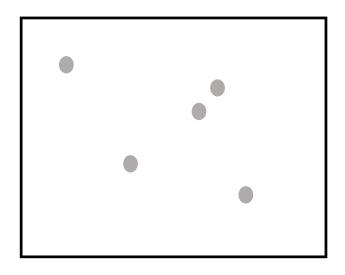
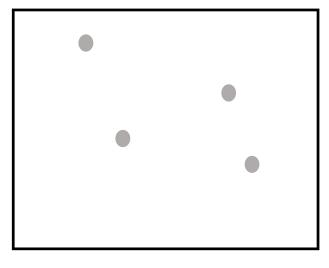
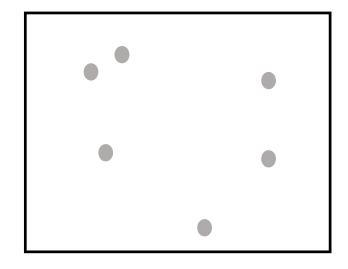
Tracking

Thierry Pécot
Research Engineer
Biosit SFR UMS CNRS 3480 – Inserm 018
CZI Imaging Scientist



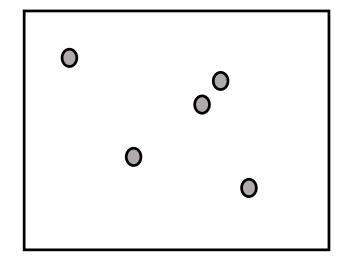


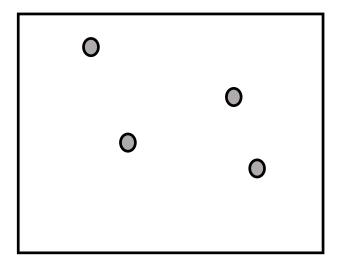


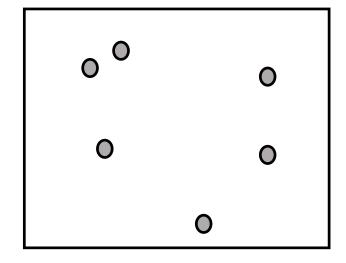


Frame #1 Frame #2 Frame #3

Segmentation

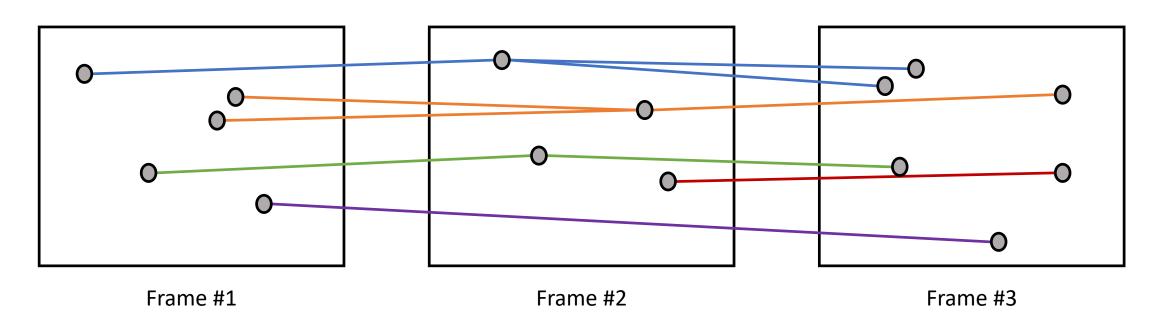




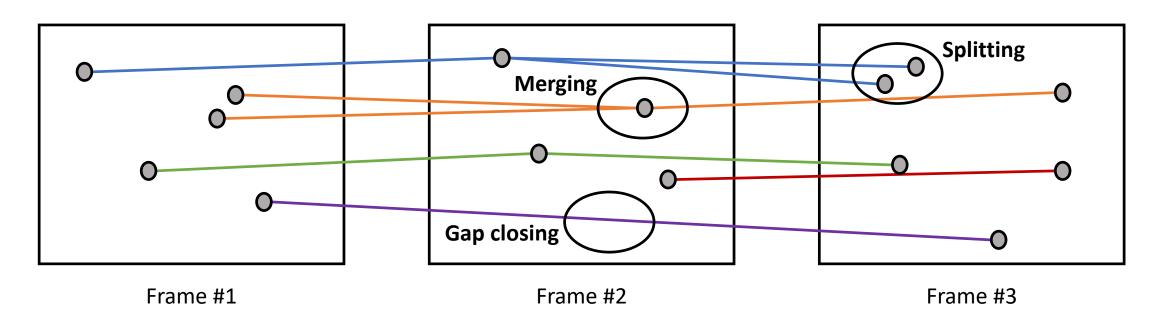


Frame #1 Frame #2 Frame #3

Data association, particle linking,...



Special events





Methods

Volume 115, 15 February 2017, Pages 80-90



TrackMate: An open and extensible platform for single-particle tracking

Jean-Yves Tinevez ^a △ , Nick Perry ^{a, 1}, Johannes Schindelin ^{b, 2}, Genevieve M. Hoopes ^c, Gregory D. Reynolds ^c, Emmanuel Laplantine ^d, Sebastian Y. Bednarek ^c, Spencer L. Shorte ^a, Kevin W. Eliceiri ^{b, e}

Bringing TrackMate into the era of machine-learning and deep-learning

- Dmitry Ershov, Minh-Son Phan, Doanna W. Pylvänäinen, DStéphane U. Rigaud, Laure Le Blanc,
- 🔟 Arthur Charles-Orszag, 🔟 James R. W. Conway, 🔟 Romain F. Laine, 🔟 Nathan H. Roy, 🔟 Daria Bonazzi,
- © Guillaume Duménil, © Guillaume Jacquemet, © Jean-Yves Tinevez

doi: https://doi.org/10.1101/2021.09.03.458852

This article is a preprint and has not been certified by peer review [what does this mean?].

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Published: 20 July 2008

Robust single-particle tracking in live-cell time-lapse sequences

Khuloud Jaqaman [™], Dinah Loerke, Marcel Mettlen, Hirotaka Kuwata, Sergio Grinstein, Sandra L Schmid & Gaudenz Danuser

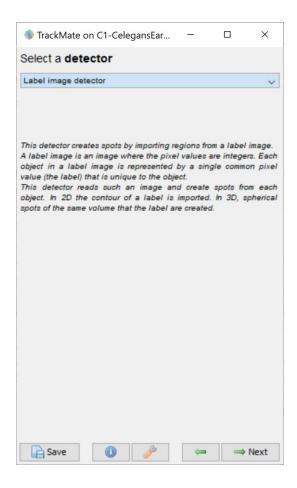
1 - SEGMENTATION



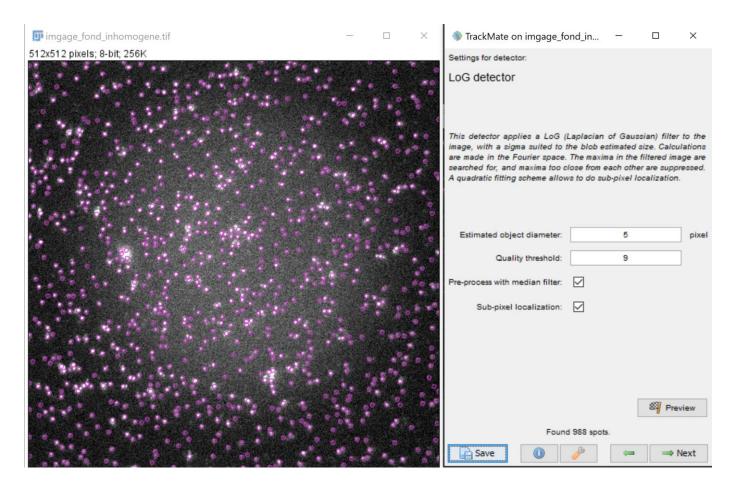
Classic detectors:

- Manual annotation
- Threshold detector
- DoG/LoG detector

1 - SEGMENTATION



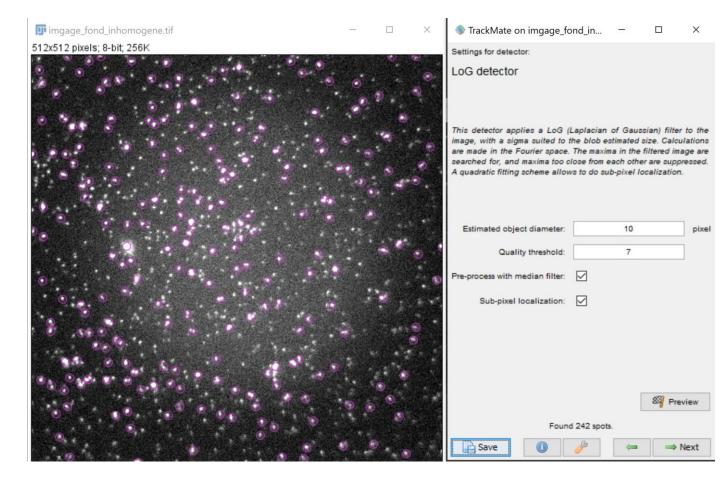
LoG detector: scale-based detector, powerful with **objects of the same size** such as intracellular particles



1 - SEGMENTATION



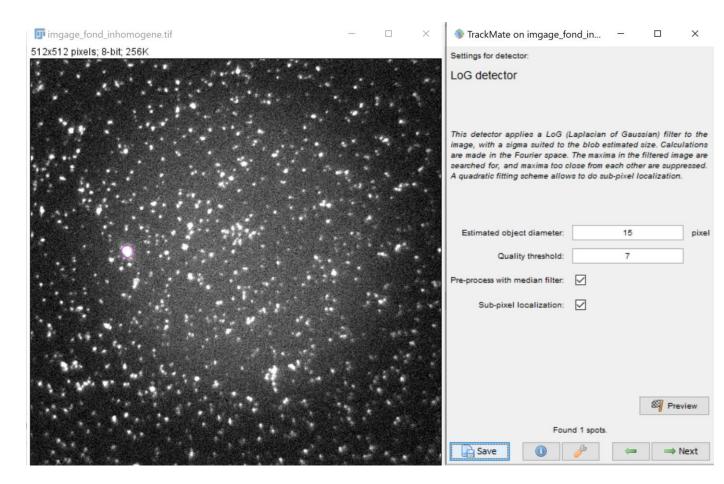
LoG detector: scale-based detector, powerful with **objects of the same size** such as intracellular particles



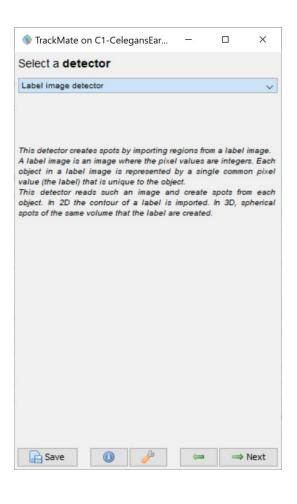
1 - SEGMENTATION



LoG detector: scale-based detector, powerful with **objects of the same size** such as intracellular particles



1 - SEGMENTATION



Classic detectors:

- Manual annotation
- Threshold detector
- DoG/LoG detector

New generation detectors:

- Stardist
- Cellpose
- Weka
- Ilastik
- MorpholibJ
- Custom segmentation via label images

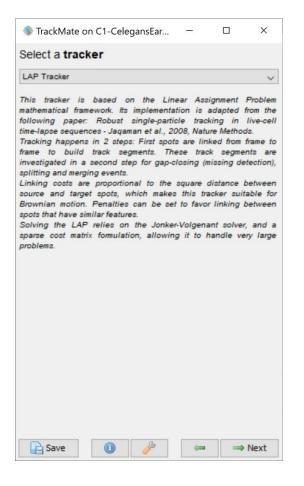
2 - SPOT FILTERING



Filter out spots based on spot features such as size, average intensity, ...

Possibility to visualize spot features with heat maps.

3 - DATA ASSOCIATION



Trackers:

- Manual tracking
- Overlap tracker: based on intersection over union between two consective frames – only 2D
- Nearest-neighbor tracker: associate closest particles between two consecutive frames
- Kalman tracker: based on Kalman filtering, suited for objects with directed and constant motion, allows gap closing
- Lap tracker: implementation of utrack (Jaqaman et al.), based on the Minear Assignment Problem mathematical framework, allows to change linking cost between particles by penalizing features and to perform splitting, merging and gap closing
- Simple LAP tracker: same as LAP tracker, without cost penalties, splitting and merging

4 - TRACK FILTERING



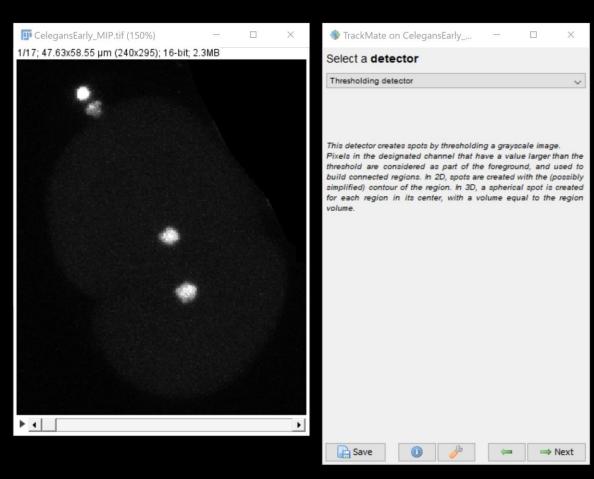
Filter out tracks based on track features such as number of spots, duration, ...

Possibility to **visualize track features** with heat maps.

Open CelegansEarly_MIP with **TrackMate** and segment cells with **Thresholding detector**

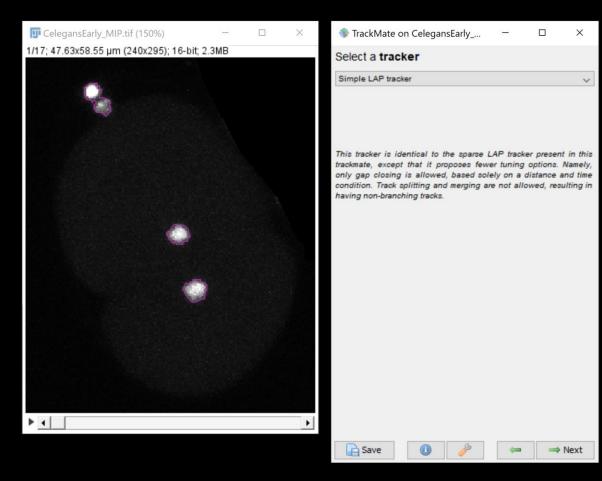
Filter out as many as possible **non-cell objects** but keep **all cells** detected





Use Simple LAP tracker, filter out track(s) corresponding to non-cell objects and manually split the tracks when cells divide with TrackScheme

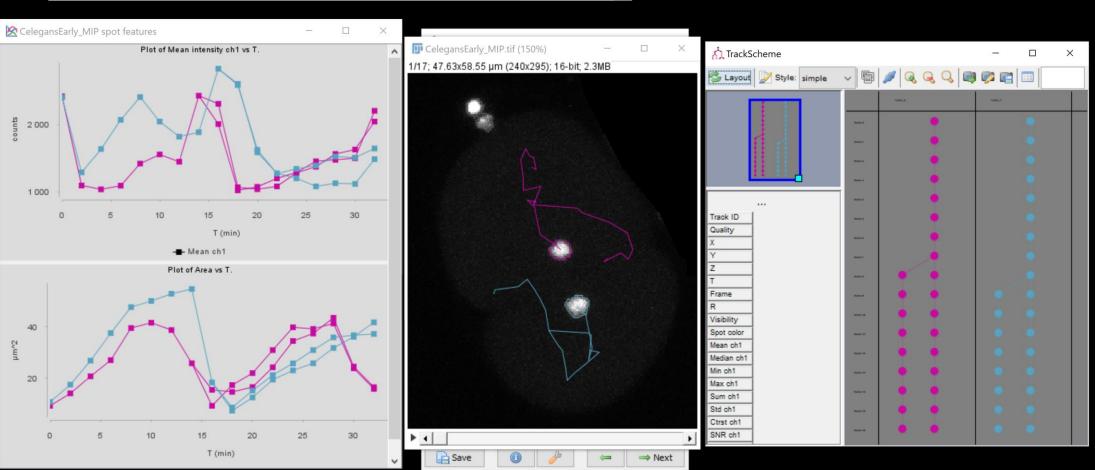




HANDS ON TRACKMATE

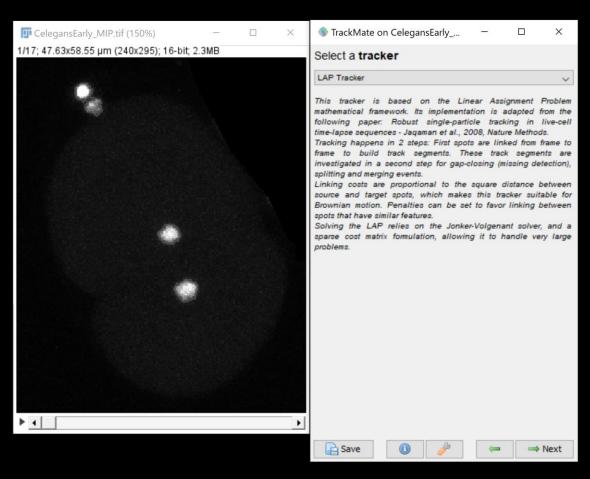
Plot features, save results...





Use LAP tracker with splitting and filter out track(s) to directly obtain the 2 tracks for cells





Use LAP tracker with splitting and filter out track(s) to directly obtain the 2 tracks for cells

Video tutorial: https://youtu.be/QBSRsv6gxi8



