CSE 330 LABORATORY -- Week 6, Spring 2018

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In this lab, you will be implemeting the ADT called Binary<u>Search</u>Tree. This data stucture will provide us with an alternative to vectors and linked lists when it comes to storing a list of data values.

Exercise 1: Implement the BinarySearchTree ADT in a file BinarySearchTree.h exactly as shown below. As always, make an effort to copy mindfully, trying to understand the purpose of each line of code as you go along.

```
// BinarySearchTree.h
// afater Mark A. Weiss, Chapter 4
// KV replaced exceptions with assert statements;
// we are writing <typename C> to indicate that the template type must be
// "comparable", i.e., have defined <, > and == operators;
#ifndef BINARY_SEARCH_TREE_H
#define BINARY_SEARCH_TREE_H
#include <cassert>
#include <algorithm>
using namespace std;
template <typename C>
class BinarySearchTree
 public:
    BinarySearchTree( ) : root{ nullptr }
    BinarySearchTree( const BinarySearchTree & rhs ) : root{ nullptr }
        root = clone( rhs.root );
   BinarySearchTree( BinarySearchTree && rhs ) : root{ rhs.root }
       rhs.root = nullptr;
    ~BinarySearchTree( )
        makeEmpty();
```

```
BinarySearchTree & operator=( const BinarySearchTree & rhs )
    BinarySearchTree copy = rhs;
    std::swap( *this, copy );
    return *this;
}
BinarySearchTree & operator=( BinarySearchTree && rhs )
    std::swap( root, rhs.root );
    return *this;
const C & findMin( ) const
  assert(!isEmpty());
   return findMin( root )->element;
const C & findMax( ) const
  assert(!isEmpty());
  return findMax( root )->element;
bool contains( const C & x ) const
    return contains( x, root );
bool isEmpty( ) const
    return root == nullptr;
void printTree( ostream & out = cout ) const
    if( isEmpty( ) )
        out << "Empty tree" << endl;</pre>
    else
        printTree( root, out );
void makeEmpty( )
    makeEmpty( root );
```

```
void insert( const C & x )
      insert( x, root );
  void insert( C && x )
      insert( std::move( x ), root );
  void remove( const C & x )
      remove( x, root );
private:
  struct BinaryNode
      C element;
      BinaryNode *left;
      BinaryNode *right;
      BinaryNode( const C & theElement, BinaryNode *lt, BinaryNode *rt )
        : element{ theElement }, left{ lt }, right{ rt } { }
      BinaryNode( C && theElement, BinaryNode *lt, BinaryNode *rt )
        : element{ std::move( theElement ) }, left{ lt }, right{ rt } { }
  };
  BinaryNode *root;
  // Internal method to insert into a subtree.
  // x is the item to insert.
  // t is the node that roots the subtree.
  // Set the new root of the subtree.
  void insert( const C & x, BinaryNode * & t )
      if( t == nullptr )
          t = new BinaryNode{ x, nullptr, nullptr };
      else if( x < t->element)
          insert( x, t->left );
      else if( t->element < x )</pre>
          insert( x, t->right );
      else
          ; // Duplicate; do nothing
  }
```

```
// Internal method to insert into a subtree.
// x is the item to insert.
// t is the node that roots the subtree.
// Set the new root of the subtree.
void insert( C && x, BinaryNode * & t )
    if( t == nullptr )
        t = new BinaryNode{ std::move( x ), nullptr, nullptr };
    else if ( x < t->element )
        insert( std::move( x ), t->left );
    else if( t->element < x )
        insert( std::move( x ), t->right );
        ; // Duplicate; do nothing
}
// Internal method to remove from a subtree.
// x is the item to remove.
// t is the node that roots the subtree.
// Set the new root of the subtree.
void remove( const C & x, BinaryNode * & t )
    if( t == nullptr )
        return; // Item not found; do nothing
    if(x < t->element)
        remove( x, t->left );
    else if( t->element < x )
        remove( x, t->right );
    else if( t->left != nullptr && t->right != nullptr ) // Two children
        t->element = findMin( t->right )->element;
        remove( t->element, t->right );
    else
        BinaryNode *oldNode = t;
        t = ( t->left != nullptr ) ? t->left : t->right;
        delete oldNode;
}
// Internal method to find the smallest item in a subtree t.
// Return node containing the smallest item.
BinaryNode * findMin( BinaryNode *t ) const
    if( t == nullptr )
        return nullptr;
    if( t->left == nullptr )
        return t;
    return findMin( t->left );
}
```

```
// Internal method to find the largest item in a subtree t.
// Return node containing the largest item.
BinaryNode * findMax( BinaryNode *t ) const
{
    if( t != nullptr )
        while( t->right != nullptr )
            t = t->right;
    return t;
}
// Internal method to test if an item is in a subtree.
// x is item to search for.
// t is the node that roots the subtree.
bool contains( const C & x, BinaryNode *t ) const
    if( t == nullptr )
        return false;
    else if( x < t->element )
        return contains( x, t->left );
    else if( t->element < x )</pre>
        return contains( x, t->right );
    else
        return true;
                       // Match
}
void makeEmpty( BinaryNode * & t )
    if( t != nullptr )
        makeEmpty( t->left );
        makeEmpty( t->right );
        delete t;
    t = nullptr;
void printTree( BinaryNode *t, ostream & out ) const
    if( t != nullptr )
        printTree( t->left, out );
        out << t->element << endl;</pre>
        printTree( t->right, out );
}
BinaryNode * clone( BinaryNode *t ) const
    if( t == nullptr )
        return nullptr;
    else
        return new BinaryNode{ t->element,
                                clone( t->left ), clone( t->right ) };
}
```

```
};
#endif
```

Exercise 2: Program your own file BinarySearchTreeMain.cpp in which your main() function will test the new data structure. Declare an instance of BinarySearchTree (short: BST) suitable to hold integer values. Then enter a random sequence of 25 integer values into the data structure (your values should NOT be in sorted order).

Use the print_Tree () member function in order to print out the values of the BST structure – What do you notice?

Next, remove 5 values from your BST and save them in a vector (use your own Vector.h or STL <vector>). Print out the reduced BST.

Exercise 3: Next add the following member function do your BinarySearchTree class:

Under public:

```
void printInternal()
{
    print_Internal(root,0);
}

Under private:

void printInternal(BinaryNode* t, int offset)
{
    if (t == nullptr)
        return;

    for (int i = 1; i ≤ offset; i++)
        cout ≪ ".."
    cout ≪ t->element ≪ endl;
    printInternal(t->left, offset + 1);
    printInternal(t->right, offset + 1);
}
```

Go back to your program BinarySearchTreeMain.cpp and change printTree to printInternal. Compile and run your program, and see what you get.

Next, insert the 5 value that have been removed back into the BST. Print the new BST with printInternal. How does this printed BST compare with the BST that the program printed befre the removal of 5 values? Same? Different? Explanation?

Credit for this lab (Tuesday Group): (1) Sign up on the signup sheet. (2) Email to Sarthak by Thursday 5/10, 11:59pm, a copy/scan/photo of the completed worksheet "Algorithm Complexities of BinarySearchTree Functions".

CSE 330 – Spring 2018 – Lab6 Worksheet "Algorithm Complexities of BinarySearchTree Functions"

Indicate worst case complexity:

BinarySearchTree Member Fct	One of: O(1), O(logN), O(N), O(NlogN), O(N ²)
void insert(x)	
void remove(x)	
bool contains(x)	
C findMin()	
C findMax()	
bool isEmpty()	
void makeEmpty()	
void printTree()	

(8 lab points for this table)

For some reason, our ADT BinarySearchTree does not have a 'int BinarySearchTree::size()' member function. We can easily add one. Write your implementation of the size() function by hand below. Recursion will make this easy.

```
template <typename C>
int BinarySearchTree<T>::size()
{
```

```
(2 lab points for this function)
```