kinematic equations	
uniform circular motion	
kintec and potential energy	

$$\bar{v} = \frac{1}{2}(v_i + v_f)$$

$$\Delta v = a\Delta t + v_i$$

$$x(t) = \frac{1}{2}at^2 + v_i t + x_i$$

$$v_f^2 - v_i^2 = 2a\Delta x$$

$$a = \frac{v^2}{r}$$

$$E_{\rm trans} = \frac{1}{2}mv^2$$
 
$$E_{\rm rot} = \frac{1}{2}I\omega^2$$
 
$$E_{\rm gpe} = mgh$$
 
$$E_{\rm sho} = \frac{1}{2}kx^2$$

potential energy, force, work
gravitational force
angular momentum



$$\vec{F} = -Gm_1m_2r^{-2}\hat{r}_{12}$$

$$\vec{L} = \vec{r} \times \vec{p} = I \vec{\omega}$$

torque
constant angular velocity
spherical elements

$$\tau = \vec{r} \times \vec{F} = \frac{d\vec{L}}{dt}$$

$$\vec{F} = -m\Omega^2 r \hat{r}_{\text{centrifuge}} - 2m\vec{\Omega} \times \vec{v}$$

$$\begin{split} d\vec{l} &= dr\hat{r} + rd\theta\hat{\theta} + r\sin\theta d\phi\hat{\phi} \\ d\vec{S} &= r^2\sin\theta d\theta d\phi\hat{r} + r\sin\theta drd\phi\hat{\theta} + rdrd\theta\hat{\phi} \\ dV &= r^2\sin\theta drd\theta d\phi \end{split}$$

moment of inertia	
Lagrangian	
Hamiltonian	

$$I=\int s^2dm$$
 
$$I=I_{\rm CM}+Ms^2$$
 
$$I_z=I_x+I_y \mbox{ for } z \mbox{ perpendicular to the body lying in the } x-y \mbox{ plane}$$

$$L(\dot{q}_i, q_i, t) = T - U$$
$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} = \frac{\partial L}{\partial q_i}$$
$$p_i = \frac{\partial L}{\partial \dot{q}_i}$$

$$\begin{split} H(p,q) &= \sum_i p_i \dot{q}_i - L \\ H &= T + U \text{ if } U \text{ is independent of } \dot{q} \text{ and } t \\ \dot{p} &= -\frac{\partial H}{\partial q} \\ \dot{q} &= \frac{\partial H}{\partial p} \end{split}$$

effective orbital potential
Kepler's laws
damped oscillation

$$E = T + V = \frac{1}{2}m\dot{r}^2 + \frac{l^2}{2mr^2} + U(r)$$

$$l = mr^2\dot{\phi}$$

$$\mu = \frac{m_1m_2}{m_1 + m_2}$$

$$E > 0 \implies \text{hyperbolic}$$

$$E = 0 \implies \text{parabolic}$$

$$E < 0 \implies \text{elliptical}$$

- Planets move in elliptical orbits with one focus at the sun
- Equal orbital area sweeps out equal orbital time
- $T = ka^{\frac{3}{2}}$  for all planets

$$0 = m\ddot{x} + b\dot{x} + kx$$
 
$$\beta = \frac{b}{2m}$$
 
$$\omega_0 = (\frac{k}{m})^{\frac{1}{2}}$$

- $\beta^2 > \omega_0^2$ : overdamped decays exponentially
- $\beta^2 = \omega_0^2$ : critically damed
- $\beta^2<\omega_0^2$ : underdamped decays exponentially, modulated by a sinusoid at  $\omega_1^2=\omega_0^2-\beta^2$

driven oscillation
oscillators
fluid dynamics

$$\begin{split} \omega_{\rm R} &= (\omega_0^2-2\beta^2)^{\frac{1}{2}} \\ D &\propto \left|\omega_0^2-\omega^2\right|^{-1} \text{ for undamped, driven oscillator} \end{split}$$

- pendulum  $\omega = (\frac{g}{l})^{\frac{1}{2}}$
- physical pendulum  $\omega = (\frac{mgR}{I})^{\frac{1}{2}}$

$$\frac{v^2}{2} + gz + \frac{p}{\rho} = \text{const}$$

p pressure,  $\rho$  fluid density, z height of a point along streamline  $F = \rho V g$