

AALBORG UNIVERSITY

---

# Design of non-linear controller for hysteresis cancellation

---

Control and Automation:  
9th. Semester project

Group:  
CA9-939

10 January 2018





**Third year of study**  
Control and Automation  
Fredrik Bajers Vej 7  
DK-9220 Aalborg Ø, Danmark  
<http://www.es.aau.dk>

## **AALBORG UNIVERSITY**

### **STUDENT REPORT**

**Title:**

Design a non-linear controller for  
hysteresis cancellation

**Abstract:**



**Project period:**

P9, Autumn semester 2017

**Projectgroup:**

CA9-939

**Participants:**

Jacob Naundrup Pedersen

**Supervisors:**

Brian Kongsgaard Nielsen  
Jan Dimon Bendtsen  
Carsten Skovmose Kallesøe

**Copies: 5**

**Pages: 85**

**Completed: 10-01-2018**



# Preface

---

This report has been created by Jacob Naundrup Pedersen. The project is performed on the 3rd semester of the master control and automation at Aalborg University. The project is constructed in an internship at Grundfos. Grundfos has contributed with the test setup for the project. The student has followed two courses at Aalborg University, non-linear systems and machine learning.

The report is intended for people with a background knowledge corresponding to a third-semester master student at Control and Automation, Aalborg University. The following programming languages MATLAB and Simulink are used in the project. All graphical elements in the report are constructed by the author. Otherwise, a reference to the source, is stated in the figure text.

Sources are indicated by [name,year], and can be found in the bibliography list at the given [name,year].

---

Jacob Naundrup Pedersen

---



# Contents

---

Nomenclature	ix
1 Introduction	1
Bibliography	3
A Appendix	5





# Nomenclature

## Abbreviation

Abbreviation	Definition
AAU	Aalborg University
OD	Opening degree
Stiction	Static friction
MM	Mickey Mouse
BBB	BeagleBone Black
KCL	Kirchoff current law

## Symbols

Symbol	Description	Units
$A$	Area	$m^2$
$q$	Water flow	$m^3/s$
$D$	Diameter meter	$m$
$r$	Radius	$m$
$\omega$	Velocity	$rad/s$
$U_a$	Voltage	$J/C$
$N$	Gear ratio	
$\tau$	Torque	$Nm$
$i_a$	Current	$C/s$
$R_a$	Resistance	$\Omega$
$L_a$	Inductor	$H$
$K$	Electromotive force	$\frac{V \cdot s}{rad}$
$F$	Force	$N$
$\theta$	Angle	$rad$
$\Delta p$	Differential pressure	$bar$
$K_{vs}$	Conductivity for fully-open valve	$m^3/h$
$v$	Velocity	$m/s$
$m$	Mass	$kg$
$V$	Volume	$m^3$
$\rho$	Density	$kg/m^3$
$l$	Length	$m$
$f$	Friction factor	
$h_f$	Surface resistance	$m$
$g$	Gravitational acceleration	$m/s^2$
$k_L$	Form-loss coefficient	
$h_l$	Form resistance	$m$
$h$	Pressure	$m$
$J$	Inertance	$kg/m^4$
$a_n$	Pump parameters	
$T$	Temperature	$^{\circ}C$

$c$	Specific heat capacity	$\frac{J}{kg \cdot K}$
$m_n$	Mass flow	$kg/s$

# Introduction

---

# 1

Indled med noget historie om kloaker hej



## Bibliography

---



# Appendix A

---