

An *a posteriori* measure of network modularity

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Abstract

Measuring the modularity of networks, and how it deviates from random expectations, important to understand their structure and emerging properties. Several measures exist to assess modularity, which when applied to the same network, can return both different modularity values (*i.e.* different estimates of how modular the network is) and different module compositions (*i.e.* different groups of species forming said modules). More importantly, as each optimization method uses a different optimization criterion, there is a need to have an *a posteriori* measure serving as an equivalent of a goodness-of-fit. In this article, I propose such a measure of modularity, which is simply defined as the ratio of interactions established between members of the same modules *vs.* members of different modules. I apply this measure to a large dataset of 290 ecological networks representing host–parasite (bipartite) and predator–prey (unipartite) interactions, to show how the results are easy to interpret and present especially to a broad audience not familiar with modularity analyses, but still can reveal new features about modularity and the ways to measure it.

1 Introduction

- Modularity, the fact that groups of nodes within a network interact more frequently with themselves than with other nodes, is an important property of several systems,

4 including genetic [1, 2], informatics [3], ecological [4], and socio-economic [5] inter-
5 actions, as well as biogeographic patterns [6, 7] and disease spread management [8].
6 Because of the relevance of modularity for network properties, it is important to as-
7 sess it correctly. There exists several methods to measure network modularity, some
8 of which rely on the optimization of a given criterion [9, 10], label propagation [11], or
9 combination of these approaches [12, 13]. These methods return two elements. The
10 first is a value of modularity for the networks, most often within the 0–1 interval.
11 Each method often has a threshold value, above which a network is considered to be
12 modular. Increasing values reflect and increasingly modular structure. The second
13 element is a “community partition”, *i.e.* the attribution of each node to a module.

14 Recently, Thébault [7] showed that different measures of modularity tailored
15 to presence/absence matrices (*i.e.* networks in which links have no weight), gave
16 roughly equal estimates of the significance of modularity, but differed in the com-
17 munity partition they returned (*i.e.* the identity of nodes composing each module
18 varied). In such situations, one might look for a way to choose which community
19 partition should be used. The challenge in this situation is that the criteria used by
20 each optimisation method cannot be meaningfully compared, and so there is a need
21 for *a posteriori* measurement of how strong the modular structure is, regardless of
22 the method used to obtain the community partition. More importantly, this crite-
23 rion should be *different* than the one used to track the progress of any optimisation
24 algorithm.

25 An important feature of modular networks is the occurrence of interactions be-
26 tween nodes of different modules. They contribute to the propagation of disturbances

27 [4], flow of information [14, 15], and cross- regulation of biological processes [16], *in-*
 28 *ter alia* [17]. In addition to measuring how modular the network is, determining
 29 to what extent modules are connected, and to identify nodes and edges responsible
 30 for connecting modules, is thus valuable information. In this article, I propose an
 31 *a posteriori* measure of the proportion of interactions established between modules,
 32 *i.e.* edges connecting different communities. I apply this measure to the community
 33 partition identified by the Louvain method on 290 ecological networks, and show
 34 that it behaves in a similar way to other modularity measures.

35 2 The measure

36 In this contribution I define the *realized modularity*, termed Q_R . Q_R measures the
 37 extent to which edges, within a network, are established between nodes belonging to
 38 the same module. For E edges in a network, if W of them are established between
 39 members of the same module, then

$$Q_R = \frac{W}{E}. \quad (1)$$

40 When there are no between-module links, then $W = 0$ and Q_R takes the maximal
 41 value of 0. When between-module interactions are as numerous as within-modules
 42 interactions, then $W = E/2$, and Q_R takes the minimal value of 1/2. To express the
 43 *realized modularity* as a value between 0 and 1, it is expressed as:

$$Q'_R = 2 \times Q_R - 1. \quad (2)$$

44 Note that Q'_R will yield values in the $[0; 1]$ interval only if there are more edges
45 established *within* than *between* modules. Although if modules are determined at
46 random, Q'_R values are expected to be centered on 0, it is expected that they will
47 increase when modules are properly optimized (only as far as the network is modular).

48 The main advantage of Q_R is that it is agnostic with regard to the measure used
49 to optimize modularity (and even to the method by which the nodes were assigned to
50 modules, which can be arbitrary), as it acts *a posteriori*, *i.e.* after nodes have been
51 attributed to modules. Nonetheless, it assumes a simple yet functional definition of
52 modularity: the fact that nodes interact more within than between modules. Given
53 that measuring to which extent this is true, it can therefore be used to select the
54 community detection method maximizing modularity. This measure works on most
55 type of networks, as it makes no difference if links are directional, or if the networks
56 are bipartite/unipartite. An illustration of this measure is given in Figure 1. This
57 measure is purposefully simple, (i) so that it makes only minimal assumptions about
58 what modularity is (except for the fact that in a modular network, nodes interact
59 more within than between modules), or how it should be optimized, and (ii) because it
60 is not meant to be used to optimize modularity, but to either compare the outcome of
61 different methods, or present the value of modularity in a way that is straightforward
62 to interpretate.

63 A python implementation of this measure, using the `networkx` package, is pro-
64 posed at <https://gist.github.com/tpoisot/4947006>. It reads data in the edge
65 list format, and offers additional functions to generate null networks, as detailed in
66 the following section.

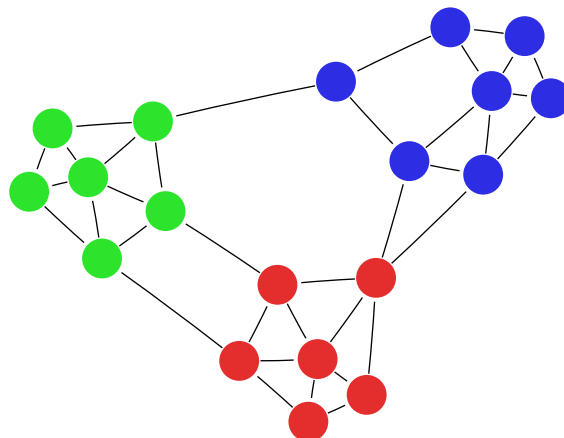


Figure 1: A cartoon depiction of a modular network with links between modules. Nodes of the same modules are identified by different colors. This network has a modularity (Louvain method) of $Q = 0.527$. Out of the 36 interactions, 31 are established within modules, and 5 between modules. This gives a Q_R value of 0.86, and $Q'_R = 0.72$.

3 Example application: realized modularity in ecological networks

In this section, I analyze the modular structure of a large dataset of 290 ecological networks (187 food webs and 113 host-parasite networks) published in previous meta-analyses [18, 19]. Modularity is an important feature of ecological interaction networks, which is linked to their resilience [20, 21], stability [7], biogeographic structure [22], functioning [23], and to the evolutionary mechanisms involved in their assembly [24]. Notably, the occurrence of interactions between and within modules plays a central role in the structure of pollination networks [4], and help buffer the effect of species extinctions [21].

77 The existence of interactions in ecological systems involves a large family of pro-
 78 cesses, ranging from abundance related [25, 26] (abundant species are more likely to
 79 interact together) to trait related [27] (pollination depends on the flower and in-
 80 sect having compatible morphologies, predators are constrained by the body-size of
 81 their preys). The interaction within these different families of mechanisms will drive
 82 heterogeneity in interaction strength [28]. Yet, the analysis of binary matrices (is
 83 there an interaction between a pair of species, or not), still has relevance to identify
 84 properties that are conserved across systems [29], especially given that one could
 85 argue that quantitative information on interaction strength is an additional level of
 86 information. The systems analyzed in this section are represented by their adjacency
 87 matrix, describing the presence or absence of an interaction. Bipartite networks have
 88 further been transformed into unipartite networks before analysis.

89 **3.1 Data and analysis**

90 I used the Louvain method [30] to detect modules, due to its rapidity and efficiency
 91 on large networks. The Louvain method works in two steps: first it optimizes mod-
 92 ularity *locally*, through clustering of neighboring nodes. These clusters are, in the
 93 second steps, aggregated together, until modularity ceases to increase. This method
 94 is known to give values of modularity comparable to what is found using *e.g.* sim-
 95 ulated annealing, and has been observed to give modules that have a functional
 96 relevance [30]. Once the partition is returned by the Louvain method, I recorded its
 97 realized modularity Q'_R , and its modularity Q (using the Newman and Girvan [31]
 98 measure).

99 For each network, I compared the values of Q and Q'_R on the empirical networks
 100 to their random estimate using a network null model. Because random networks will
 101 by chance (here meaning, as expected by networks having a given connectance and
 102 thus degree distribution, Poisot and Gravel [32]) display a modular (among other)
 103 structure, it is important to confront the empirical measures of both Q and Q'_R to
 104 their random expectations. The null model is defined as follows. For each node n
 105 of the network, I measured its degree d_n , its number of successors (the number of
 106 node it links to, or generality in ecological terms, as *per* [33]) g_n , and its number
 107 of predecessors (the number of nodes that link to it, or vulnerability) v_n . In each
 108 random network, for each pair of nodes (i, j) , the probability that i interacts with j
 109 is given by

$$P(i \rightarrow j) = \frac{1}{2} \left(\frac{g_i}{d_i} + \frac{v_j}{d_j} \right), \quad (3)$$

110 and conversely for $P(j \rightarrow i)$. This null model allowed the generation of pseudo-
 111 random networks through a Bernoulli process (in each replicate, the occurrence of
 112 a link is randomly determined), with the same expected connectance, and the same
 113 expected distribution of degrees, generality, and vulnerability, as the original one
 114 (these properties are also conserved at the *node* level). For each of the 290 networks,
 115 1000 pseudo-random replicates are generated. For each of them, the average value of
 116 Q_R and Q'_R are estimated along with their 90% confidence interval. When the em-
 117 pirical value lies outside the confidence interval, it can be assumed that the modular
 118 structure of the network is different than expected by chance.

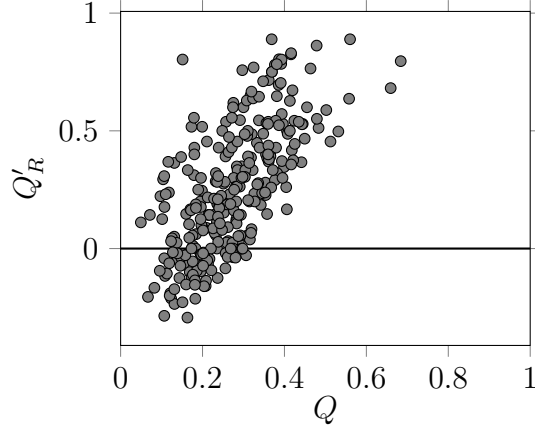


Figure 2: Relationship between the modularity of the best partition using the Louvain method and the *a posteriori* realized modularity. There exists a strong, positive relationship between the two variables. Worth noting is that fact that, for some networks, the best partition resulted in *negative* versions of Q'_R , *i.e.* there were more interactions between than within modules. Each dot correspond to a network.

3.2 Results and Discussion

There is a strong, positive relationship, between the values of Q'_R and the values of Q (Pearsons's product-moment correlation coefficient, as implemented in R 2.15 [34], $\rho = 0.64$, 288 d.f., $p < 10^{-6}$), *i.e.* networks for which a high modularity is detected tend to have relatively few between-module links (Figure 2). It is worth noting that some Q'_R values were negative: in some cases, the best community division resulted in more interactions between than within modules. This result highlights why using an *a posteriori* measure is useful: other measures of modularity do not reveal the fact that there were more interactions between than within modules. In the dataset examined, most of the networks with a modularity lower than 0.2 had a negative realized modularity. This result suggests that discussing the modularity of such

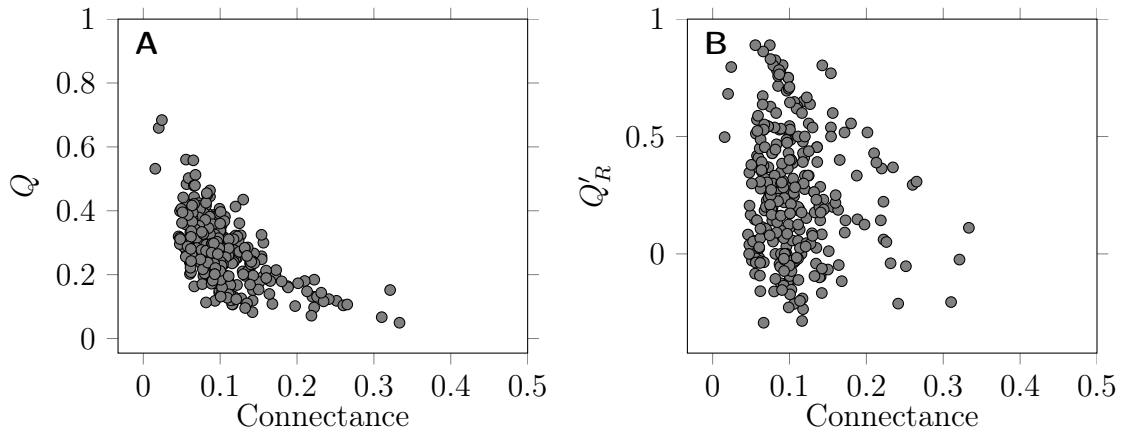


Figure 3: Relationship between the two measures of modularity and network connectance. **A.** Q is negatively affected by connectance, *i.e.* densely connected networks are more likely not to be modular. **B.** Q'_R is not affected by connectance, allowing to use it to compare different networks. Each dot correspond to a network.

networks makes little sense, as their modules are not more densely connected, within a module, than other random collections of nodes within the graph. Q and Q'_R have different relationships with connectance (Figure 3). Increased connectance values resulted in lower modularity ($\rho = -0.61$, 288 d.f., $p < 10^{-6}$), but had no impact on Q'_R . This is a desirable property, as it allows easy comparison with the Q'_R values of networks with extremely different connectances.

There is a linear relationship between the deviation from random expectation of Q and Q'_R ($\rho = 0.78$, 288 d.f., $p < 10^{-6}$ – Figure 4). The deviations (respectively ΔQ and $\Delta Q'_R$) are calculated as the empirical value, minus the average of the values on the networks generated by the null model. As an example, a ΔQ less than zero indicates that the empirical network is less modular than expected by chance. Confidence intervals for the average of the null models were typically very narrow

142 (not represented in the figure to avoid cluttering – see associated original dataset),
 143 probably owing to the fact that the null model is restrictive on the type of networks
 144 which are generated. It is worth noting that for some networks, the diagnostic of
 145 the null model analysis conflicted. In a vast majority of the situations, this corre-
 146 sponds to networks having a lower modularity than expected by chance, yet having
 147 a higher realized modularity (dots in the upper left corner of Fig. 4). In this type
 148 of situations, whereas one would usually conclude that the networks are not sig-
 149 nificantly modular, the identified modules are nonetheless more densely connected
 150 (internally) than they are with the rest of the network. Because the dataset presents
 151 these contrasted situations, it allows to understand how the measure reacts to differ-
 152 ent network structures. Depending on whether the true modularity, or the realized
 153 modularity, is the most relevant metric of the processes studied, the interpretation
 154 of the null models for these networks will be different.

155 Finally, for the unipartite network dataset, I compare the results of three alterna-
 156 tive methods of community detection (the walktrap, spinglass, and edge betweenness
 157 methods, as implemented in the *igraph* library). For each of the unipartite networks,
 158 I computed the value of Barber’s Q , and Q'_R , on the best partition found. The
 159 strong correlation between Q and Q'_R were observed for the spinglass method ($\rho =$
 160 0.61, 165 d.f., $t = 10.02$), and the weakest for the edge-betweenness method ($\rho = 0.04$,
 161 non-significant at $\alpha = 0.05$). The walktrap algorithm gave results in between ($\rho =$
 162 0.489, 165 d.f., $t = 7.20$). For both the walktrap and edge-betweenness methods, sev-
 163 eral networks had negative values of Q'_R , which indicates that the “best” community
 164 partition had more links between than within modules. The spinglass method had,

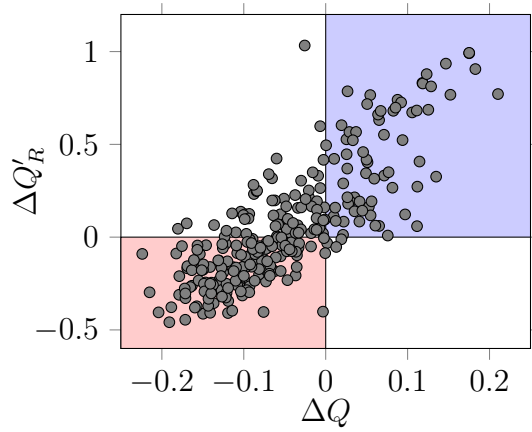


Figure 4: Linear relationship between the deviation from random expectation in Q and Q'_R . Networks in the red area are detected as being less modular than expected both by Q'_R and Q , while networks in the blue area are detected as being more modular. Although the agreement between the two measures is good (see main text for statistics), some networks are detected as having a higher than expected realized modularity Q'_R , despite a lower than expected modularity Q . Each dot correspond to a network.

by contrast, less than 8% of all networks with values of Q'_R lower than 0, meaning that this algorithm should be preferred when one wants to group nodes in densely connected clusters. This result reinforces the statement made by Thébault [7], *i.e.* that several modularity optimisation methods will return best modular structure that widely in their properties; thus, there is a need for *a posteriori* comparison of these outputs.

4 Conclusions

The Q'_R measure presented here allows the estimation of the proportion of interactions established between different modules in a network. This measure can be analyzed much in the same way as other measures of modularity, but is applied *a posteriori*. As such, it can help choose the “best” community partition according to the property of the network that one wants to maximize. For example, choosing the partition giving the lowest Q'_R can help identify which species are more likely to act as connectors between different modules. Ultimately, this information may have some practical relevance as a decision tool. Saavedra et al. [5] showed that different nodes contribute differently to overall network properties. In a context in which networks are increasingly being used as management tools to address *e.g.* conservation or pest management [8], knowing the realized modularity, and developing methods to estimate which species have the highest impact on it, can allow the design of efficient policies to maximize, or decrease, the ability of network modules to interact.

185 Competing interests

186 No competing interests were disclosed.

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