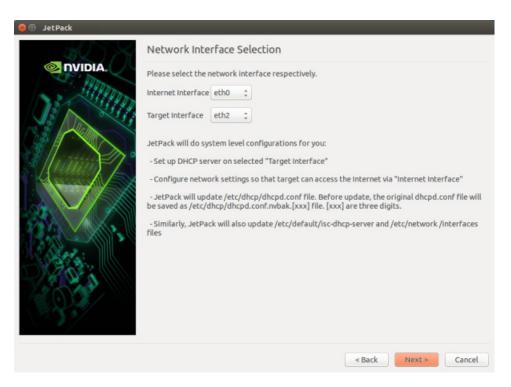
10. If you selected **Flash OS** in the <u>Component Manager</u>, you will need to select the network layout for your specific environment.



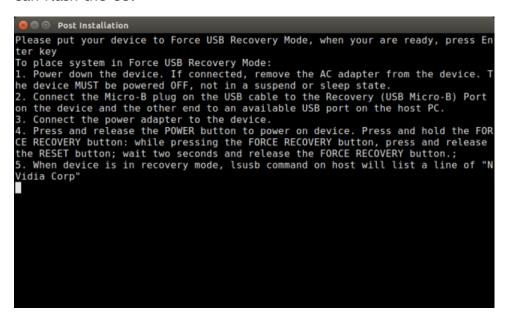
11. If you selected the **Device access Internet via router/switch** layout, you will be asked to select which interface to use for Internet access.



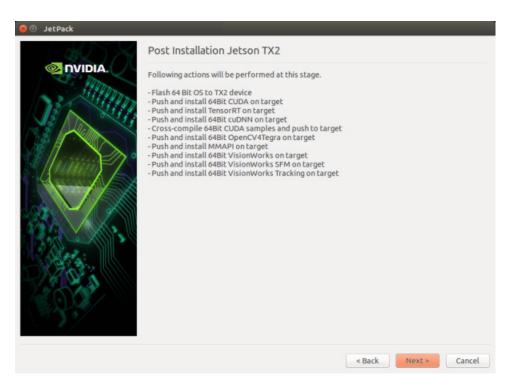
12. If you selected the **Device get IP assigned by DHCP server on host and access Internet via host machine** layout, you must select which interface is to be used for Internet access, and which is to be used for the target interface.



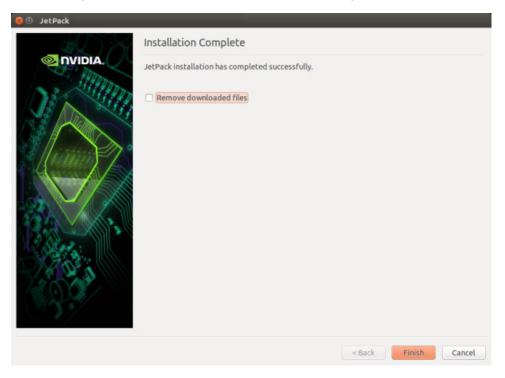
13. A pop-up window will instruct you to put your device into Force USB Recovery Mode, so you can flash the OS.



14. Next, you will be prompted to install components on the specific target machine, and to compile samples.



15. After the post installation tasks have been completed, the installation will be complete.



Compiling Samples

JetPack automatically compiles all samples, if **Compile Samples** was checked during the component selection portion of the installation. CUDA samples can be found in the following directory:

```
<JetPack_Install_Dir>/NVIDIA_CUDA-<version>_Samples
```

You can recompile the samples by running:

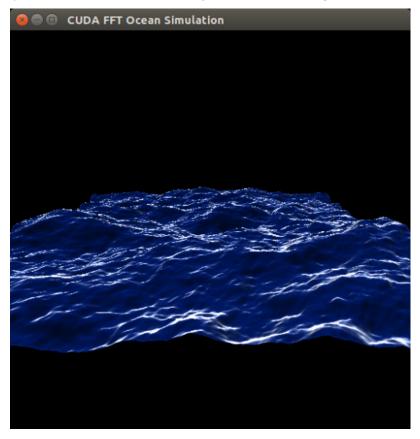
```
SMS=53 EXTRA_LDFLAGS=--unresolved-symbols=ignore-in-shared-libs TARGET ARCH=aarch64 make
```

Run Sample Code

The CUDA samples directory will be copied to the home directory on your device by JetPack. The built binaries are in the following directory:

```
/home/ubuntu/NVIDIA CUDA-<version> Samples/bin/aarch64/linux/release/
```

Run them by calling them in terminal, or double-clicking on them in the file browser. For example, when you run the oceanFFT sample, the following screen will be displayed.



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